university of groningen

Languages and Machines

L8: Turing machines

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Languages and Their Machines

Regular	$\leftrightarrow$	Finite State Machines (FSMs)
Context-free	$\leftrightarrow$	Pushdown Machines
Context-sensitive	$\leftrightarrow$	Linearly-bounded Machines
Decidable	$\leftrightarrow$	**Always-terminating Turing Machines**
Semi-decidable	$\leftrightarrow$	**Turing Machines**

Languages and Machines, Up to Here

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- What kind of machines do we need to recognize L_2?

Turing Machines (TMs)

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- A Turing machine (TM) may access and modify any memory position, using a sequence of elementary operations
- No limitation on the space/time available for a computation
- A finite state machine equipped with a **tape**, divided into **squares**, which can be written on as a result of a transition
- The **head** of the machine can move to the right or to the left, allowing the TM to read and manipulate the input as desired

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In other words, a transition:

- changes the state
- writes a symbol on the square scanned by the head
- moves the head

Turing Machines (TMs)

A (simple) **Turing machine** M is a quintuple $(Q, \Sigma, \Gamma, \delta, q_0)$ where

- Q is a set of **states**
- $q_0 \in Q$ is the **start state**
- Γ is the **tape alphabet**, a set of symbols disjoint from Q. Contains a **blank symbol** $\mathtt{B}$, not in Σ
- $\Sigma \subseteq \Gamma \setminus \{\mathtt{B}\}$ is the **input alphabet**
- The transition function δ is a partial function such that

$$\delta : Q \times \Gamma \to Q \times \Gamma \times \{\mathtt{L}, \mathtt{R}\}$$

If $\delta(q, X)$ is undefined then $\delta(q, X) = \bot$.

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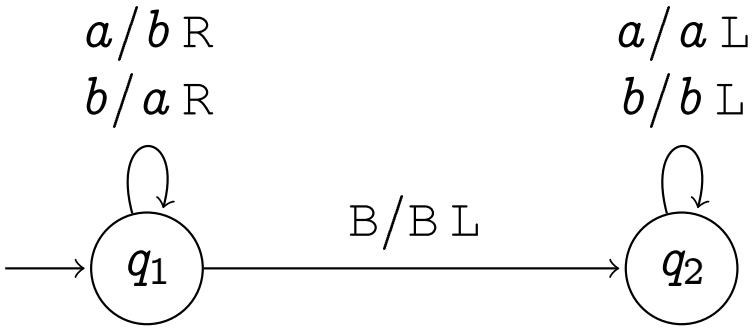
A set of accepting states $F \subseteq Q$ is possible but not indispensable for defining acceptance (see later).

Example 1

A TM that reads the input string and interchanges symbols a and b:



In state q_1, label '$a/b\,\mathtt{R}$' indicates:
- symbol a is rewritten into b, and
- the head moves right ($\mathtt{R}$).

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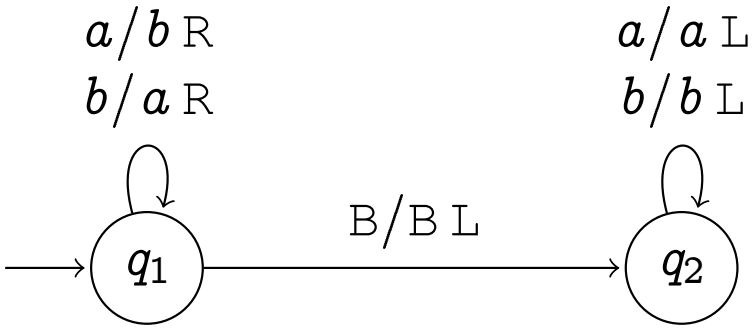
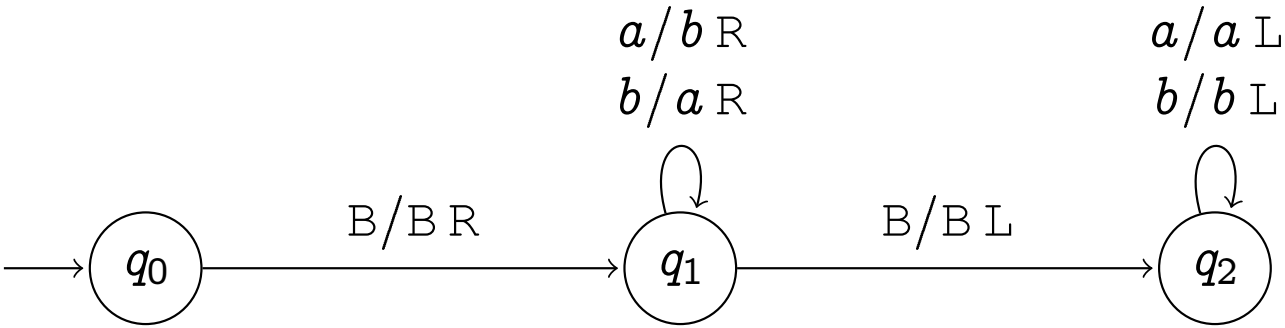


A slightly more general machine:



Turing Machines (TMs)

The global state of the TM is determined by the state $q \in Q$, the contents of the tape (a string in Γ^*) and the position of the head

- A **configuration** of the TM is a string uqv in $\Gamma^* Q \Gamma^*$, in which:
  - u is a string on the tape to the left of the head
  - q is the **current** state
  - v is a string on the tape that begins under the head
- The initial configuration is $q_0 w$, where $w \in \Sigma^*$ is the input string
- The first symbol of $v\mathrm{B}^\infty$ is called the **current** symbol

Turing Machines (TMs)

Suppose X, Y, Z are tape symbols (in Γ).
Moving to the next configuration:

$$\begin{aligned}
\delta(q, X) = (r, Y, \mathtt{R}) &\Rightarrow u\ Z\ q\ X\ v \vdash u\ Z\ Y\ r\ v \\
\delta(q, X) = (r, Y, \mathtt{L}) &\Rightarrow u\ Z\ q\ X\ v \vdash u\ r\ Z\ Y\ v \\
\delta(q, X) = \bot &\Rightarrow u\ q\ X\ v \vdash \bot
\end{aligned}$$

Turing Machines (TMs)

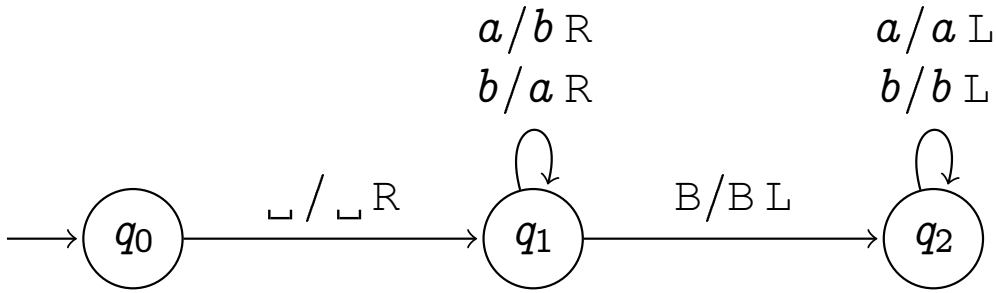
Suppose X, Y, Z are tape symbols (in Γ).
Moving to the next configuration:

$$\begin{aligned} \delta(q, X) = (r, Y, \mathtt{R}) &\Rightarrow u\, Z\, q\, X\, v \vdash u\, Z\, Y\, r\, v \\ \delta(q, X) = (r, Y, \mathtt{L}) &\Rightarrow u\, Z\, q\, X\, v \vdash u\, r\, Z\, Y\, v \\ \delta(q, X) = \bot &\Rightarrow u\, q\, X\, v \vdash \bot \end{aligned}$$

- A computation is a sequence of steps, as defined by $\vdash$
- A TM **computes a function** f
  - if starting in $q_0 w$, the final tape upon termination is always $\mathtt{B}^\infty u \mathtt{B}^\infty$, with $u = f(w)$.

Example 1, Revisited

Consider a variation of the previous machine with $\Sigma = \{a, b, \text{␣}\}$, where '␣' is always at the beginning of all input strings. We have:



Computation for input $abab$:

$$
\begin{aligned}
&\rightarrow [q_0\rangle \text{␣}\ a\ b\ a\ b\ \text{B}\\
&\vdash \text{␣}\ [q_1\rangle\ a\ b\ a\ b\ \text{B}\\
&\vdash \text{␣}\ b\ [q_1\rangle\ b\ a\ b\ \text{B}\\
&\vdash \text{␣}\ b\ a\ [q_1\rangle\ a\ b\ \text{B}\\
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&\vdash \text{␣}\ b\ a\ b\ [q_2\rangle\ a\ \text{B}\\
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&\vdash [q_2\rangle\ \text{␣}\ b\ a\ b\ a\ \text{B}
\end{aligned}
$$

Example 2

A TM that duplicates the input string $w \in \{0,1\}^*$.

- Before: A tape with the string w
- After: The tape contains the string $w\,w$
- What is your (programming) strategy?

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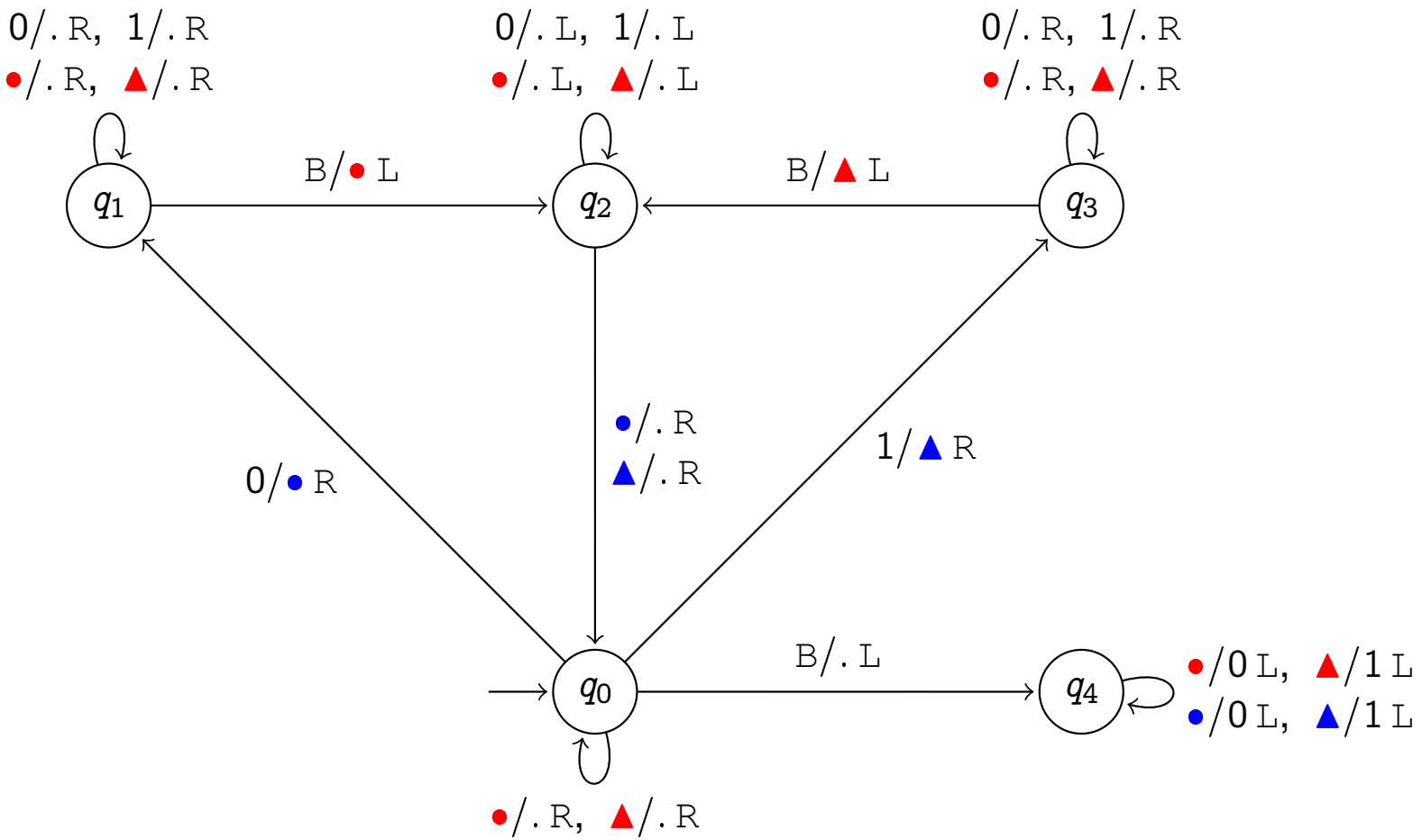

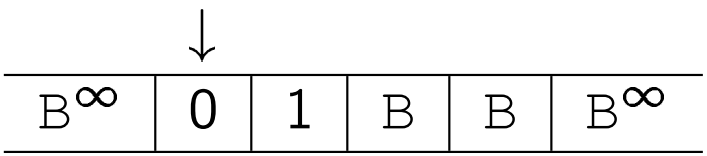

(State = q_0)

