

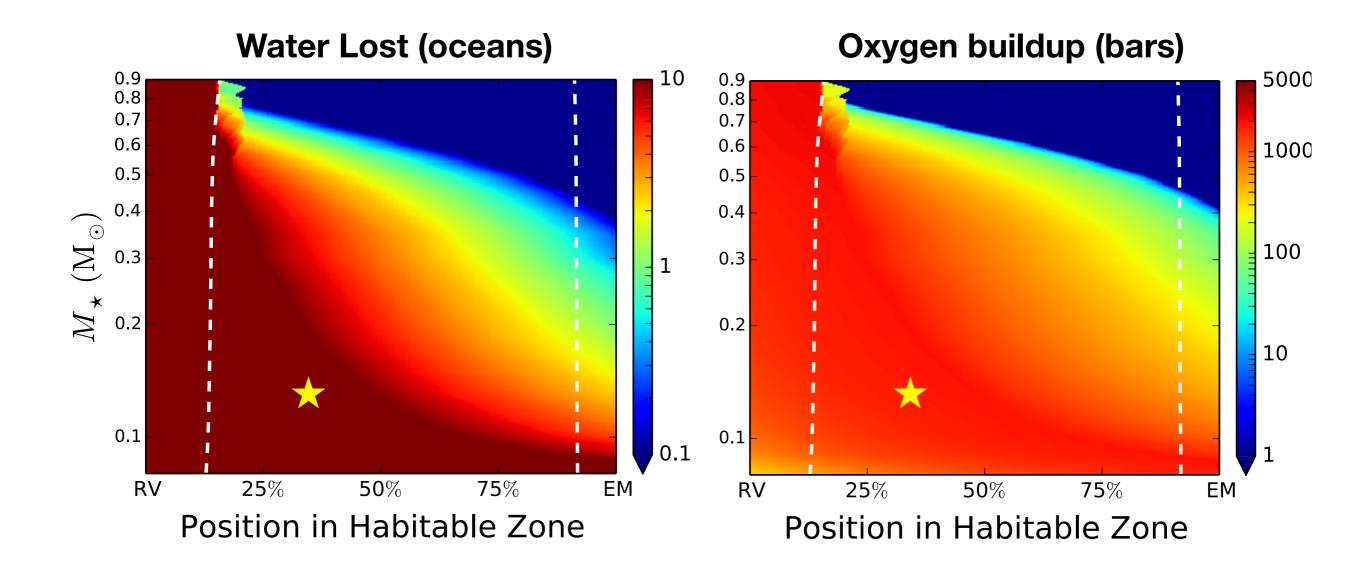
How Much Water is There on Proxima Cen B?

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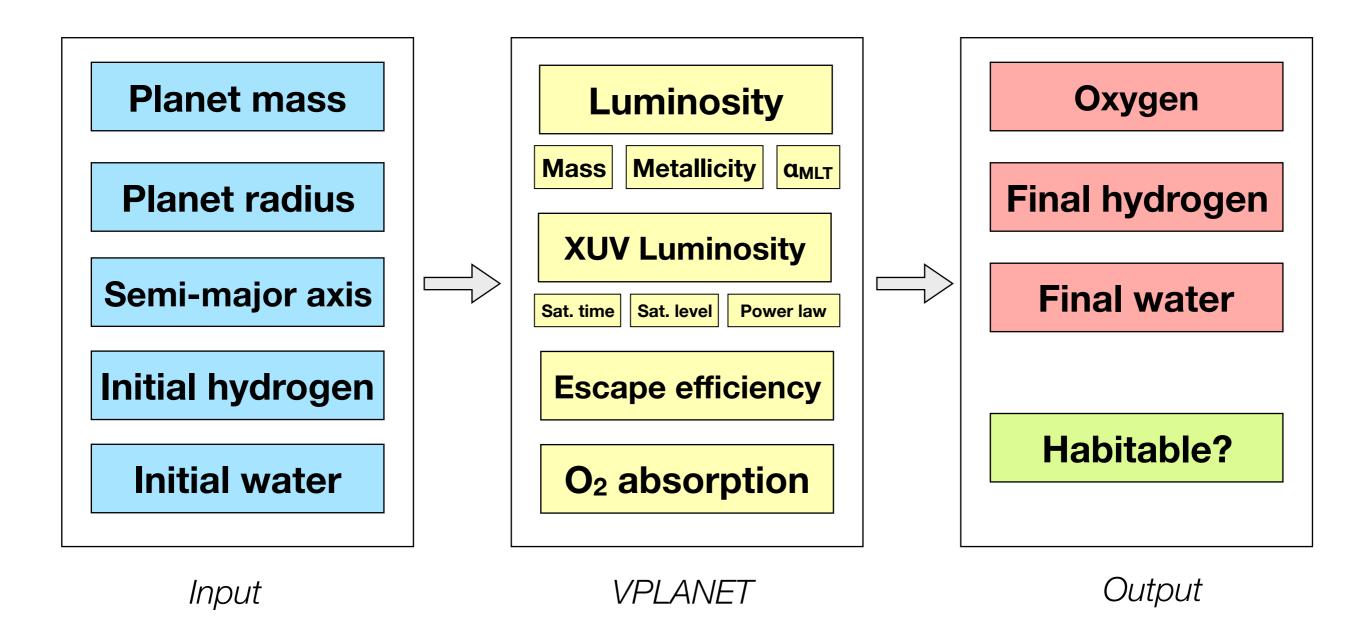
Rodrigo Luger

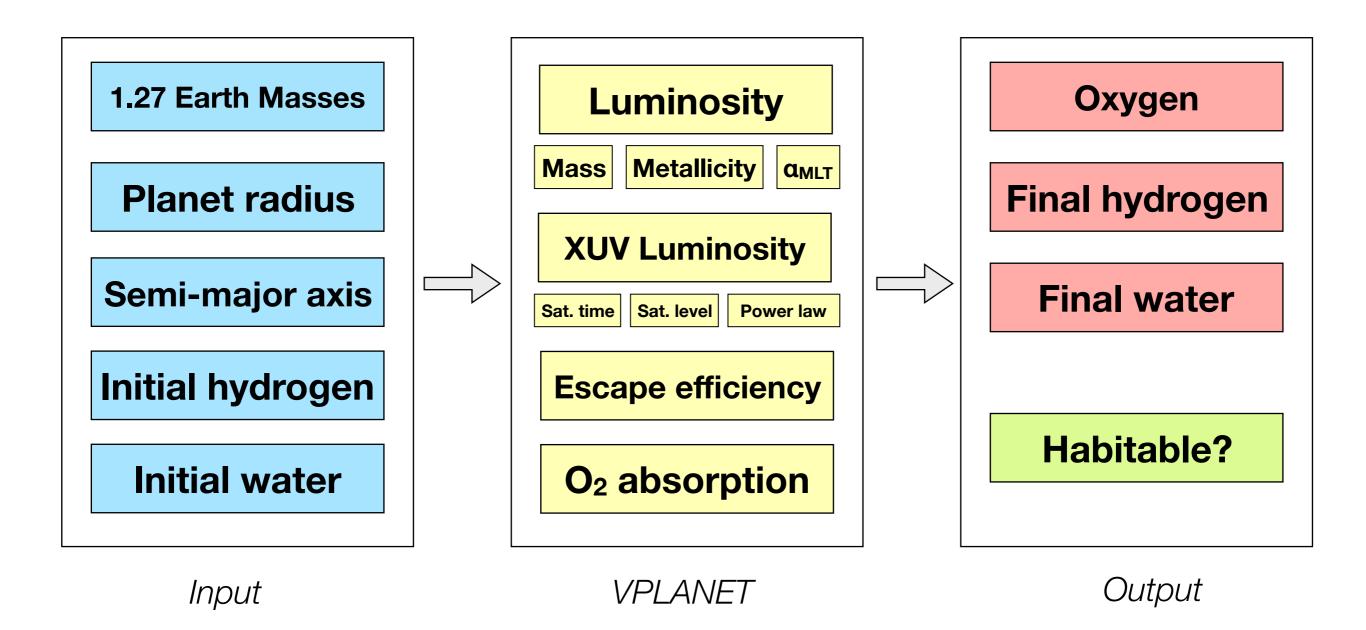
with Rory Barnes, Russel Deitrick, Peter Driscoll, Thomas Quinn, David Fleming, Benjamin Guyer, Diego McDonald, and the VPL Team

