

Models and Semantics of Computation

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The π -calculus: A Calculus of Mobile Processes (I)

- ▶ informal introduction; contrast with CCS
- ▶ syntax and basic examples
- ▶ expressiveness (polyadic communication, recursion vs replication)

The π -calculus: A Calculus of Mobile Processes

Arguably, the paradigmatic calculus for concurrency

- ▶ Proposed by Milner, Parrow, and Walker in 1992.
Developed significantly by Sangiorgi.

Interactive systems with **dynamic connectivity** (topology).

A dual role:

- ▶ A model of **networked computation**:
Exchanged messages which contain links referring to communication channels themselves
- ▶ A basic **model of computation**:
Interaction as the primitive notion of concurrent computing
(Just as the λ -calculus for functional computing)

The π -calculus, in these lectures

- ▶ The theory of the π -calculus is richer than that of CCS.
In some aspects, however, it is also more involved.
- ▶ We will overview this theory, contrasting it with CCS
- ▶ Hence, we present the π -calculus without going too much into technical details

Mobility as dynamic connectivity (1)

Towards the meaning of ‘mobility’:

- ▶ What kind of entity moves? In what space does it move?

Many possibilities—the two most relevant in this course are:

1. Processes move, in the virtual space of linked processes
2. Links move, in the virtual space of linked processes

Observe that

- ▶ A process’ location is given by the links it has to other processes (think of your contacts in your mobile phone)
- ▶ Hence, the movement of a process can be represented by the movement of its links

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Mobility as dynamic connectivity (2)

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The π -calculus commits to mobility in the sense of (2)...

- ▶ Economy, flexibility, and simplicity (at least wrt CCS)

...while models of higher-order concurrency stick to (1):

- ▶ Inspired in the λ -calculus
- ▶ It might be difficult/inconvenient to “normalize” all concurrency phenomena in the sense of (2)

We will argue that (1) and (2) need not be mutually exclusive

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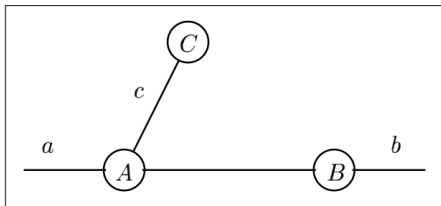
Dynamic connectivity in CCS is limited (1)

What's the main difference of the π -calculus wrt CCS?

The answer is **dynamic connectivity**.

Suppose a CCS process $S \stackrel{\text{def}}{=} (\nu x)(A \parallel C) \parallel B$.

Name a is free in A , while b is free in B . Graphically:



(1)

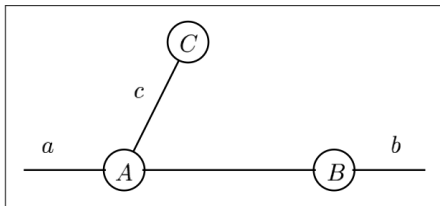
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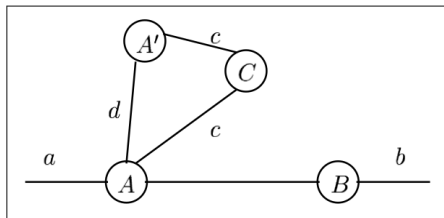
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Dynamic connectivity in CCS is limited (2)

Suppose a CCS process $S \stackrel{\text{def}}{=} (\nu x)(A \parallel C) \parallel B$.

Name a is free in A , while b is free in B .