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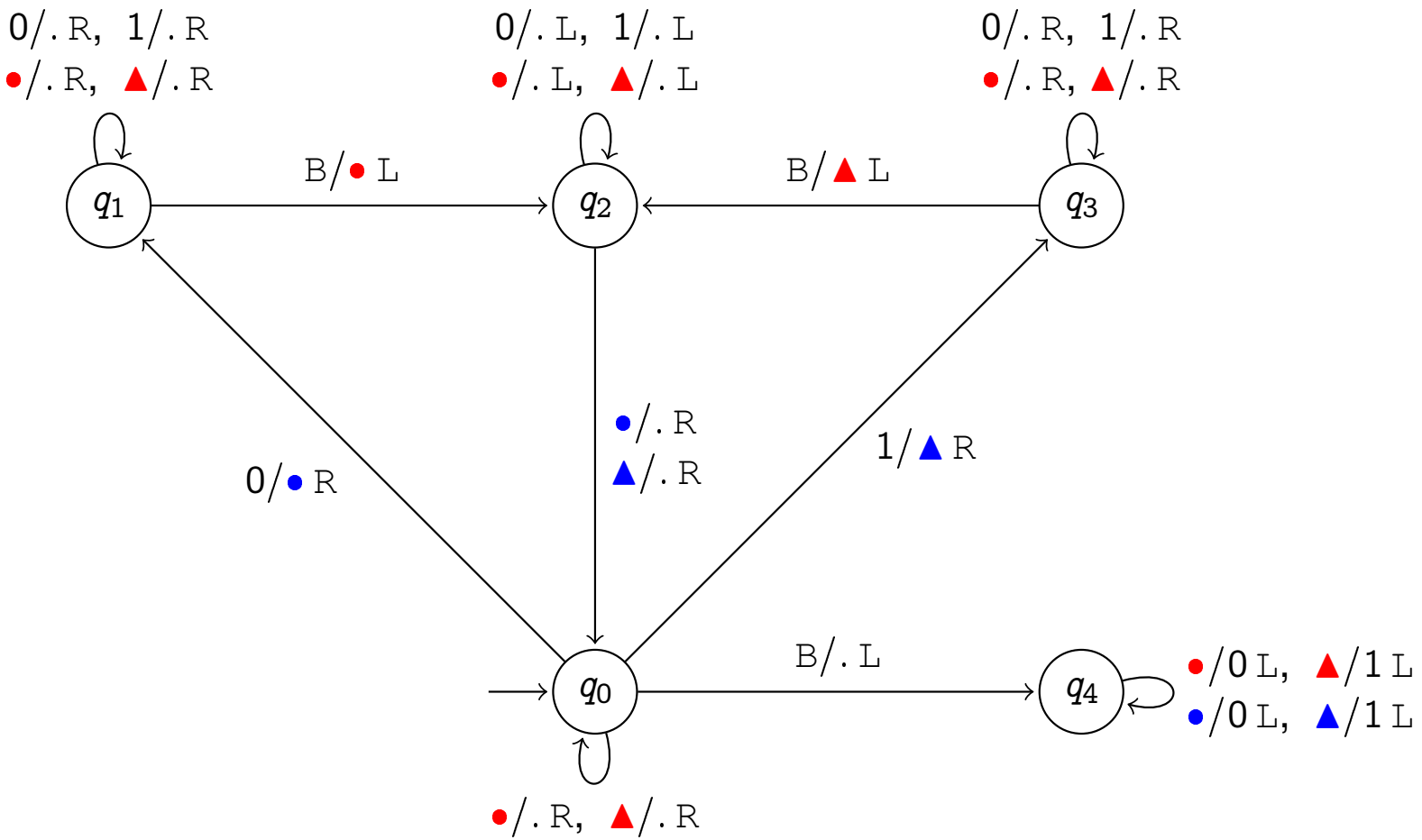

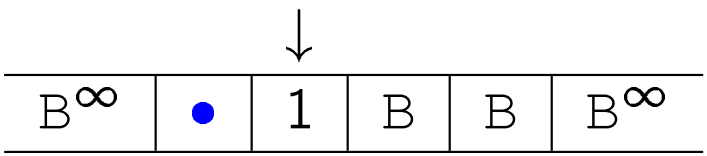

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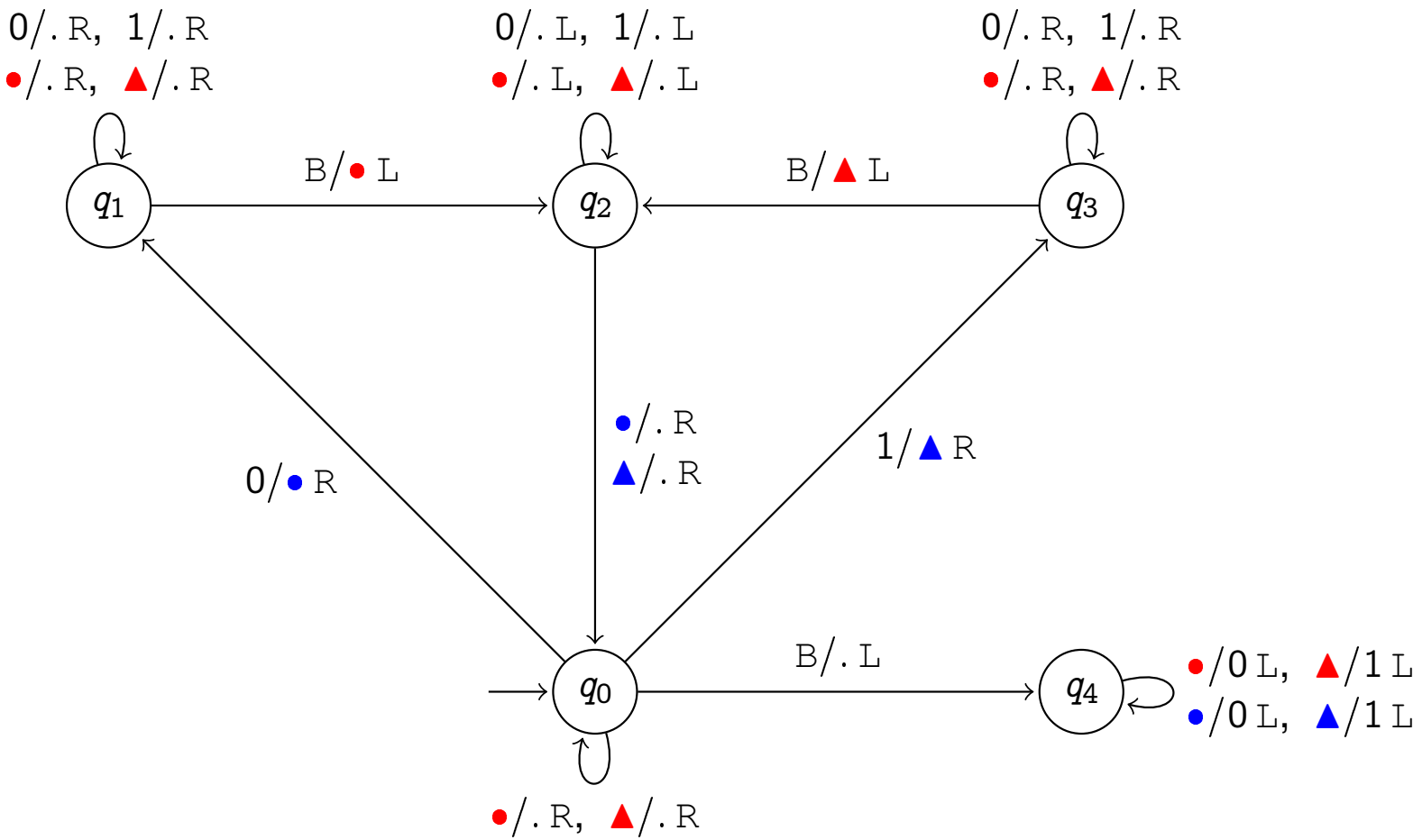

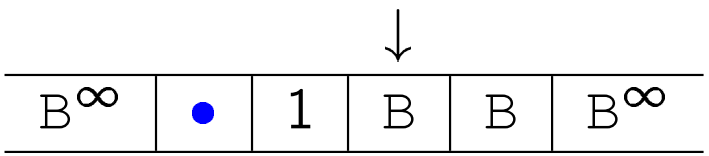

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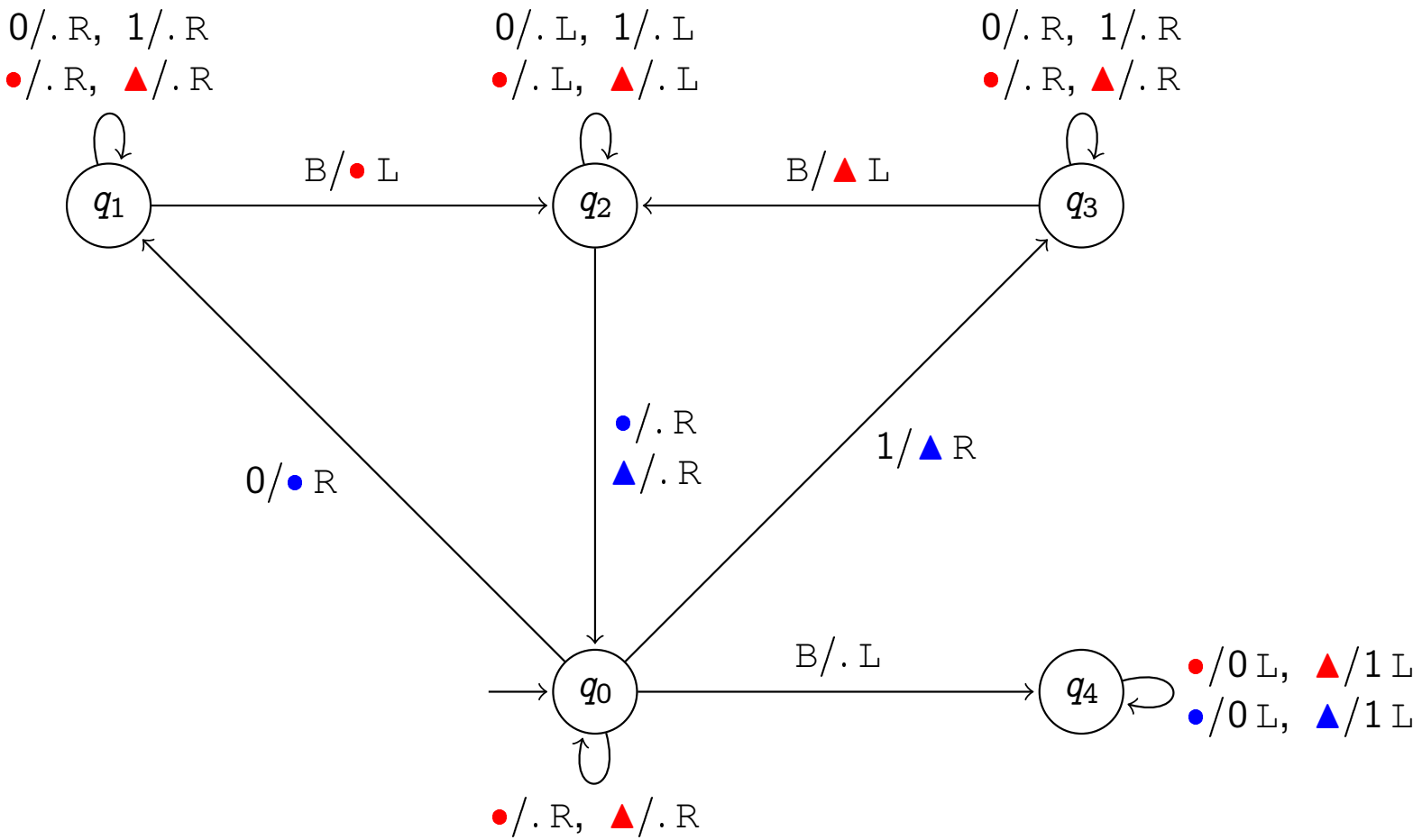

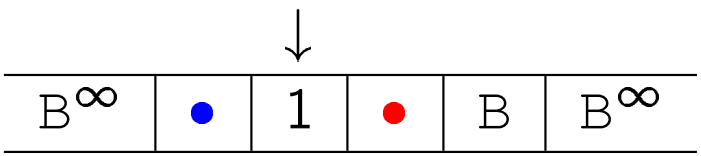

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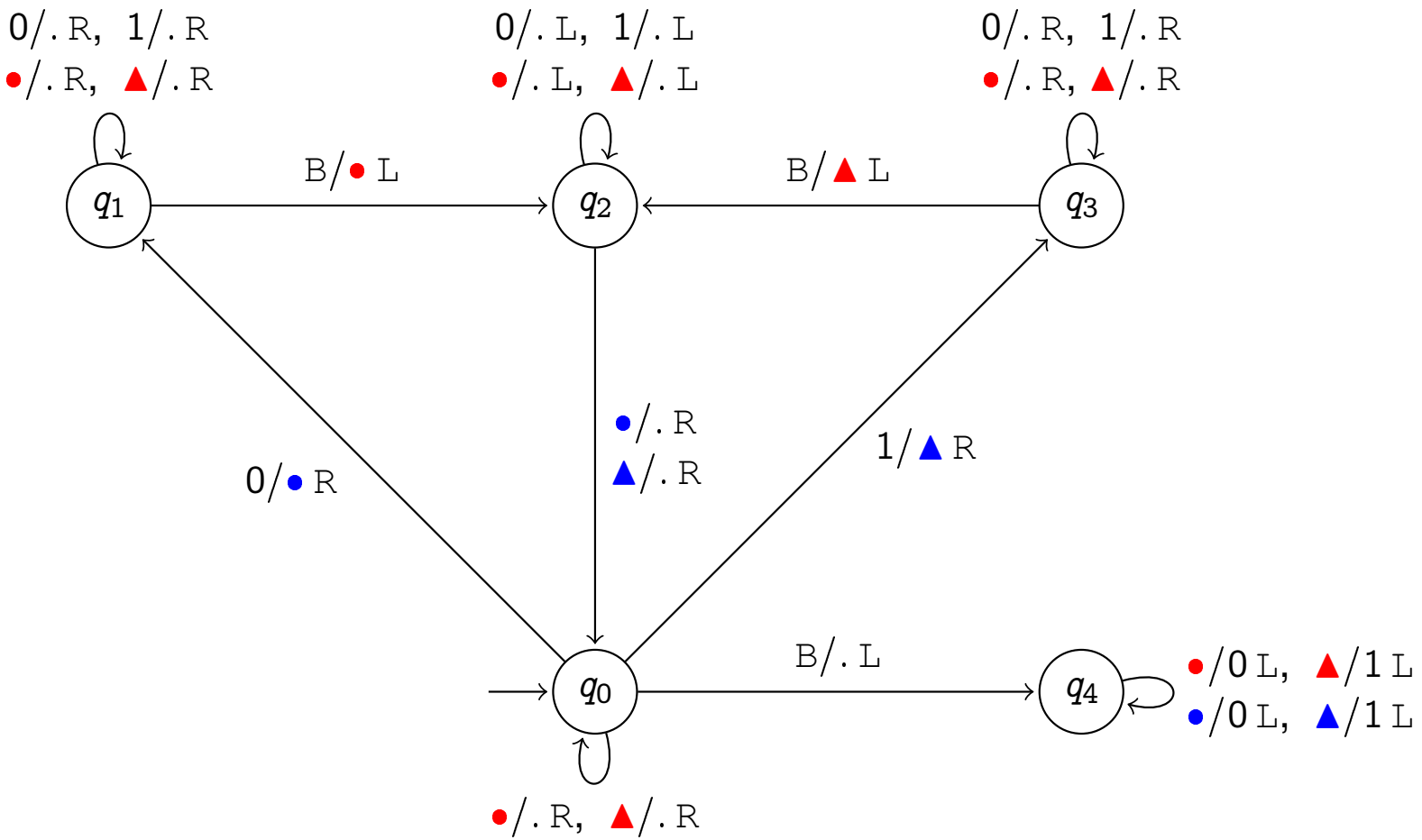

