

Languages and Machines

L8: Turing machines

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Languages and Their Machines



Regular

→ Finite State Machines (FSMs)

Context-free
→ Pushdown Machines

Context-sensitive
→ Linearly-bounded Machines

Decidable → **Always-terminating Turing Machines**

 $\textbf{Semi-decidable} \quad \leftrightarrow \quad \textbf{Turing Machines}$



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 Example:

$$L_2 = \{ a^n \ b^n \ c^n \ | \ n \geq 0 \}$$

• What kind of machines do we need to recognize L_2 ?





- A Turing machine (TM) may access and modify any memory position, using a sequence of elementary operations
- No limitation on the space/time available for a computation
- A finite state machine equipped with a tape, divided into squares, which can be written on as a result of a transition
- The head of the machine can move to the right or to the left, allowing the TM to read and manipulate the input as desired



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In other words, a transition:

- changes the state
- writes a symbol on the square scanned by the head
- moves the head



A (simple) **Turing machine** M is a quintuple $(Q, \Sigma, \Gamma, \delta, q_0)$ where

- Q is a set of states
- $q_0 \in Q$ is the start state
- Γ is the tape alphabet, a set of symbols disjoint from Q.
 Contains a blank symbol B, not in Σ
- $\Sigma \subseteq \Gamma \setminus \{\mathtt{B}\}$ is the input alphabet
- The transition function δ is a partial function such that

$$\delta: Q imes \Gamma o Q imes \Gamma imes \{$$
L,R $\}$

If $\delta(q, X)$ is undefined then $\delta(q, X) = \bot$.



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A set of accepting states $F \subseteq Q$ is possible but not indispensable for defining acceptance (see later).



A TM that reads the input string and interchanges symbols $\it a$ and $\it b$:

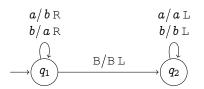
$$a/b R$$
 $a/a L$ $b/b L$ $B/B L$ q_2

In state q_1 , label 'a/b R' indicates:

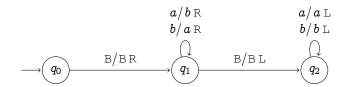
- symbol \boldsymbol{a} is rewritten into \boldsymbol{b} , and
- the head moves right (R).



A TM that reads the input string and interchanges symbols a and b:



A slightly more general machine:





The global state of the TM is determined by the state $q \in Q$, the contents of the tape (a string in Γ^*) and the position of the head

- A **configuration** of the TM is a string uqv in $\Gamma^*Q\Gamma^*$, in which:
 - u is a string on the tape to the left of the head
 - q is the **current** state
 - v is a string on the tape that begins under the head
- The initial configuration is q_0w , where $w\in \Sigma^*$ is the input string
- The first symbol of vB^{∞} is called the **current** symbol



Suppose X, Y, Z are tape symbols (in Γ). Moving to the next configuration:

$$egin{array}{lll} \delta(q,X) = (r,\,Y,\, ext{R}) & \Rightarrow & u\,Z\,q\,X\,v dash u\,Z\,Y\,r\,v \ \delta(q,X) = (r,\,Y,\, ext{L}) & \Rightarrow & u\,Z\,q\,X\,v dash u\,r\,Z\,Y\,v \ \delta(q,X) = ota & \Rightarrow & u\,q\,X\,v dash ota \end{array}$$



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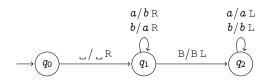
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- A computation is a sequence of steps, as defined by ⊢
- A TM computes a function f
 - if starting in q_0w , the final tape upon termination is always $\mathbb{B}^{\infty}u\mathbb{B}^{\infty}$, with u=f(w).