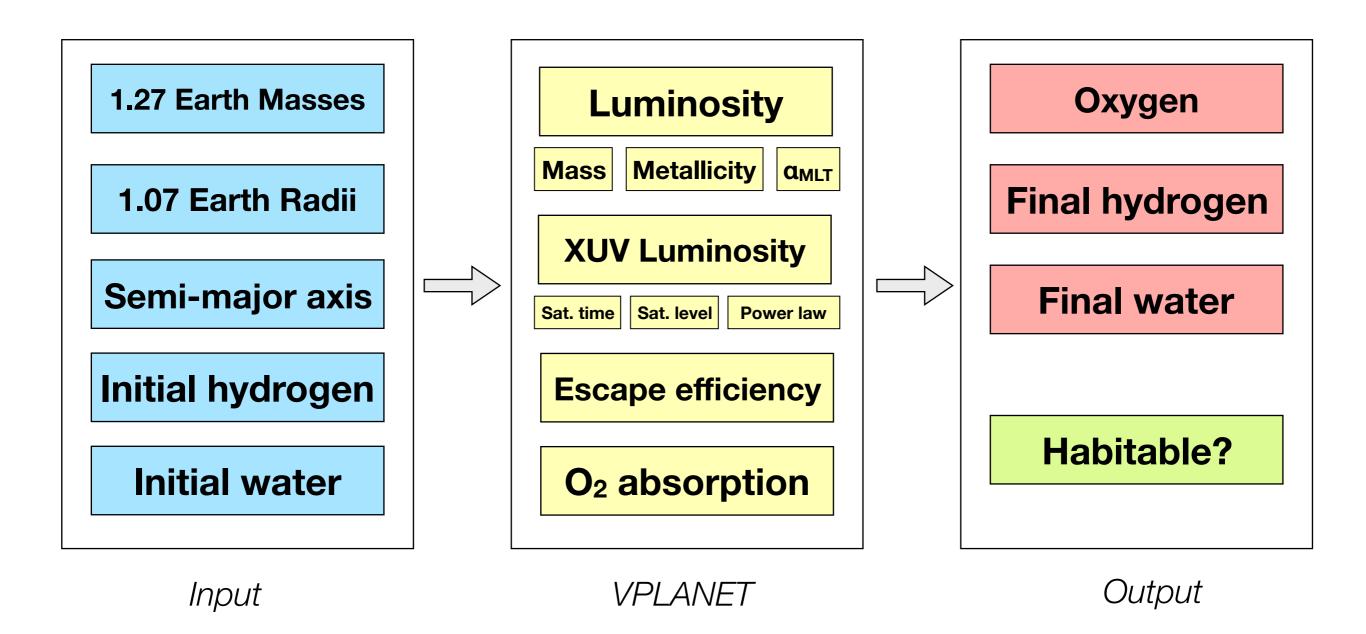
Water Loss

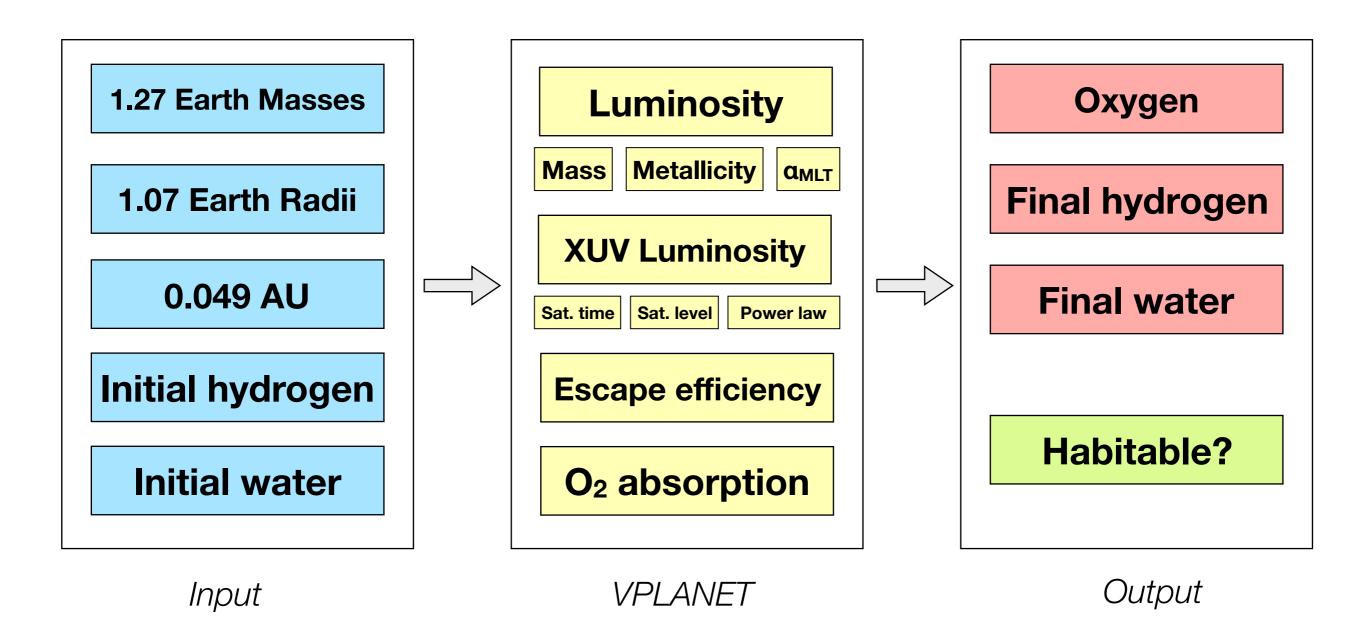


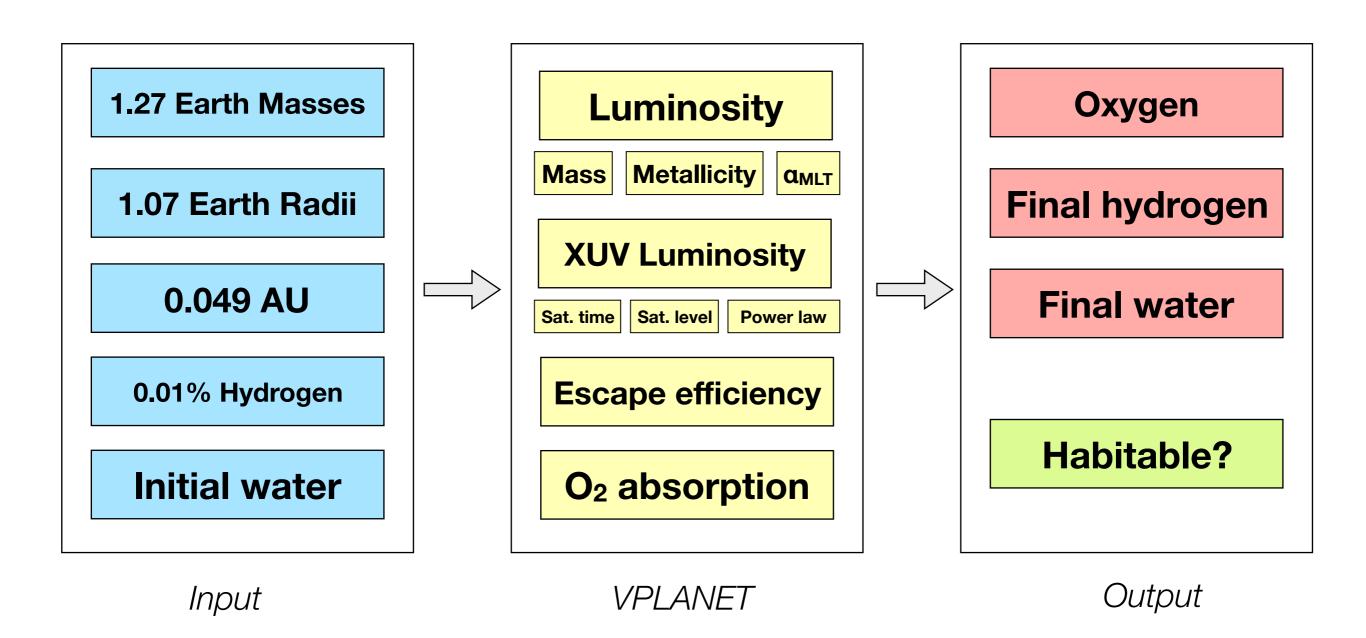
Luger and Barnes (2015)



