

Basic approach to solving non-linear problems

Problem : find root of $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ (n eqs., n vars)
~ solve $f(x) = 0$

Newton iteration :

initial guess $x_0 \in \mathbb{R}^n$ \leftarrow Jacobian off in x_k , $n \times n$ matrix

$$x_{k+1} = x_k - \partial f(x_k)^{-1} f(x_k) \quad (\text{in Matlab } "\backslash")$$

$$\text{until } \|x_k - x_{k-1}\| < \text{tol} \text{ & } \|f(x_k)\| < \text{tol}$$

When does this work?

- 1) f has root x_* ($f(x_*) = 0$)
- 2) $\partial f(x_*)$ not singular / inverse exists) \leftarrow we don't know x_* but most matrices are invertible
- 3) x_0 sufficiently close to x_* \leftarrow serious restriction if n is large

If 1)-3) are satisfied Newton converges fast

define $m(x) = \partial f(x)^{-1}$, $e_k = x_k - x_*$

$$f(x) = f(x_*) + m(x_*)^{-1}(x - x_*) + O((x - x_*)^2)$$

$$m(x) = m(x_*) + O(x - x_*)$$

$$x_{k+1} - x_* = x_k - x_* - m(x_k) [f(x_k) - f(x_*)]$$

$$e_{k+1} = e_k - [m(x_*) + O(e_k)] [m(x_*)^{-1} e_k + O(e_k^2)]$$

$$\underline{= O(e_k^2)} \quad \text{Quadratic convergence}$$

Basic approach to over coming problem (3) : $x_0 \approx x_\infty$

In practice, problems depend on parameters

$$\Theta = f(x, p) \quad , \quad f: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^m$$

We often know solution when p is special (e.g. $u_p=1, p=0$)

then (case $u_p=1$):

a) We know x_0 s.t. $f(x_0, p_0) = 0$

choose $\Delta t < 1$, $p_{k+1} = p_k + \Delta t$ for $k \geq 0$

b) use x_{k-1} , the solution of $f(x_{k-1}, p_{k-1}) = 0$ as initial guess when solving $f(x, p_k) = 0$

This works as long as $\frac{\partial f}{\partial x}(x_k, p_k)$ is not singular.

Example: equilibria of A B reactions \Rightarrow Demo

$$\dot{x}_1 = -x_1 + \alpha (1-x_1) e^{x_2}$$

x_1 = concentration fraction

$$\dot{x}_2 = -(\gamma\beta)x_2 + \beta(1-x_1) e^{x_2}$$

γ = temperature

\Rightarrow Problem occurs when equilibria make curve that "turns around" ($=$ fold) in parameter p

\Rightarrow more general approach **Pseudo arclength continuation**

$$(x, p) = y \in \mathbb{R}^{n+1}, f(x, p) = f(y), \varphi: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$$

set of equations $Y = \{y \in \mathbb{R}^{n+1}: f(y) = 0\} \subseteq \mathbb{R}^{n+1}$ forms curve

We know one point y_0 with $f(y_0) = 0$, and tangent z_0 to Y in y_0 .
 $(\|z_0\| = 1)$

Set $s \ll 1$ stepsize.

Step 1) predictor : $P_{k+1} = y_k + s z_k$

2) corrector : apply Newton iteration to

$$f(y) = 0 \quad n \text{ eqs.}$$

$$z_k^T (y - P_{k+1}) = 0 \quad 1 \text{ eq.}$$

solution y_{k+1}

$$K^3) \text{ new tangent: solve } \begin{bmatrix} 0 & f(y_{k+1}) \\ z_k^T & 1 \end{bmatrix} z_{k+1} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

rescale $z_{k+1} \rightarrow z_{k+1} / \|z_{k+1}\|$

