

Bayesian deep learning /
MASH & IASD

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Bayesian neural network, predictive distribution:

$$p(t|x, \mathcal{D}) = \int p(t|x, w) p(w|\mathcal{D}) dw$$

Approximations to the posterior $p(w|\mathcal{D})$:

- Laplace (yesterday)
- Variational inference
- Monte Carlo dropout

VI (Blundell, 2015)

parameters are weights $w = (w_1, \dots, w_{\bar{w}})$

Approximate family: Gaussian: $N(\mu, \sigma^2)$

w_i approximated by $\theta_i = (\mu_i, \sigma_i^2)$, $i = 1, \dots, \bar{w}$

$$\underline{q_{\theta}(w)} = \prod_{i=1}^{\bar{w}} N(w_i | \mu_i, \sigma_i^2)$$

$$\mathcal{Q} = \{q_{\theta}(w), \mu_i \in \mathbb{R}, \sigma_i > 0\}$$

$$KL(q_{\theta}(w) \parallel p(w | x, y)) \quad x, y \begin{cases} X = (x_i) \\ Y = (y_i) \end{cases} \quad i=1 \dots N$$

$$= \int q_{\theta}(w) \log \left(\frac{q_{\theta}(w)}{p(w | x, y)} \right) dw$$

$$= \int q_{\theta}(w) \log \left(\frac{q_{\theta}(w) P(y | x)}{P(w) P(y | w, x)} \right) dw$$

$$= \underbrace{\left(- \int q_{\theta}(w) \log p(y|w, x) \right)}_{\text{expected log-lik.}} + \underbrace{\text{KL} \left(q_{\theta}(w) \parallel p(w) \right)}_{\text{KL for prior}} + \underbrace{\log p(y|x)}_{\text{evidence}}$$

$$= \underbrace{\left(- \mathcal{L}_{\text{VI}}(\theta) \right)}_{\text{VI}} + \underbrace{\log p(y|x)}_{\text{evidence}}$$

Since $\text{KL} \geq 0$, $\mathcal{L}_{\text{VI}}(\theta) \leq \log p(y|x)$

so \mathcal{L}_{VI} is called evidence lower bound ELBO

Minimize VI \iff Maximize ELBO

$$\text{ELBO} : \mathcal{L}_{\text{VI}}(\theta) = \mathbb{E}_{q_{\theta}(w)} [\log p(y|x, w)] - \underbrace{\text{KL} \left(q_{\theta}(w) \parallel p(w) \right)}_{\text{closed-form}}$$

$$\mathcal{L}_{\text{VI}}(\theta) = \sum_{i=1}^N \mathbb{E}_{q_{\theta}(w)} [\log p(y_i | w, x_i)] - \text{KL}$$

approximate by sampling : $\hat{w} \sim q_{\theta}(\cdot)$

In order to estimate the gradient of $L_{VI}(\theta)$, use the reparametrization trick.

idea : $w = g(\theta, \varepsilon)$, g is deterministic

$$w_j \sim N(w_j | \mu_j, \sigma_j^2) = q_{\theta_j}(w) \quad \left\{ \begin{array}{l} \varepsilon \perp \theta \end{array} \right.$$

$$w_j = g(\theta_j, \varepsilon_j) = \mu_j + \sigma_j \varepsilon_j, \text{ with } \varepsilon_j \sim N(0, 1).$$

$$ELBO(\theta) = L_{VI}(\theta) \approx \underbrace{\sum_{i=1}^N \log p(y_i | y(x_i, g(\theta, \hat{\varepsilon}_i)))}_{\text{MC approx of } E} - KL$$

Algorithm : Stochastic VI

Given X, Y data, η : learning rate, initialise θ

Repeat: Sample $\{\varepsilon_j \sim p(\varepsilon) \mid j \in S$
 $\left[S \text{ subset from } \{1, \dots, N\} \text{ of size } \pi \right.$

Stochastic derivative estimator wrt θ :

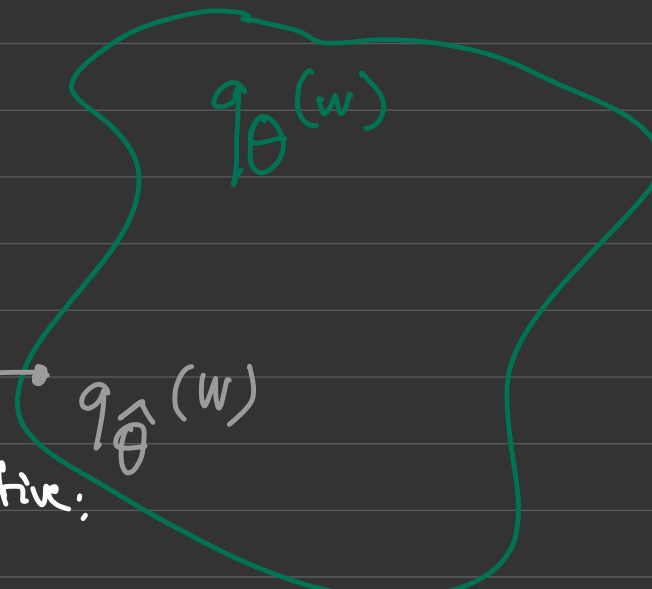
$$\hat{\Delta\theta} = -\frac{N}{\pi} \sum_{i \in S} \frac{\partial \log p(Y_i \mid \gamma(g(\theta, \hat{\varepsilon}_i), x_i))}{\partial \theta} + \frac{\partial KL}{\partial \theta}$$

avail. by reparam. trick. closed-form.

$$\theta \leftarrow \theta + \eta \hat{\Delta\theta}.$$

Until (some) convergence.

$$\mathcal{L}_{VI}(\theta)$$

$p(w|x, y)$


$q_{\hat{\theta}}(w)$ can be plugged-in predictive:

$$p(t|x, \mathcal{D}) \approx \underbrace{\int p(t|x, w)}_{\downarrow} \underbrace{q_{\hat{\theta}}(w) dw}$$

can be made Gaussian by some Taylor expansion as yesterday

Gaussian approx by VI

Monte Carlo dropout (Gal, Ghahramani, ICML, 2016)

based on: Dropout (Hinton, 2012)

▫ training a NN with dropout

\Leftrightarrow training a BNN with variational posterior $q_{\theta}(w)$

▫ MC dropout:

sampling several passes of NN with dropout

\Leftrightarrow MC approx. inference with $q_{\theta}(w)$.