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# Languages and Machines

## L8: Turing machines

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Regular  $\leftrightarrow$  Finite State Machines (FSMs)

Context-free  $\leftrightarrow$  Pushdown Machines

Context-sensitive  $\leftrightarrow$  Linearly-bounded Machines

**Decidable  $\leftrightarrow$  Always-terminating Turing Machines**

**Semi-decidable  $\leftrightarrow$  Turing Machines**

# Languages and Machines, Up to Here



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- What kind of machines do we need to recognize  $L_2$ ?

# Turing Machines (TMs)







- A Turing machine (TM) may access and modify any memory position, using a sequence of elementary operations
- No limitation on the space/time available for a computation
- A finite state machine equipped with a **tape**, divided into **squares**, which can be written on as a result of a transition
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In other words, a transition:

- ▶ changes the state
- ▶ writes a symbol on the square scanned by the head
- ▶ moves the head



A (simple) **Turing machine**  $M$  is a quintuple  $(Q, \Sigma, \Gamma, \delta, q_0)$  where

- $Q$  is a set of **states**
- $q_0 \in Q$  is the **start state**
- $\Gamma$  is the **tape alphabet**, a set of symbols disjoint from  $Q$ .  
Contains a **blank symbol**  $\sqcup$ , not in  $\Sigma$
- $\Sigma \subseteq \Gamma \setminus \{\sqcup\}$  is the **input alphabet**
- The transition function  $\delta$  is a partial function such that

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

If  $\delta(q, X)$  is undefined then  $\delta(q, X) = \perp$ .



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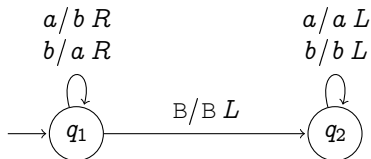
If  $\delta(q, X)$  is undefined then  $\delta(q, X) = \perp$ .

A set of accepting states  $F \subseteq Q$  is possible but not indispensable for defining acceptance (see later).

## Example 1



A TM that reads the input string and interchanges symbols  $a$  and  $b$ :



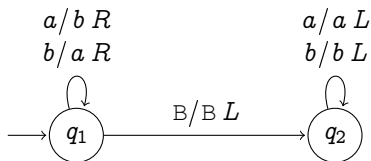
In state  $q_1$ , label ' $a/b R$ ' indicates:

- symbol  $a$  is rewritten into  $b$ , and
- the head moves right ( $R$ ).

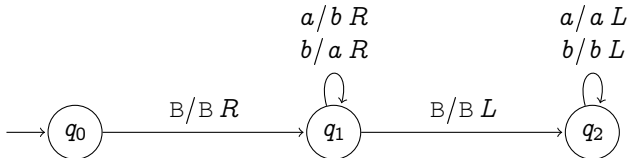
## Example 1



A TM that reads the input string and interchanges symbols  $a$  and  $b$ :



A slightly more general machine:





The global state of the TM is determined by the state  $q \in Q$ , the contents of the tape (a string in  $\Gamma^*$ ) and the position of the head

- A **configuration** of the TM is a string  $uqv$  in  $\Gamma^* Q \Gamma^*$ , in which:
  - $u$  is a string on the tape to the left of the head
  - $q$  is the **current** state
  - $v$  is a string on the tape that begins under the head
- The initial configuration is  $q_0 w$ , where  $w \in \Sigma^*$  is the input string
- The first symbol of  $v_{B^\infty}$  is called the **current** symbol



Suppose  $X, Y, Z$  are tape symbols (in  $\Gamma$ ).

Moving to the next configuration:

$$\delta(q, X) = (r, Y, R) \Rightarrow u Z q X v \vdash u Z Y r v$$

$$\delta(q, X) = (r, Y, L) \Rightarrow u Z q X v \vdash u r Z Y v$$

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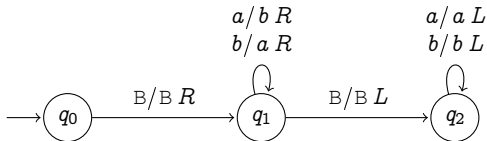
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$$\delta(q, X) = \perp \Rightarrow u q X v \vdash \perp$$

- A computation is a sequence of steps, as defined by  $\vdash$
- A TM **computes a function**  $f$ 
  - if starting in  $q_0 w$ , the final tape upon termination is always  $B^\infty u B^\infty$ , with  $u = f(w)$ .

# Example 1, Revisited



Computation for input *abab*:

$\rightarrow [q_0] B a b a b B$   
 $\vdash B [q_1] a b a b B$   
 $\vdash B b [q_1] b a b B$   
 $\vdash B b a [q_1] a b B$   
 $\vdash B b a b [q_1] b B$   
 $\vdash B b a b a [q_1] B$

$\vdash B b a b [q_2] a B$   
 $\vdash B b a [q_2] b a B$   
 $\vdash B b [q_2] a b a B$   
 $\vdash B [q_2] b a b a B$   
 $\vdash [q_2] B b a b a B$

## Example 2



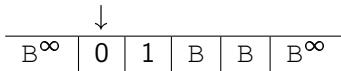
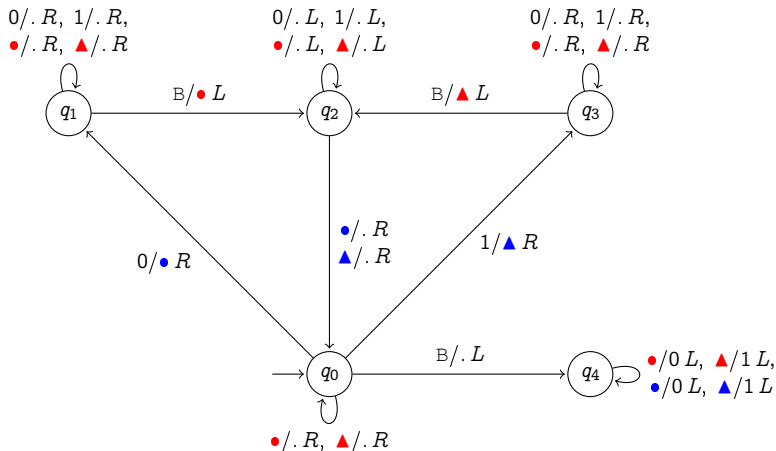
A TM that duplicates the input string  $w \in \{0, 1\}^*$ .