Example 1, Revisited



Consider a variation of the previous machine with $\Sigma = \{a, b, _\}$, where ' $_$ ' is always at the beginning of all input strings. We have:



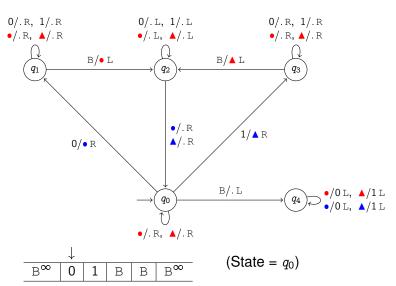
Computation for input abab:

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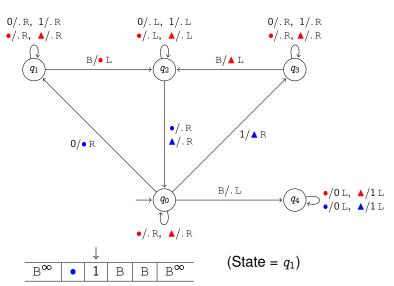


- ightharpoonup Before: A tape with the string w
- ightharpoonup After: The tape contains the string w w
- What is your (programming) strategy?

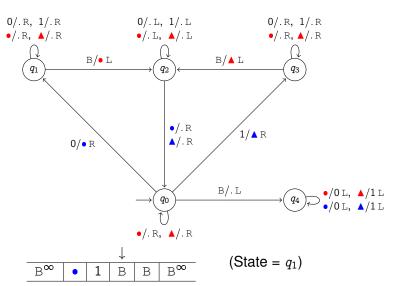




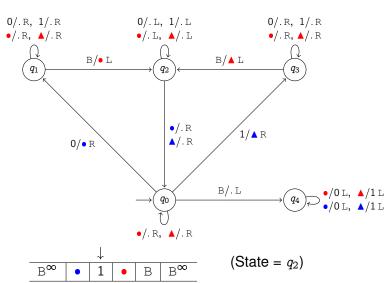




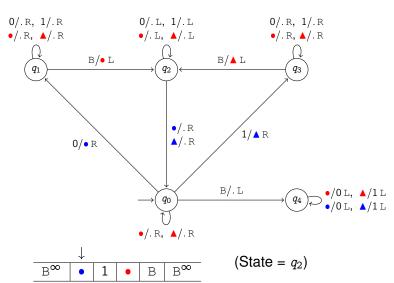




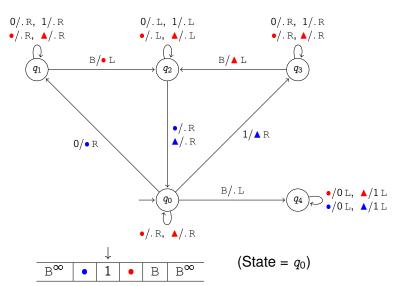