Suppose now that $A \stackrel{\text{def}}{=} a.(\nu d)(A \parallel A') + c.A''$. Graphically:



(2)

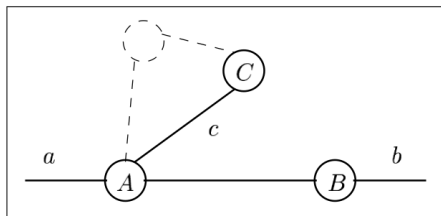
Dynamic connectivity in CCS is limited (3)

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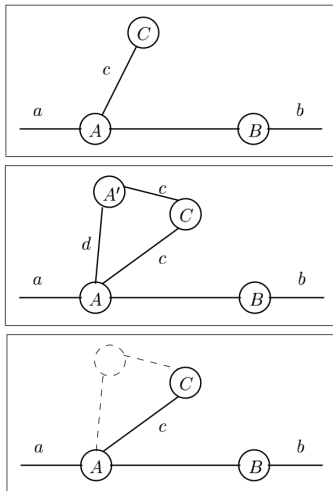
Finally, suppose that $A' = c.\mathbf{0}$. Process A' then dies. Graphically:



(3)

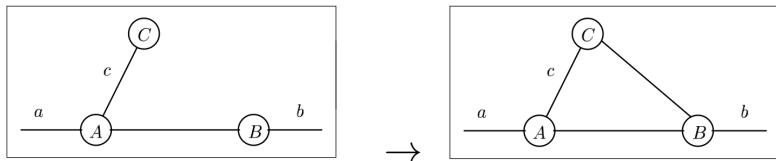
Dynamic connectivity in CCS is limited (4)

In CCS, links can proliferate and die:



Dynamic connectivity in CCS is limited (5)

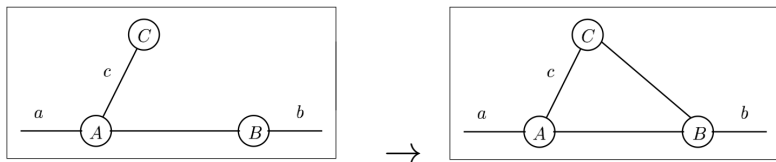
However, new links between existing processes cannot be created.
The following transition is not possible in CCS:



Dynamic connectivity refers to this kind of transitions.
The π -calculus goes beyond CCS by allowing dynamic communication topologies.

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The π -calculus, more formally

We now formally introduce the π -calculus. Some highlights:

- ▶ The major novelty is **communication of names**
- ▶ Dynamic connectivity formalized as **scope extrusion**
- ▶ Two different semantics:
 - ▶ A reduction semantics, using a relation of **structural congruence**
 - ▶ A semantics based on labeled transitions (LTS)

Roughly: a step in the reduction semantics, noted $P \mapsto P'$, corresponds to a transition $P \xrightarrow{\tau} P'$ in the LTS (and vice versa).

The π -calculus, more formally

We use x, y, z, \dots to range over \mathcal{N} , an infinite set of names.

The **action prefixes** of the π -calculus generalize the actions of CCS:

$$\begin{array}{ll} \alpha & ::= \bar{x}\langle y \rangle \quad \text{send name } y \text{ along } x \\ & \quad x(y) \quad \text{receive a name along } x \\ & \quad \tau \quad \text{unobservable action} \end{array}$$

Brackets in $\bar{x}\langle y \rangle$ represent a tuple of values.

- ▶ Above, **monadic** communication: exactly one name is sent.
- ▶ In **polyadic** communication more than one value (a list of values) may be sent.

Process expressions of the π -calculus

$P, Q ::=$	$\mathbf{0}$	Inactive process
	$\alpha.P$	Prefix
	$P + P$	Sum
	$P \parallel Q$	Parallel composition
	$(\nu y)P$	Name creation/restriction
	$A\langle y_1, \dots, y_n \rangle$	Identifier

We assume each identifier A is equipped with a recursive definition $A(x_1, \dots, x_n) \stackrel{\text{def}}{=} P$, where $i \neq j$ implies $x_i \neq x_j$.

Free and bound names

- ▶ Restriction and input actions are name binders:
In $(\nu y)P$ and $x(y).P$ name y is **bound** with **scope** P .
- ▶ In contrast, in $\bar{x}\langle y \rangle$ name y is free.

