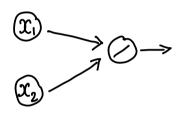
Consider a two-input problem with a continuous dependent vaniable and no hidden layers.



What are the parameters to be learnel?

$$(x_1)$$
  $(x_2)$   $(x_3)$   $(x_4)$   $(x_4)$   $(x_5)$   $(x_5$ 

model 
$$(x_1, x_2) = b + w_1 x_1 + w_2 x_2$$
  
loss =  $(\text{model}(x_1, x_2) - y)^2$   
loss =  $(b + w_1 x_1 + w_2 x_2 - y)^2$ 

$$\frac{\partial loss}{\partial b} = 2(b + w_1 x_1 + w_2 x_2 - y)$$

$$\frac{\partial loss}{\partial w_1} = 2(b + w_1 x_1 + w_2 x_2 - y) x_1$$

$$\frac{\partial loss}{\partial w_2} = 2(b + w_1 x_1 + w_2 x_2 - y) x_2$$

Now, let's organize the Let  $C_1 = W_1 \times 1$ Calculations a bit  $C_2 = W_2 \times 2$ differently

Let 
$$\alpha_1 = W_1 \times 1$$
  
if  $\alpha_2 = W_2 \times 2$   
 $\hat{y} = b + \alpha_1 + \alpha_2$   
Physing  $\gamma$  into  $\gamma$ 

Loss = (b+w, x, +w2x2 - y)2

we get:

$$\frac{\partial loss}{\partial b} = ? \qquad \frac{\partial loss}{\partial \omega_1} = ? \qquad \frac{\partial loss}{\partial \omega_2} = ?$$

We can apply the Chain Rule!

$$\frac{\partial loss}{\partial b} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial b}$$

$$\frac{\partial loss}{\partial b} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial b}$$

$$\frac{\partial loss}{\partial w_{1}} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial a_{1}} \cdot \frac{\partial a_{1}}{\partial w_{1}}$$

$$\frac{\partial loss}{\partial w_{2}} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial a_{1}} \cdot \frac{\partial a_{2}}{\partial w_{2}}$$

$$\frac{\partial loss}{\partial w_{2}} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial a_{2}} \cdot \frac{\partial \dot{y}}{\partial w_{2}} \cdot \frac{\partial a_{2}}{\partial w_{2}}$$

$$\frac{\partial loss}{\partial w_{2}} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial a_{1}} \cdot \frac{\partial a_{2}}{\partial w_{2}}$$

$$\frac{\partial loss}{\partial w_{2}} = \frac{\partial loss}{\partial \dot{y}} \cdot \frac{\partial \dot{y}}{\partial a_{2}} \cdot \frac{\partial \dot{y}}{\partial w_{2}}$$

Next, we need to cakulate

$$\frac{\partial U_{SS}}{\partial \hat{y}}$$
,  $\frac{\partial \hat{y}}{\partial b}$ ,  $\frac{\partial \alpha_1}{\partial w_1}$  and  $\frac{\partial \alpha_2}{\partial w_2}$ 

But that's easy!

Loss = 
$$(\mathring{y}-\mathring{y})^2$$

$$\frac{\partial \mathring{u}s}{\partial \mathring{y}} = 2(\mathring{y}-\mathring{y})$$

$$\mathring{y} = \mathring{b} + \alpha_1 + \alpha_2$$

$$\frac{\partial \mathring{y}}{\partial \mathring{b}} = \frac{\partial \mathring{y}}{\partial \alpha_1} = \frac{\partial \mathring{y}}{\partial \alpha_2} = 1$$

$$\alpha_1 = W_1 \times 1$$

$$\alpha_2 = W_2 \times 2$$

$$\frac{\partial \alpha_2}{\partial W_2} = \times 2$$

$$\frac{\partial \alpha_2}{\partial W_2} = \times 2$$

Putting everything together:

$$\frac{\partial loss}{\partial b} = \frac{\partial loss}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial b} = 2(\hat{y}-y) \cdot 1$$

$$\frac{\partial loss}{\partial \omega_{1}} = \frac{\partial loss}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial a_{1}} \cdot \frac{\partial a_{1}}{\partial \omega_{1}} = 2(\hat{y}-y) \cdot 1 \cdot x_{1}$$

$$\frac{\partial loss}{\partial \omega_{2}} = \frac{\partial loss}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial a_{2}} \cdot \frac{\partial \hat{y}}{\partial a_{2}} \cdot \frac{\partial a_{2}}{\partial \omega_{1}} = 2(\hat{y}-y) \cdot 1 \cdot x_{2}$$

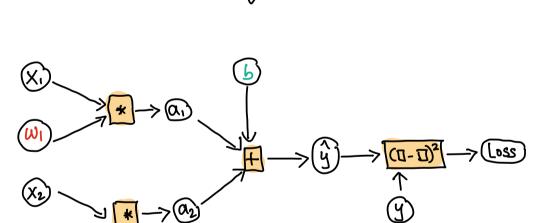
You can check this matches the "old fashioned" alcolation!!