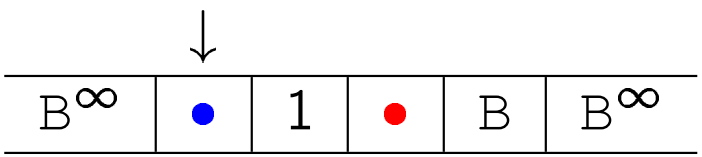

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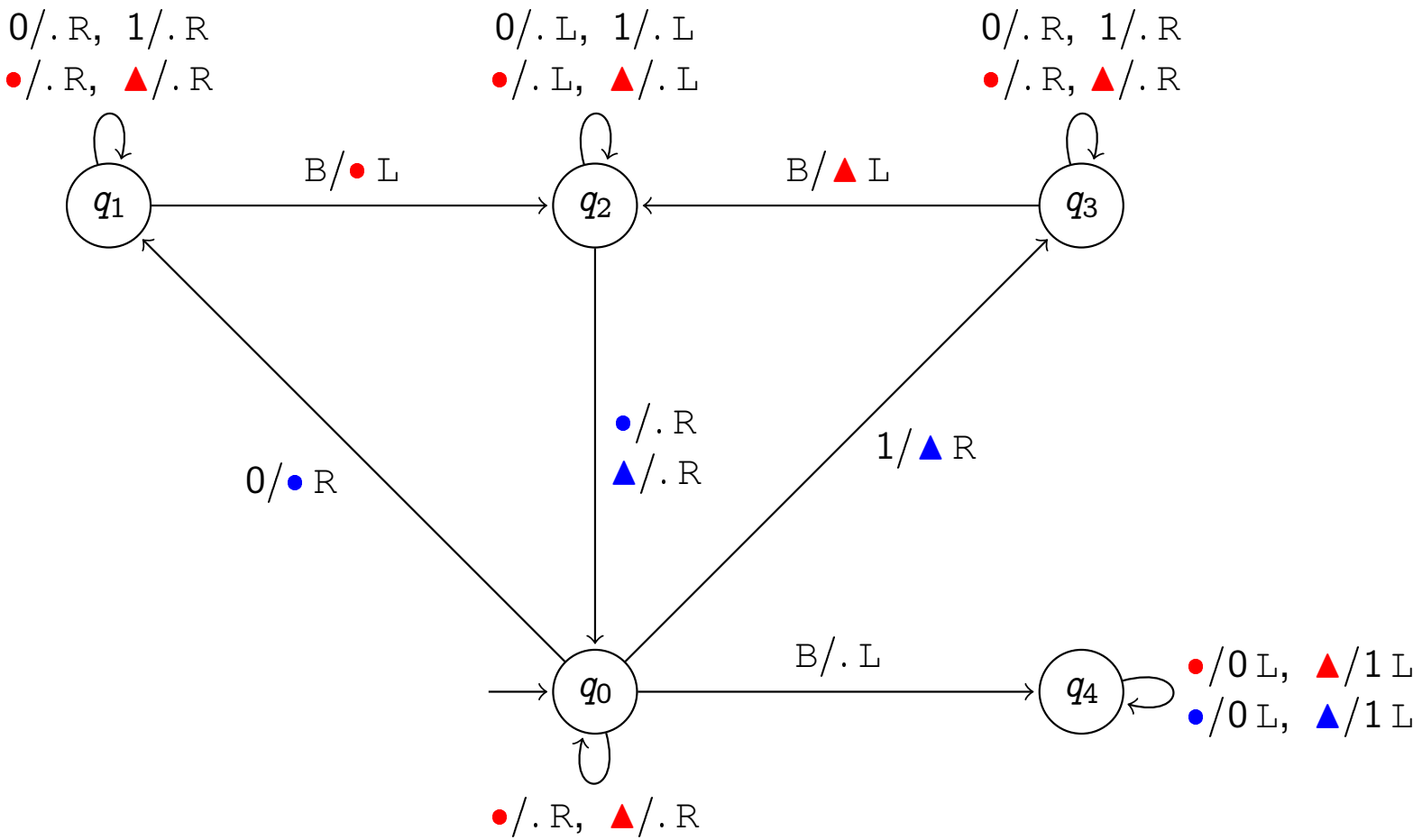

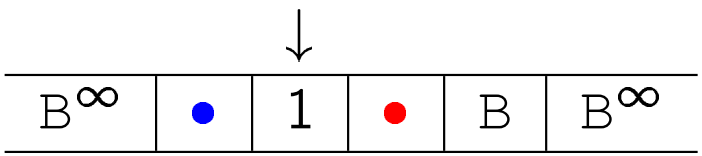

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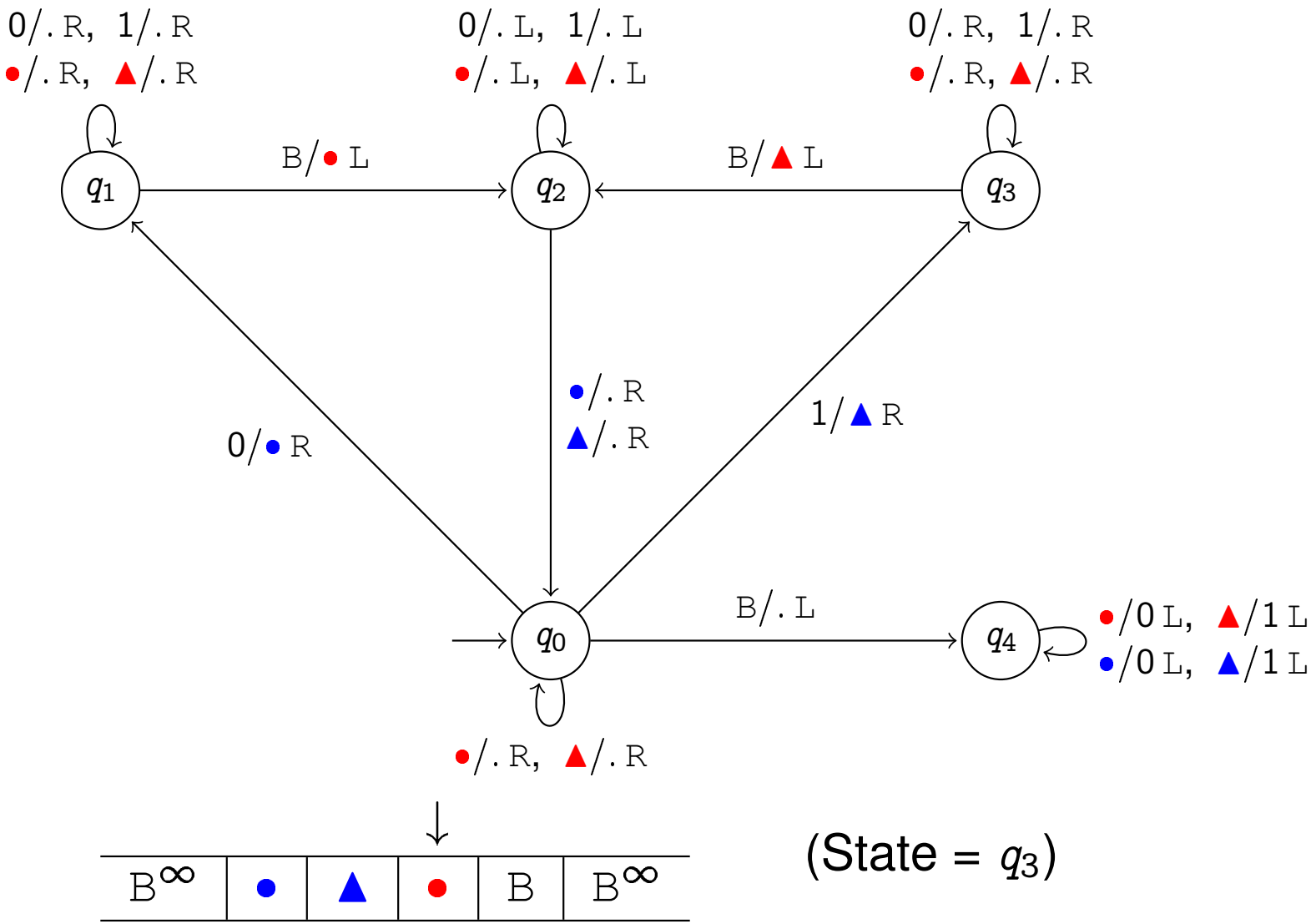

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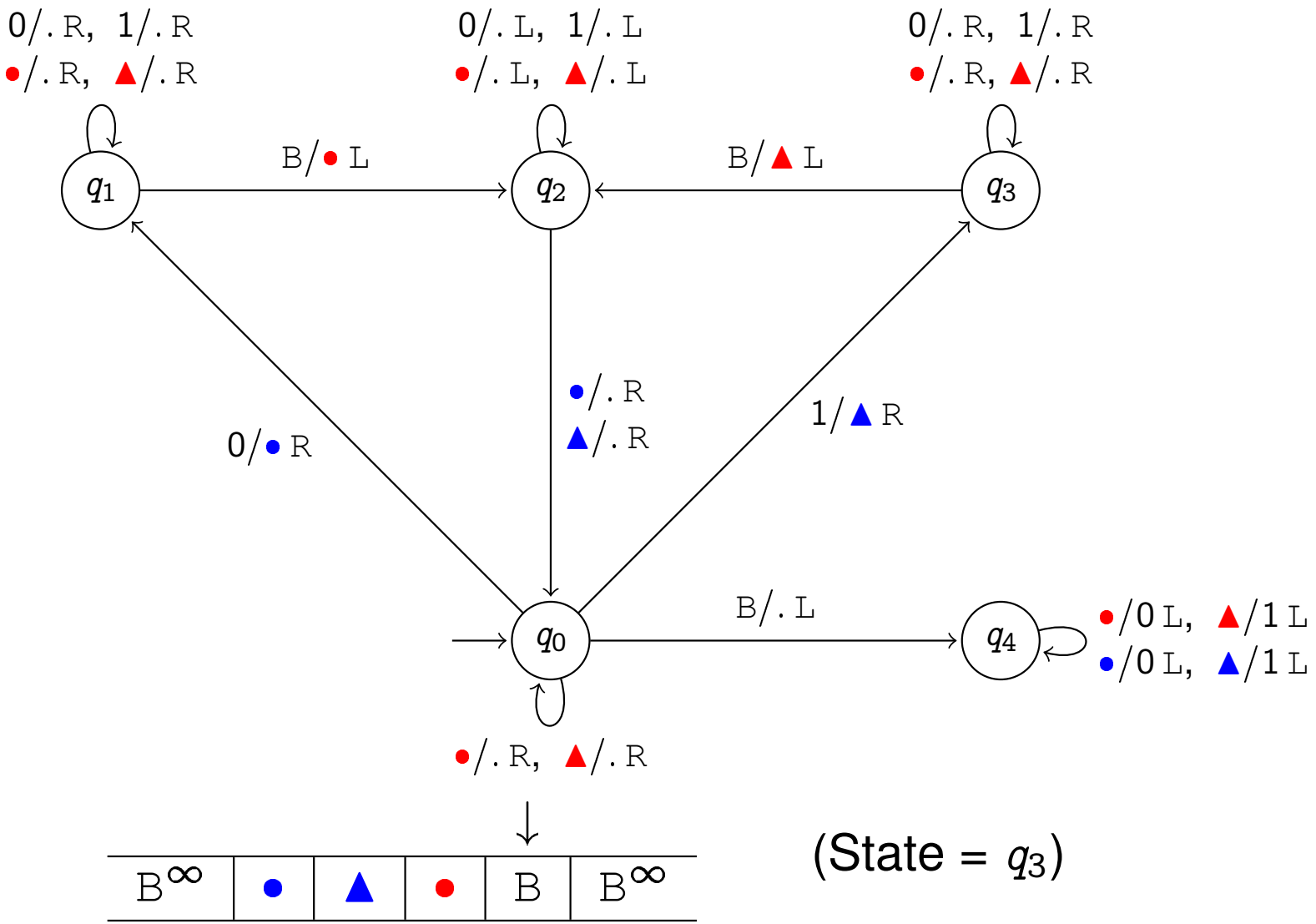

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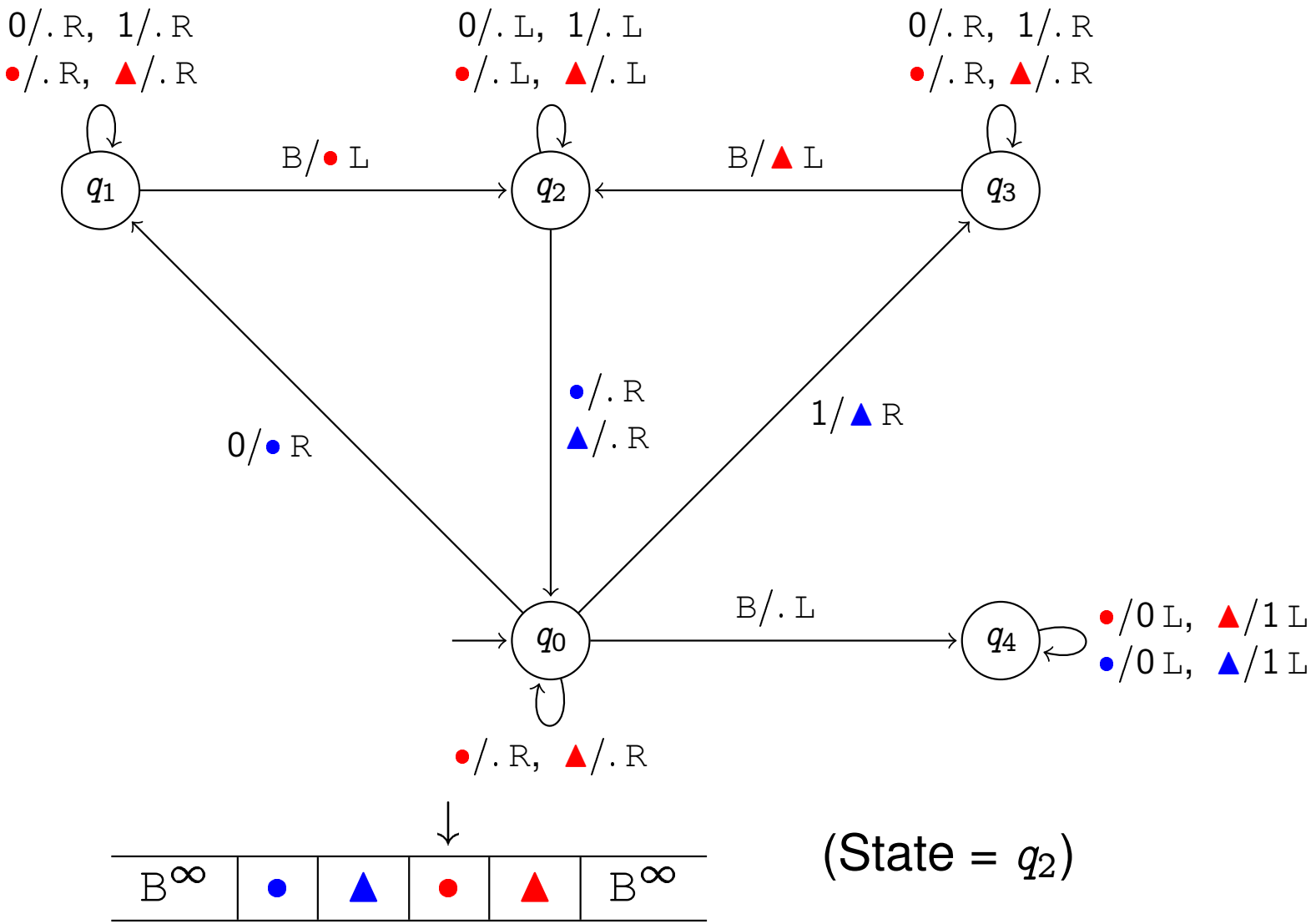