Structural Congruence: Intuitions

- ▶ The syntax of processes is too concrete: there are syntactically different terms that represent the “same behavior”. Examples:

$$a(x).\bar{b}\langle x \rangle \quad \text{and} \quad a(y).\bar{b}\langle y \rangle$$
$$P \parallel Q \quad \text{and} \quad Q \parallel P$$

[We often omit trailing **0**s, and write $\bar{b}\langle y \rangle$ instead of $\bar{b}\langle y \rangle.0$.]

- ▶ Structural congruence identifies processes which are “obviously the same” based on **their syntactical structure**
- ▶ In this sense, structural congruence will be **stronger** than any behavioral equivalence — that is, will equate less processes.

Structural Congruence

P and Q structurally congruent, written $P \equiv Q$, if we can transform one into the other by using the following equations:

1. α -conversion: change of bound names
2. Laws for parallel composition:

$$P \parallel \mathbf{0} \equiv P$$

$$P \parallel Q \equiv Q \parallel P$$

$$P \parallel (Q \parallel R) \equiv (P \parallel Q) \parallel R$$

3. Law for recursive definitions: $A\langle\tilde{y}\rangle \equiv P\{\tilde{y}/\tilde{x}\}$ if $A(\tilde{x}) \stackrel{\text{def}}{=} P$
4. Laws for restriction:

$$(\nu x)(P \parallel Q) \equiv P \parallel (\nu x)Q \quad \text{if } x \notin \text{fn}(P)$$

$$(\nu x)\mathbf{0} \equiv \mathbf{0}$$

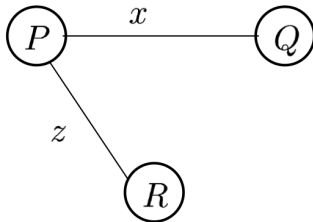
$$(\nu x)(P + Q) \equiv P + (\nu x)Q$$

$$(\nu x)(\nu y)P \equiv (\nu y)(\nu x)P$$

Scope Extrusion (1)

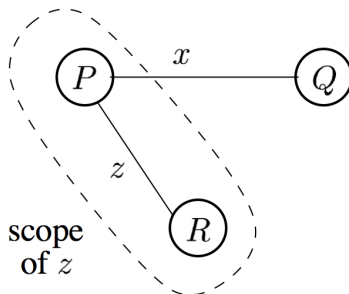
A process $P \parallel Q \parallel R$.

Name x is free in P and Q , while z is free in P and R :



Scope Extrusion (2)

Suppose that z is restricted to P and R , while x is free in P and Q . That is, we have the process $(\nu z)(P \parallel R) \parallel Q$:

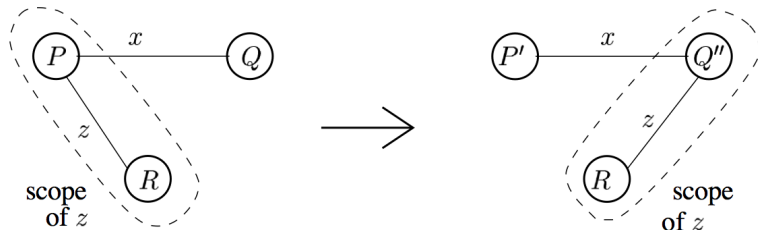


What happens if P wishes to send z to Q ?

Scope Extrusion (3)

Suppose $P = \bar{x}\langle z \rangle.P'$, with $z \notin \text{fn}(P')$.

Suppose also $Q = x(y).Q'$, with $z \notin \text{fn}(Q')$.



where $Q'' = Q'\{z/y\}$. We have graphically described the reduction

$$(\nu z)(P \parallel R) \parallel Q \mapsto P' \parallel (\nu z)(R \parallel Q'')$$

The above describes a movement of a way of **accessing** R (rather than a movement of R).

Initial Examples

We present some simple examples of scope extrusion.

