



university of  
 groningen

# Languages and Machines

## L4: Finite State Machines (Part 2)

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Regular  $\leftrightarrow$  Finite State Machines (FSMs)

Context-free  $\leftrightarrow$  Pushdown Machines

Context-sensitive  $\leftrightarrow$  Linearly-bounded Machines

Decidable  $\leftrightarrow$  Always-terminating Turing Machines

Semi-decidable  $\leftrightarrow$  Turing Machines



## Regular Languages

- Built from  $\emptyset$ ,  $\{\epsilon\}$ , and  $\{a_i\}$  (for every  $a_i \in \Sigma$ ) by applications of union, concatenation, and Kleene star operators

## Finite State Machines (FSMs)

1. Deterministic FSMs (DFSMs)
2. Nondeterministic FSMs (NFSMs)
3. Nondeterministic FSMs with  $\epsilon$ -transitions ( $N\epsilon$ FSMs)

# The Three Machines are Equivalent



## Previous Lecture:

- Every DFSM can be regarded as an equivalent NFSM, and
- Every NFSM can be regarded as an equivalent  $N\epsilon$ FSM.

Thus, DFSMs  $\rightsquigarrow$   $N\epsilon$ FSMs.

Also:

- For every regexp there is an  $N(\epsilon)$ FSM.

# The Three Machines are Equivalent



## Previous Lecture:

- Every DFMSM can be regarded as an equivalent NFSM, and
- Every NFSM can be regarded as an equivalent  $N\epsilon$ FSM.

Thus, DFMSMs  $\rightsquigarrow$   $N\epsilon$ FSMs.

Also:

- For every regexp there is an  $N(\epsilon)$ FSM.

## Today:

$N\epsilon$ FSMs  $\rightsquigarrow$  DFMSMs.

- Every  $N(\epsilon)$ FSM is equivalent to a DFMSM (possibly larger).
- Given an  $N(\epsilon)$ FSM  $M$ , we will determine a regexp for  $L(M)$

From NFSMs to DFSMs

From  $N\epsilon$ FSMs to DFSMs

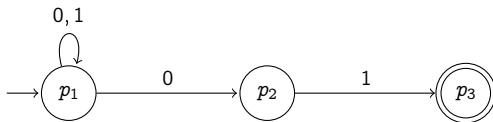
The regular expression for a machine

# From NFSMs to DFSMs: Idea

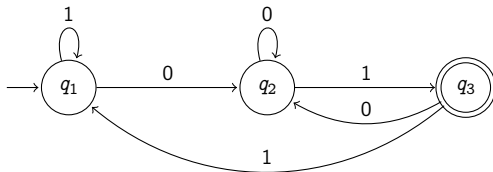


Let  $L = \{x \in \{0, 1\}^* \mid x \text{ has suffix '01'}\}$ .

An NFSM  $N$  that recognizes  $L$ :



We will see how to transform  $N$  into the **equivalent** DFSM  $D$ :

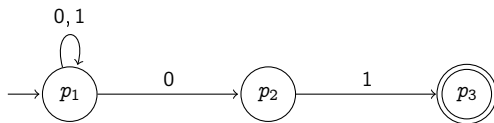


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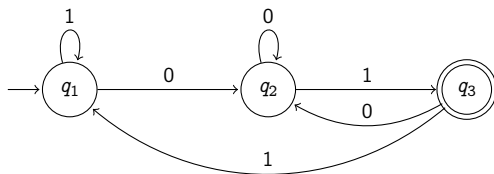


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Here *equivalence* means  $L(N) = L(D) = L$ .



## From NFSMs to DFSMs

Suppose given an NFSM  $N = (Q_N, \Sigma, \delta_N, q_0, F_N)$ .  
The DSFM  $D$  is defined as

$$D = (Q_D, \Sigma, \delta_D, \{q_0\}, F_D)$$



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$$\delta_D(S, a) = \bigcup_{q \in S} \delta_N(q, a)$$

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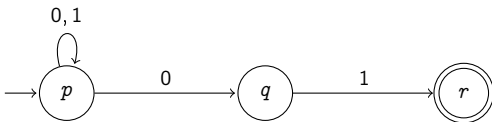
$$\delta_D(S, a) = \bigcup_{q \in S} \delta_N(q, a)$$

*Intuition:* For every  $q \in S$ , we check the states that  $N$  goes to from  $q$  on input  $a$ , and then take the union of all those states.