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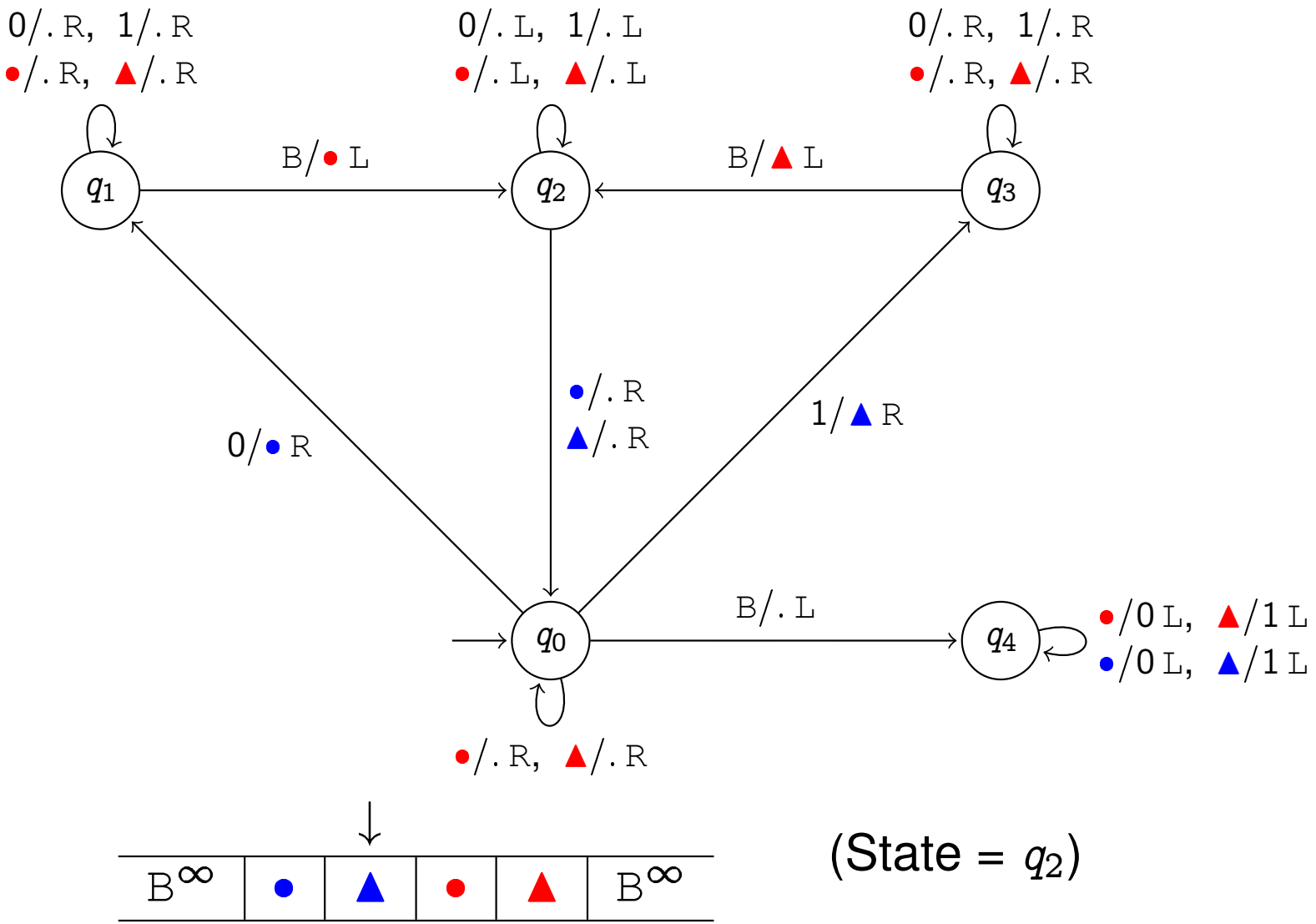

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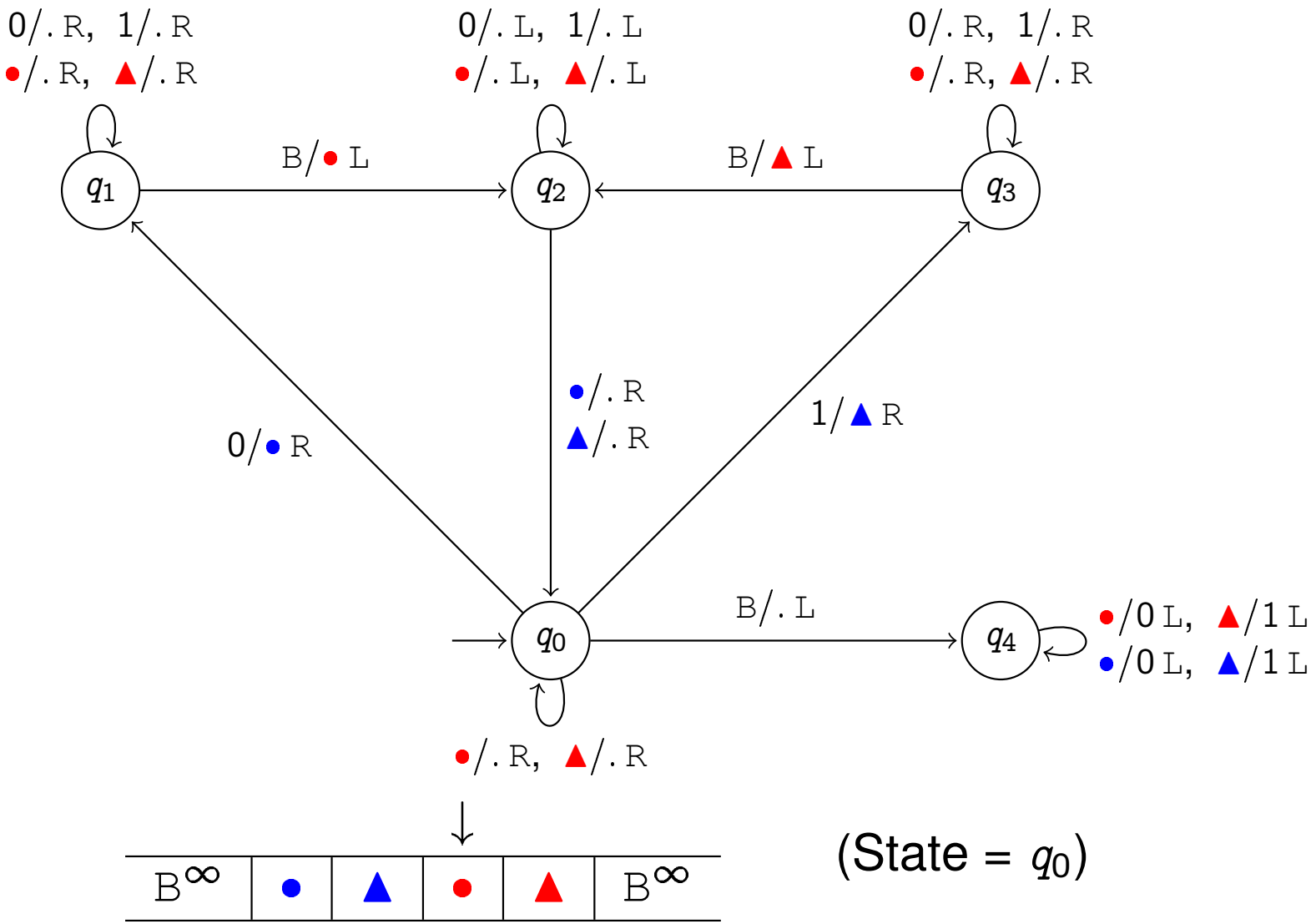

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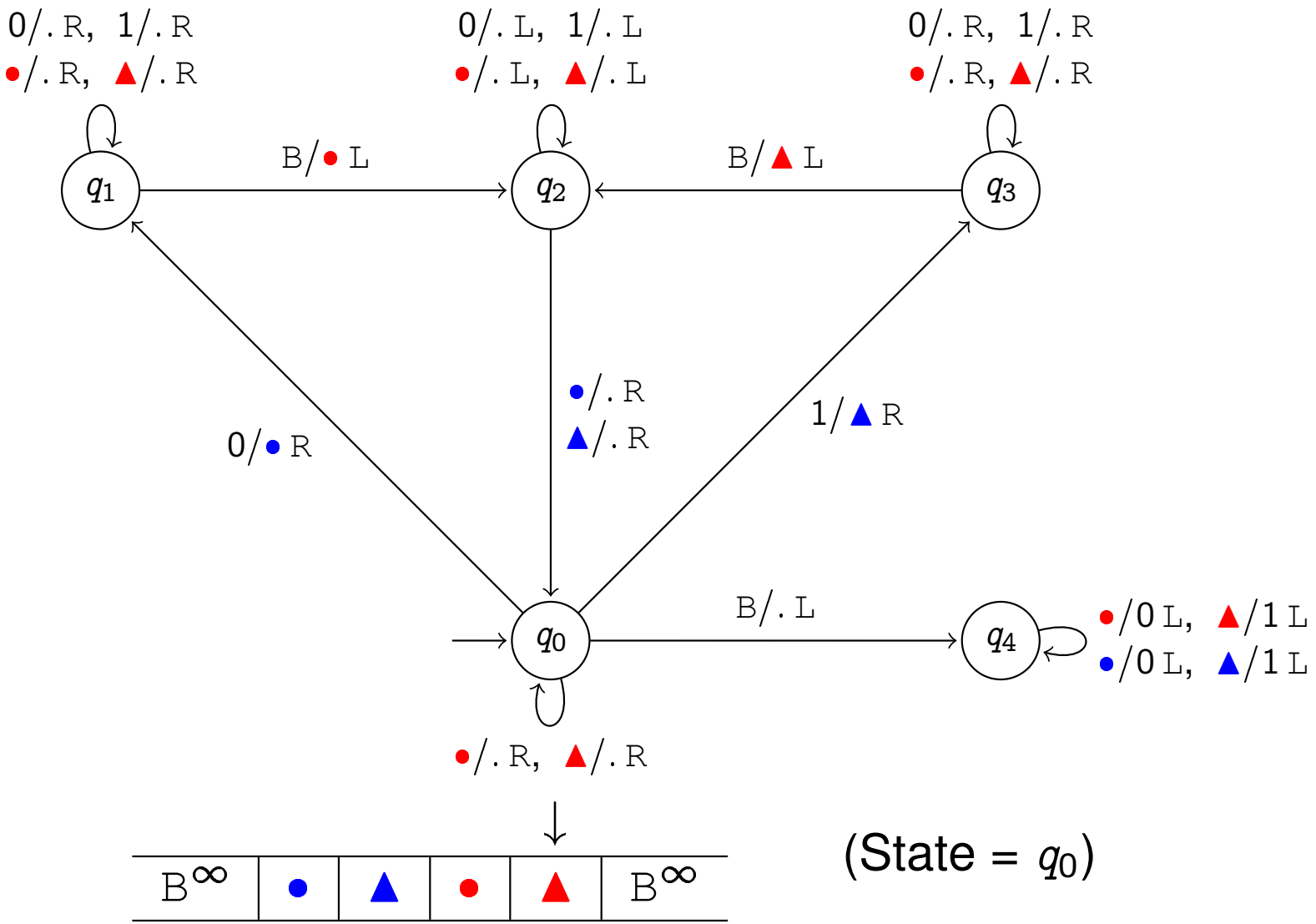

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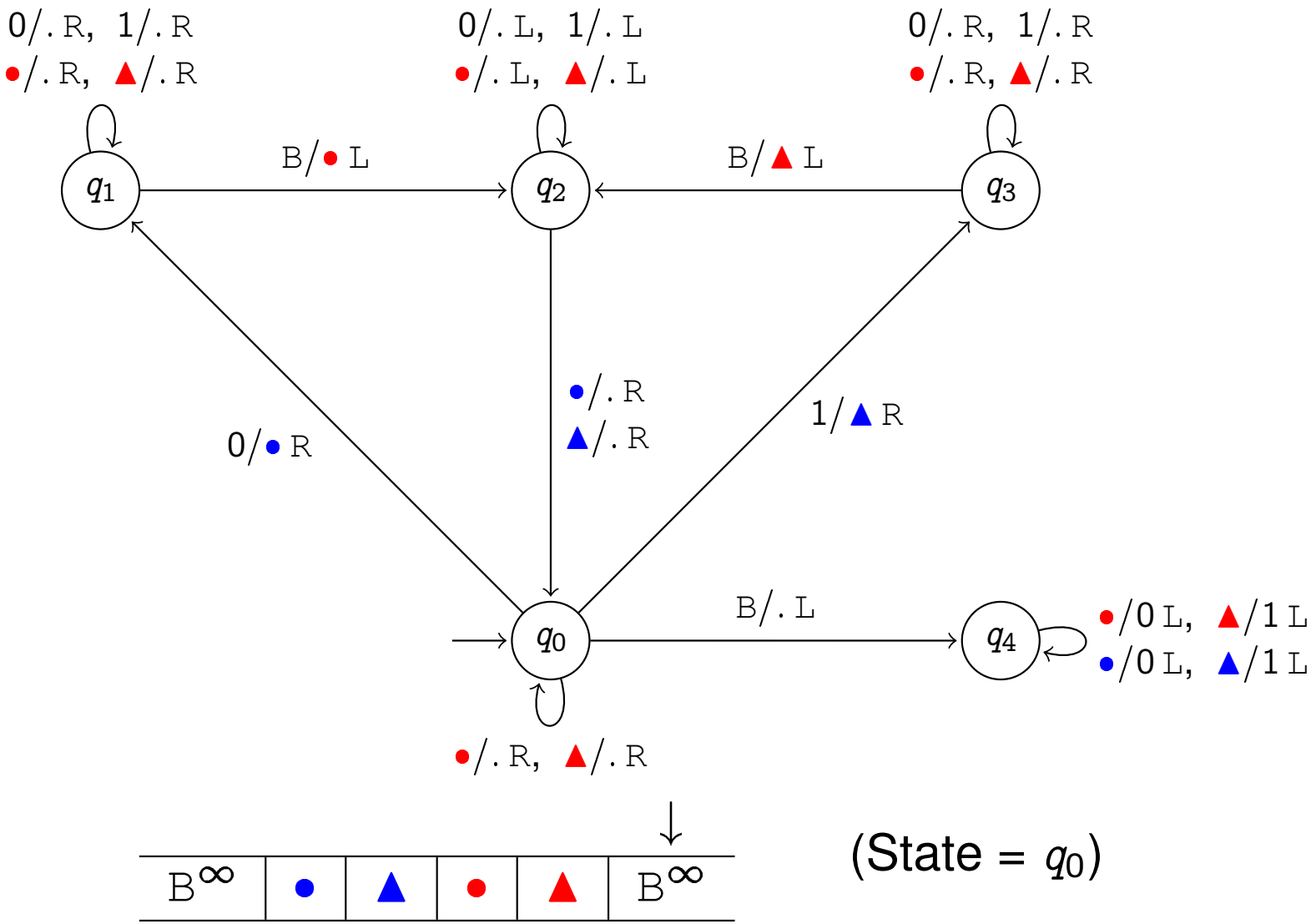