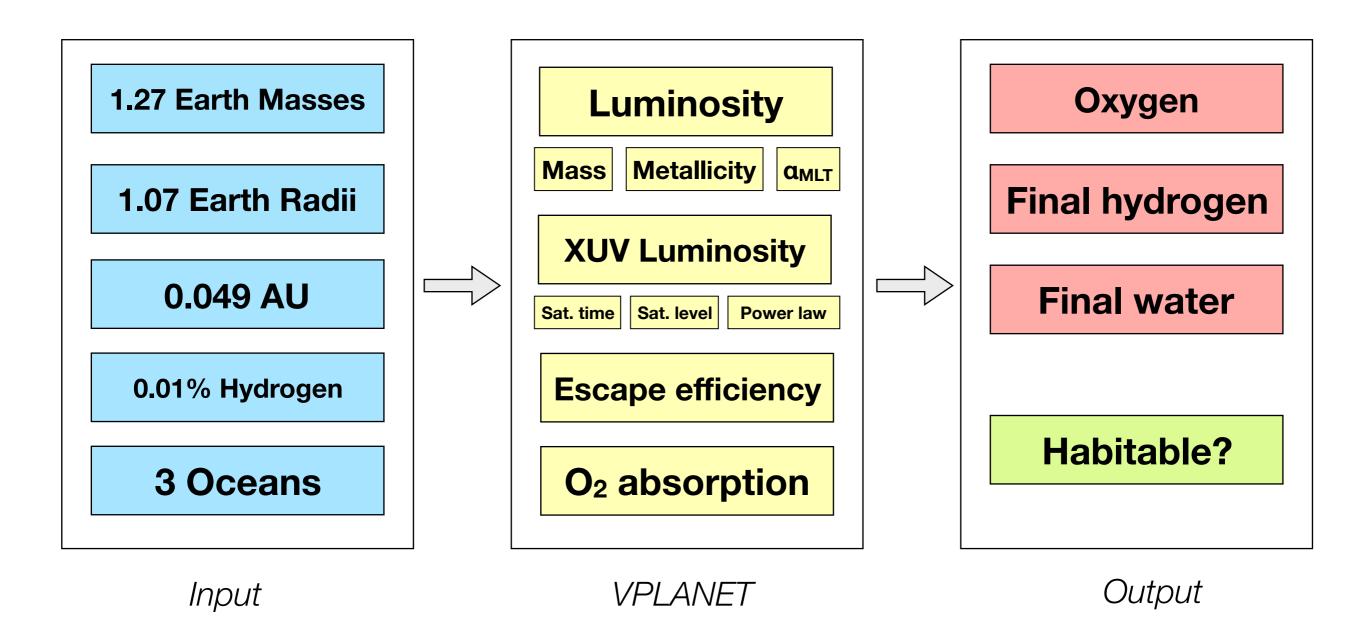


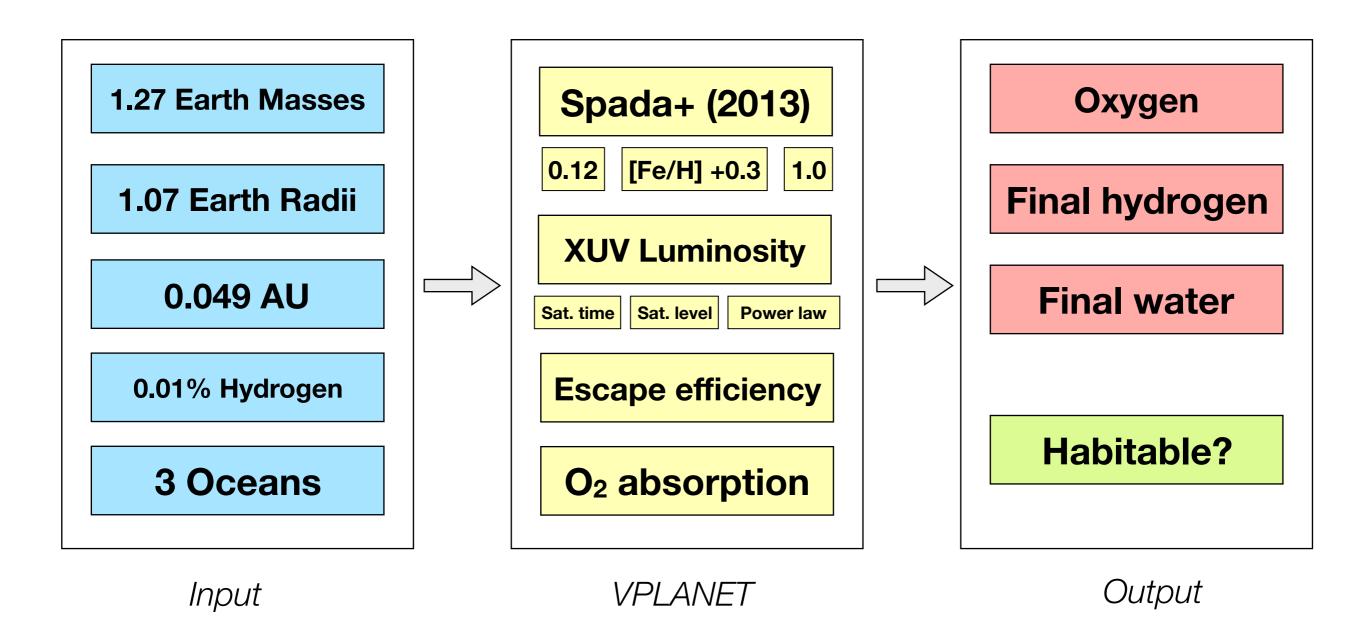


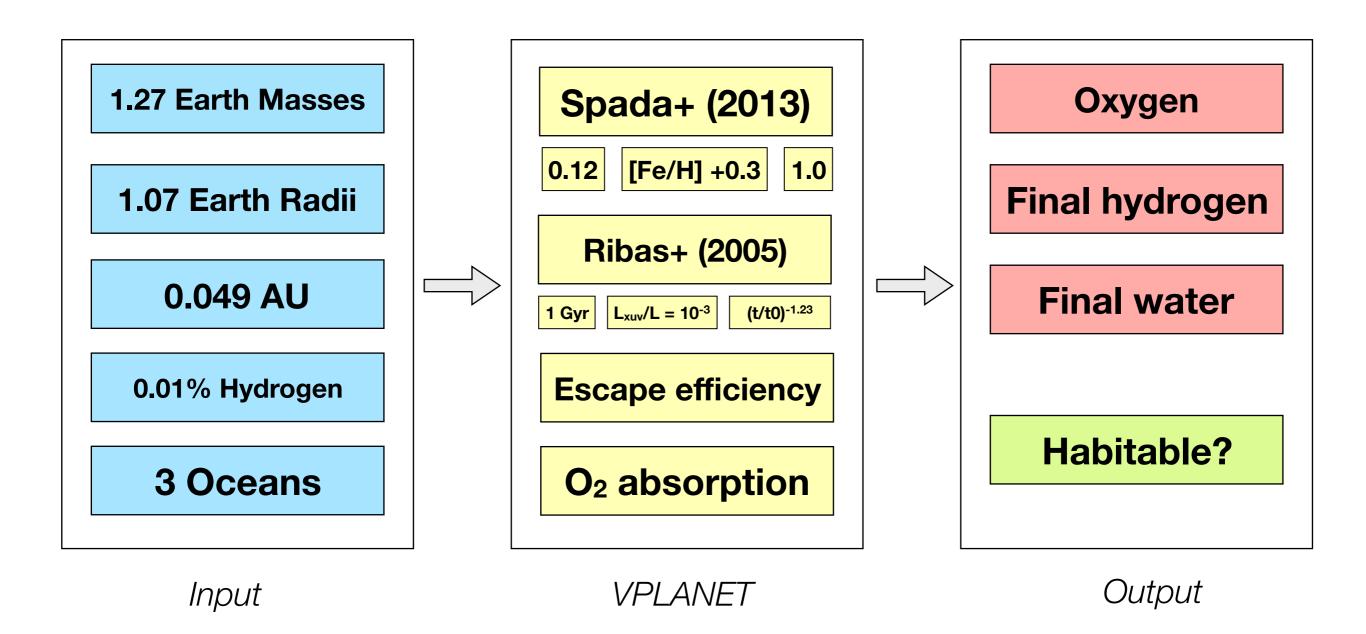


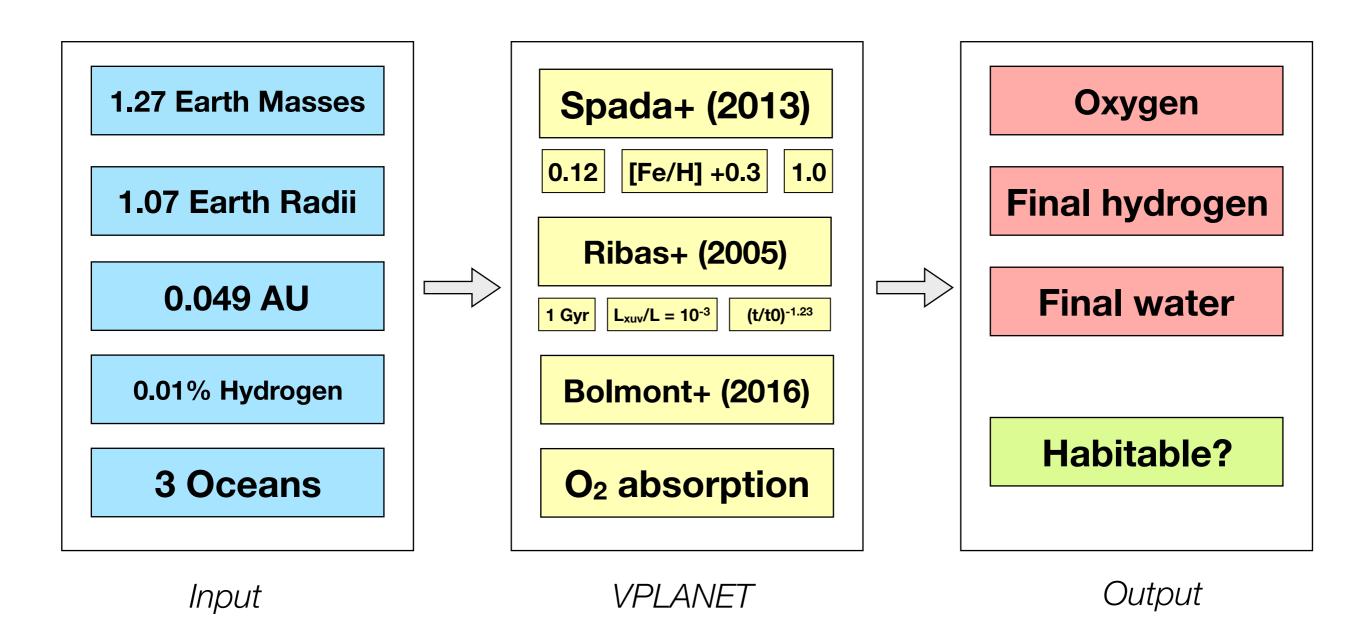


