

# Functional differential equations

$$M \dot{x}(t) = f(x(t), \underbrace{x(t-\tau_1), \dots, x(t-\tau_m)}_{\text{many discrete delays approximate distributed delay}}, p)$$

many discrete delays approximate distributed delay

$$M \in \mathbb{R}^{n \times n}, \text{possibly singular}$$

→ neutral DDEs possible

$$\frac{d}{dt} [x + g(x(t), x(t-\tau_1), \dots, x(t-\tau_m), p)] = f(x(t), x(t-\tau_1), \dots, p)$$

or

$$\dot{y} = f(x(t), x(t-\tau_1), \dots, p)$$

$$\theta = x(t) + g(x(t), x(t-\tau_1), \dots, p) - y(t)$$

$\tau$  can depend on state:  $\tau_1(x(t), p), \tau_2(x(t), x(t-\tau_1), p), \dots$

→ implicitly defined delays are possible  
(H.-O. Walther, echo control)

$$\dot{x} = k[x_{ref} - \frac{c}{2}s(t-\tau_0)]$$

$$cs(t) = x(t-s(t)) + x(t)$$

Equilibria simple, solve  $\theta = f(x, \dot{x}, \dots, p)$

Periodic orbits: only addition is non-local terms.

$M\ddot{x} = T^f(x(t), x(t - \frac{\tau_1}{T}), \dots, p)$  for  $t \in (0, 1)$ , wrapping around for  $t \notin (0, 1)$   
on n.t.s.

Stability of equilibria: pseudo spectral method by Dimitri  
likely many eigenvalues relevant

$$M\partial_t x(t) = A_0 x(t, 0) + A_1 x(t, -\varepsilon_1) + \dots + A_m x(t, -\varepsilon_m)$$

$$\partial_t x(t, 0) = \theta_0 x(t, 0)$$

~ replace  $\begin{bmatrix} M & 0 \dots 0 \\ I & \end{bmatrix} \partial_t x = \begin{bmatrix} A_1 \theta(-\varepsilon_1) + \dots + A_m \theta(-\varepsilon_m) \\ \theta_0 \end{bmatrix}$

by (eg.) Chebyshev polynomials

Hopf bifurcations:  $\theta = f(x, \dot{x}, \dots, p)$

$$\text{variables: } x \in \mathbb{R}^n, p \in \mathbb{C}^m \text{ in } \theta = -M_i \omega v + \sum_{k=1}^m \partial_{x_k} f(x, \dot{x}, p) e^{-i\omega t_k}$$

