Formal Languages and Decision Problems

Foundations of Computer Science, Fall 2018

First, a quick refresher on set theory.

A set is a collection of elements. Those elements can be anything, including other sets.

Sets can be described by listing their elements, such as $\{a, b, c, \ldots\}$.

The empty set is denoted \emptyset , or $\{\}$.

A set A is *finite* if it has a finite number of elements, that is, if there is a natural number $n \in \mathbb{N}$ such that A has n elements. If no such n exists, then A is *infinite*.

The main relation on sets is set membership, written $a \in A$: a is an element of set A.

Two sets are equal if they have exactly the same elements.

Another relation on sets is *set inclusion*, written $A \subseteq B$: A is a subset of B, meaning that every element of A is an element of B).

Some properties of \subseteq :

$$\emptyset \subseteq A$$
 for every A

$$A \subseteq A$$
 for every A

If
$$A \subseteq B$$
 and $B \subseteq C$, then $A \subseteq C$

$$A = B$$
 if and only if $A \subseteq B$ and $B \subseteq A$.

If P is a property, then $\{x \mid P(x)\}$ is the set of all elements satisfying the property. (Technically speaking, there are some restrictions on what makes up an acceptable property in this context — but they won't impact us.)

Common operations on sets:

$$A \cup B = \{x \mid x \in A \text{ or } x \in B\}$$

$$A \cap B = \{x \mid x \in A \text{ and } x \in B\}$$

 $\overline{A} = \{x \in \mathcal{U} \mid x \notin A\}$ (where \mathcal{U} is a universe of elements such that $A \subseteq \mathcal{U}$ — the definition of $\overline{}$ therefore depends on the universe under consideration)

 $A \times B = \{\langle x, y \rangle \mid x \in A, y \in B\}$, the set of all pairs of elements from A and B. This generalizes in the obvious way to products $A_1 \times A_2 \times \cdots \times A_k$.

A function $f: A \longrightarrow B$ associates (or maps) every element of A to an element of B. Set A is the domain of the function, and B is the codomain. The image of A under f is the subset of B defined by $\{b \in B \mid f(a) = b \text{ for some } a \in A\}$.

If $f:A\longrightarrow B$ and $g:B\longrightarrow C$, then the composition $g\circ f:A\longrightarrow C$ defined by $(g\circ f)(x)=g(f(x)).$

A function $f:A\longrightarrow B$ is one-to-one if it maps distinct elements of A into distinct elements of B (that is, if $a\neq b$, then $f(a)\neq f(b)$). A function $f:A\longrightarrow B$ is onto if every element of B is in the image of A under f (that is, if for every element $b\in B$ there is an element $a\in A$ with f(a)=b). A function $f:A\longrightarrow B$ is a one-to-one correspondence if it is both one-to-one and onto.

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Intuitively, a computation is a way to "implement" a mathematical function $f: A \longrightarrow B$. A big part of the course is to build an understanding of what that intuition means.

Arbitrary functions between arbitrary sets A and B is too broad a class of functions to work with. Historically, researchers have looked at two classes of functions to study computation:

1. Natural number functions of the form

$$f:(\mathbb{N}\times\cdots\times\mathbb{N})\longrightarrow\mathbb{N}$$

2. **Decision problems** of the form

$$d: D \longrightarrow \{1, 0\}$$

(where 1 can be interpreted as true and 0 as false). Decision problems represent predicates on the domain D. For example, determining if a graph is planar.

The abacus model we saw last time is an example of computation model that can be used to define what it means for a natural number functions to be computable. For the next several lectures, we will consider decision problems instead.

The domain D of decision problems is usually constrained to be a set of *strings*.

Let Σ be a non-empty finite set we will call the *alphabet*. A *string over* Σ is a (possibly empty) finite sequence of elements of Σ , usually written $a_1 \cdots a_k$, where $a_i \in \Sigma$. For example, aaccabc is a string over alphabet $\{a, b, c\}$. It is also a string over alphabet $\{a, b, c, d\}$. We will use u, v, w to range over strings.

The length of $u = a_1 \dots a_k$, written |u|, is k.