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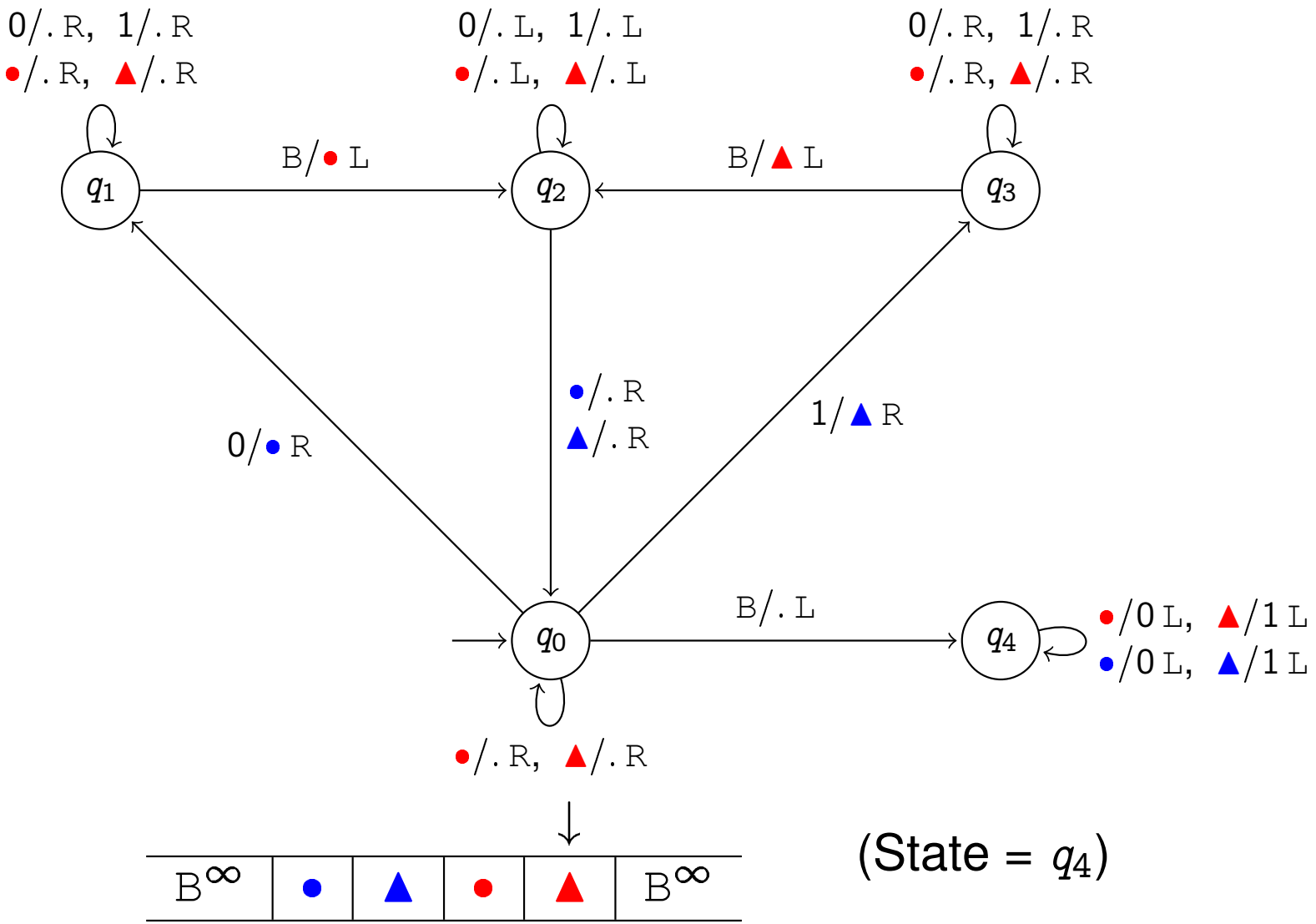
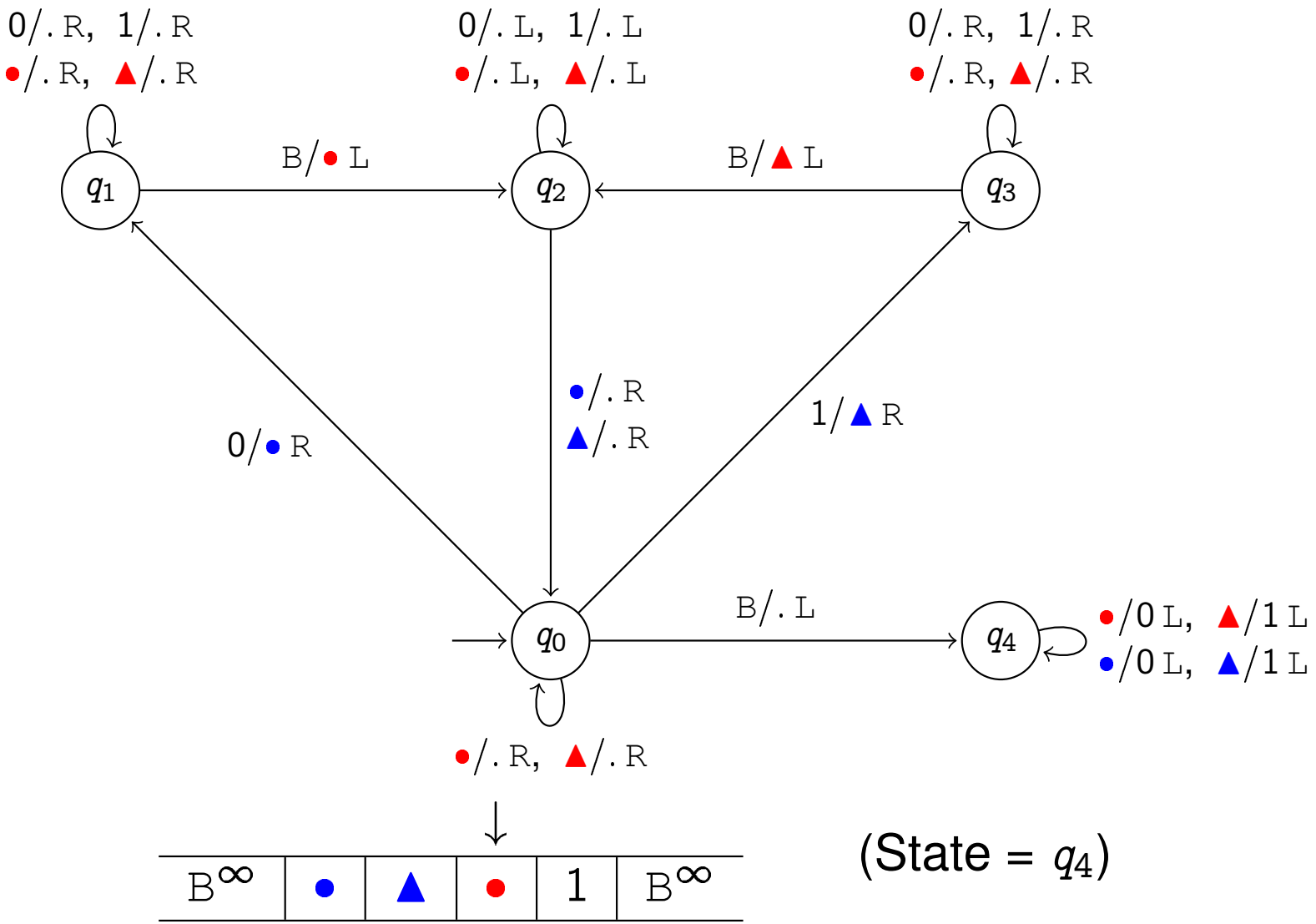


(State = q_4)

Example 2

A TM that duplicates the input string $w \in \{0,1\}^*$.



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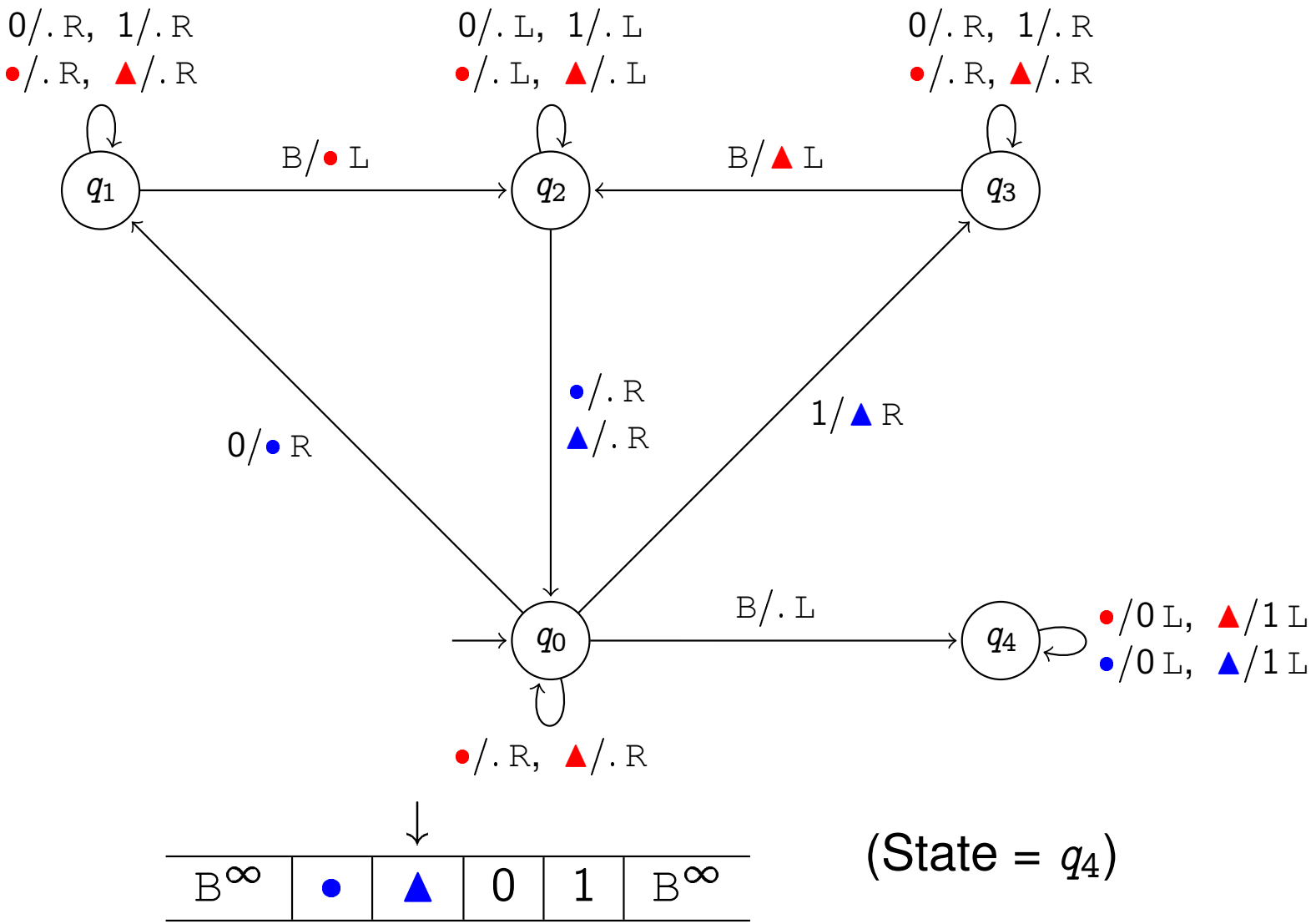

