

Languages and Machines

L8: Turing machines

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Languages and Their Machines



Regular

→ Finite State Machines (FSMs)

Context-free
→ Pushdown Machines

Context-sensitive
→ Linearly-bounded Machines

Decidable → **Always-terminating Turing Machines**

 $\textbf{Semi-decidable} \quad \leftrightarrow \quad \textbf{Turing Machines}$



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- Finite state machines (FSMs), in different flavors, fully characterize regular languages.
- There are, however, languages that are not regular. Example:

$$L_1 = \{ a^n b^n | n > 0 \}$$

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- There are, however, languages that are not context-free.
 Example:

$$L_2 = \{ a^n \ b^n \ c^n \ | \ n \geq 0 \}$$

• What kind of machines do we need to recognize L_2 ?





- A Turing machine (TM) may access and modify any memory position, using a sequence of elementary operations
- No limitation on the space/time available for a computation
- A finite state machine equipped with a tape, divided into squares, which can be written on as a result of a transition
- The head of the machine can move to the right or to the left, allowing the TM to read and manipulate the input as desired



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In other words, a transition:

- changes the state
- writes a symbol on the square scanned by the head
- moves the head



A (simple) **Turing machine** M is a quintuple $(Q, \Sigma, \Gamma, \delta, q_0)$ where

- Q is a set of states
- $q_0 \in Q$ is the start state
- Γ is the tape alphabet, a set of symbols disjoint from Q.
 Contains a blank symbol B, not in Σ
- $\Sigma \subseteq \Gamma \setminus \{\mathtt{B}\}$ is the input alphabet
- The transition function δ is a partial function such that

$$\delta: Q imes \Gamma o Q imes \Gamma imes \{L,R\}$$

If $\delta(q, X)$ is undefined then $\delta(q, X) = \bot$.



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$$\delta: Q \times \Gamma \to Q \times \Gamma \times \{L, R\}$$

If $\delta(q, X)$ is undefined then $\delta(q, X) = \bot$.

A set of accepting states $F \subseteq Q$ is possible but not indispensable for defining acceptance (see later).



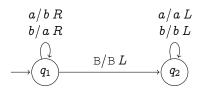
A TM that reads the input string and interchanges symbols a and b:

In state q_1 , label 'a/b R' indicates:

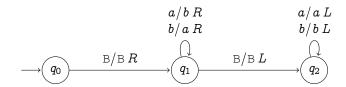
- symbol a is rewritten into b, and
- the head moves right (R).



A TM that reads the input string and interchanges symbols a and b:



A slightly more general machine:





The global state of the TM is determined by the state $q \in Q$, the contents of the tape (a string in Γ^*) and the position of the head

- A **configuration** of the TM is a string uqv in $\Gamma^*Q\Gamma^*$, in which:
 - u is a string on the tape to the left of the head
 - q is the **current** state
 - v is a string on the tape that begins under the head
- The initial configuration is q_0w , where $w\in \Sigma^*$ is the input string
- The first symbol of vB^{∞} is called the **current** symbol



Suppose X, Y, Z are tape symbols (in Γ). Moving to the next configuration:

$$\delta(q,X) = (r,Y,R) \Rightarrow u Z q X v \vdash u Z Y r v \ \delta(q,X) = (r,Y,L) \Rightarrow u Z q X v \vdash u r Z Y v \ \delta(q,X) = \bot \Rightarrow u q X v \vdash \bot$$



Suppose X, Y, Z are tape symbols (in Γ). Moving to the next configuration:

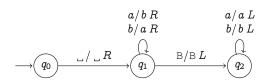
$$egin{array}{lll} \delta(q,X) = (r,\,Y,R) & \Rightarrow & u\,Z\,q\,X\,v dash u\,Z\,Y\,r\,v \ \delta(q,X) = (r,\,Y,L) & \Rightarrow & u\,Z\,q\,X\,v dash u\,r\,Z\,Y\,v \ \delta(q,X) = ota & \Rightarrow & u\,q\,X\,v dash ota \end{array}$$

- A computation is a sequence of steps, as defined by ⊢
- A TM computes a function f
 - if starting in q_0w , the final tape upon termination is always $\mathbb{B}^{\infty}u\mathbb{B}^{\infty}$, with u=f(w).