- ▶ Before: A tape with the string  $w$
- ▶ After: The tape contains the string  $w w$
- ▶ What is your (programming) strategy?

## Example 2



A TM that duplicates the input string  $w \in \{0, 1\}^*$ .

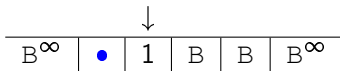
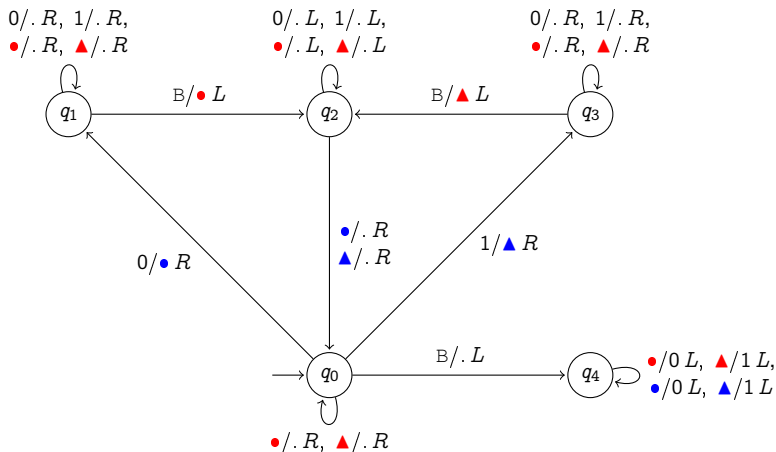


(State =  $q_0$ )

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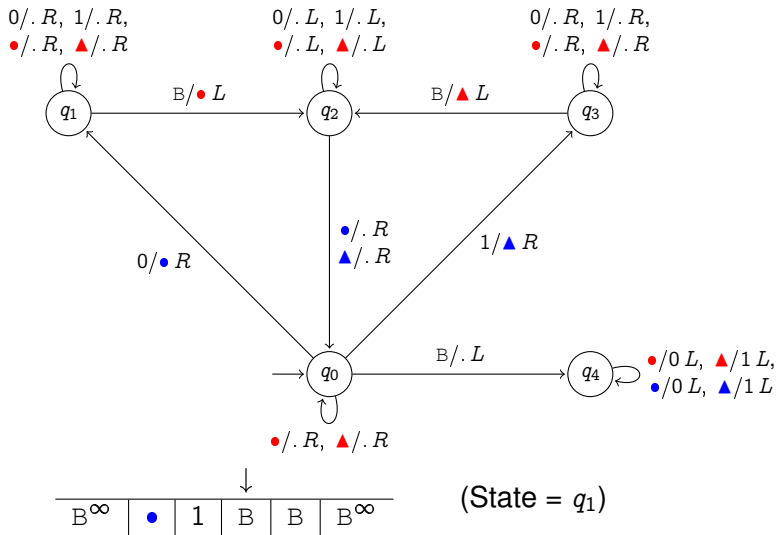


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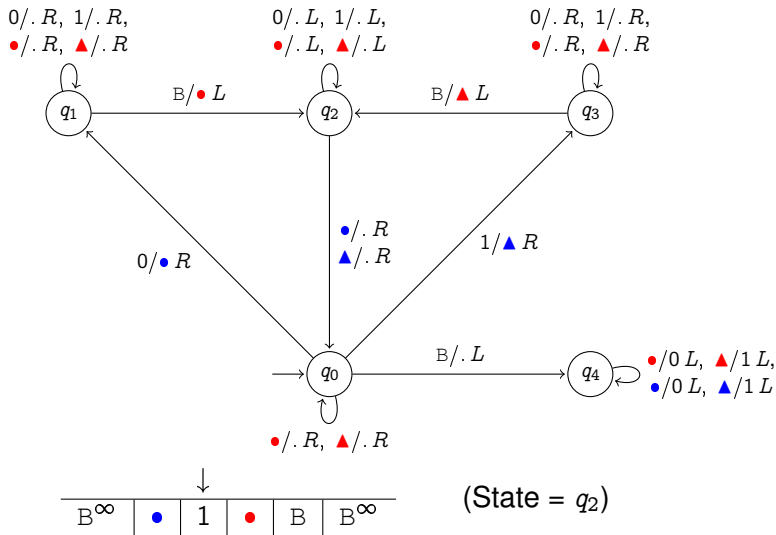
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## Example 2