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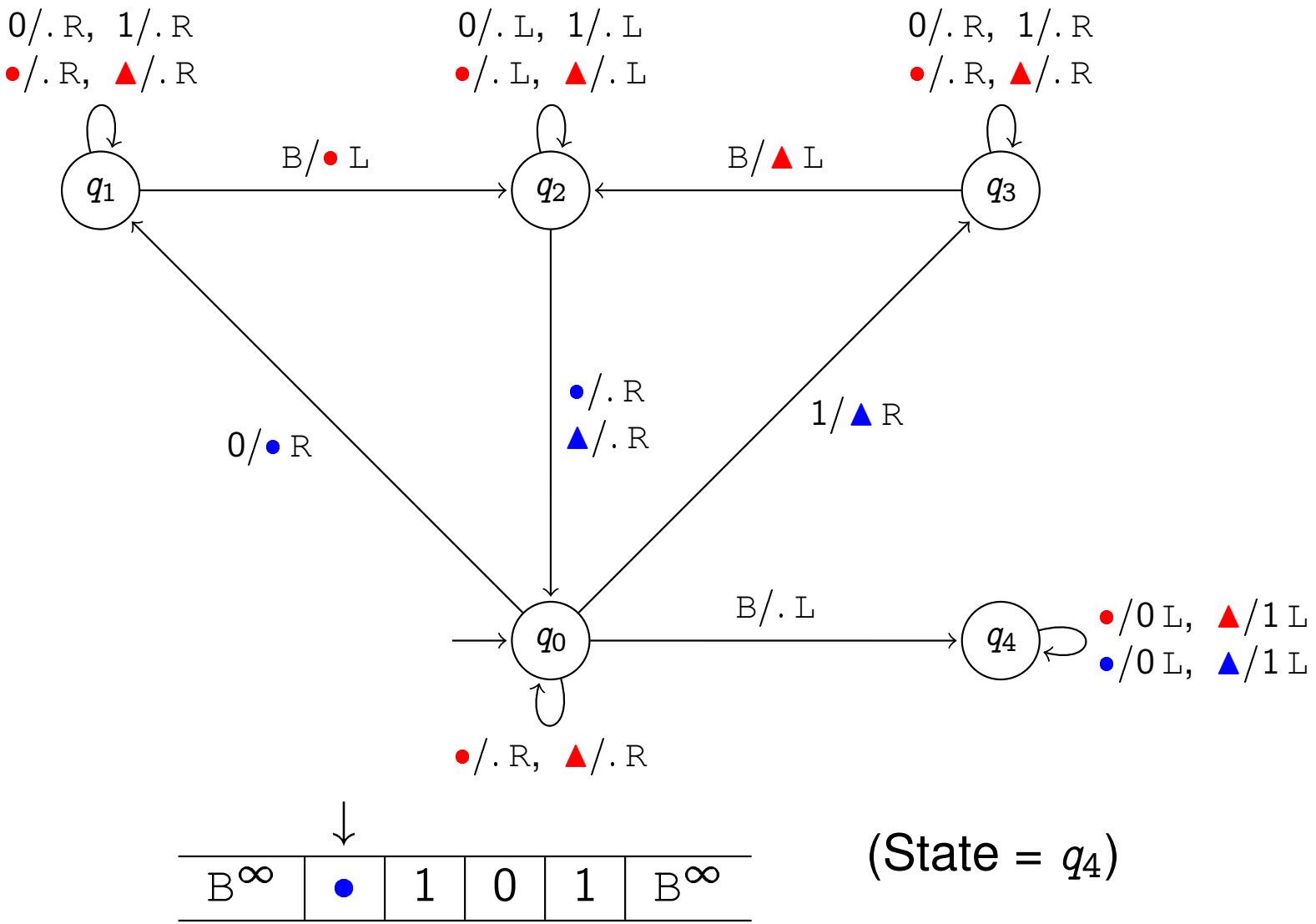

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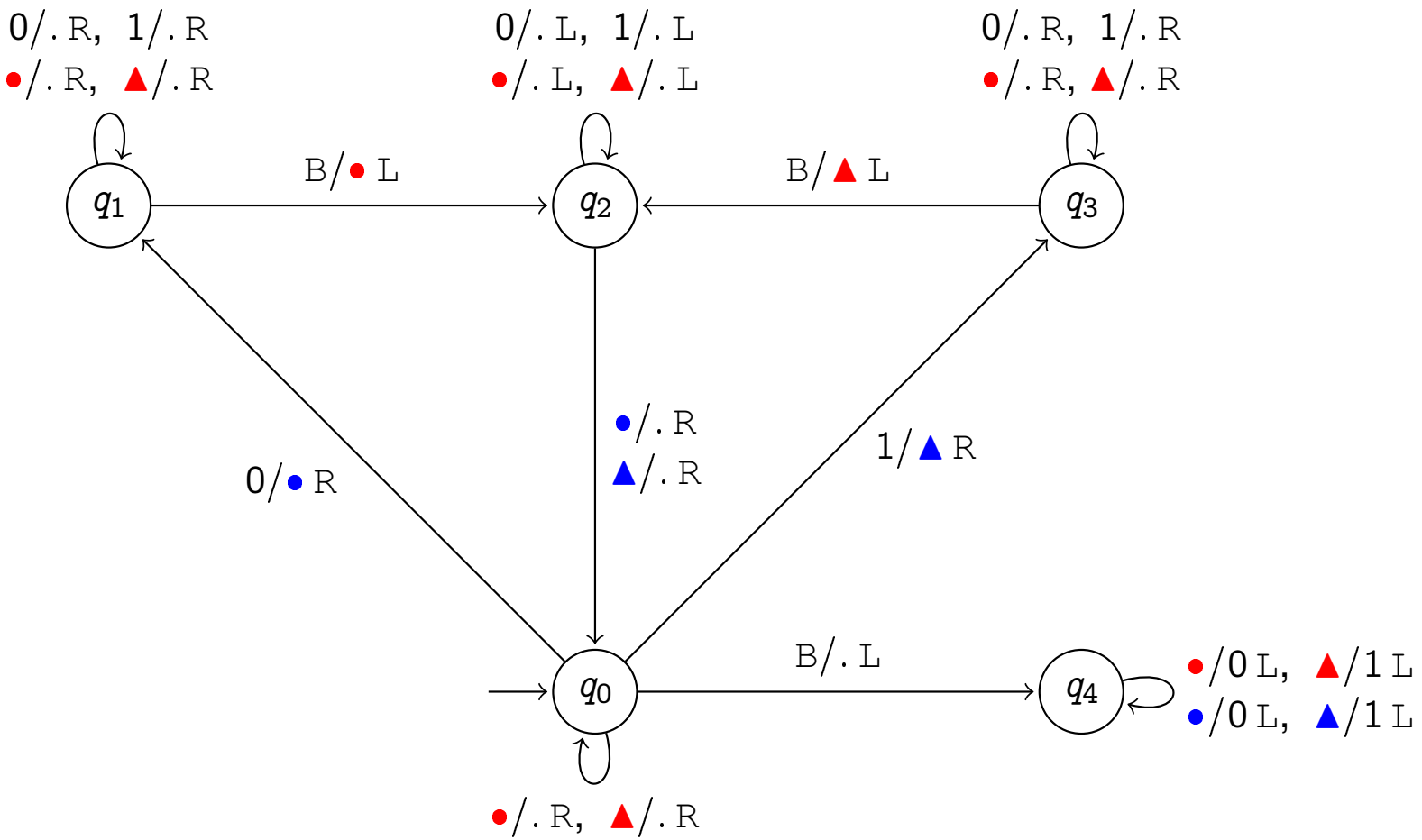

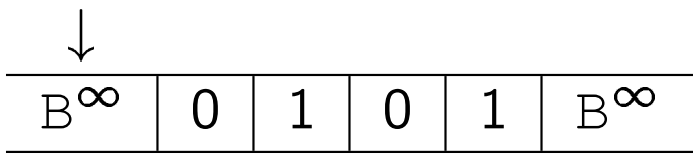

(State = q_4)

Example 2

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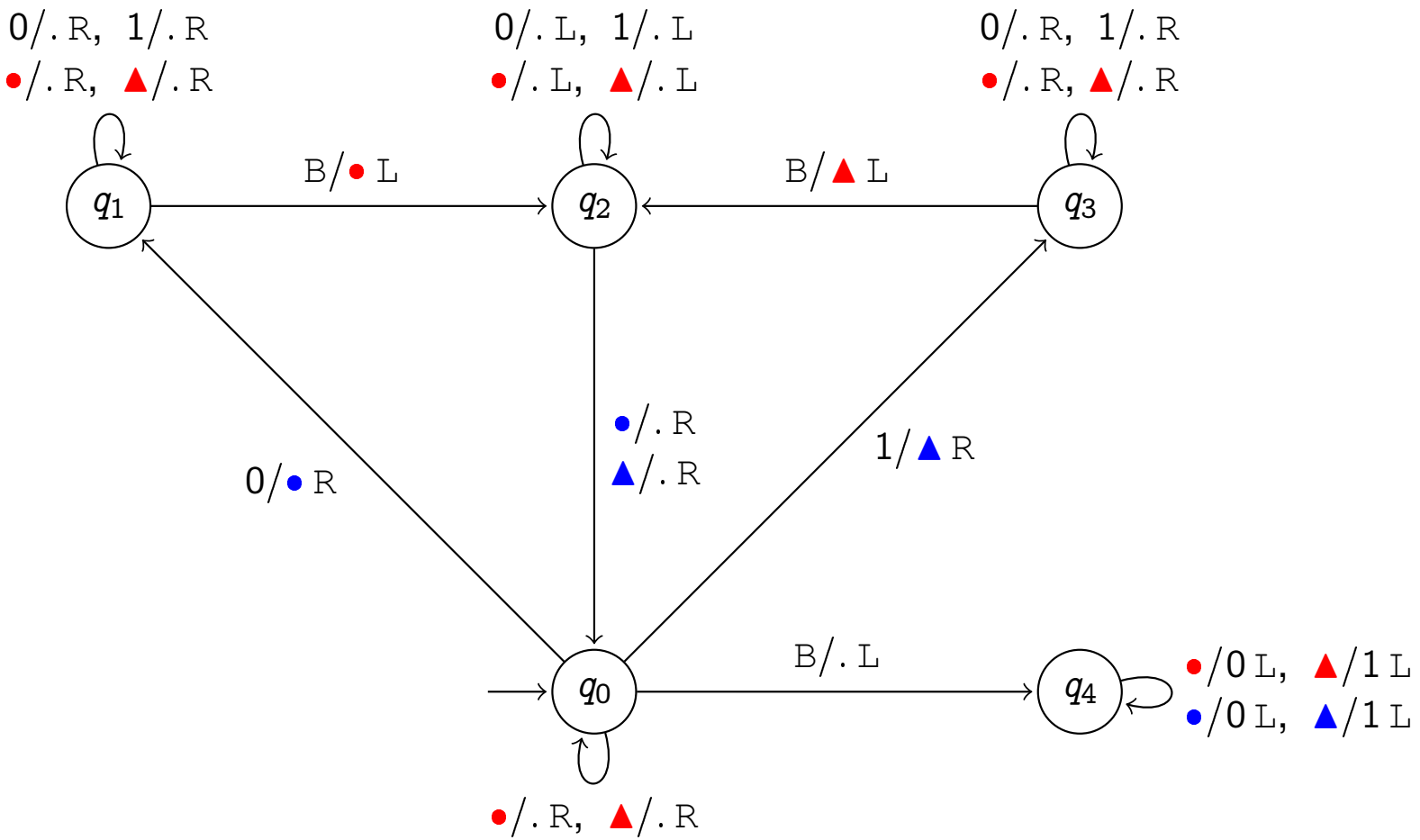

What does each state/transition represent?

Acceptance

The set $L(M)$ can be defined in two different ways.

1. A TM M **accepts by termination** the language of the input strings w for which it terminates:

$$L(M) = \{w \in \Sigma^* \mid q_0 w \vdash^* \bot\}$$

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$$L(M) = \{w \in \Sigma^* \mid q_0 w \vdash^* \bot\}$$

   No need for accepting states.

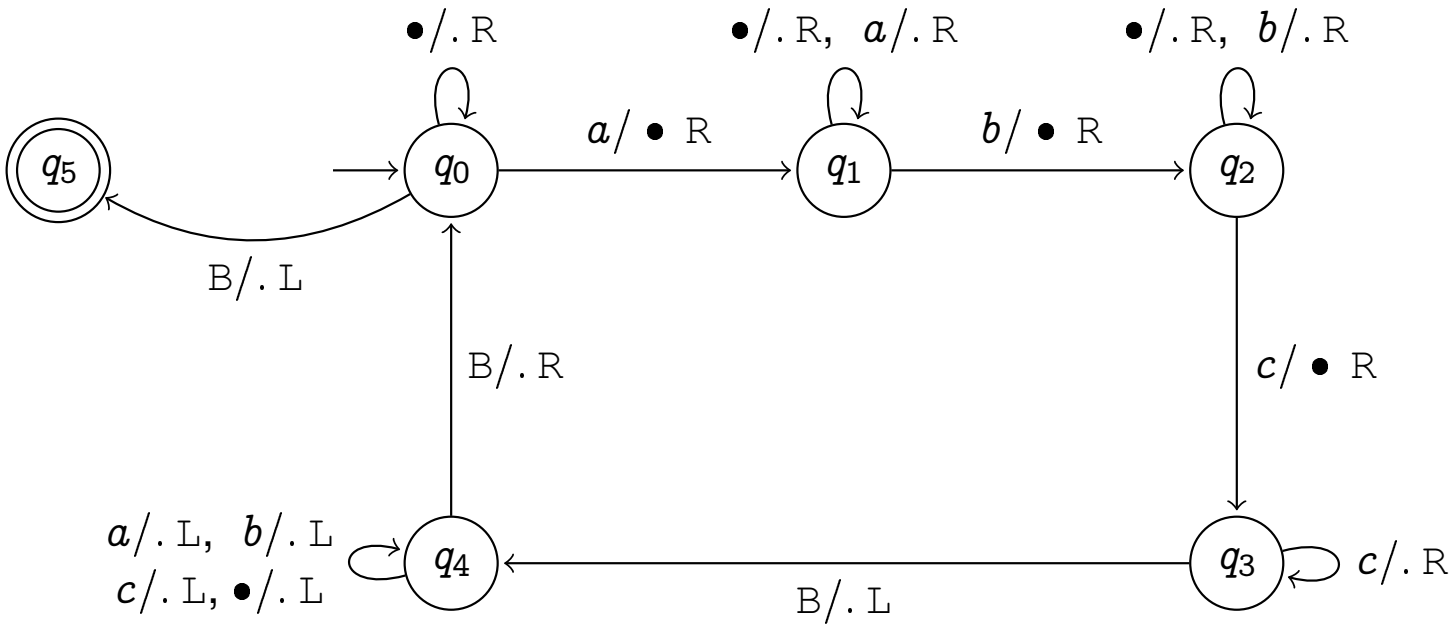
2. $L(M)$ can also be defined by **termination in an accepting state**, extending M with a set $F \subseteq Q$:

$$L(M) = \{w \in \Sigma^* \mid \exists q_f \in F,\ u, v \in \Gamma^* : q_0 w \vdash^* u\, q_f\, v \vdash \bot\}$$

   This definition can be reduced to the first one by letting $F = Q$. In fact, both definitions are equivalent.

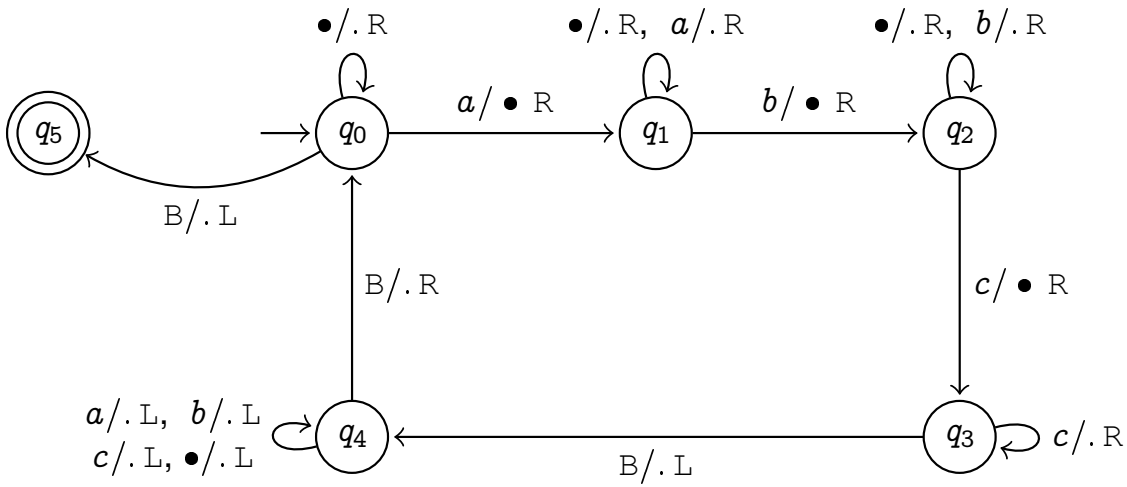
Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$

A TM with accepting state(s):



How does it work?