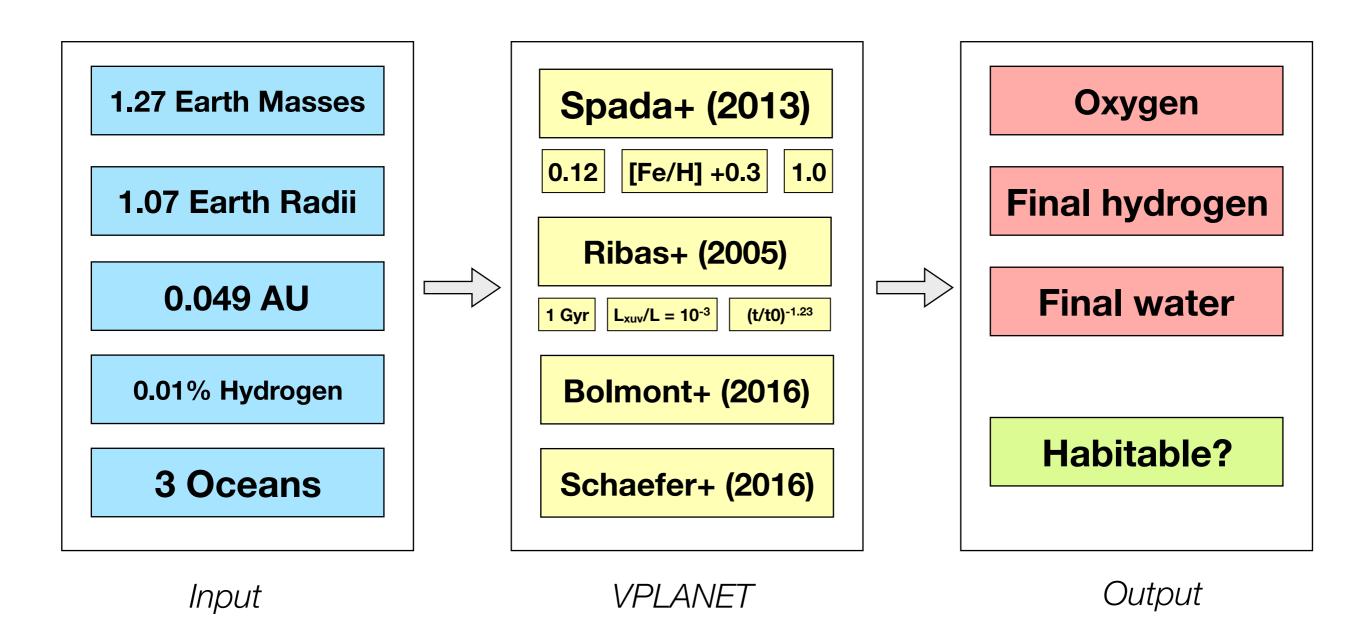
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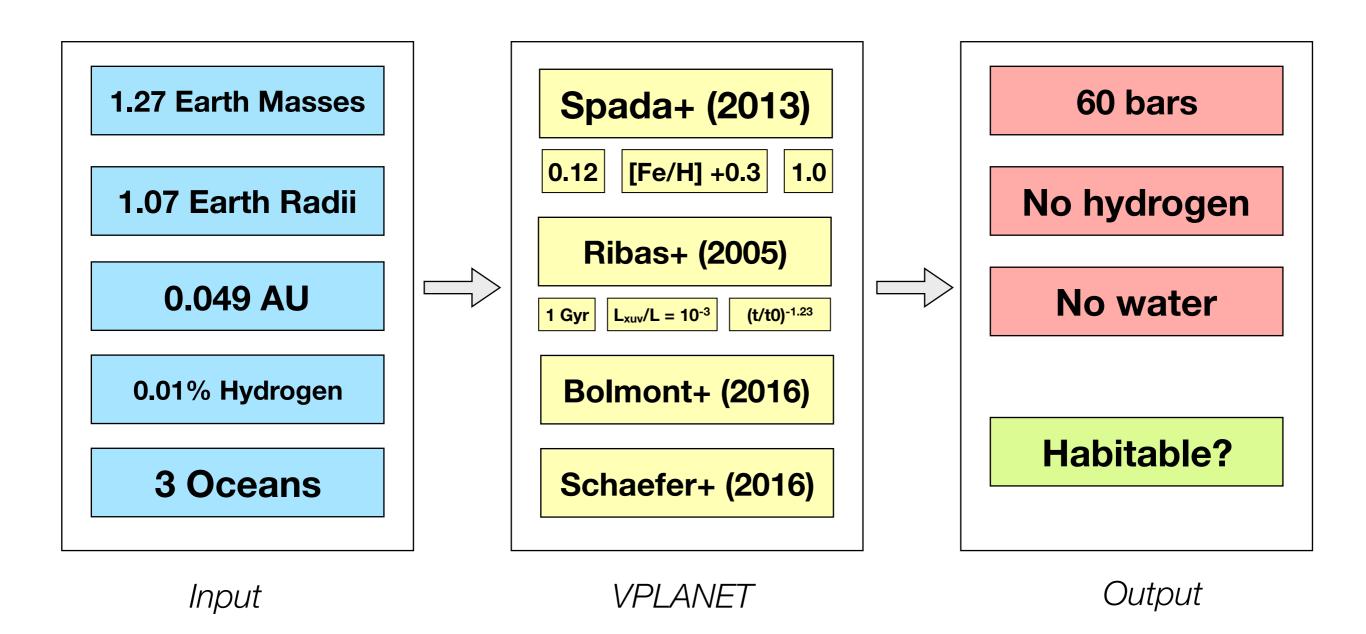


