## LISTA 2

1. Ache a matriz de eliminação E que reduz a matriz de Pascal em uma menor:

$$E\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix}.$$

Qual matriz M reduz a matriz de Pascal à matriz identidade?

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$E_{32}(1)$$

$$E_{32}(1)$$

$$E_{31}(1)$$

$$E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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0-110 \\
00-11
\end{bmatrix}
\begin{bmatrix}
1000 \\
1000 \\
1000 \\
0100
\end{bmatrix}
=
\begin{bmatrix}
1000 \\
0100 \\
01100 \\
01100 \\
0121 \\
0121 \\
00-11
\end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0$$

2. Use o método de Gauss-Jordan para achar a inversa da matriz triangular inferior:

$$U = \begin{bmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{bmatrix}.$$

$$\begin{bmatrix}
1 & b \\
0 & 1 & C \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & a - b & 0 \\
0 & 1 & C \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & a - b & 0 \\
0 & 1 & C \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & a - b & 0 \\
0 & 1 & C \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & a - b & 0 \\
0 & 1 & C \\
0 & 0 & 1
\end{bmatrix}$$

E13(a)

$$\begin{bmatrix}
1 & -\frac{b}{c} & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 0 & 1
\end{bmatrix}
\begin{bmatrix}
1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 1
\end{bmatrix}$$

$$E_{12}(a-\frac{b}{c})$$

$$= \begin{bmatrix} 1 & -a^{\frac{1}{2}} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -\frac{b}{2} & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

3. Para quais valores de a o método de eliminação não dará 3 pivôs?

$$\begin{bmatrix} a & 2 & 3 \\ a & a & 4 \\ a & a & a \end{bmatrix}.$$

$$\begin{bmatrix} a & 2 & 3 \\ a & a & 4 \\ a & a & a \end{bmatrix} \xrightarrow{L_3 - L_2} \begin{bmatrix} a & 2 & 3 \\ a & a & 4 \\ 0 & 0 & a - 4 \end{bmatrix} \xrightarrow{L_2 - L_1} \begin{bmatrix} a & 2 & 3 \\ 0 & a - 2 & 1 \\ 0 & 0 & a - 4 \end{bmatrix}$$

$$a = 0, \quad a = 2 \quad \text{E} \quad a = 4$$

- (a) Se  $A^2$  está bem definida, então A é quadrada.
- (b) Se AB e BA estão bem definidas, então A e B são quadradas.
- (c) Se AB e BA estão bem definidas, então AB e BA são quadradas.
- (d) Se AB = B, então A = I.

AMBAG RETANGULARES COM PRODUTOS BEM-DEFINIDOS

5. Mostre que se 
$$BA = I$$
 e  $AC = I$ , então  $B = C$ .

6. Ache uma matriz não-zero A tal que  $A^2 = 0$  e uma matriz B com  $B^2 \neq 0$  e  $B^3 = 0$ .

$$\begin{bmatrix} a_1 & a_2 \\ a_3 & a_4 \end{bmatrix} \begin{bmatrix} \alpha_1 & \alpha_2 \\ \alpha_3 & \alpha_4 \end{bmatrix} = \begin{bmatrix} a_1^2 + \alpha_2 \alpha_3 & \alpha_2 (\alpha_1 + \alpha_4) \\ \alpha_3 (\alpha_1 + \alpha_4) & \alpha_3 \alpha_2 + \alpha_4^2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$$

$$\mathbf{A} = \begin{bmatrix} 3 & 2 & 0 & 0 \\ 4 & 3 & 0 & 0 \\ 0 & 0 & 6 & 5 \\ 0 & 0 & 7 & 6 \end{bmatrix} e \begin{bmatrix} 0 & 0 & 0 & 2 \\ 0 & 0 & 3 & 0 \\ 0 & 5 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} = \mathbf{B}$$

$$\begin{bmatrix}
3 & 2 & 0 & 0 & 0 & 0 \\
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$$\begin{bmatrix}
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0 & 0 & 0 & 0$$