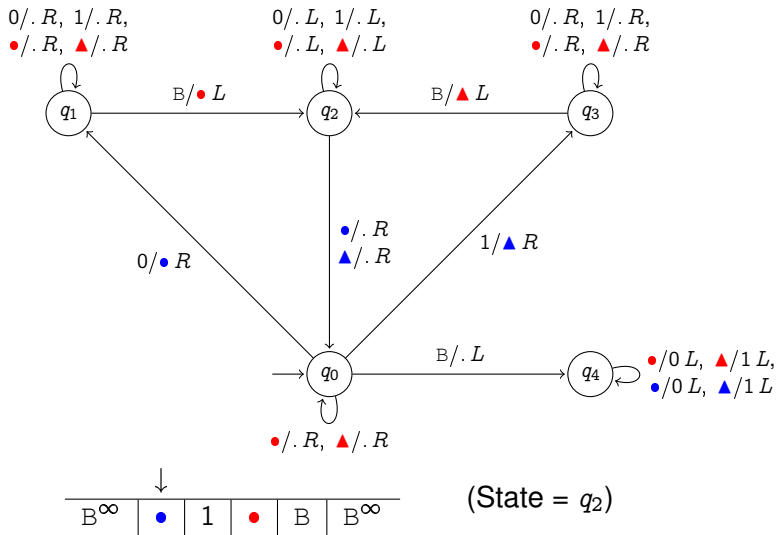
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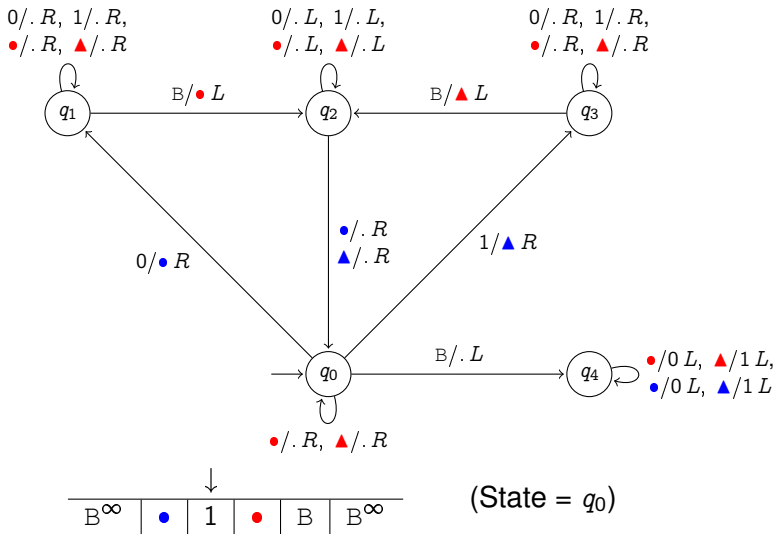