## Example 1



An NFSM for  $L = \{x \in \{0, 1\}^* \mid x \text{ has suffix '01'}\}$ :

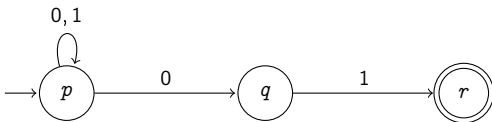




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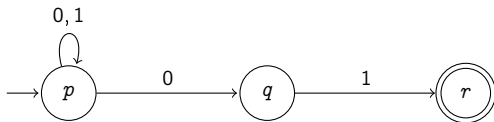


Notice: From  $p$  we go to two different states ( $p$  and  $q$ ) by reading 0.

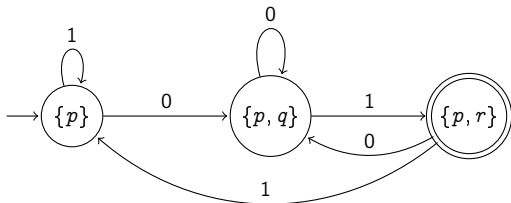
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Notice: From  $p$  we go to two different states ( $p$  and  $q$ ) by reading 0. Let's transform it into the DFSM:





From NFSMs to DFSMs

From NεFSMs to DFSMs

The regular expression for a machine

# The Subset Construction



**Recall:** For each  $S \subseteq Q_N$  and for each  $a$  in  $\Sigma$ ,

$$\delta_D(S, a) = \bigcup_{q \in S} \delta_N(q, a)$$

To compute  $\delta_D(S, a)$ , for every  $q \in S$ : we see what states  $q_1, \dots, q_k$   $N$  goes to from  $q$  on input  $a$ , and take their union  $\{q_1, \dots, q_k\}$ .

# The Subset Construction

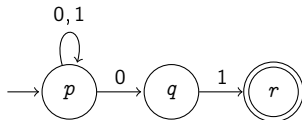


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**In our example:**



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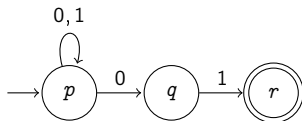
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**In our example:**

$\delta_D$	0	1
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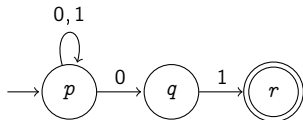
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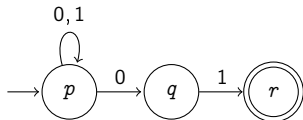
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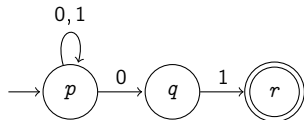


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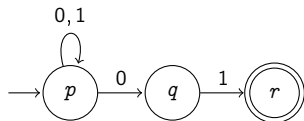


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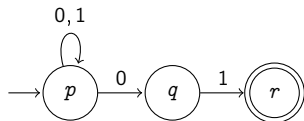


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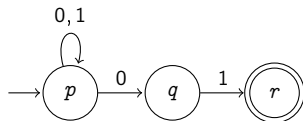


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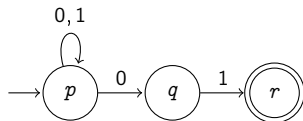


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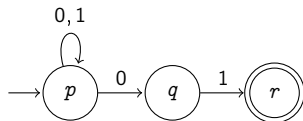


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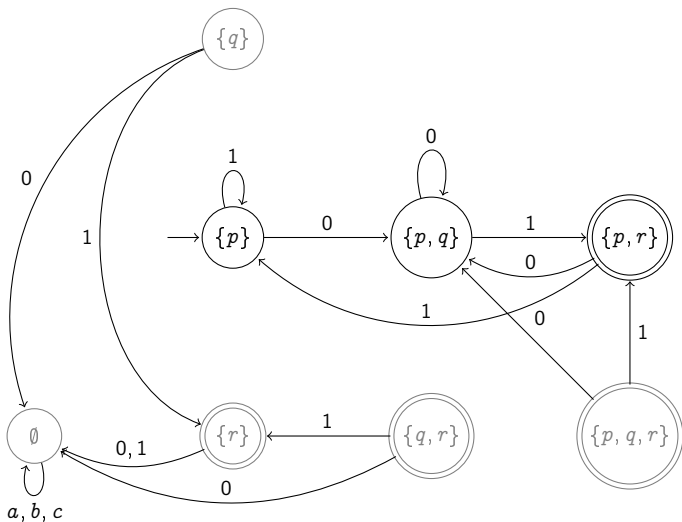
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## Not all States are Reachable