For the moment, we use an informal account of reduction (\longmapsto), based on three postulates:

1. A law for inferring interactions:

$$a(x).P \parallel \bar{a}\langle b \rangle.Q \longmapsto P\{b/x\} \parallel Q$$

2. Restrictions respect silent transitions:

$$P \longmapsto Q \text{ implies } (\nu x)P \longmapsto (\nu x)Q$$

3. Structurally congruent processes should have the same behavior.

A Simple Example

We use str. congruence to infer an interaction for the process

$$a(x).\bar{c}\langle x \rangle \parallel (\nu b)\bar{a}\langle b \rangle$$

Since $b \notin \text{fn}(a(x).\bar{c}\langle x \rangle)$, we have

$$a(x).\bar{c}\langle x \rangle \parallel (\nu b)\bar{a}\langle b \rangle \equiv (\nu b)(a(x).\bar{c}\langle x \rangle \parallel \bar{a}\langle b \rangle)$$

We can infer that

$$(\nu b)(a(x).\bar{c}\langle x \rangle \parallel \bar{a}\langle b \rangle) \longmapsto (\nu b)(\bar{c}\langle b \rangle \parallel \mathbf{0})$$

because $a(x).\bar{c}\langle x \rangle \parallel \bar{a}\langle b \rangle \longmapsto \bar{c}\langle b \rangle \parallel \mathbf{0}$ is a valid interaction.

Removing $\mathbf{0}$, in general we have, for any $b \notin \text{fn}(P)$:

$$a(x).P \parallel (\nu b)\bar{a}\langle b \rangle.Q \longmapsto (\nu b)(P\{b/x\} \parallel Q)$$

and the scope of b has **moved** from the right to the left.

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Another Example

$$P = (\nu z)((\bar{x}\langle y \rangle + z(w).\bar{w}\langle y \rangle) \parallel x(u).\bar{u}\langle v \rangle \parallel \bar{x}\langle z \rangle)$$

Observe that $\text{fn}(P) = \{x, v, y\}$ and $\text{bn}(P) = \{z, w, u\}$.

There are two possibilities for reduction.

1. Interaction among the first and second components:

$$\begin{aligned} P &\longmapsto (\nu z)(\mathbf{0} \parallel \bar{u}\langle v \rangle\{y/u\} \parallel \bar{x}\langle z \rangle) \\ &= (\nu z)(\mathbf{0} \parallel \bar{y}\langle v \rangle \parallel \bar{x}\langle z \rangle) = P_1 \end{aligned}$$

Process $P\{y/u\}$ represents the process P in which the free occurrences of name u have been **substituted** with y .

2. Interaction among the second and third components:

$$\begin{aligned} P &\longmapsto (\nu z)((\bar{x}\langle y \rangle + z(w).\bar{w}\langle y \rangle) \parallel \bar{u}\langle v \rangle\{z/u\} \parallel \mathbf{0}) \\ &= (\nu z)((\bar{x}\langle y \rangle + z(w).\bar{w}\langle y \rangle) \parallel \bar{z}\langle v \rangle \parallel \mathbf{0}) = P_2 \end{aligned}$$

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Try it yourself

- ▶ Three agents: a printing server, a client, and a printer.
The client wishes to print a document d .
- ▶ The client and the server share a public name b .
- ▶ The server and the printer share a name a .
- ▶ However, the client doesn't share names with the printer, so it cannot contact it.
- ▶ The document d cannot be transmitted along public names.

Try it yourself

The client, the server, and the printer in three different processes:

$$C = (\nu r)\bar{b}\langle r\rangle.r(y).$$

$$(\nu s)\bar{y}\langle s\rangle.s(c).\bar{s}\langle d\rangle.0$$

$$S = b(x).\bar{x}\langle a\rangle.0$$

$$P = a(u).\bar{u}\langle c\rangle.u(w).\overline{print}\langle w\rangle.0$$

$$N = C \parallel S \parallel P$$

- ▶ The client uses private names (r, s) to send requests: first to the server and then to the printer
- ▶ For simplicity, the server ends after receiving a client's request. By design of C , name a is exchanged on a private name (r) .
- ▶ The printer sends a confirmation c after getting a request on a . All exchanges are along s , private to C and P .
- ▶ The entire network is the composition of the three processes

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Basic Expressiveness of the π -calculus

We examine the basic expressiveness of the π -calculus. We show:

- ▶ How to represent **polyadicity** using monadic name passing
- ▶ The relationship between recursive definitions and **replication**

We appeal to **encodings** from one language to another to justify our claims.