OK, we are finally really for backpropagation!!

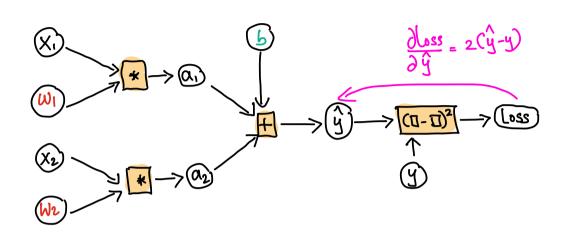
$$CI = W_1 \times I$$
 $Q2 = W_2 \times 2$ 
 $\hat{y} = b + Q_1 + Q_2$ 

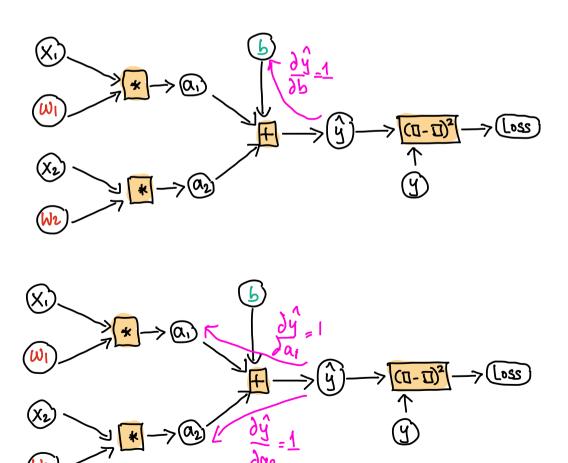
Loss =  $(\hat{y} - \hat{y})^2$ 

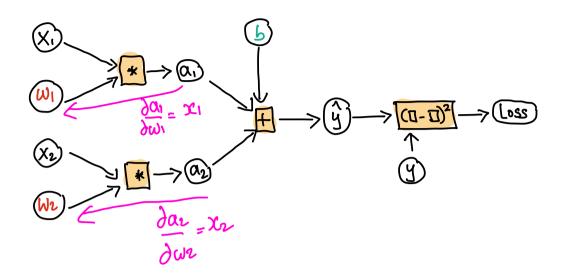
We will rewrite these equations as a computational graph



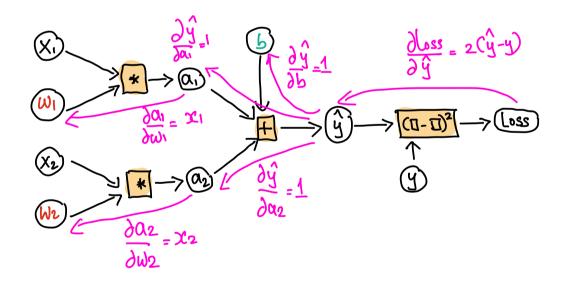
We can "attach" each of those little derivations we calculated earlier to the grouph.







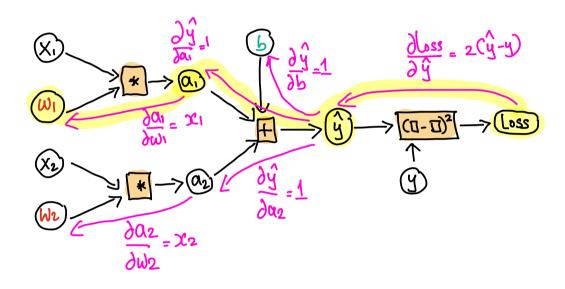
Putting everything fogether:



To calculate aloss, stoot from the lass and any parameter travel backwards to the parameter, multiplying the partial delivatives as you go.

This is called BACKPROPAGATION

To calculate <u>dloss</u>, for example:



Multiplying all the partial derivative on the yellow paths we get the answer:

$$\frac{\partial loss}{\partial w_{1}} = \frac{\partial loss}{\partial g} \cdot \frac{\partial g}{\partial a_{1}} \cdot \frac{\partial g}{\partial w_{1}} = 2(g-g) \cdot 1 \cdot x_{1}$$

## Does this match what we calculated earlier?

- Backprop is very efficient

   Cakulate once and use many times (e.g. doss)

   (When more than one newson in the layer) traversing backward is a series of matrix multiplications
  - GPUs are perfect for matrix multiplications!!