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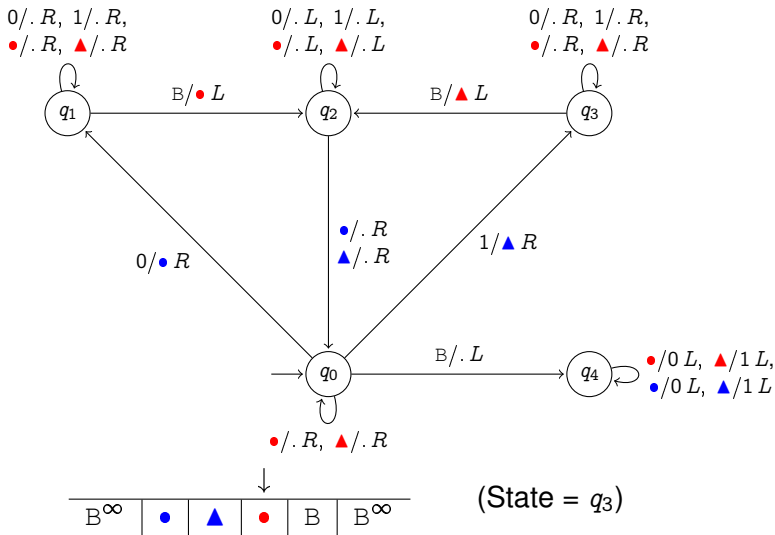
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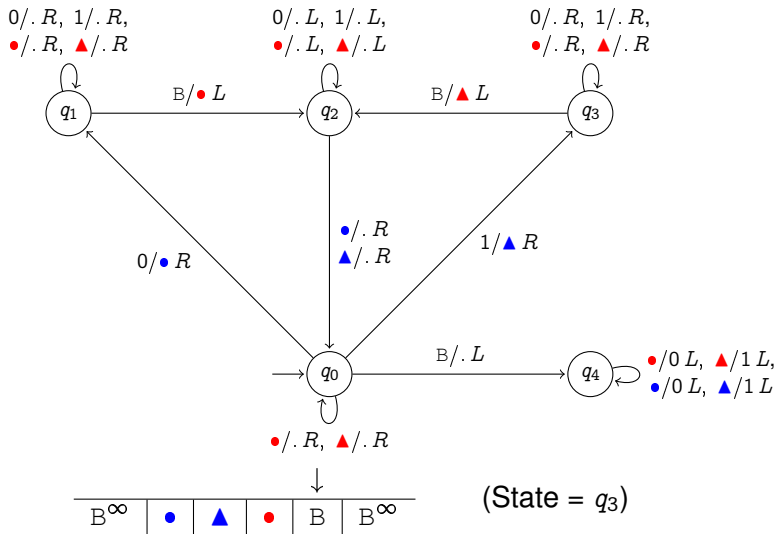
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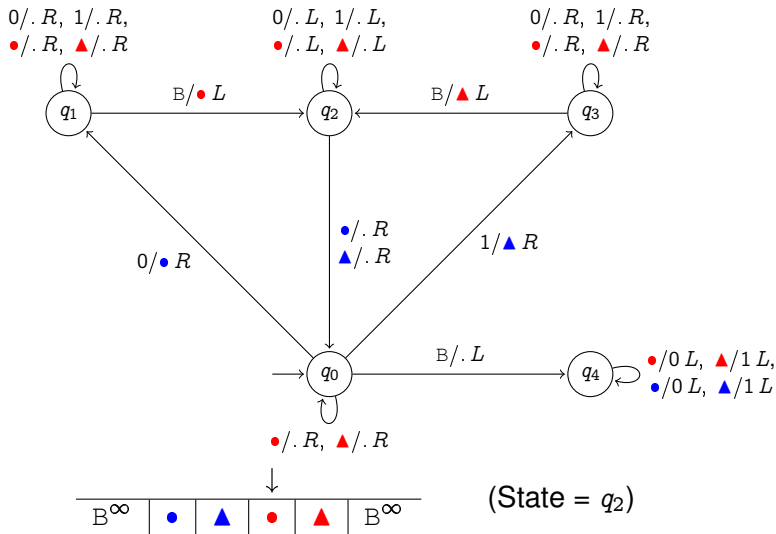
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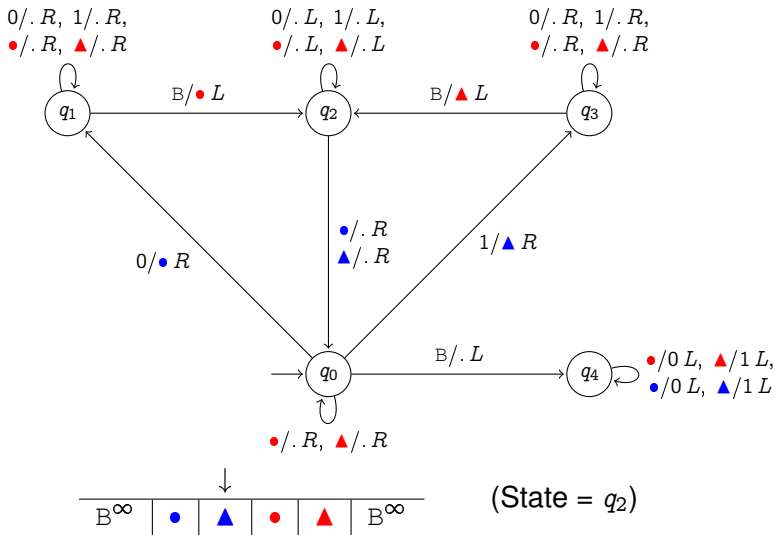
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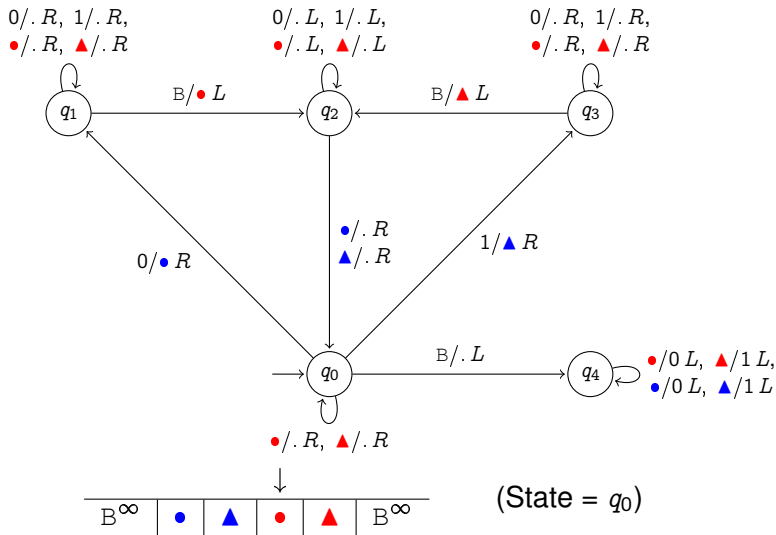
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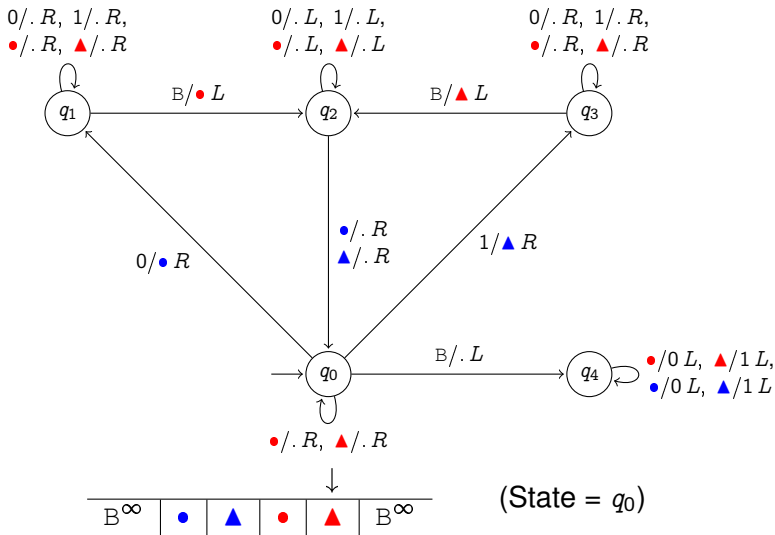
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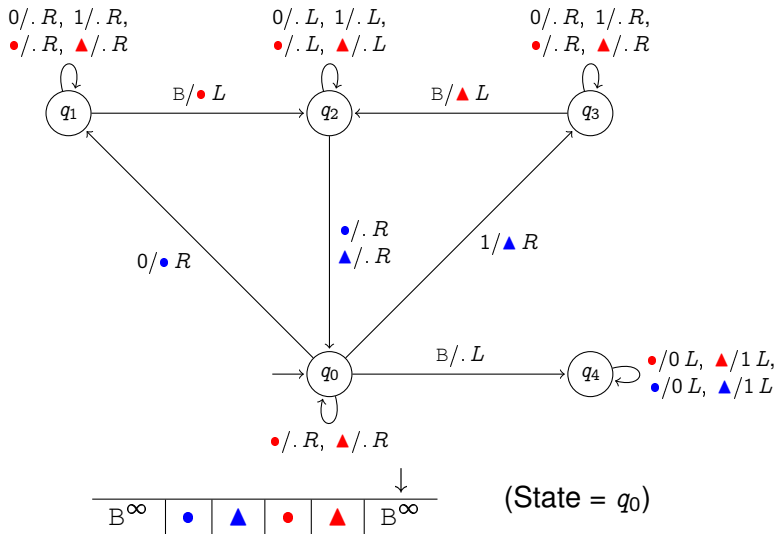
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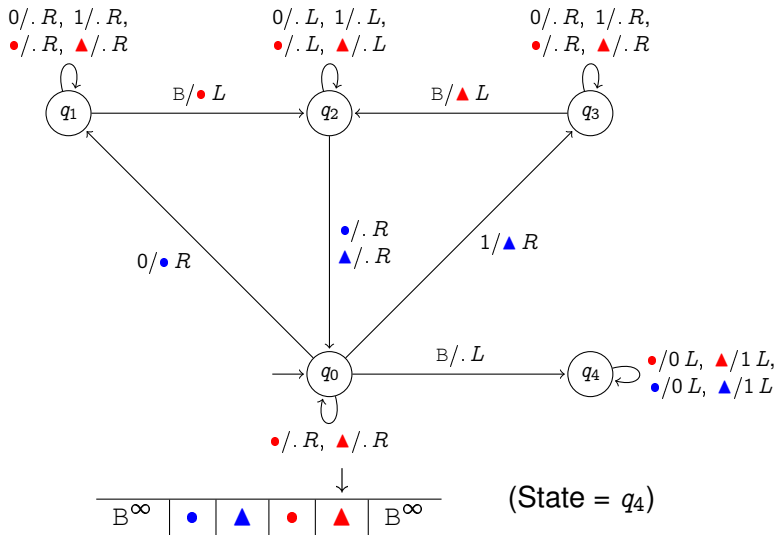