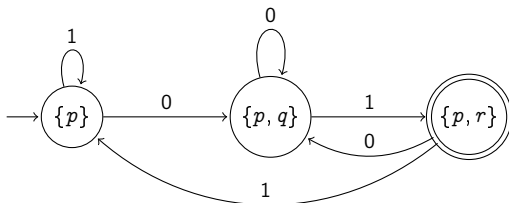
States in gray are inaccessible from the starting state  $\{p\}$ :



# Not all States are Reachable



Hence, by erasing inaccessible states, we obtain:



Note: The resulting DFSM has the same number of states as the given NFSM (3) but has more transitions (6 vs 4).



From NFSMs to DFSMs

From  $N\epsilon$ FSMs to DFSMs

The regular expression for a machine

# From $N\epsilon$ FSMs to DFSMs



If the machine is an  $N\epsilon$ FSM, then the general idea of the subset construction is as just discussed. We just need an additional notion.

Give a set of states  $S$ , its  $\epsilon$ -**closure** is the set of states that can be reached from  $S$  via zero or more  $\epsilon$ -transitions.

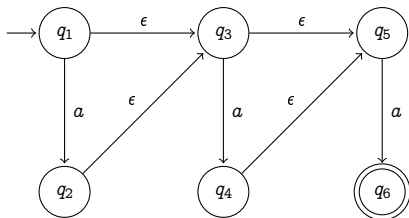
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**Example:**



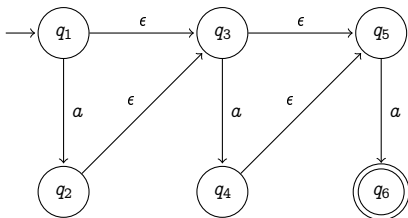
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**Example:**



	$\epsilon$ -closure
$\{q_1\}$	$\{q_1, q_3, q_5\}$
$\{q_2\}$	$\{q_2, q_3, q_5\}$
$\{q_3\}$	$\{q_3, q_5\}$
$\{q_4\}$	$\{q_4, q_5\}$
$\{q_5\}$	$\{q_5\}$
$\{q_6\}$	$\{q_6\}$



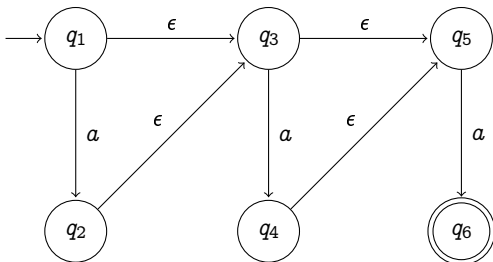
To transform an N $\epsilon$ FSM  $N$  into a DFSM  $D$ :

1. Compute the  $\epsilon$ -closure of  $N$ 's start state (as a singleton).  
The resulting set is  $D$ 's start state.
2. For every state  $S$  of  $D$  (a set of states of  $N$ ) and every  $a \in \Sigma$ , construct a new state: the set of states reachable from some  $q \in S$  by an  $a$ -transition followed by zero or more  $\epsilon$ -transitions. (That is, this step concerns computing  $a\epsilon^*$ .)
3. Recurse until no new states are created.

## Example 2



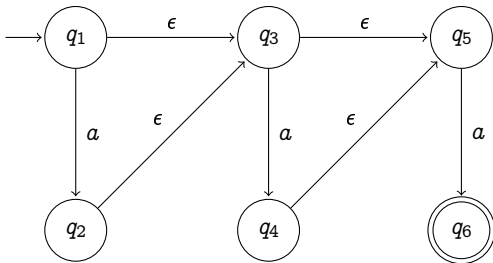
Let's transform the  $N\epsilon$ FSM



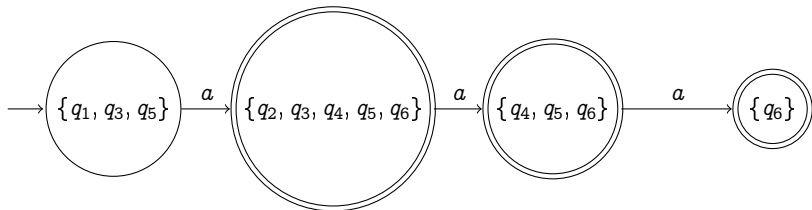
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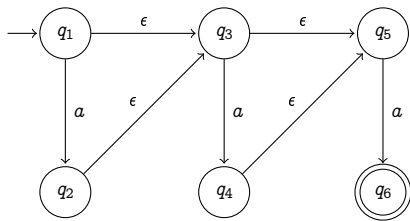
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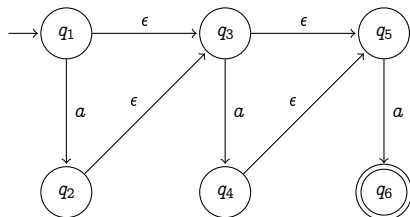


