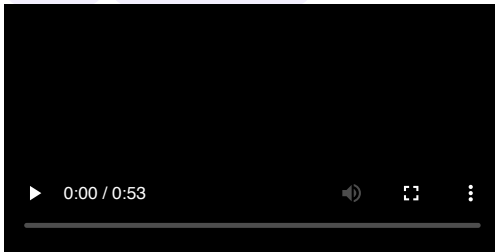


DUMP Research

#vector #Euclidean_plane



A More Fluid Model for Ocean Currents D ^[1]

- Oceans are modeled by putting buoys into the ocean and then measuring the velocities that the buoys return and then computing the currents as a [vector field](#).^[1-1]
- "Reconstructing ocean currents accurately can facilitate weather forecasting, maritime navigation, and forecasting of oil spill dispersion." ^[1-2]
- The method has limitations because the buoys can sometimes fail to collect data due to ocean vortices
- The framework used to model the ocean was created in 2 parts one simulated and one realistic model and then the difference between the 2 is then calculated.
- The Helmholtz Decomposition.**
 - The motion of a volume element of a fluid, such as the ocean, can be decomposed into a divergent velocity and a rotational velocity.
 - Is a vector field.

$$\underbrace{F}_{\text{ocean flow}} = \underbrace{\text{grad } \Phi}_{\text{divergent velocity}} + \underbrace{\text{rot } \Psi}_{\text{rotational velocity}}$$

Stream function \rightarrow

- We can relate the model to how the oceans use energy because this model simulates the energy of the ocean using vector field.
 - Does this mean that are modeling based off a differential equation?
- Is the study interpreting the data of the boueys and then creating a model?
- "our goal is to reconstruct the vector field from sparse observations."
- "Our primary goals are (1) prediction of the field F at new locations, not observed in the training data, and (2) estimation of the divergence, itself a function of location and which we define next as part of the Helmholtz decomposition. Secondly, we are interested in recovering vorticity, another functional of F described below."
- The Helmholtz Decomposition is used to extrapolate the data used in the training of the boueys to a model and to have a high covariance inbetween those 2.
- $(x_m^{(1)}, y_m^{(2)})^T \in \mathbb{R}^2$ represnt the location of a bouey and x_m is represented as a collum vector usually latitude and longitude
 - This makes sense becasue the points coll vectors x, y are part of the set used to then calculate the ocean flow.
- if a fluid is "incompressable" the velocity vector feild must have a divergence of 0 everywhere.
 - Is this what divergent free means?

Curl

- Curl is also is expressed because of the fluid flow around it but it is "tendancy" that something has to rotate because as in divergence its neighbors.
- Positive curl means clockwise rotation while counter clockwise rotation is negative

- seen for example when the fluid is slow at the "top" and "fast" at the bottom causing rotation
- true curl is 3d.
- $\text{curl } F = \nabla \times F$
- for GP study^[1-3] ζ is the curl.

Maxwells equations

$$\text{div } E = \frac{\rho}{\epsilon_0}$$

- Divergence is proportional to charge density. This basically means that protons act as a "source" and electrons act as a "sink"
- and where there is no charge the fluid flows incompressible

$$\text{div } B = 0$$

- Means that there is 0 divergence everywhere and that the "fluid" is incompressible.
- This is relative to^[1-4] because this is the situation that the ocean takes a divergent free field.

$$\text{curl } E$$

. Helmholtz decomposition

- Operation in vector calculus that states that a vector field in 3 dimensions can be represented as a the sum of a divergence free vector field.

Divergence

- Vector fields are planes where each point in space has a vector
- in our case they are the velocity of each particle of fluid.
- static vector fields are a steady state system
- Vector fields can describe other physical phenomenon such as fluid flow.
- divergence is the amount that fluids flow into regions near it
 - Maybe of the amount of fluid coming out of a space?
 - divergence of "sources" is positive and the opposite is true as channels where fluid flows into it are negative
- In this context a vector field takes in 2d input and outputs.
- the output of a divergence function depends on the "neighbors" that's what makes it similar to [derivatives](#)
- $\text{div } F = \nabla \cdot F$ (dot product of the derivatives)
- for GP^[1-5] study the divergence is δ .

New vocab

- **covariance**: Covariance is a statistical tool that measures the relationship between two random variables
- **Divergence**: In [vector calculus](#), **divergence** is a [vector operator](#) that operates on a [vector field](#), producing a [scalar field](#) giving the quantity of the vector field's source at each point. More technically, the divergence represents the volume density of the outward [flux](#) of a vector field from an infinitesimal volume around a given point. [Divergence](#)
- **Scalar potential** describes the situation where the difference in the [potential energies](#) of an object in two different positions depends only on the positions, not upon the path taken by the object in traveling from one position to the other.
- **Elements** $x \in A$ means that a is an element of A
- Phase space: a solution to a given system an [ODE](#)
-

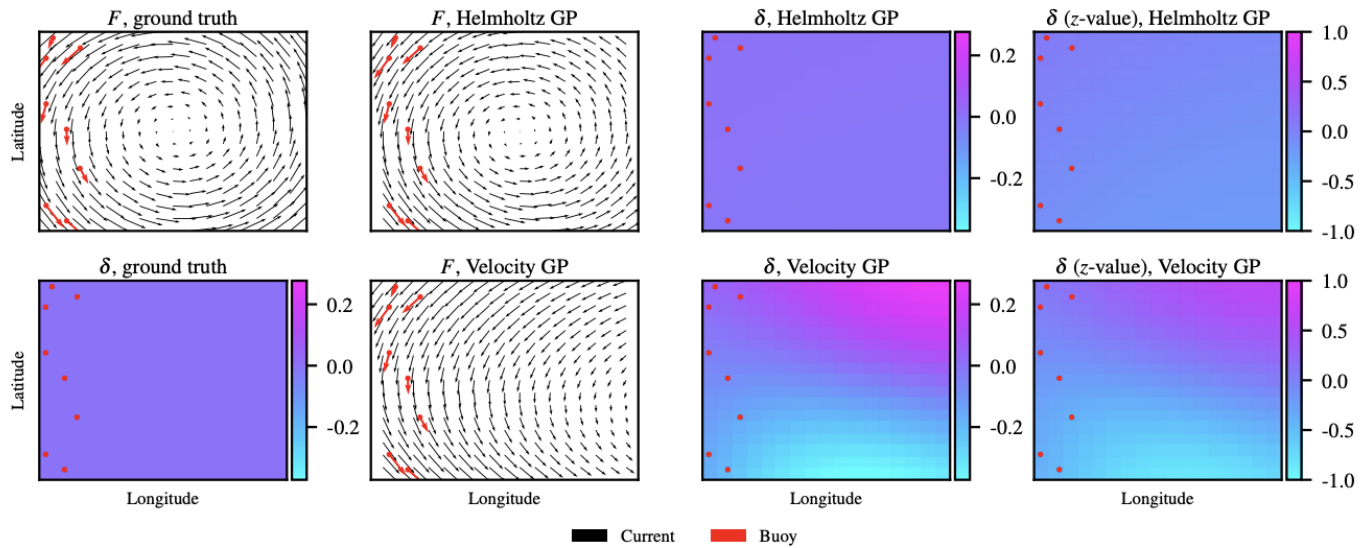


Figure 1. First column: ground truth predictions (upper) and divergence (lower). Second column: current predictions. Third column: divergence estimates. Fourth column: posterior divergence z-values.

Resources

Environmental effects on the currents.

1. [Gaussian Processes at the Helm\(holtz\): A More Fluid Model for Ocean Currents](#) ↩ ↩ ↩ ↩ ↩