Polyadic Communication

- ▶ For any $n \leq 0$, we would like to have prefixes

$$x(y_1, \dots, y_n).P \quad \text{and} \quad \bar{x}\langle z_1, \dots, z_n \rangle.Q \quad (\text{all } y_i \text{ are distinct})$$

- ▶ The naive encoding (ne) sends one name at the time:

$$\begin{aligned} \llbracket x(y_1, \dots, y_n).P \rrbracket_{ne} &= x(y_1). \dots x(y_n).P \\ \llbracket \bar{x}\langle z_1, \dots, z_n \rangle.Q \rrbracket_{ne} &= \bar{x}\langle z_1 \rangle. \dots \bar{x}\langle z_n \rangle.Q \end{aligned}$$

- ▶ Problem: this encoding is sensible to **undesirable interferences**.
Take the process

$$S = x(y_1 y_2).P \parallel \bar{x}\langle z_1 z_2 \rangle.Q \parallel \bar{x}\langle v_1 v_2 \rangle.R$$

Using the encoding we get:

$$\llbracket S \rrbracket_{ne} = x(y_1).x(y_2).P \parallel \bar{x}\langle z_1 \rangle.\bar{x}\langle z_2 \rangle.Q \parallel \bar{x}\langle v_1 \rangle.\bar{x}\langle v_2 \rangle.R$$

$\llbracket S \rrbracket_{ne}$ features unintended behavior: 'mix-ups' in sent values.

Polyadic Communication

- ▶ For any $n \leq 0$, we would like to have prefixes

$$x(y_1, \dots, y_n).P \quad \text{and} \quad \bar{x}\langle z_1, \dots, z_n \rangle.Q \quad (\text{all } y_i \text{ are distinct})$$

- ▶ The naive encoding (ne) sends one name at the time:

$$\begin{aligned} \llbracket x(y_1, \dots, y_n).P \rrbracket_{ne} &= x(y_1). \dots x(y_n).P \\ \llbracket \bar{x}\langle z_1, \dots, z_n \rangle.Q \rrbracket_{ne} &= \bar{x}\langle z_1 \rangle. \dots \bar{x}\langle z_n \rangle.Q \end{aligned}$$

- ▶ Problem: this encoding is sensible to **undesirable interferences**.
Take the process

$$S = x(y_1 y_2).P \parallel \bar{x}\langle z_1 z_2 \rangle.Q \parallel \bar{x}\langle v_1 v_2 \rangle.R$$

Using the encoding we get:

$$\llbracket S \rrbracket_{ne} = x(y_1).x(y_2).P \parallel \bar{x}\langle z_1 \rangle.\bar{x}\langle z_2 \rangle.Q \parallel \bar{x}\langle v_1 \rangle.\bar{x}\langle v_2 \rangle.R$$

$\llbracket S \rrbracket_{ne}$ features unintended behavior: ‘mix-ups’ in sent values.

Polyadic Communication

- ▶ A correct encoding first establishes a **fresh link** in which values are sent, one by one
- ▶ More precisely, we define $\llbracket \cdot \rrbracket_{\text{pc}} : \text{poly}\pi \rightarrow \text{mona}\pi$:

$$\begin{aligned}\llbracket x(y_1 \cdots y_n).P \rrbracket_{\text{pc}} &= x(w).w(y_1).\cdots.w(y_n).\llbracket P \rrbracket_{\text{pc}} \\ \llbracket \bar{x}\langle z_1 \cdots z_n \rangle.Q \rrbracket_{\text{pc}} &= (\nu w)(\bar{x}\langle w \rangle.\bar{w}\langle z_1 \rangle.\cdots.\bar{x}\langle z_n \rangle).\llbracket Q \rrbracket_{\text{pc}}\end{aligned}$$

(the other operators are translated homomorphically)

- ▶ n -adic communication thus requires $n + 1$ reductions.
- ▶ Question: would the above strategy work if the fresh name is created by the receiver?
- ▶ We say that polyadic communication is **representable** in the monadic π -calculus. The latter can be regarded as basic.