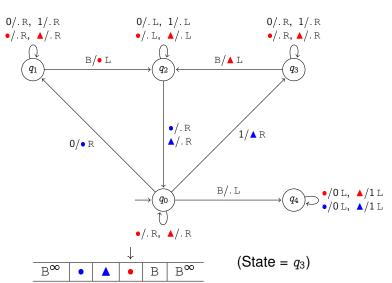




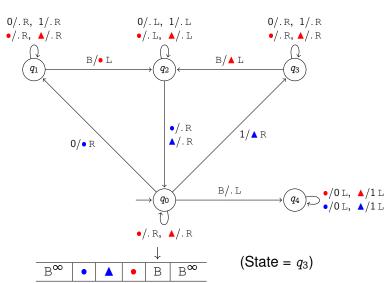




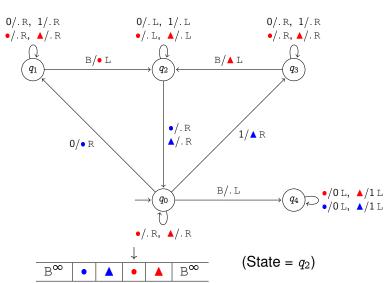




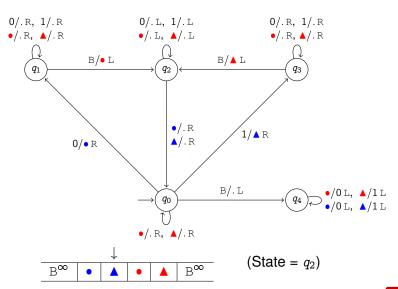




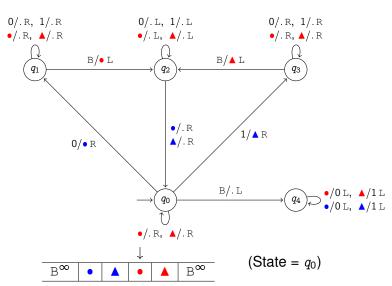




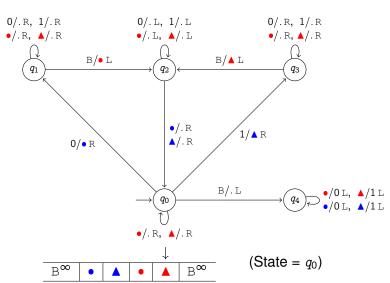




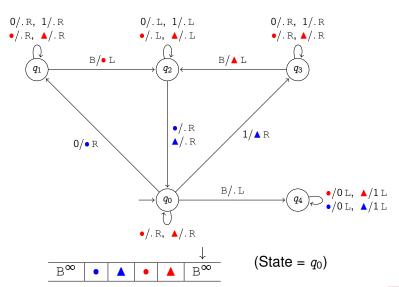




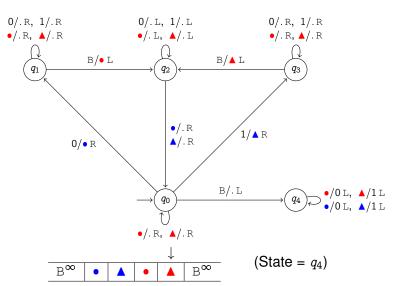




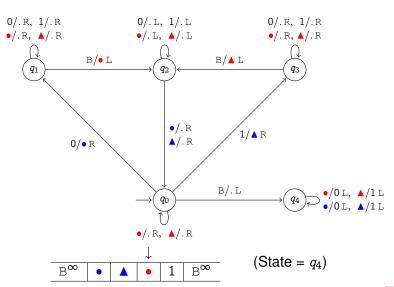




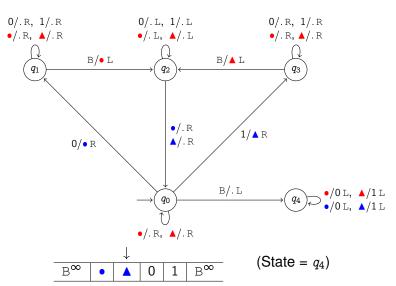




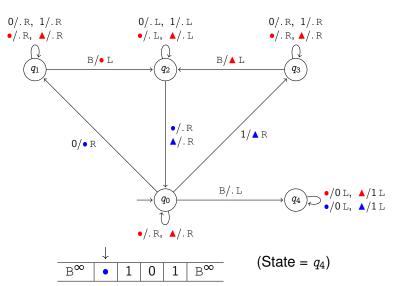








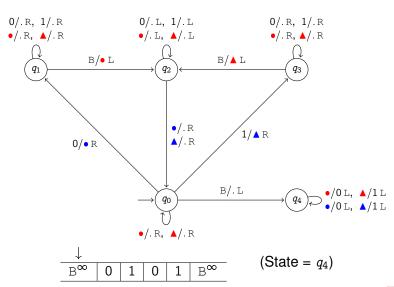




Example 2



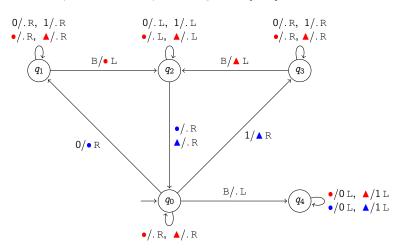
A TM that duplicates the input string $w \in \{0, 1\}^*$.