The empty string is written ϵ . It has length 0.

The set of all strings over Σ is denoted Σ^* . Note that this is an infinite set. (Why?)

If $u = a_1 \dots a_k$ and $v = b_1 \cdots b_m$ are strings over Σ , then the *concatenation uv* is the string $a_1 \cdots a_k b_1 \cdots b_m$. Note that $\epsilon u = u \epsilon = u$ for every string u.

We define $u^0 = \epsilon$, $u^1 = u$, $u^2 = uu$, $u^3 = uuu$, etc.

One reason why decision problems are an interest class of problems to study is that they can be studied using sets of strings. To every decision problem

$$d: \Sigma^* \longrightarrow \{1, 0\}$$

you can associate a set of strings S(d) defined by

$$S(d) = \{ u \in \Sigma^* \mid d(u) = 1 \}$$

that completely characterizes d. Indeed, given any set of strings A, you can construct a decision problem D(A) by:

$$D(A)(u) = \begin{cases} 1 & \text{if } u \in A \\ 0 & \text{otherwise} \end{cases}$$

with the property that D(S(d)) = d. In other words, given any decision problem d, you can associate with d a set of strings A with the property that you can reconstruct d from A alone.

We will transform the problem of determining whether a decision problem is computable into the problem of determining whether a set of strings is computable. But of course, what we will mean when we say that a set of strings A is computable is that the corresponding decision problem constructed from A as above is computable. Why do we do this? Because sets of strings are much easier to work with: they are sets, and we can manipulate sets in many different ways.

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Because sets of strings are so important, let's give them a name. A formal language (usually called only a language) over alphabet Σ is a set of strings over Σ .

Since languages are sets, we inherit the usual set operations $A \cup B$, $A \cap B$, \overline{A} (where the universe of A is taken to be Σ^*).

Because a language A is a set of strings specifically, we can also define more specific operations.

 $A \cdot B = \{uv \mid u \in A \text{ and } v \in B\}$, that is, the set of all strings obtained by concatenating a string of A and a string of B.

$$A^{0} = \{\epsilon\}$$

$$A^{1} = A$$

$$A^{2} = A \cdot A$$

$$A^{3} = A \cdot A \cdot A, \text{ etc}$$

$$A^{*} = A^{0} \cup A^{1} \cup A^{2} \cup A^{3} \cup \dots = \bigcup_{k>0} A^{k}$$

The * operation is called the *Kleene star*.

Some properties that are easy to verify:

$$\varnothing \cdot A = A \cdot \varnothing = \varnothing$$

 $\{\epsilon\} \cdot A = A \cdot \{\epsilon\} = A$

Example: $\Sigma = \{a, b\}$, and $A = \{aa, bb\}$. Then $A^* = \{\epsilon, aaaa, aabb, bbaa, bbbb, aaaaaa, aaabbb, aabbaa, aabbbb, bbaaaa, bbaabb, bbbbaa, bbbbbb, ... \}.$

This explains why I wrote Σ^* for the set of all strings: if we consider Σ as a set of strings, each of length 1, then Σ^* according to the above definition indeed gives the set of all strings over alphabet Σ .

The operations \cup , \cdot , and * are called the *regular operations*.

A language over alphabet $\Sigma = \{a_1, \ldots, a_k\}$ is regular if it can be obtained from the sets $\emptyset, \{\epsilon\}, \{a_1\}, \ldots, \{a_k\}$ and finitely many applications of the regular operations.

Example: consider the language of all even-length strings over alphabet $\{a,b\}$. It can be obtained as:

$$((\{a\} \cup \{b\} \cup \{c\}) \cdot (\{a\} \cup \{b\} \cup \{c\}))^*$$

Therefore, that language is regular.

Example: consider the language of all strings over $\{a, b, c\}$ that start and end with an a:

$$(\{a\} \cdot (\{a\} \cup \{b\} \cup \{c\})^* \cdot \{a\}) \cup \{a\}$$

Therefore, that language is also regular.

Regular languages form a very natural class of languages, and we will see soon that they arise out of an equally natural model of computation.