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Recursive Definitions and Replication

We have seen the π -calculus with **recursive definitions** of the form

$$A(\tilde{x}) \stackrel{\text{def}}{=} Q_A$$

where

- ▶ A is a process identifier
- ▶ Q_A is a process expression which may contain calls of A and other parametric processes.

Another form of introducing infinite behavior is **replication**.

The replication of process P , written $!P$, is given by the definition

$$!P \stackrel{\text{def}}{=} P \parallel !P$$

That is, $!P$ represents an unbounded number of copies of P :

$$!P \equiv P \parallel !P \equiv P \parallel P \parallel !P \equiv P \parallel P \parallel P \parallel !P \dots$$

Recursive definitions and replication can be mutually represented!

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Encoding Replication into Recursive Definitions

- ▶ From the previous description, it is clear that replication is a particular case of recursive definition.
- ▶ So the encoding formalizes a simple idea: each $!P$ is translated into a process A_P , recursively defined as

$$A_P(\tilde{x}) \stackrel{\text{def}}{=} P \parallel A_P\langle\tilde{x}\rangle$$

which can provide an unbounded number of copies of P .

- ▶ More formally: let $\pi_!$ and π_{rd} denote the set of π -calculus expressions with replication and recursive definitions, resp. Let $\llbracket \cdot \rrbracket_{\text{rep}} : \pi_! \rightarrow \pi_{\text{rd}}$ be the encoding defined as

$$\llbracket !P \rrbracket_{\text{rep}} = A\langle\tilde{x}\rangle \quad \text{where } A(\tilde{x}) \stackrel{\text{def}}{=} P \parallel A\langle\tilde{x}\rangle \text{ with } \tilde{x} \subseteq \text{fn}(P)$$

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Encoding Recursive Definitions into Replication

The encoding in the other direction is a bit more interesting.

Intuitively, for each definition $A(\tilde{x}) \stackrel{\text{def}}{=} Q_A$ we use

- ▶ message passing to model the passing of parameters
- ▶ replication to model the multiple activations
- ▶ restriction to model the scope of the definition

Encoding Recursive Definitions into Replication

In two steps, we set up a “server” for each recursive definition.

First, we define the encoding $\llbracket \cdot \rrbracket_{\text{rd}_0} : \pi_{\text{rd}} \rightarrow \pi_!$:

$$\begin{aligned}\llbracket A_i(\tilde{x}_i) \stackrel{\text{def}}{=} Q_i \rrbracket_{\text{rd}_0} &= !a_i(\tilde{x}_i). \llbracket Q_i \rrbracket_{\text{rd}_0} \\ \llbracket A\langle \tilde{z} \rangle \rrbracket_{\text{rd}_0} &= \overline{a_i} \langle \tilde{z} \rangle\end{aligned}$$

(the other constructs are translated homomorphically)

Then, we treat processes which contain identifiers.

Let P be a process with $A_1(\tilde{x}_1) \stackrel{\text{def}}{=} Q_1, \dots, A_k(\tilde{x}_k) \stackrel{\text{def}}{=} Q_k$ as the sets of definitions of its process identifiers. We have:

$$\llbracket P \rrbracket_{\text{rd}} = (\nu a_1, \dots, a_k) (\llbracket P \rrbracket_{\text{rd}_0} \parallel \prod_{i \in \{1, \dots, k\}} \llbracket A_i(\tilde{x}_i) \stackrel{\text{def}}{=} Q_i \rrbracket_{\text{rd}_0})$$

where $a_1, \dots, a_k \notin \text{fn}(P)$.

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Recursive Definitions and Replication

- ▶ The two encodings demonstrate that infinite behavior in the π -calculus is a natural concept
- ▶ We can choose the form of infinite behavior that fits better in our models
- ▶ Interestingly, a similar result **does not** hold for CCS