Example 2



A TM that duplicates the input string $w \in \{0, 1\}^*$.



What does each state/transition represent?

Acceptance



The set L(M) can be defined in two different ways.

1. A TM M accepts by termination the language of the input strings w for which it terminates:

$$L(M) = \{w \in \Sigma^* \mid q_0w \vdash^* \bot\}$$

No need for accepting states.

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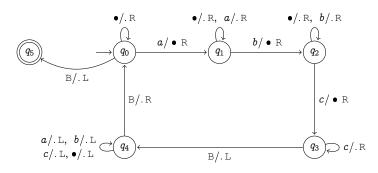
2. L(M) can also be defined by **termination in an accepting state**, extending M with a set $F \subseteq Q$:

$$L(M) = \{w \in \Sigma^* \mid \exists \mathit{q_f} \in \mathit{F}, \; u, v \in \Gamma^* : \mathit{q_0}w \vdash^* u \; \mathit{q_f} \; v \vdash \bot \}$$

This definition can be reduced to the first one by letting F=Q. In fact, both definitions are equivalent.

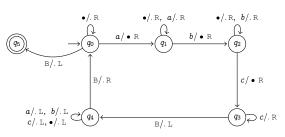


A TM with accepting state(s):



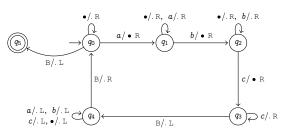
How does it work?





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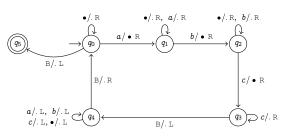




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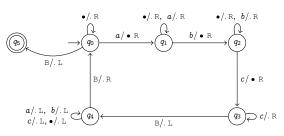
Computation for input aabbcc:

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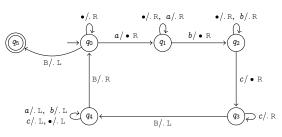
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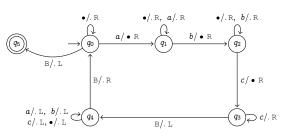
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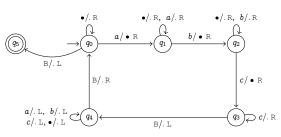
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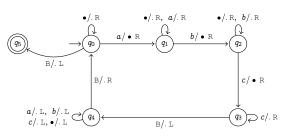
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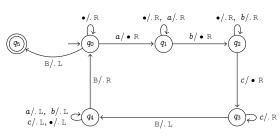
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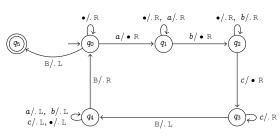
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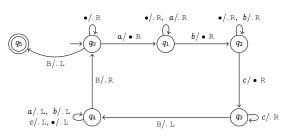
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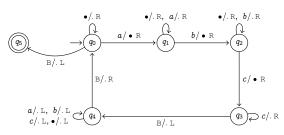
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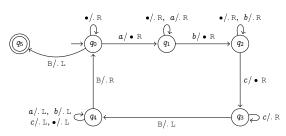
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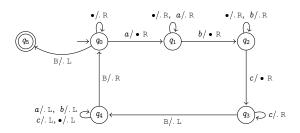
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Example 5.1.2: $\{a^nb^nc^n\,|\,n\in\mathbb{N}\}$





Consider now the computation for aabcc: where does it get stuck?

Further Terminology



A TM is always terminating if it terminates for every input.

Let L be a language.

- L is semi-decidable (or recursively enumerable, RE)
 if there exists a TM M such that L = L(M).
- L is decidable (or recursive)
 if there is an always terminating TM that accepts L by termination in an accepting state.
- If L is decidable, then it is also semi-decidable.
 The converse doesn't hold!

Taking Stock



This lecture (Sections 5.1 and 5.2):

- ▶ Turing machines
- Key terminology for TM-accepted languages

Next Lecture (Sections 5.3–5.8)

- Further examples of TMs
- Variants of TMs: multiple-track, multiple-tape, non-deterministic