# The Two-Table Method (cf. Ex. 3.7)





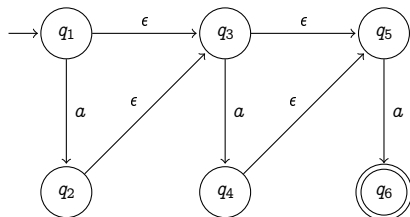
# The Two-Table Method (cf. Ex. 3.7)



First table:

	$a$	$\epsilon^*$
$\rightarrow \{q_1\}$	$\{q_2\}$	$\{q_1, q_3, q_5\}$
$\{q_2\}$	$\emptyset$	$\{q_2, q_3, q_5\}$
$\{q_3\}$	$\{q_4\}$	$\{q_3, q_5\}$
$\{q_4\}$	$\emptyset$	$\{q_4, q_5\}$
$\{q_5\}$	$\{q_6\}$	$\{q_5\}$
$*\{q_6\}$	$\emptyset$	$\{q_6\}$

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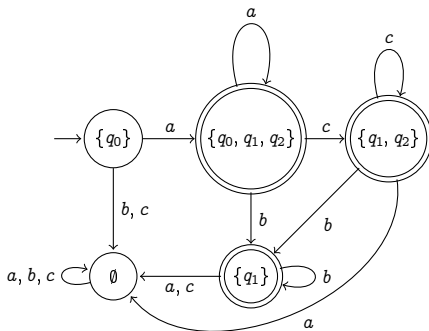
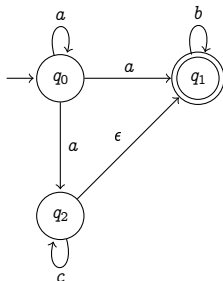
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$\{q_5\}$	$\{q_6\}$	$\{q_5\}$
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Second table:

$\delta_D$	$a\epsilon^*$
$\rightarrow \{q_1, q_3, q_5\}$	$\{q_2, q_3, q_5\} \cup \{q_4, q_5\} \cup \{q_6\} = \{q_2, q_3, q_4, q_5, q_6\}$
$*\{q_2, q_3, q_4, q_5, q_6\}$	$\emptyset \cup \{q_4, q_5\} \cup \emptyset \cup \{q_6\} \cup \emptyset = \{q_4, q_5, q_6\}$
$*\{q_4, q_5, q_6\}$	$\emptyset \cup \{q_6\} \cup \emptyset = \{q_6\}$
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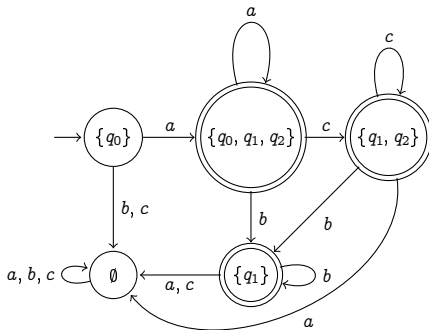
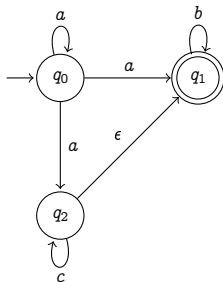
# Example 3



First table:

	$\epsilon^*$	$a$	$b$	$c$
$\rightarrow \{q_0\}$	$\{q_0\}$	$\{q_0, q_1, q_2\}$	$\emptyset$	$\emptyset$
$*\{q_1\}$	$\{q_1\}$	$\emptyset$	$\{q_1\}$	$\emptyset$
$\{q_2\}$	$\{q_1, q_2\}$	$\emptyset$	$\emptyset$	$\{q_2\}$