Example 1, Revisited



Suppose there is a special symbol '_' preceding the input string. We can adapt the previous machine as follows:



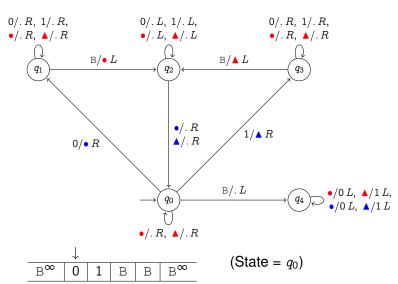
Computation for input abab:

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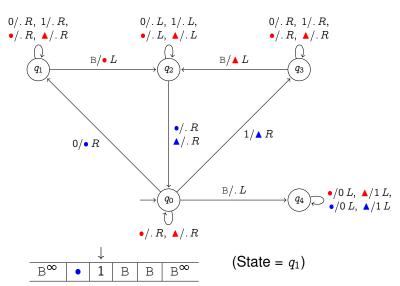


- ightharpoonup Before: A tape with the string w
- ightharpoonup After: The tape contains the string w w
- What is your (programming) strategy?

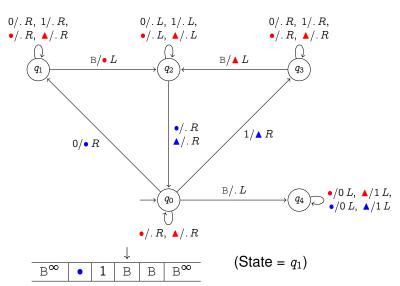




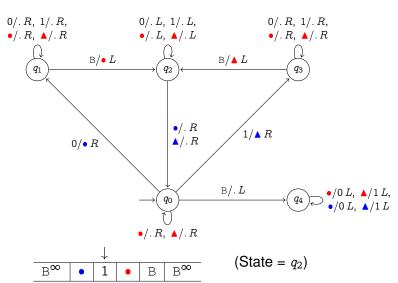




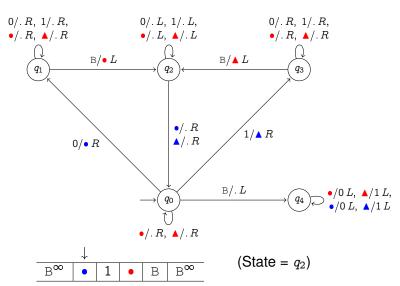




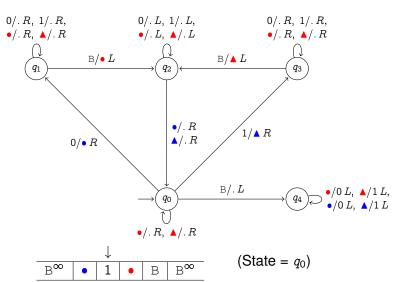




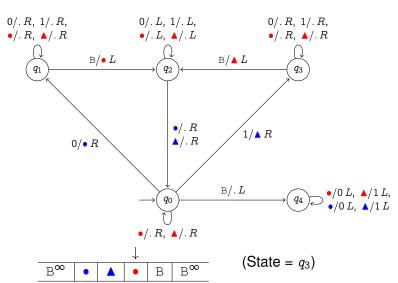




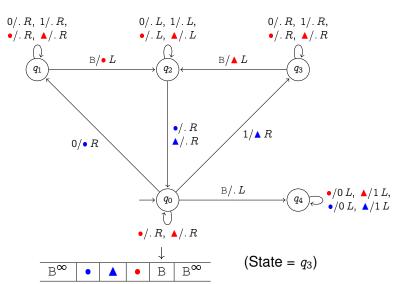




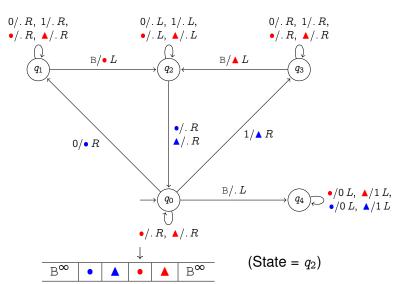




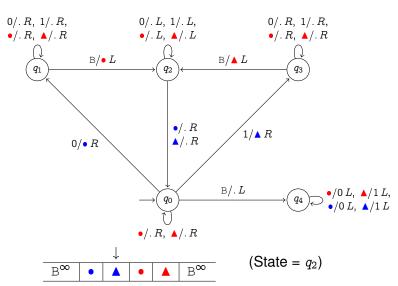