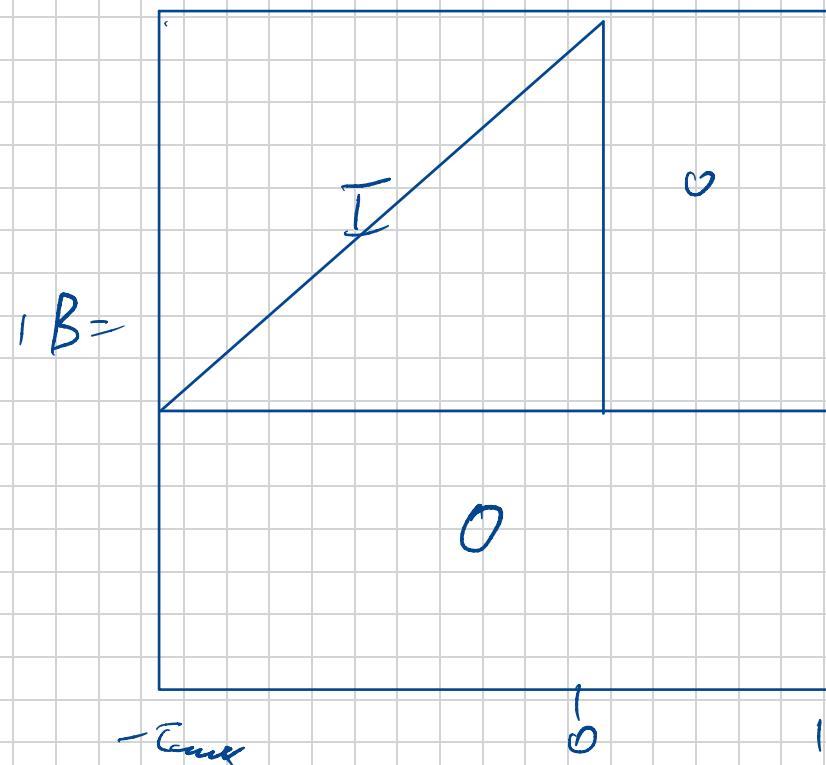
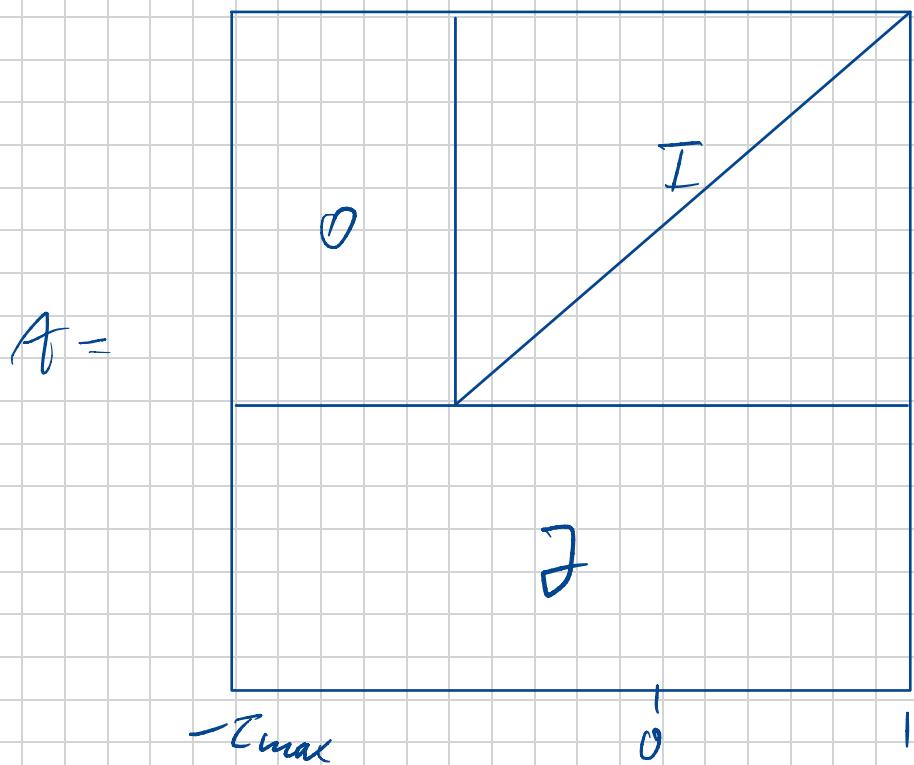
$$v \in \mathbb{R}, v \in \mathbb{C}^m \quad | \quad \theta = \bar{v}^T v - i$$

$$\frac{1}{3k+2} \theta = \log(\bar{v}_{kp}^T v)$$

# Stability of periodic orbits determine matrix

$$\mathcal{J}: \mathbf{y} \mapsto -MD\mathbf{y} + \sum_{k=1}^n p_k \partial_{x_k} f(\dots) [\mathbf{y}(t-\tau_k) - \sum_{j=1}^{k-1} x'(t-\tau_k) g_{kj} \mathbf{y}(t-\tau_j)]$$

$n_{\text{TSF}} \cdot \deg n \times (\text{TSF deg } n) \left( 1 + \frac{\tau_{\max}}{T} \right)$  matrix



& solve generalized sparse eigenvalue problem

$$A u = \mu B u$$

eigenvalues accumulate only at 0 if invertible.

interface identical to ODEcase  $\Rightarrow$  see demo, e.g. Mackey-Glass

difficulties: solving for neutral DDEs, for reversal equations

$$\text{Example: } x(t) = \frac{\delta}{\tau} \int_{\tau_2}^{t+\tau_2} x(s)(-x(s)) ds$$

$\Rightarrow$  demo in dde-problems