8. Verifique que a inversa de  $M=I-\mathbf{u}\mathbf{v}^T$  é dada por  $M^{-1}=I+\frac{\mathbf{u}\mathbf{v}^T}{1-\mathbf{v}^T\mathbf{u}}$ . Verifique também que a inversa de  $N=A-UW^{-1}V$  é dada por  $N^{-1}=A^{-1}+A^{-1}U(W-VA^{-1}U)^{-1}VA^{-1}$ .

VAMOS VERIFICAR QUE 
$$M^{-1} = I + UU^{T} = J$$
 $MJ = I \rightarrow (I - uv^{T})(I + \frac{uv^{T}}{I - v^{T}u}) = I$ 
 $I + \frac{uv^{T}}{I - v^{T}u} - uv^{T} - \frac{uv^{T}uv^{T}}{I - v^{T}u} = I \rightarrow \frac{uv^{T}}{I - v^{T}u}$ 

$$\rightarrow -\mu V + \mu V \left(\frac{1-V \pi}{V V \pi}\right) \rightarrow \boxed{0=0}$$

VERIFICAR A INVERSA DE N=A-UW'V  $J = A^{-1} + A^{-1}U(W-VA^{-1}U)^{-1}VA^{-1}$ 

SUPONDO DOIS VETORES X E Y TAIS QUE

$$Nx = y \longrightarrow Ax - UW^{-1}Vx = y$$

$$Jy = x \longrightarrow A^{-1}y + A^{-1}U(W - VA^{-1}U)^{-1}VA^{-1}y = x$$

 $Ax - y = UW^{-1}Ux$ 

 $A(A^{-1}y + A^{-1}U(W - VA^{-1}U)^{-1}VA^{-1}y) - y = UW^{-1}U \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}Y - y = UW^{-1}V \times X + U(W - VA^{-1}U)^{-1}VA^{-1}U + U(W - VA^{-1}U)^{-1}VA^{-1}Y - y = UW^{-1}VX + U(W - VA^{-1}U)^{-1}VX + U(W - VA^{-1}U)^{-1}V$ 

 $U(W-VA^{-1}U)VA^{-1}y = UW^{-1}Ux$ 

 $A \times - U(W - VA^{-1}U)VA^{-1}y = y$ 

Ax= Y+ U(W-VA'U) VA'Y => x = A'y+A'U(W-VA'U) VA'Y

9. Sabemos que a matriz de diferenças tem a seguinte inversa

$$L^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}.$$

Use essa propriedade (e sua versão triangular superior) para achar a inversa de

$$T = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}.$$

Dica: escreva T como produto de duas matrizes

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 1 & 1 \end{bmatrix}$$

10. Mostre que I+BA e I+AB são ambas invertíveis ou singulares. Relacione a inversa de I+BA com a inversa de I+AB, caso elas existam.

11. (Bônus) Mostre que se  $\alpha_k A^k + \alpha_{k-1} A^{k-1} + \dots + \alpha_1 A + \alpha_0 I = 0$ , com  $\alpha_0 \neq 0$ , então A é invertível

DADA A MATRIZ DE ELIMINAÇÃO E, SE A NÃO FOR INVERTÍVEL, TEMOS QUE EA GERA n-k pivôs E K LINHAS DE O.

E A NÃO FOR INVERTÍVEL, TODA POTÊNCIA EA' TEM E LWHAS O (E:A:A'-1). OU SEUA, AO SOMAR TODAS, -YOE DEVE TER N-K PIVÔS, O QUE É ABSURDO, POIS, POR DEFINIÇÃO, E POSSUI INVERSA, LOGO, ISSO SÓ PODE ACONTECER SE YO = OI OU SEUA, A DEVE TER N PIVÔS => A É INVERTÍVEL.