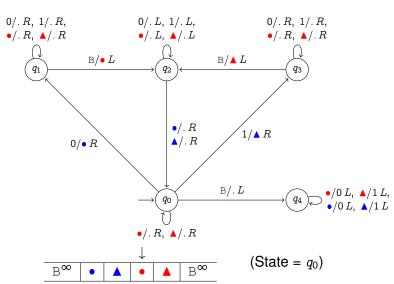




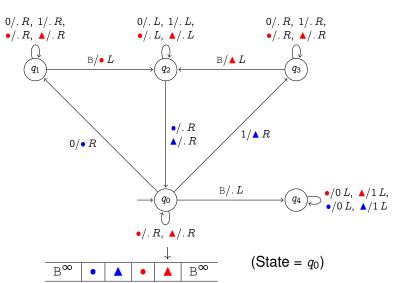




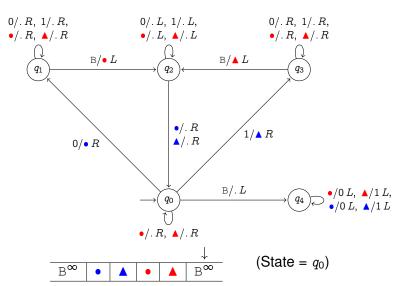




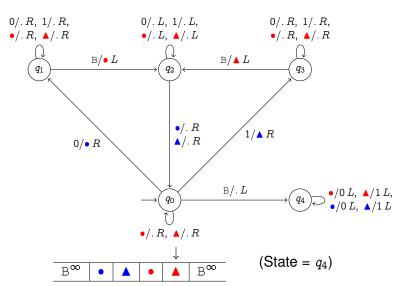




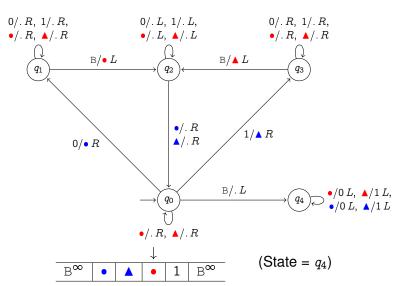




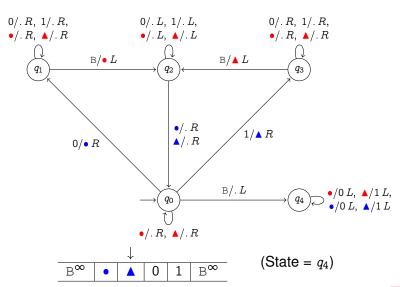




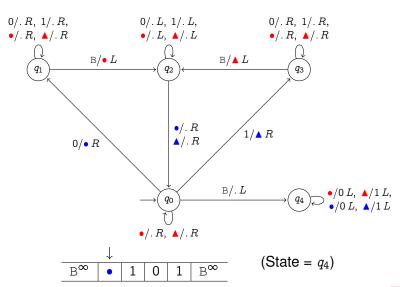








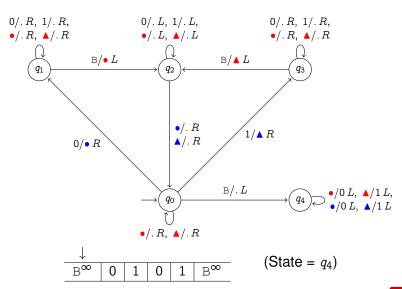




Example 2



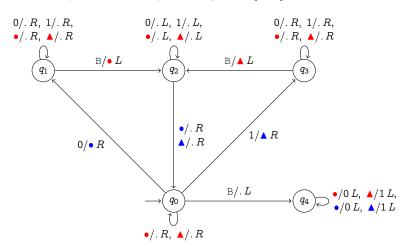
A TM that duplicates the input string $w \in \{0, 1\}^*$.



Example 2



A TM that duplicates the input string $w \in \{0, 1\}^*$.



What does each state/transition represent?

Acceptance



The set L(M) can be defined in two different ways.

1. A TM M accepts by termination the language of the input strings w for which it terminates:

$$L(M) = \{w \in \Sigma^* \mid q_0w \vdash^* \bot\}$$

No need for accepting states.