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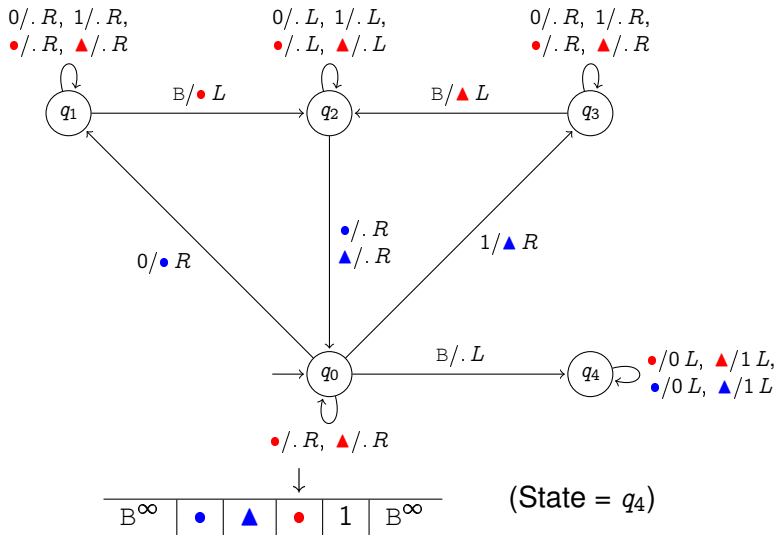
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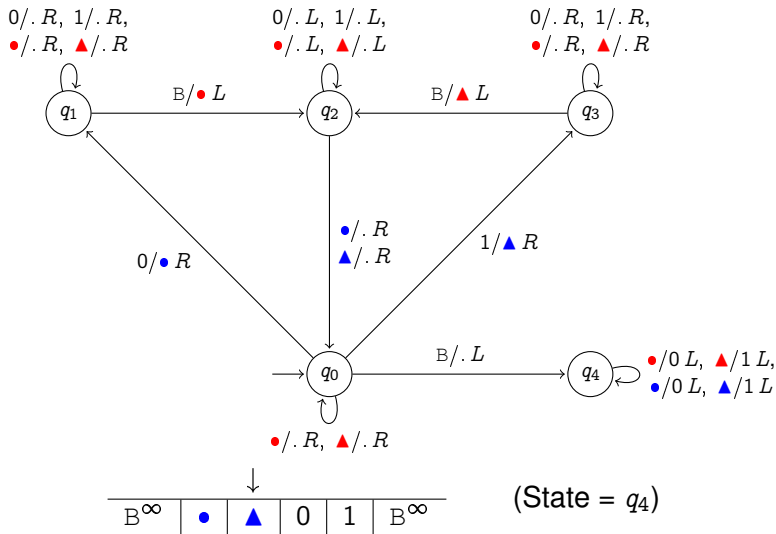
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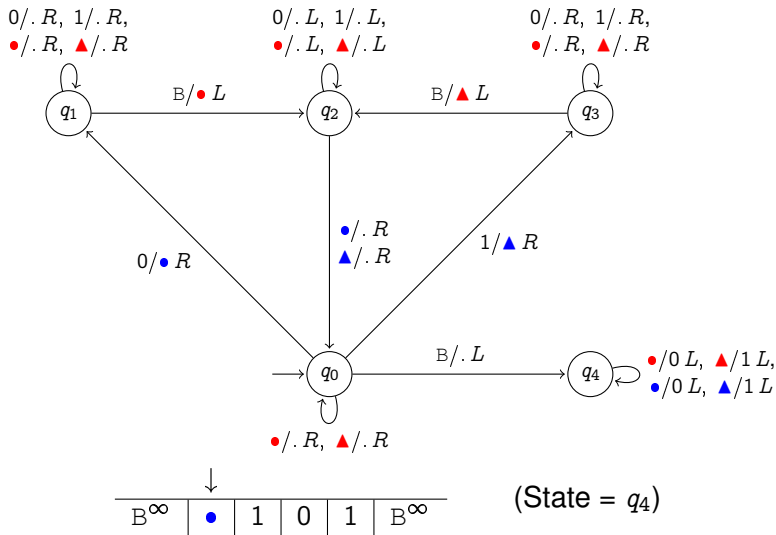
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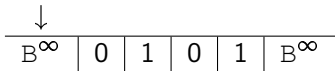
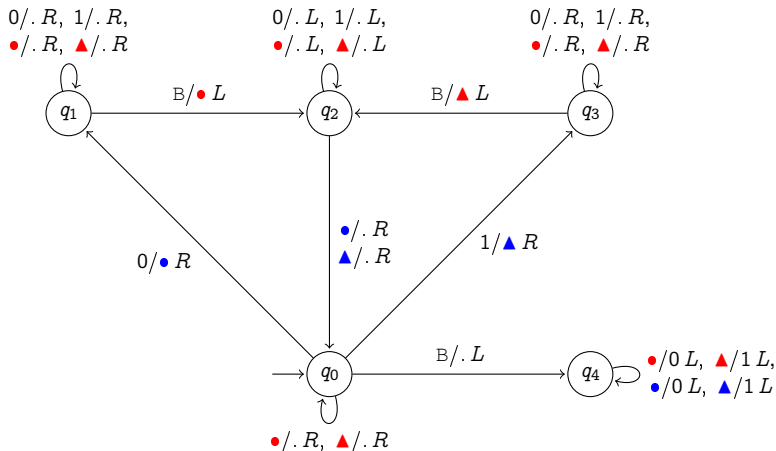
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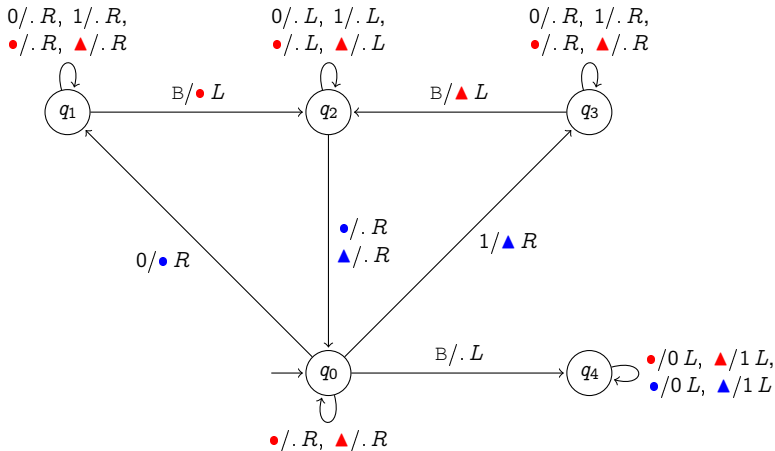