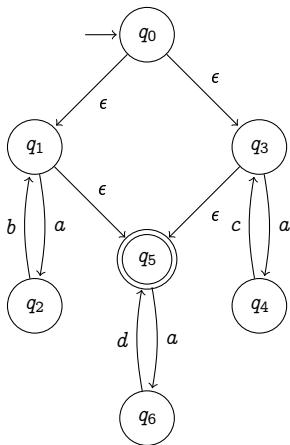
# Example 3



Second table:

$\delta_D$	$a\epsilon^*$	$b\epsilon^*$	$c\epsilon^*$
$\rightarrow \{q_0\}$	$\{q_0, q_1, q_2\}$	$\emptyset$	$\emptyset$
$*\{q_0, q_1, q_2\}$	$\{q_0, q_1, q_2\}$	$\{q_1\}$	$\{q_1, q_2\}$
$*\{q_1\}$	$\emptyset$	$\{q_1\}$	$\emptyset$
$*\{q_1, q_2\}$	$\emptyset$	$\{q_1\}$	$\{q_1, q_2\}$
$\emptyset$	$\emptyset$	$\emptyset$	$\emptyset$

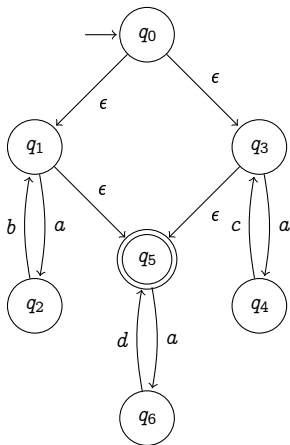
## Example 4: A Single Table



The transition function  $\delta_D$  ( $n$  stands for  $q_n$ ):

$\delta_D$	$a$	$b$	$c$	$d$
$\rightarrow * \{0, 1, 3, 5\}$	$\{2, 4, 6\}$	$\emptyset$	$\emptyset$	$\emptyset$

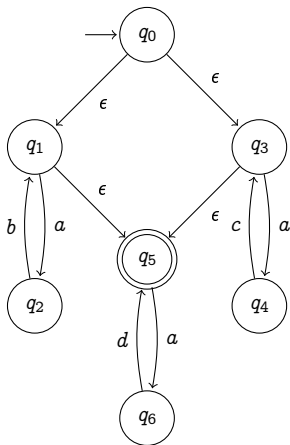
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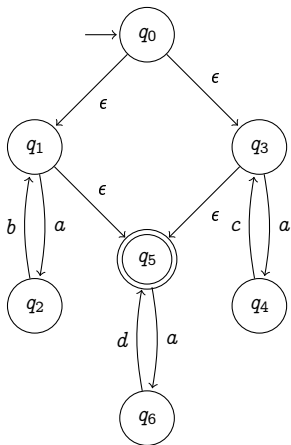
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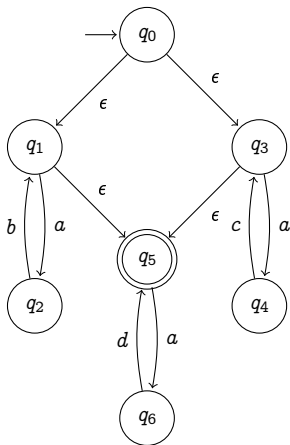


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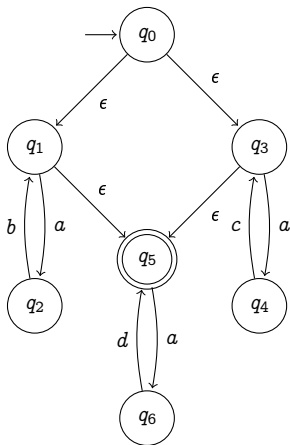
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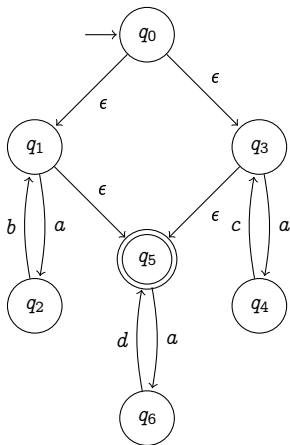
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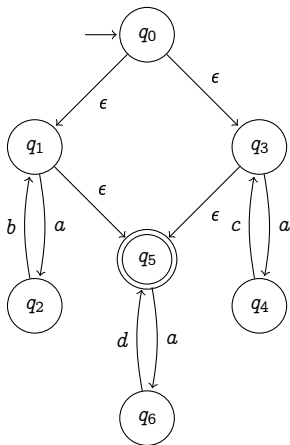
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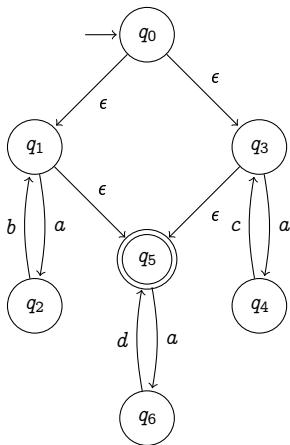
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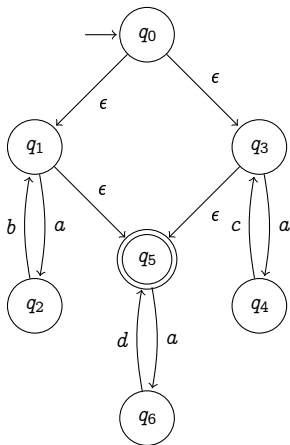
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- Every DFSA can be regarded as an equivalent NFA
  - Every NFA can be transformed into an equivalent DFA
- ⇒ The languages accepted by DFSA or NFAs are equal  
This is the class of the languages accepted by FSAs