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2. L(M) can also be defined by **termination in an accepting state**, extending M with a set $F \subseteq Q$:

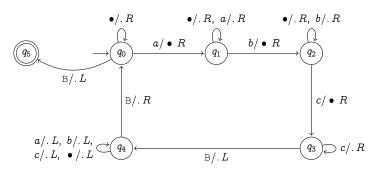
$$L(M) = \{w \in \Sigma^* \mid \exists \mathit{q_f} \in \mathit{F}, \; u, v \in \Gamma^* : \mathit{q_0}w \vdash^* u \; \mathit{q_f} \; v \vdash \bot \}$$

This definition can be reduced to the first one by letting F=Q. In fact, both definitions are equivalent.

Example 5.1.2: $\{a^nb^nc^n\mid n\in\mathbb{N}\}$

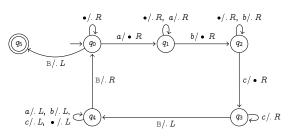


A TM with accepting state(s):



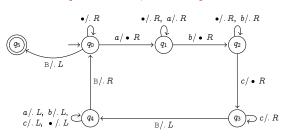
How does it work?





$$ightarrow$$
 B $[q_0
angle$ a a b b c c B

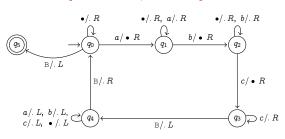




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$$\vdash$$
B • $[q_1\rangle$ a b b c c B





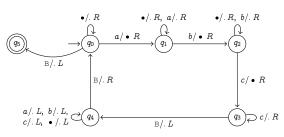
Computation for input aabbcc:

ightarrow B $[q_0
angle$ a a b b c c B

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 \vdash B • a $[q_1\rangle$ b b c c B

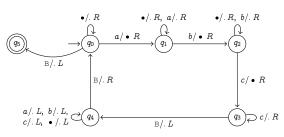




- ightarrow B $|q_0
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 - \vdash B $[q_1\rangle$ a b b c c B
 - \vdash B a $[q_1\rangle$ b b c c B
 - \vdash B a $|q_2\rangle$ b c c B
 - \vdash B a b $|q_2\rangle$ c c B

Example 5.1.2: $\{a^nb^nc^n\mid n\in\mathbb{N}\}$

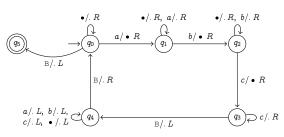




- ightarrow B $|q_0
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 - \vdash B a $[q_1\rangle$ b b c c B
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 - \vdash B a b $|q_2\rangle$ c c B
 - \vdash B a b $[q_3\rangle c$ B

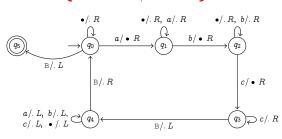
Example 5.1.2: $\{a^nb^nc^n\mid n\in\mathbb{N}\}$





- ightarrow B $|q_0
 angle$ a a b b c c B
 - \vdash B $[q_1\rangle$ a b b c c B
 - \vdash B a $[q_1
 angle$ b b c c B
 - \vdash B a $|q_2\rangle$ b c c B
 - \vdash B a b $\ket{q_2}$ c c B
 - \vdash B a b $|q_3\rangle$ c B
 - \vdash B a b c $[q_3\rangle$ B





 \vdash B • a • b • $|q_4\rangle c$ B

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B • $[q_1\rangle a b b c c B$

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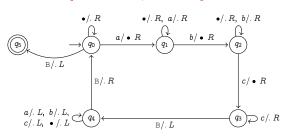
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B • a • b • $|q_3\rangle$ c B

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B • a • b • $c \mid q_3 \rangle$ B





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 B $|q_0\rangle$ a a b b c c B

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B • $[q_1\rangle$ a b b c c B

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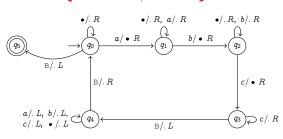
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$$\vdash$$
B • a • b • $|q_4\rangle$ c B

$$\vdash^* [q_4\rangle \ \mathtt{B} \ ullet \ a \ ullet \ b \ ullet \ c \ \mathtt{B}$$





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$$\vdash$$
B • a $[q_1\rangle$ b b c c B

$$\vdash$$
B • a • $[q_2\rangle$ b c c B

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B • a • b $|q_2\rangle$ c c B

$$\vdash$$
B • a • b • $[q_3\rangle$ c B

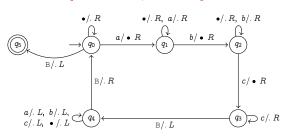
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$$\vdash^* [q_4\rangle \ \mathsf{B} \bullet a \bullet b \bullet c \ \mathsf{B}$$

$$\vdash^*$$
 B • • • • • $[q_3\rangle$ B





$$\rightarrow$$
 B $|q_0\rangle$ a a b b c c B

$$\vdash$$
B • $[q_1\rangle$ a b b c c B

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B • a $[q_1\rangle$ b b c c B