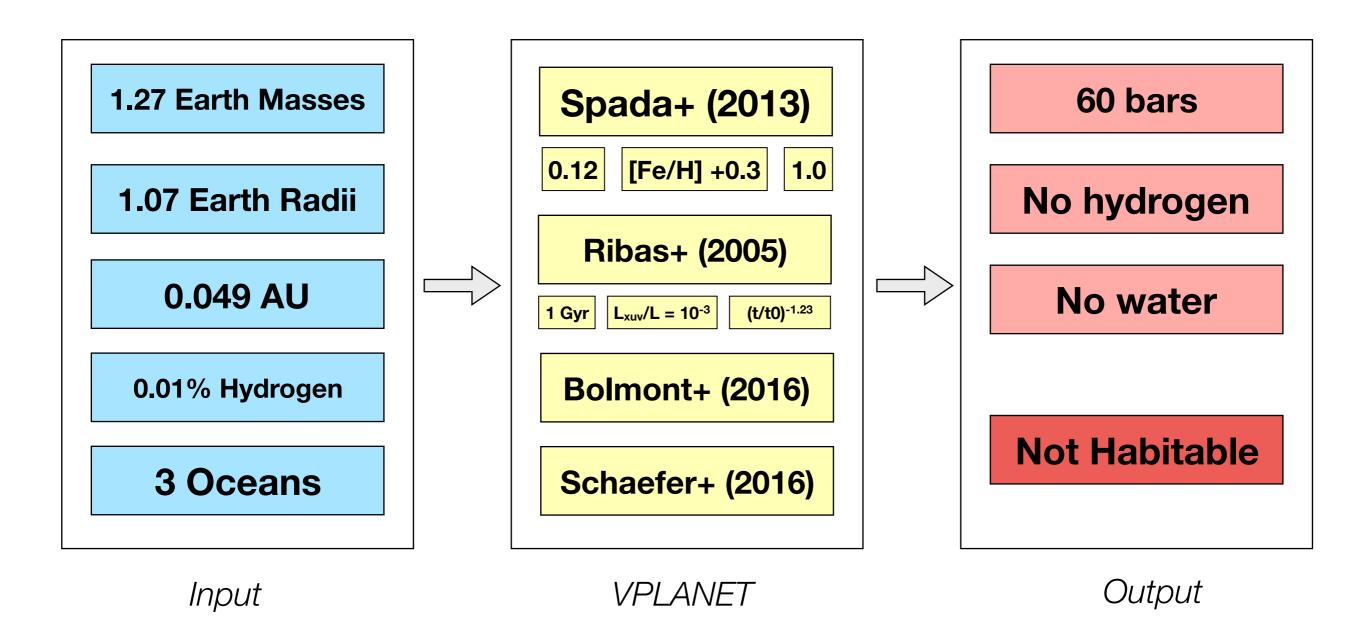












Conclusions

Proxima Cen b is not habitable

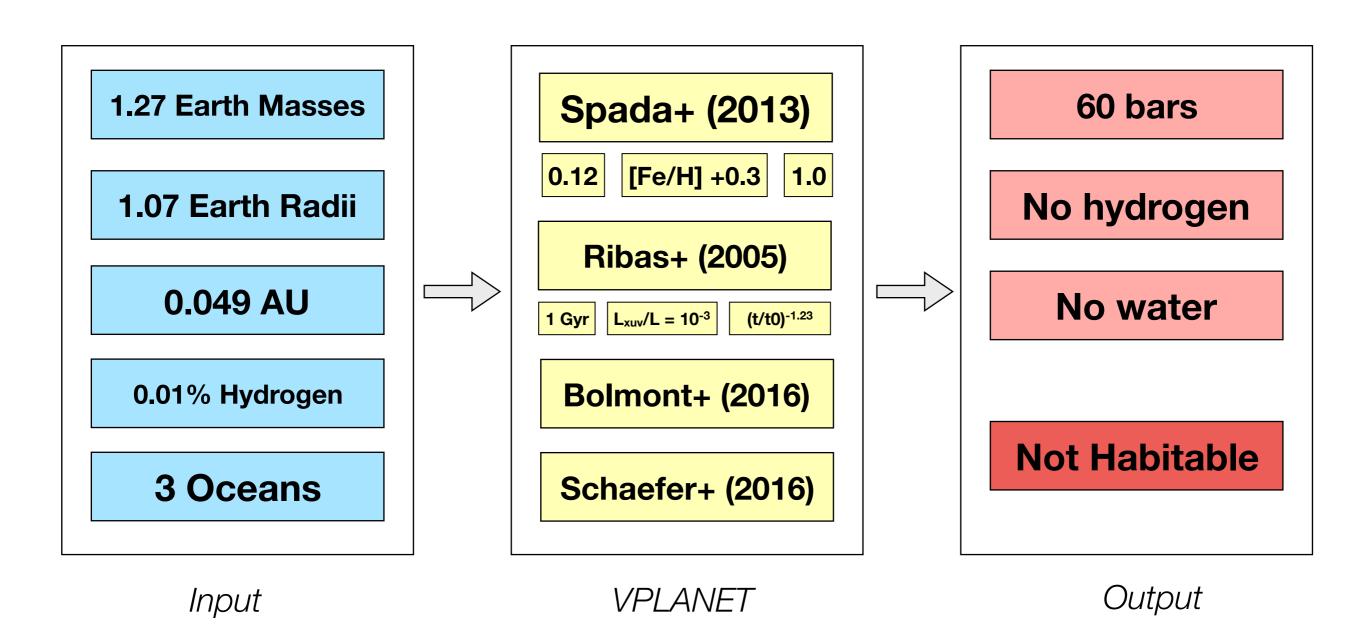
Conclusions

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