From NFSMs to DFSMs

From NεFSMs to DFSMs

The regular expression for a machine



# A regular expression for a machine



Machines in **normal form**:

- the start state  $q_0$  has no incoming arrows
- $q_f$  is the only accepting state, and has no outgoing arrows.

States different from  $q_0$  and  $q_f$  are called **internal nodes**.

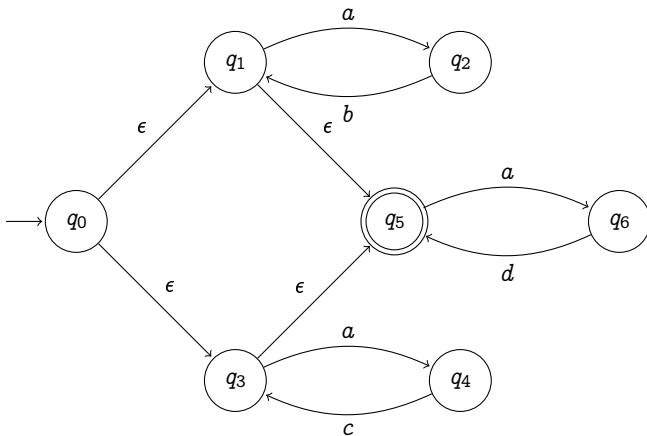
*Intuition:* The state diagram of the machine seen as a **directed graph**, with edges labelled by regular expressions.

- Initially, an edge's label is the finite set of the symbols at the edge.
- One by one, we eliminate the internal nodes of the graph.
- When all internal nodes are eliminated, there is only one remaining edge, namely from  $q_0 \rightarrow q_f$ .
- The label of the last edge is the resulting regular expression.

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6\}.$$

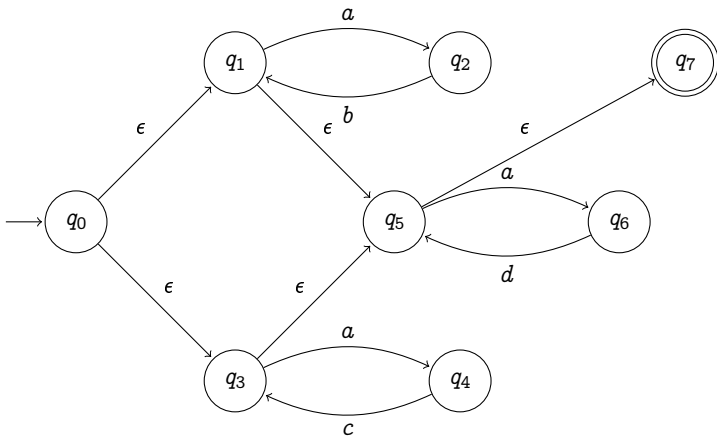


We first bring the machine to normal form.