(State =  $q_4$ )

## Example 2



A TM that duplicates the input string  $w \in \{0, 1\}^*$ .



What does each state/transition represent?



The set  $L(M)$  can be defined in two different ways.

1. A TM  $M$  **accepts by termination** the language of the input strings  $w$  for which it terminates:

$$L(M) = \{w \in \Sigma^* \mid q_0 w \vdash^* \perp\}$$

No need for accepting states.



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No need for accepting states.

2.  $L(M)$  can also be defined by **termination in an accepting state**, extending  $M$  with a set  $F \subseteq Q$ :

$$L(M) = \{w \in \Sigma^* \mid \exists q_f \in F, u, v \in \Gamma^* : q_0 w \vdash^* u q_f v \vdash \perp\}$$

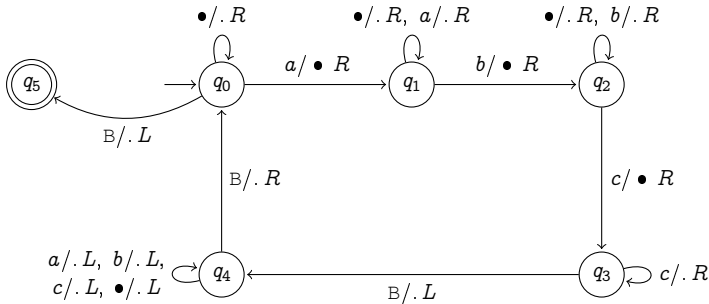
This definition can be reduced to the first one by letting  $F = Q$ .  
In fact, both definitions are equivalent.



## Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$

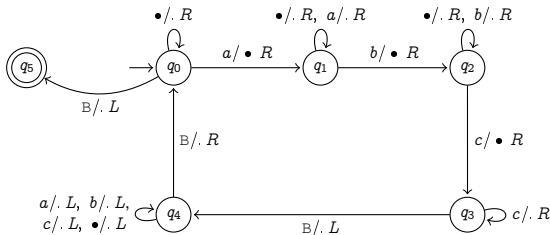


A TM with accepting state(s):



How does it work?