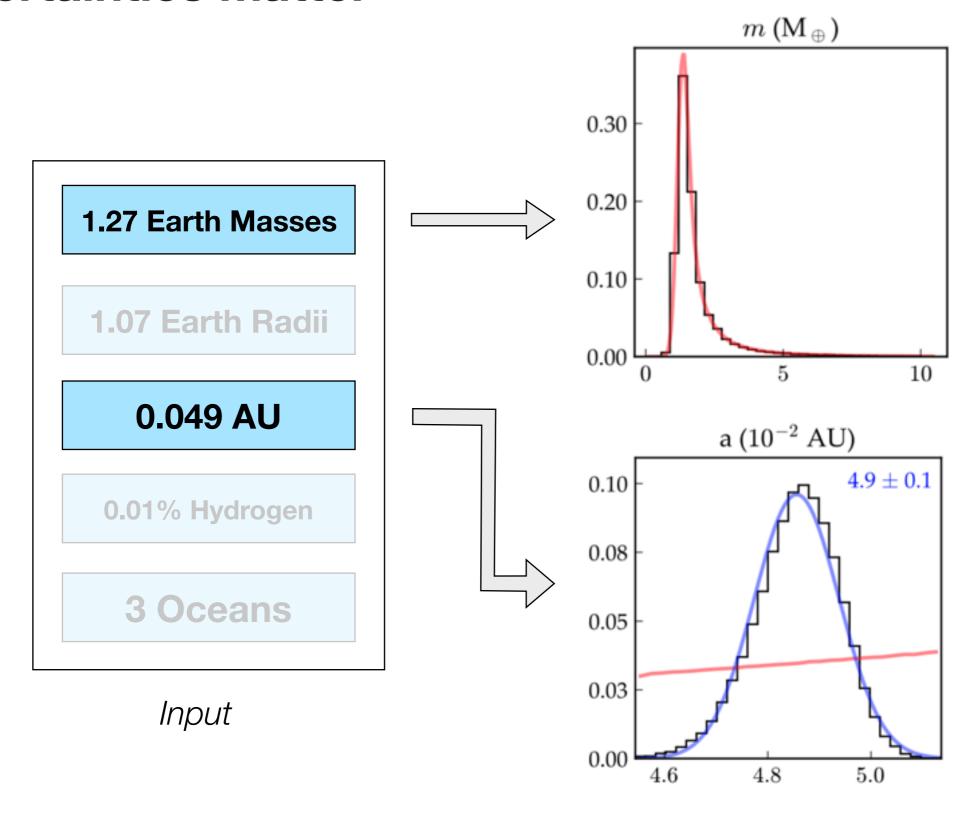
(Just kidding.)

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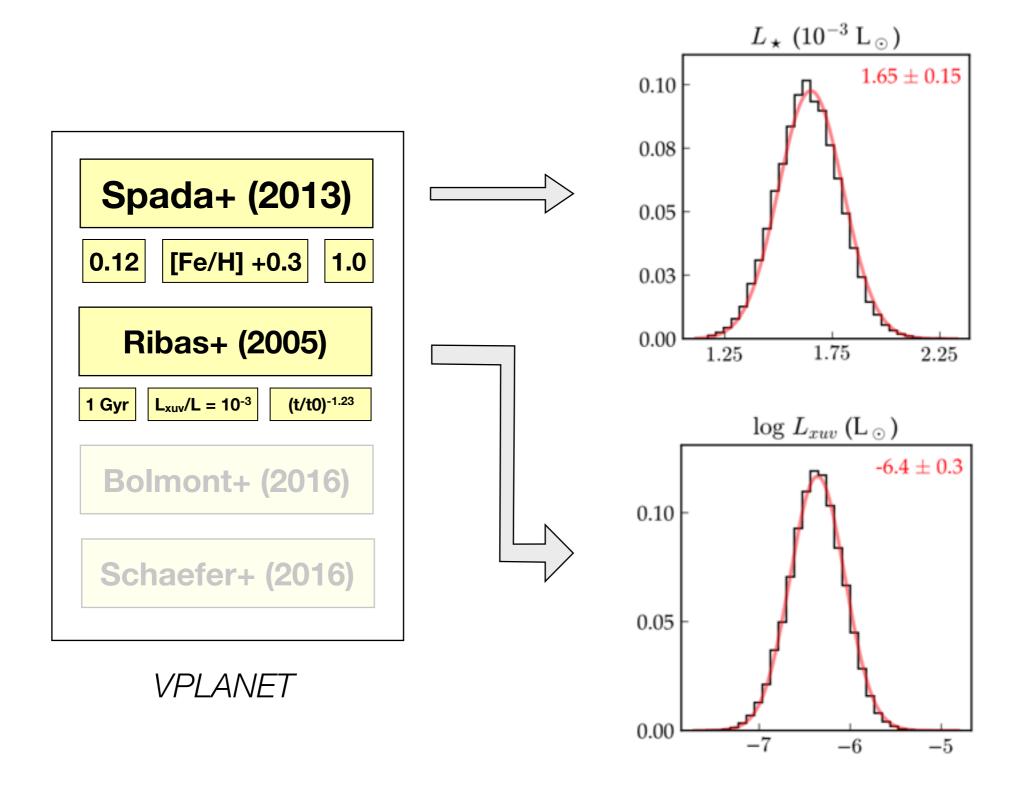
Can we really say this with any confidence?