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}.$$

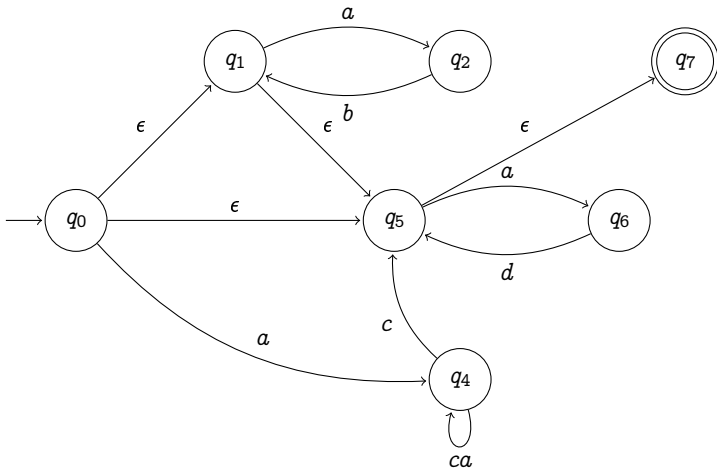


We added state  $q_7$ . Next we will remove  $q_3$ .

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$

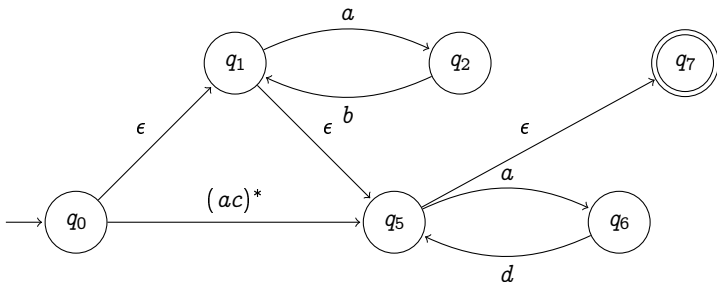


We removed  $q_3$ . Note:  $(ac)^n = a(ca)^{n-1}c$   
Next we will remove  $q_4$ .

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$

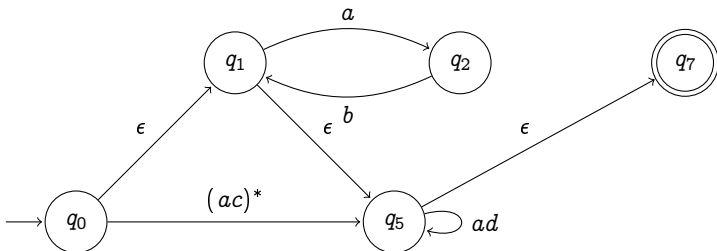


We removed  $q_4$ . Next we will remove  $q_6$ .

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$

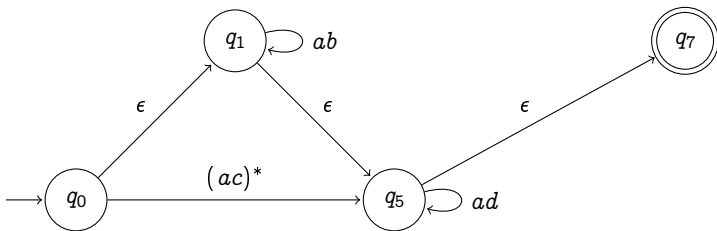


We removed  $q_6$ . Next we will remove  $q_2$ .

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$

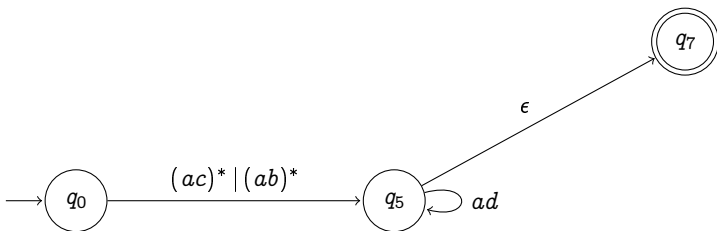


We removed  $q_2$ . Next we will remove  $q_1$ .

# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$



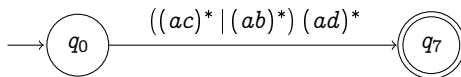
We removed  $q_1$ . Finally, we will remove  $q_5$ .



# Example



$$W = \{q_0, q_1, q_2, q_3, q_4, q_5, q_6, q_7\}$$



We are done!



We may then conclude:

- ▶ A language is regular iff it is described by a regular expression
- ▶ A language is regular iff it is described by a regular grammar
- ▶ A language is regular iff it is described by a DFSA
- ▶ A language is regular iff it is described by a  $N(\epsilon)$ FSM

## Next Lecture

- Closure properties of regular languages
- The pumping lemma for regular languages