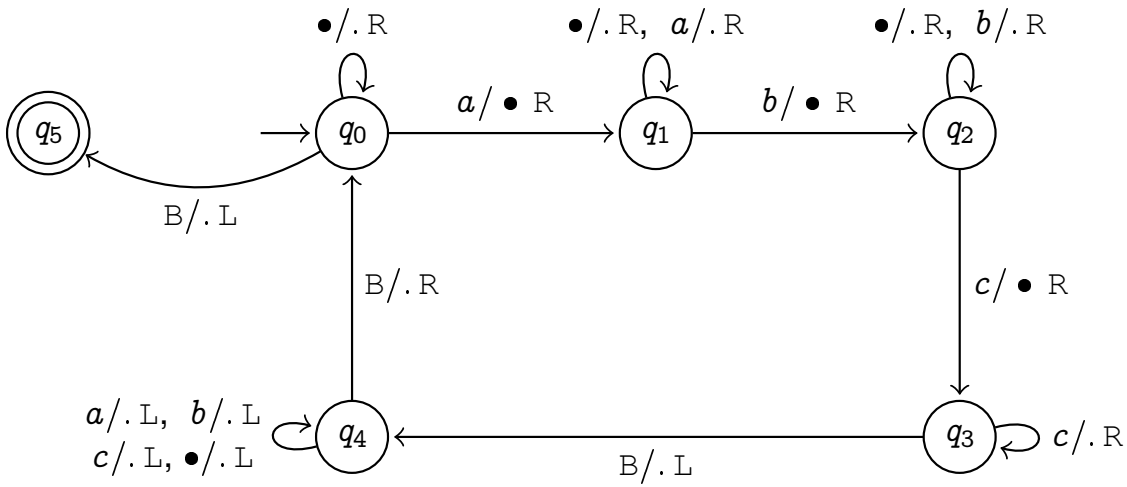
Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input $aabbcc$:

$\rightarrow$ B $[q_0\rangle$ a a b b c c B

Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

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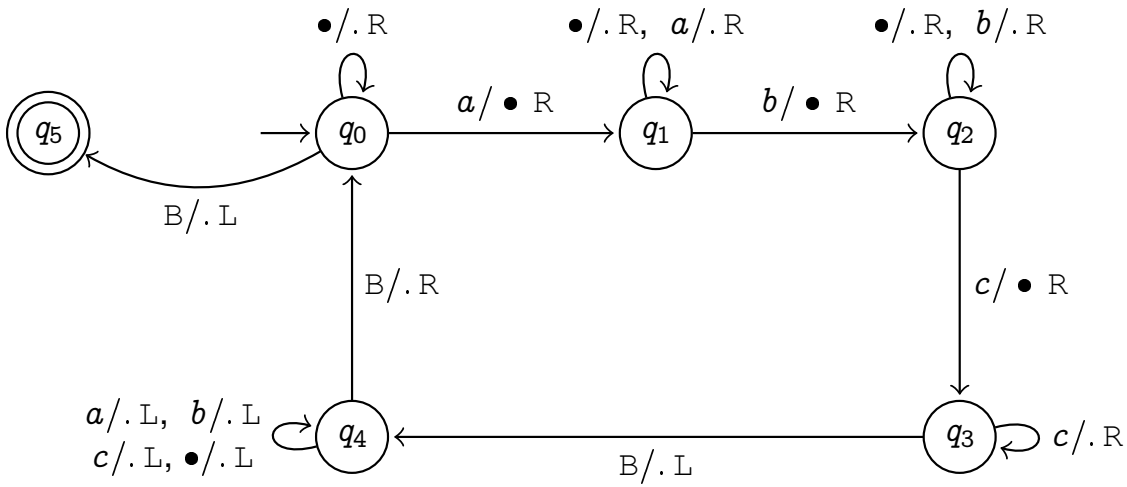

Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ [q_1\rangle\ b\ b\ c\ c\ \mathtt{B}$

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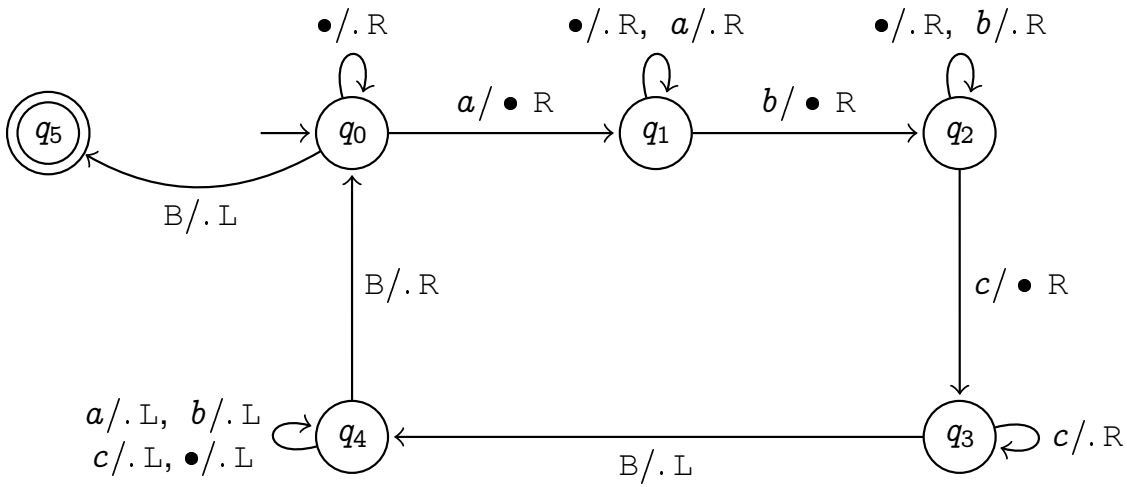

Computation for input $aabbcc$:

$\rightarrow$ B $[q_0\rangle$ a a b b c c B

$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

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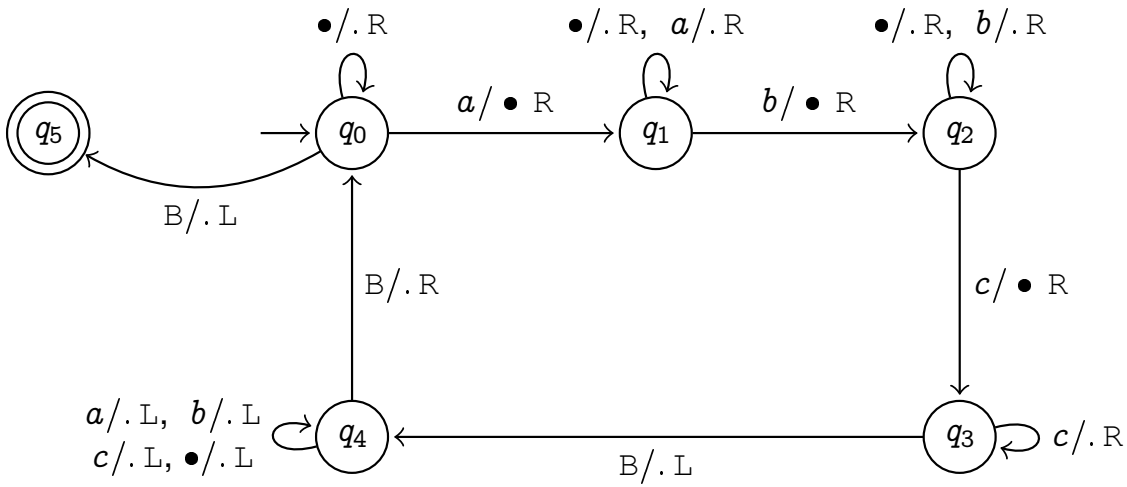

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$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

$\vdash$B • a • b • $[q_3\rangle$ c B

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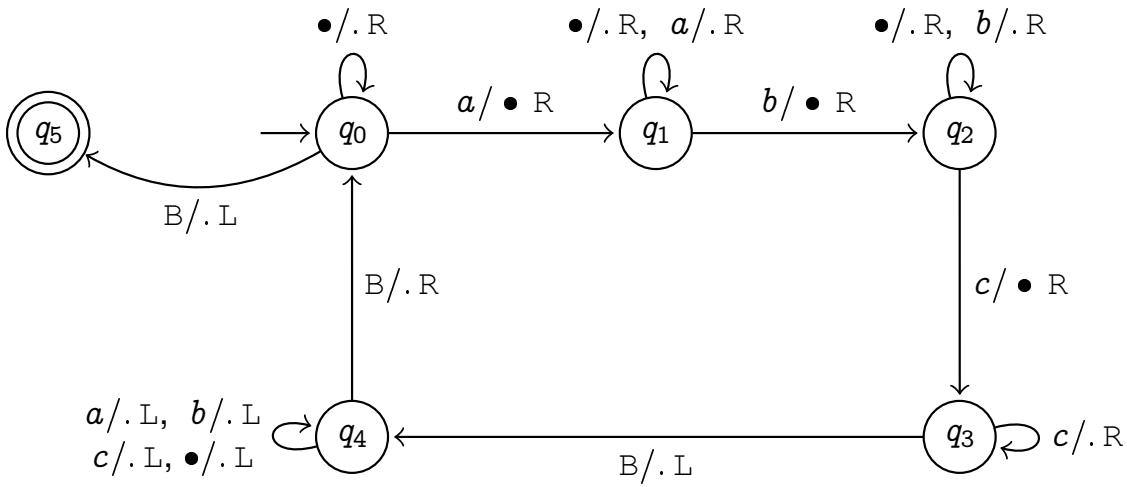

Computation for input $aabbcc$:

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$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

$\vdash$B • a • b • $[q_3\rangle$ c B

$\vdash$B • a • b • c $[q_3\rangle$ B

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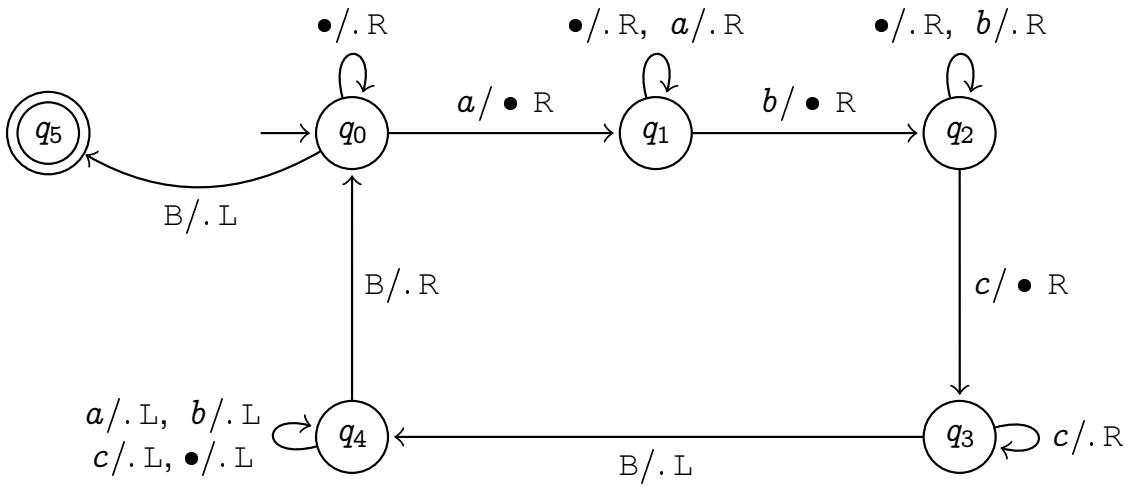

Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ [q_1\rangle\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ [q_2\rangle\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ [q_2\rangle\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_3\rangle\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ [q_3\rangle\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_4\rangle\ c\ \mathtt{B}$

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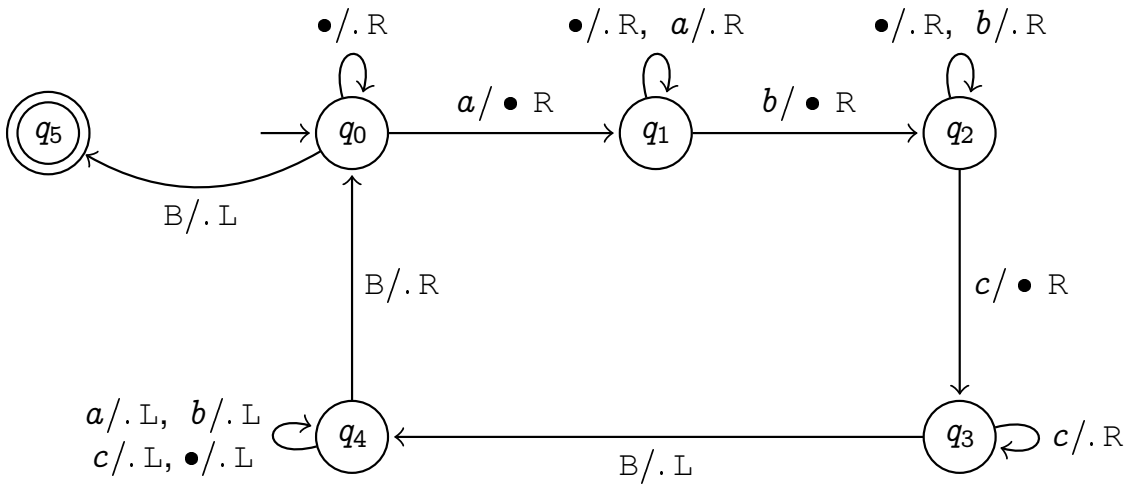


Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ [q_1\rangle\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ [q_2\rangle\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ [q_2\rangle\ c\ c\ \mathtt{B}$