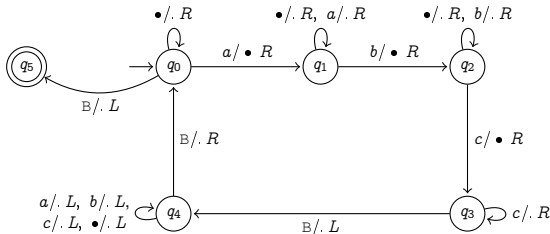
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Computation for input  $aabbcc$ :

$\rightarrow B [q_0] a a b b c c B$

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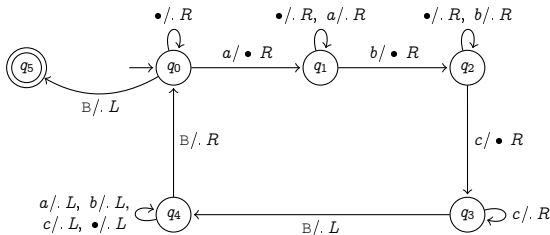


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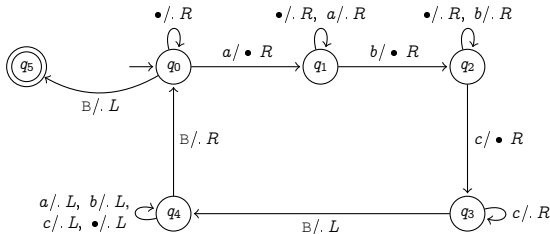
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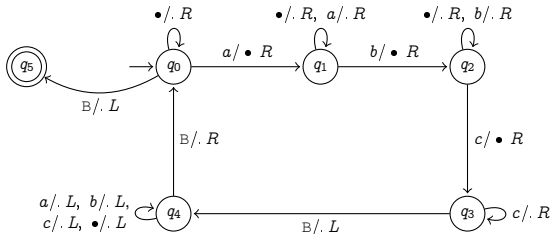
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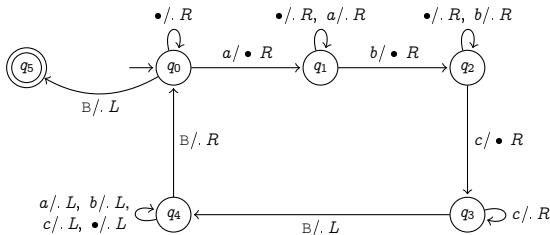
$\vdash B \bullet a [q_1] b b c c B$

$\vdash B \bullet a \bullet [q_2] b c c B$

$\vdash B \bullet a \bullet b [q_2] c c B$

$\vdash B \bullet a \bullet b \bullet [q_3] c B$

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$\vdash B \bullet [q_1] a b b c c B$

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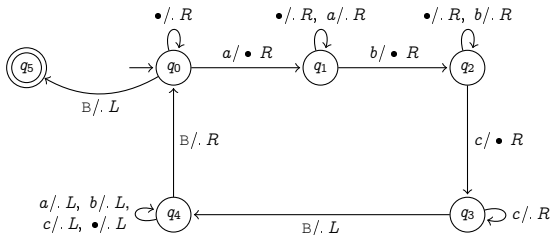
$\vdash B \bullet a \bullet [q_2] b c c B$

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Computation for input  $aabbcc$ :

$\rightarrow B [q_0] a a b b c c B$

$\vdash B \bullet a \bullet b \bullet [q_4] c B$

$\vdash B \bullet [q_1] a b b c c B$

$\vdash B \bullet a [q_1] b b c c B$

$\vdash B \bullet a \bullet [q_2] b c c B$

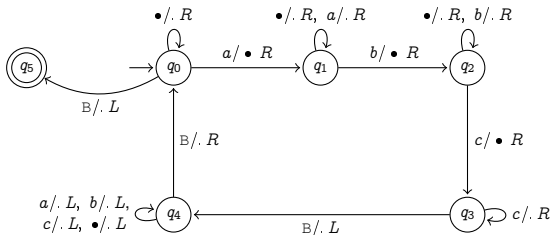
$\vdash B \bullet a \bullet b [q_2] c c B$

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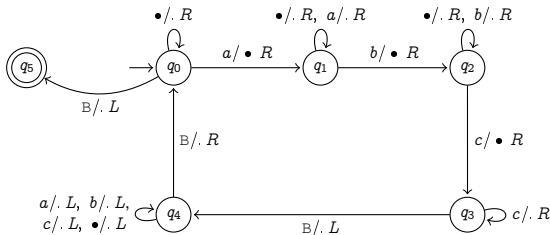
$\vdash B \bullet a \bullet b \bullet [q_3] c B$

$\vdash B \bullet a \bullet b \bullet c [q_3] B$

$\vdash B \bullet a \bullet b \bullet [q_4] c B$

$\vdash^* [q_4] B \bullet a \bullet b \bullet c B$

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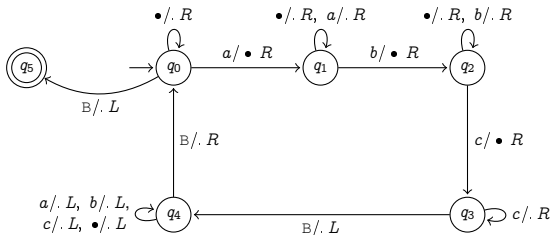
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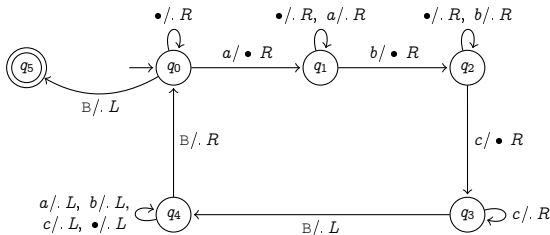
$\vdash B \bullet a \bullet b \bullet [q_4] c B$