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B • a • b • c $[q_3\rangle$ B

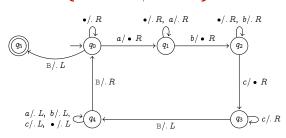
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$$\vdash^*$$
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$$\vdash^* [q_4\rangle \text{ B} \bullet \bullet \bullet \bullet \bullet \text{ B}$$





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$$\vdash$$
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$$\vdash$$
B • a • $|q_2\rangle$ b c c B

$$\vdash$$
B • a • $b \mid q_2 \rangle c c B$

$$\vdash$$
B • a • b • $|q_3\rangle$ c B

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B • a • b • $c \mid q_3 \rangle$ B

$$\vdash_{\mathsf{B}} \bullet a \bullet b \bullet [q_4\rangle c \mathsf{B}$$

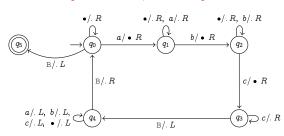
$$\vdash^* [q_4\rangle \mathsf{B} \bullet a \bullet b \bullet c \mathsf{B}$$

$$\vdash^* \mathsf{B} \bullet \bullet \bullet \bullet \bullet [q_3\rangle \mathsf{B}$$

$$\vdash^* [q_4\rangle \mathsf{B} \bullet \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$

$$\vdash \mathsf{B}[q_0\rangle \bullet \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$





Computation for input aabbcc:

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$$\vdash$$
B • a • b • c $[q_3\rangle$ B

$$\vdash \mathsf{B} \bullet a \bullet b \bullet [q_4\rangle c \mathsf{B}$$

$$\vdash^* [q_4\rangle \mathsf{B} \bullet a \bullet b \bullet c \mathsf{B}$$

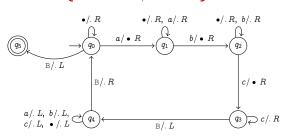
$$\vdash^* \mathsf{B} \bullet \bullet \bullet \bullet \bullet [q_3\rangle \mathsf{B}$$

$$\vdash^* [q_4\rangle \mathsf{B} \bullet \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$

$$\vdash \mathsf{B}[q_0\rangle \bullet \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$

 \vdash^* B • • • • • $\lceil q_0 \rangle$ B





Computation for input aabbcc:

 \vdash B • a • b • $c \mid q_3 \rangle$ B

$$\vdash_{\mathsf{B}} \bullet a \bullet b \bullet [q_4\rangle c \mathsf{B}$$

$$\vdash^* [q_4\rangle \mathsf{B} \bullet a \bullet b \bullet c \mathsf{B}$$

$$\vdash^* \mathsf{B} \bullet \bullet \bullet \bullet \bullet [q_3\rangle \mathsf{B}$$

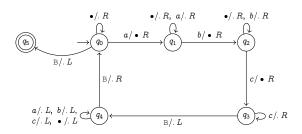
$$\vdash^* [q_4\rangle \mathsf{B} \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$

$$\vdash \mathsf{B}[q_0\rangle \bullet \bullet \bullet \bullet \bullet \mathsf{B}$$

$$\vdash^* \mathsf{B} \bullet \bullet \bullet \bullet [q_5\rangle \bullet \mathsf{B}$$

Example 5.1.2: $\{a^nb^nc^n\,|\,n\in\mathbb{N}\}$





Consider now the computation for aabcc: where does it get stuck?

Further Terminology



A TM is always terminating if it terminates for every input.

Let L be a language.

- L is semi-decidable (or recursively enumerable, RE)
 if there exists a TM M such that L = L(M).
- L is decidable (or recursive)
 if there is an always terminating TM that accepts L by termination in an accepting state.
- If L is decidable, then it is also semi-decidable.
 The converse doesn't hold!

Taking Stock



This lecture (Sections 5.1 and 5.2):

- ▶ Turing machines
- Key terminology for TM-accepted languages

Next Lecture (Sections 5.3–5.8)

- Further examples of TMs
- Variants of TMs: multiple-track, multiple-tape, non-deterministic