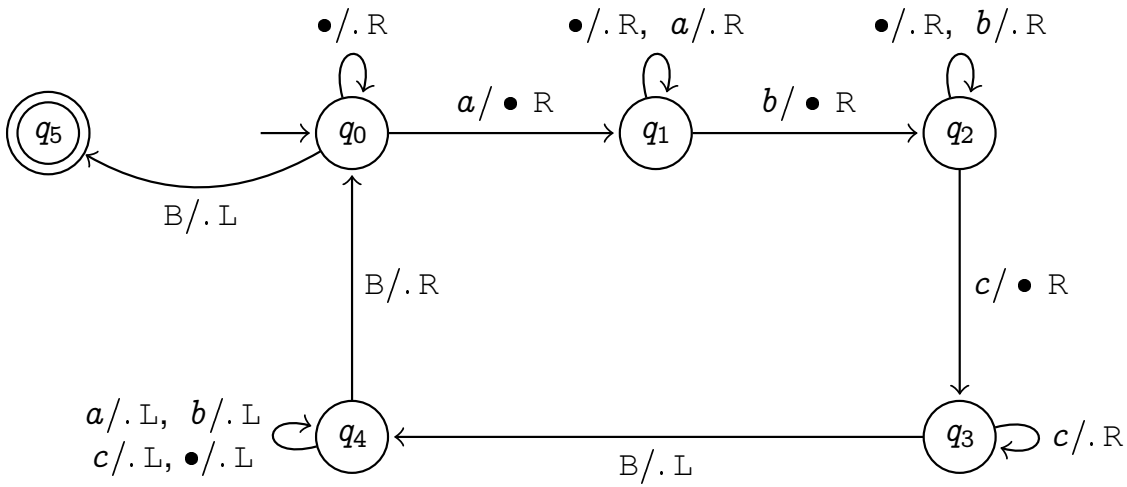
$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_3\rangle\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ [q_3\rangle\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_4\rangle\ c\ \mathtt{B}$

$\vdash^* [q_4\rangle\ \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ \mathtt{B}$

Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ [q_1\rangle\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ [q_2\rangle\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ [q_2\rangle\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_3\rangle\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ [q_3\rangle\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_4\rangle\ c\ \mathtt{B}$

$\vdash^* [q_4\rangle\ \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ \mathtt{B}$

$\vdash^* \mathtt{B}\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ [q_3\rangle\ \mathtt{B}$

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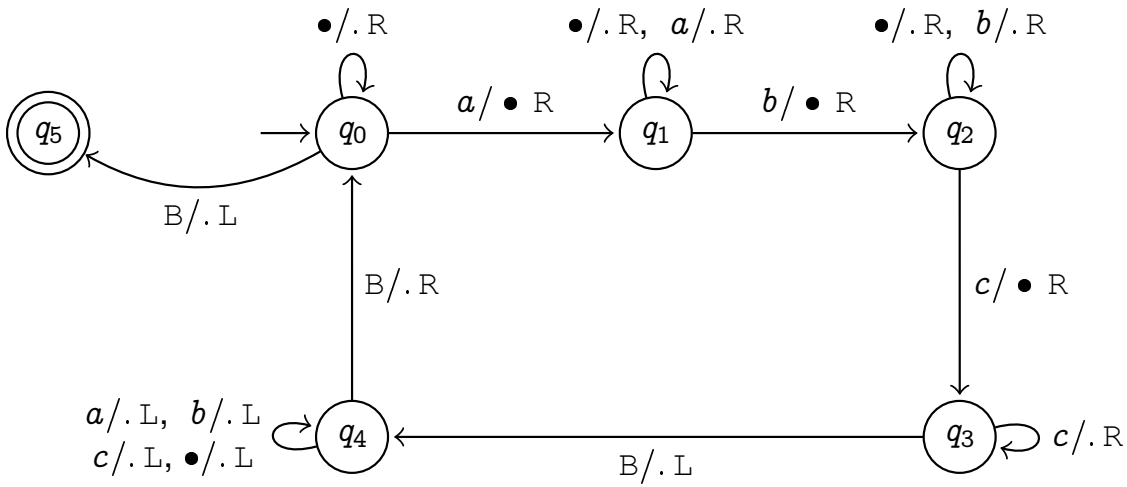

Computation for input $aabbcc$:

$\rightarrow \mathtt{B}\ [q_0\rangle\ a\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ [q_1\rangle\ a\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ [q_1\rangle\ b\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ [q_2\rangle\ b\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ [q_2\rangle\ c\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_3\rangle\ c\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ [q_3\rangle\ \mathtt{B}$

$\vdash \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ [q_4\rangle\ c\ \mathtt{B}$

$\vdash^* [q_4\rangle\ \mathtt{B}\ \bullet\ a\ \bullet\ b\ \bullet\ c\ \mathtt{B}$

$\vdash^* \mathtt{B}\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ [q_3\rangle\ \mathtt{B}$

$\vdash^* [q_4\rangle\ \mathtt{B}\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ \bullet\ \mathtt{B}$

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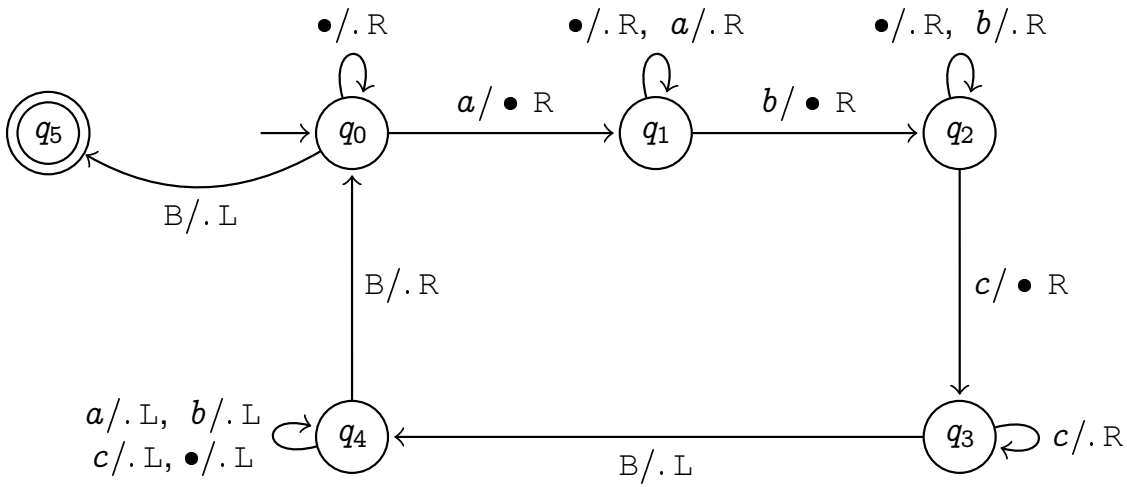


Computation for input $aabbcc$:

$\rightarrow$ B $[q_0\rangle$ a a b b c c B

$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

$\vdash$B • a • b • $[q_3\rangle$ c B

$\vdash$B • a • b • c $[q_3\rangle$ B

$\vdash$B • a • b • $[q_4\rangle$ c B

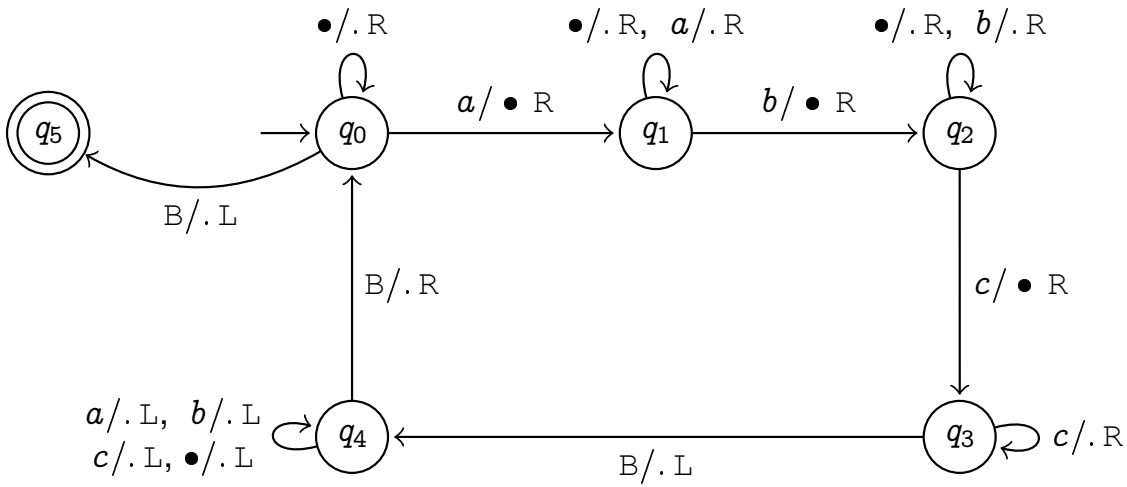
$\vdash^*$ $[q_4\rangle$ B • a • b • c B

$\vdash^*$ B • • • • • • $[q_3\rangle$ B

$\vdash^*$ $[q_4\rangle$ B • • • • • • B

$\vdash$ B$[q_0\rangle$ • • • • • • B

Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input $aabbcc$:

$\rightarrow$ B $[q_0\rangle$ a a b b c c B

$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

$\vdash$B • a • b • $[q_3\rangle$ c B

$\vdash$B • a • b • c $[q_3\rangle$ B

$\vdash$B • a • b • $[q_4\rangle$ c B

$\vdash^*$ $[q_4\rangle$ B • a • b • c B

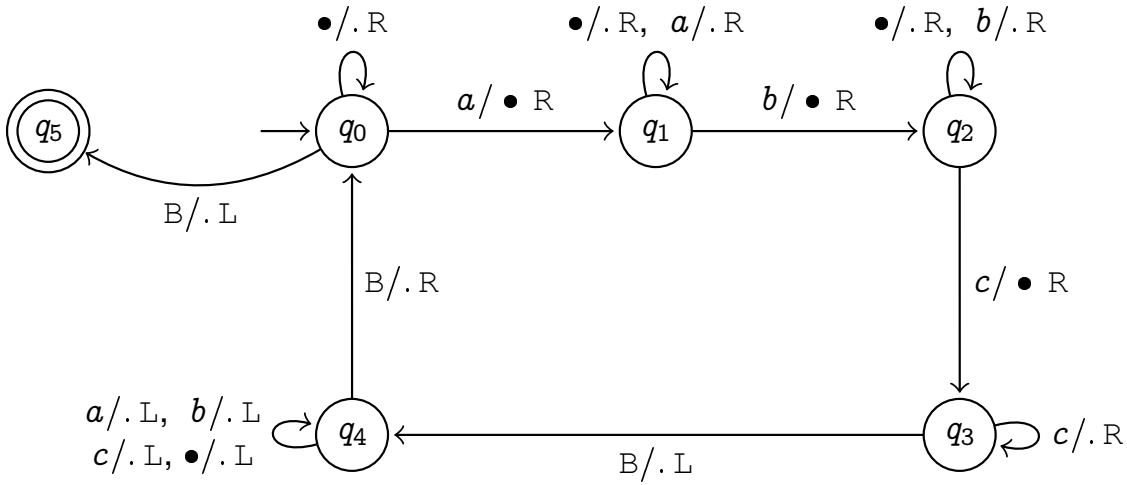
$\vdash^*$ B • • • • • • $[q_3\rangle$ B

$\vdash^*$ $[q_4\rangle$ B • • • • • • B

$\vdash$ B$[q_0\rangle$ • • • • • • B

$\vdash^*$ B • • • • • • $[q_0\rangle$ B

Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input $aabbcc$:

$\rightarrow$ B $[q_0\rangle$ a a b b c c B

$\vdash$B • $[q_1\rangle$ a b b c c B

$\vdash$B • a $[q_1\rangle$ b b c c B

$\vdash$B • a • $[q_2\rangle$ b c c B

$\vdash$B • a • b $[q_2\rangle$ c c B

$\vdash$B • a • b • $[q_3\rangle$ c B

$\vdash$B • a • b • c $[q_3\rangle$ B

$\vdash$B • a • b • $[q_4\rangle$ c B

$\vdash^*$ $[q_4\rangle$ B • a • b • c B

$\vdash^*$ B • • • • • • $[q_3\rangle$ B

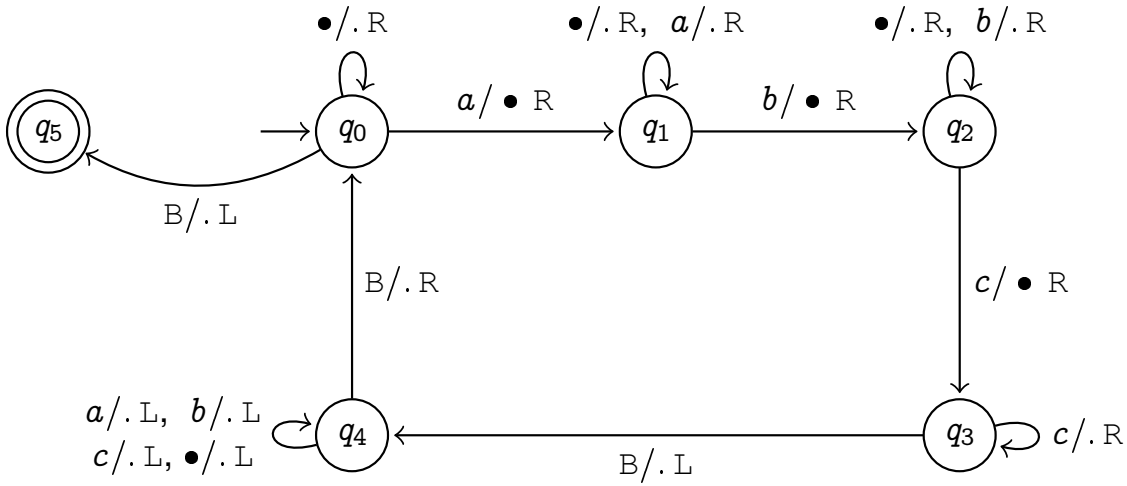
$\vdash^*$ $[q_4\rangle$ B • • • • • • B

$\vdash$ B$[q_0\rangle$ • • • • • • B

$\vdash^*$ B • • • • • • $[q_0\rangle$ B

$\vdash$B • • • • • $[q_5\rangle$ • B

Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Consider now the computation for $aabcc$: where does it get stuck?

Further Terminology

A TM is **always terminating** if it terminates for every input.

Let L be a language.

- L is **semi-decidable** (or **recursively enumerable, RE**) if there exists a TM M such that $L = L(M)$.
- L is **decidable** (or **recursive**) if there is an always terminating TM that accepts L by termination in an accepting state.
- If L is decidable, then it is also semi-decidable. The converse doesn't hold!

Taking Stock

This lecture (Sections 5.1 and 5.2):

- Turing machines
- Key terminology for TM-accepted languages

Next Lecture (Sections 5.3–5.8)

- Further examples of TMs
- Variants of TMs: multiple-track, multiple-tape, non-deterministic