$\vdash^* [q_4] B \bullet a \bullet b \bullet c B$

$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_3] B$

$\vdash^* [q_4] B \bullet \bullet \bullet \bullet \bullet B$

## Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input  $aabbcc$ :

$\rightarrow B [q_0] a a b b c c B$

$\vdash B \bullet [q_1] a b b c c B$

$\vdash B \bullet a [q_1] b b c c B$

$\vdash B \bullet a \bullet [q_2] b c c B$

$\vdash B \bullet a \bullet b [q_2] c c B$

$\vdash B \bullet a \bullet b \bullet [q_3] c B$

$\vdash B \bullet a \bullet b \bullet c [q_3] B$

$\vdash B \bullet a \bullet b \bullet [q_4] c B$

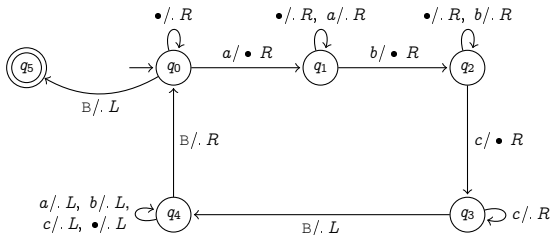
$\vdash^* [q_4] B \bullet a \bullet b \bullet c B$

$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_3] B$

$\vdash^* [q_4] B \bullet \bullet \bullet \bullet \bullet B$

$\vdash B [q_0] \bullet \bullet \bullet \bullet \bullet B$

## Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input  $aabbcc$ :

$\rightarrow B [q_0] a a b b c c B$

$\vdash B \bullet [q_1] a b b c c B$

$\vdash B \bullet a [q_1] b b c c B$

$\vdash B \bullet a \bullet [q_2] b c c B$

$\vdash B \bullet a \bullet b [q_2] c c B$

$\vdash B \bullet a \bullet b \bullet [q_3] c B$

$\vdash B \bullet a \bullet b \bullet c [q_3] B$

$\vdash B \bullet a \bullet b \bullet [q_4] c B$

$\vdash^* [q_4] B \bullet a \bullet b \bullet c B$

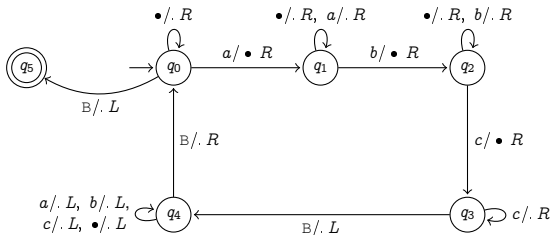
$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_3] B$

$\vdash^* [q_4] B \bullet \bullet \bullet \bullet \bullet B$

$\vdash B [q_0] \bullet \bullet \bullet \bullet \bullet B$

$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_0] B$

## Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Computation for input  $aabbcc$ :

$\rightarrow B [q_0] a a b b c c B$

$\vdash B \bullet [q_1] a b b c c B$

$\vdash B \bullet a [q_1] b b c c B$

$\vdash B \bullet a \bullet [q_2] b c c B$

$\vdash B \bullet a \bullet b [q_2] c c B$

$\vdash B \bullet a \bullet b \bullet [q_3] c B$

$\vdash B \bullet a \bullet b \bullet c [q_3] B$

$\vdash B \bullet a \bullet b \bullet [q_4] c B$

$\vdash^* [q_4] B \bullet a \bullet b \bullet c B$

$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_3] B$

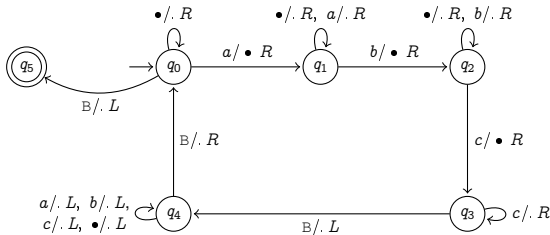
$\vdash^* [q_4] B \bullet \bullet \bullet \bullet \bullet B$

$\vdash B [q_0] \bullet \bullet \bullet \bullet \bullet B$

$\vdash^* B \bullet \bullet \bullet \bullet \bullet [q_0] B$

$\vdash B \bullet \bullet \bullet \bullet \bullet [q_5] \bullet B$

## Example 5.1.2: $\{a^n b^n c^n \mid n \in \mathbb{N}\}$



Consider now the computation for  $aabcc$ : where does it get stuck?



A TM is **always terminating** if it terminates for every input.

Let  $L$  be a language.

- $L$  is **semi-decidable** (or **recursively enumerable, RE**) if there exists a TM  $M$  such that  $L = L(M)$ .
- $L$  is **decidable** (or **recursive**) if there is an always terminating TM that accepts  $L$  by termination in an accepting state.
- If  $L$  is decidable, then it is also semi-decidable.  
The converse doesn't hold!





This lecture (Sections 5.1 and 5.2):

- ▶ Turing machines
- ▶ Key terminology for TM-accepted languages

**Next Lecture** (Sections 5.3–5.8)

- Further examples of TMs
- Variants of TMs: multiple-track, multiple-tape, non-deterministic