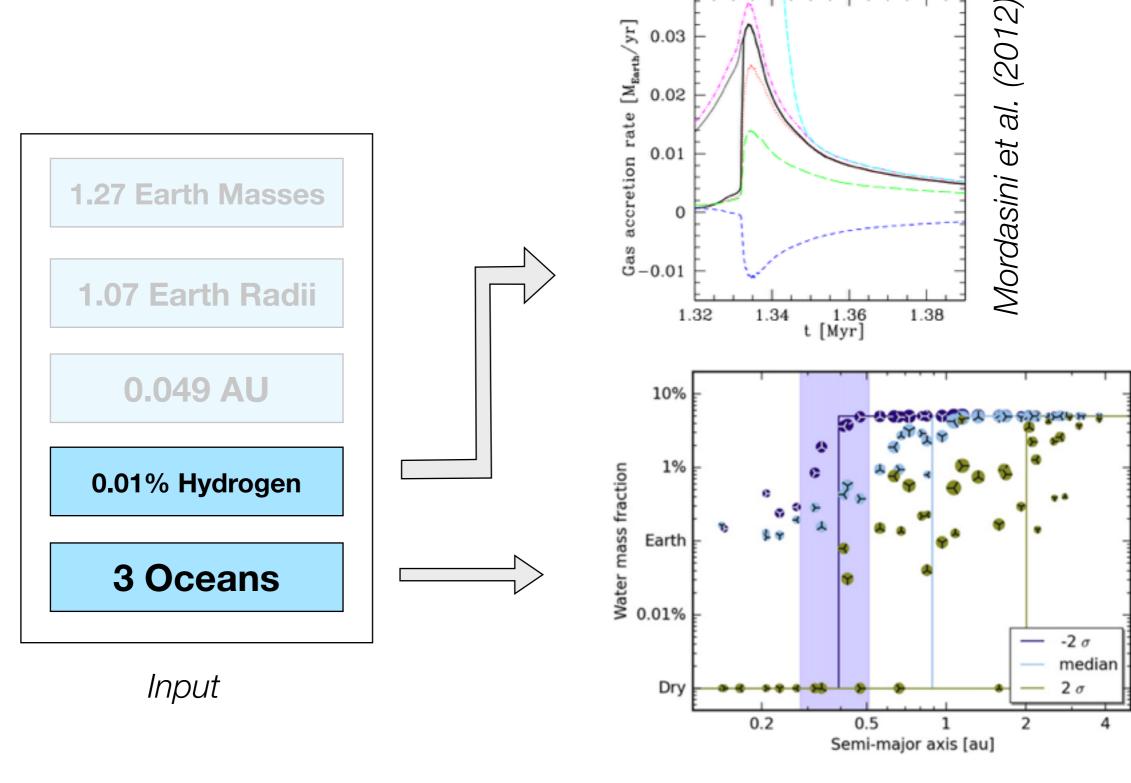
Uncertainties matter



Data matters

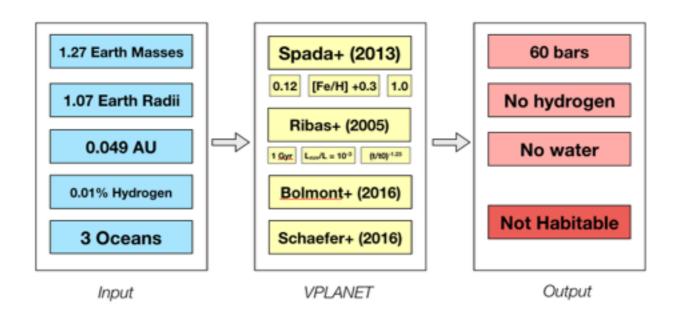


Priors matter

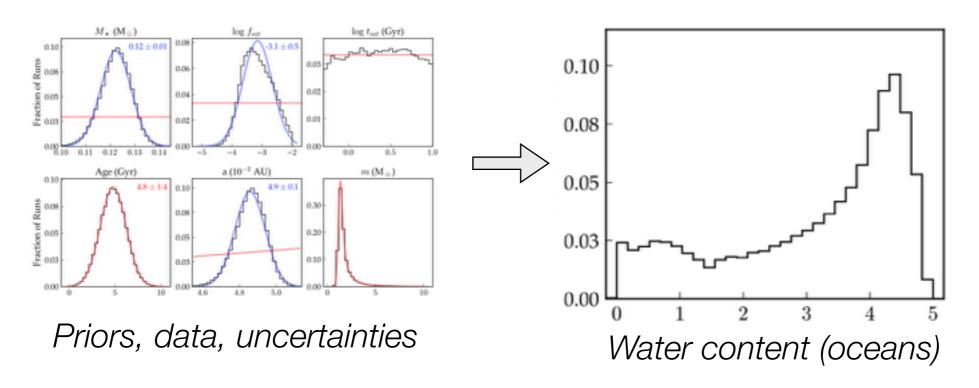


Mulders et al. (2015)

Maximum Likelihood



The Bayesian Approach



Framing the problem

Priors & data

$$\mathbf{x} = \{M_{\star}, t_{\star}, f_{\text{sat}}, t_{\text{sat}}, \beta_{\text{xuv}}, a, M_p, M_{\text{H}}^0, M_{\text{H}_2\text{O}}^0\}$$

Model outputs

22

$$\mathbf{y}(\mathbf{x}) = \{L_{\star}, L_{\text{xuv}}, M_{\text{H}}, M_{\text{H}_2\text{O}}, M_{\text{O}_2}\}$$

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Framing the problem

Priors & data

$$\mathbf{x} = \{M_{\star}, t_{\star}, f_{\text{sat}}, t_{\text{sat}}, \beta_{\text{xuv}}, a, M_p, M_{\text{H}}^0, M_{\text{H}_2\text{O}}^0\}$$

Model outputs

$$\mathbf{y}(\mathbf{x}) = \{L_{\star}, L_{\text{xuv}}, M_{\text{H}}, M_{\text{H}_2\text{O}}, M_{\text{O}_2}\}$$

Likelihood Function

$$\ln \mathcal{L}(\mathbf{x}) = -\frac{1}{2} \left[\frac{(L_{\star}(\mathbf{x}) - L_{\star})^2}{\sigma_{L_{\star}}^2} + \frac{(L_{\text{xuv}}(\mathbf{x}) - L_{\text{xuv}})^2}{\sigma_{L_{\text{xuv}}}^2} \right] + \ln \text{Prior}(\mathbf{x}) + C$$