Some natural ways to form regular languages:

- The empty language is regular, pretty much by definition.
- Every singleton language (language with a single string) is regular. This is easy to see: language $\{a_1 \dots a_k\}$ is obtained by taking $\{a_1\} \cup \dots \cup \{a_k\}$.

- Every finite language (i.e., language with a finite number of strings) is regular. Again, this is easy to see. Say $A = \{u_1, \ldots, u_k\}$. By the previous statement, each of $\{u_1\}$, ..., $\{u_k\}$ are regular. Therefore, their union is regular.
- if A and B are regular languages, then $A \cup B$ and $A \cdot B$ are regular languages. That follows directly from the definition.
- If A is regular, then A^* is regular. Again, this follows directly from the definition. This means, in particular, that Σ^* , the set of all strings over a given alphabet, is regular.
- If A and B are regular, then $A \cap B$ is regular. We'll show this is the case later, because we don't have enough techniques to show that just yet.
- If A is regular, then $\overline{A} = \Sigma^* A$ is regular. Again, we don't have enough techniques to show that just yet.
- If A is regular, then rev(A), the set of all strings from A but in reverse (where the reverse of $a_1 \ldots a_k$ is just $a_k \ldots a_1$) is regular. We'll be able to show that next section.

You might be led to believe at this point that every language is regular. That's not true. The most natural non-regular language is probably the language of all *palindrome* strings over an alphabet Σ . A palindrome string is a string with the property that it and its reverse are equal, such as aaa, or abba. It's not obvious that this is not regular, and we don't have enough techniques to show that yet.

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Regular expressions are a convenient notation for regular languages.

A regular expression over alphabet Σ is defined by the following syntax:

$$r ::= 1$$

$$0$$

$$a \quad \text{for every } a \in \Sigma$$

$$(r_1 + r_2)$$

$$(r_1 r_2)$$

$$(r_1^*)$$

We usually drop parentheses, under the assumption that r_1^* binds tighter than concatenation r_1r_2 which binds tighter than r_1+r_2 . For example, ab+ac is a regular expression, as is a(b+c) and a*(b+c)*.

A regular expression r denotes a language [r] over Σ in the following way:

For example:

$$\begin{aligned}
[ab+ac] &= [ab] \cup [ac] \\
&= ([a] \cdot [b]) \cup ([a] \cdot [c]) \\
&= (\{a\} \cdot \{b\}) \cup (\{a\} \cdot \{c\}) \\
&= \{ab\} \cup \{ac\} \\
&= \{ab, ac\}
\end{aligned}$$

$$\begin{aligned} [\![a^*(b+c)^*]\!] &= [\![a^*]\!] \cdot [\![(b+c)^*]\!] \\ &= [\![a]\!]^* \cdot [\![b+c]\!]^* \\ &= \{a\}^* \cdot ([\![b]\!] \cup [\![c]\!])^* \\ &= \{a\}^* \cdot (\{b\} \cup \{c\})^* \\ &= \{a\}^* \cdot \{b,c\}^* \end{aligned}$$

And thinking about this last set (which is difficult to write down), it is basically the set of all strings obtained by concatenating a sequence of as (including none) to a sequence of bs and cs (in any order, including none). So aaaaaa is in this set, as is aaaab, aaaabbbb, aaaabbbcbcbc, etc.

Theorem: A language A is regular exactly if there is a regular expression r such that [r] = A.

We can use regular expressions to show that if A is regular, then $rev(A) = \{rev(u) \mid u \in A\}$, where rev(u) is the reverse of string u, is regular: since A is regular, there is a regular expression r with $[\![r]\!] = A$. We take this regular expression and transform it into regular expression \hat{r} as follow:

$$\widehat{1} = 1$$

$$\widehat{0} = 0$$

$$\widehat{a} = a$$

$$\widehat{r_1 + r_2} = \widehat{r_2} + \widehat{r_1}$$

$$\widehat{r_1 r_2} = \widehat{r_2} \cdot \widehat{r_1}$$

$$\widehat{r_1^*} = (\widehat{r_1})^*$$

Now, if [r] = A, then $[\hat{r}] = rev(A)$, and therefore rev(A) is regular.