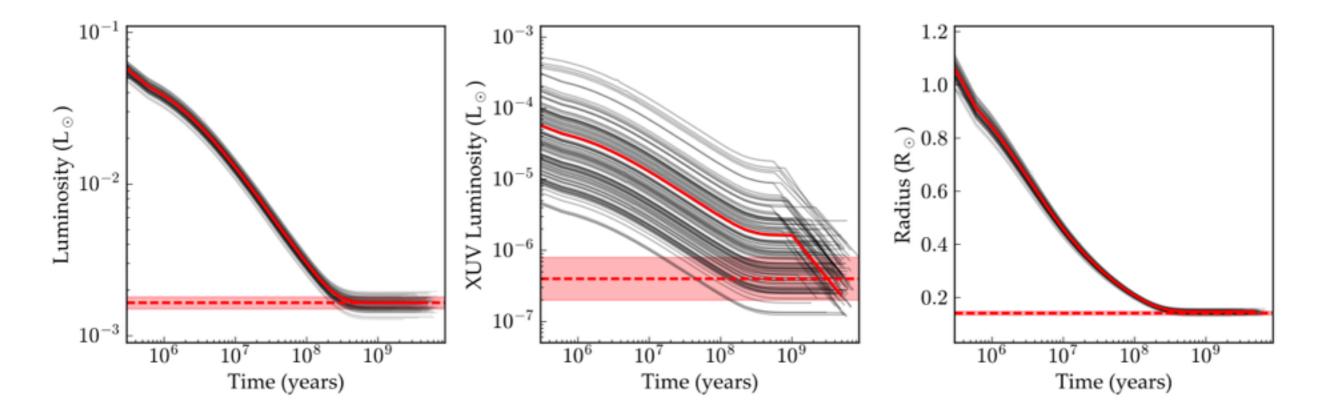
Markov Chain Monte Carlo (MCMC)

$$\ln \mathcal{L}(\mathbf{x}) \to P(M_{\mathrm{H_2O}})$$

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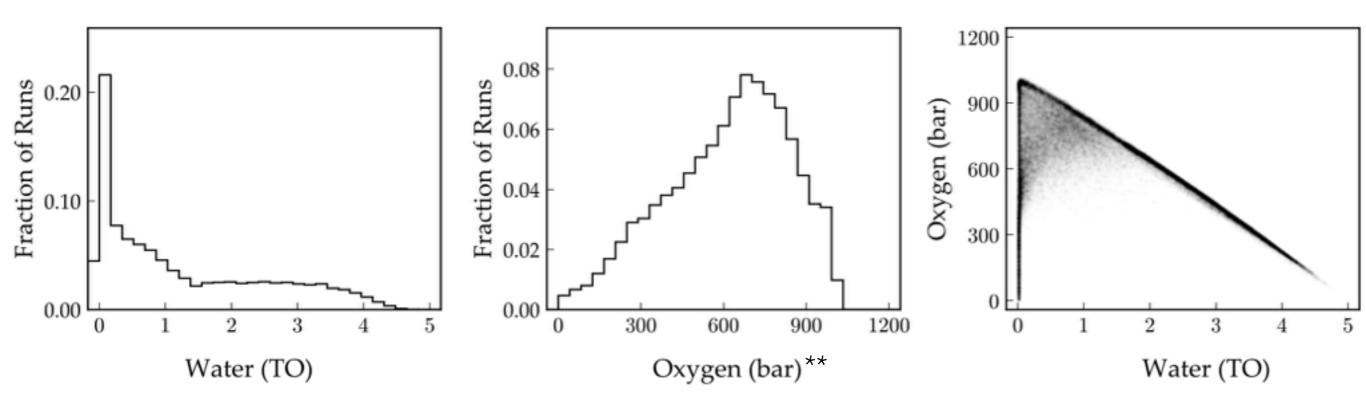
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Stellar Evolution



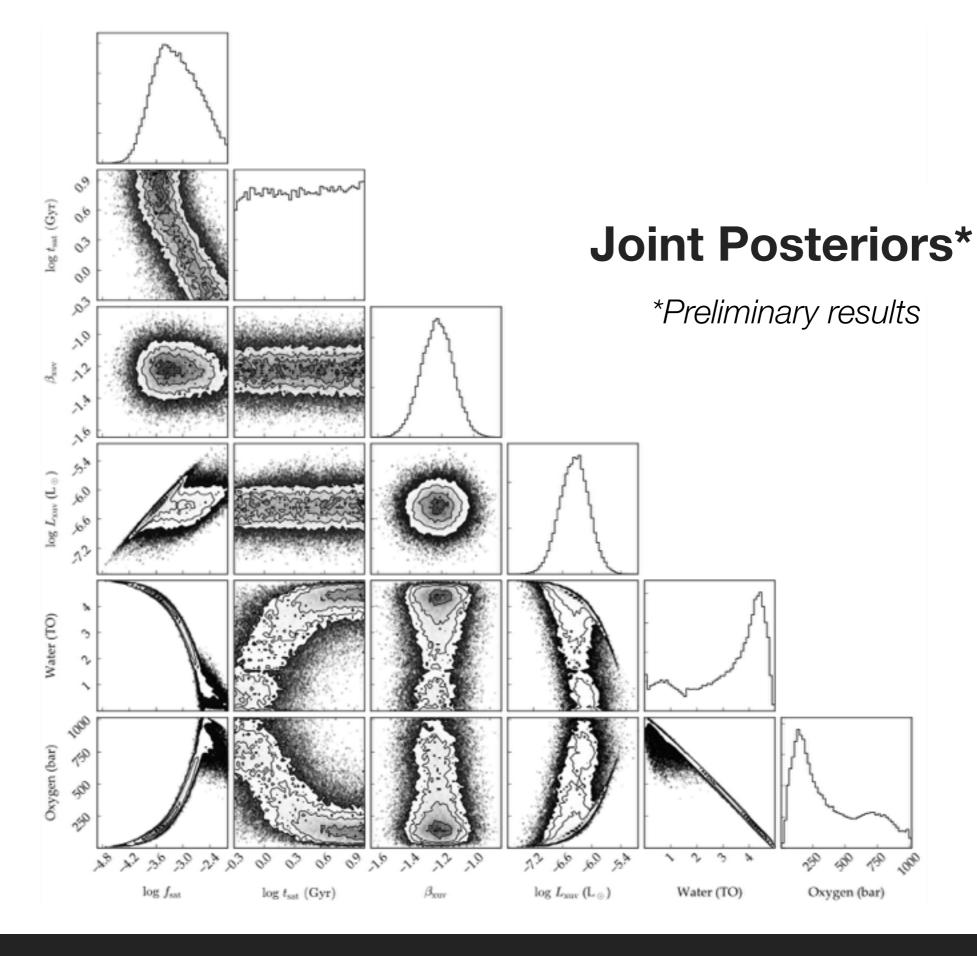
Posterior samples

Water Evolution*



*Not marginalized over population synthesis outputs $(M_{H_2O}^0 = 5 \text{ Oceans}, M_H^0 = 0)$

**Inefficient O2 sinks



Conclusions (For real this time)

We must account for the **uncertainty** on all model inputs.

We must correctly account for all **prior information.****A flat prior is **not** uninformative!

We need **robust posterior distributions** to assess habitability.

This will be an **incremental**, iterative problem.