
SUMMARY & SKILLS

I have a broad interest in computer science. My research interests include blockchain, mobile robotics, discrete mathematics, computational geometry, game theory, graph theory, and distributed computing.

Languages: Python, C/C++, Java, JavaScript

Technologies/Frameworks: Docker, Tendermint, Git, React

Graduate Courses: Advanced Algorithm Design, Distributed Systems, Formal Verification, Randomized Algorithms, Theory of Computation, Programming Languages, Operating Systems

EDUCATION

University of Southern California

Ph.D. in Computer Science; GPA: 4.0

Los Angeles, CA

Aug 2020 – Present

California State University, Long Beach

Master of Science in Computer Science; GPA: 4.0

Bachelor of Science in Computer Science; GPA: 3.6

Long Beach, CA

Aug 2018 – May 2020

Aug 2013 – May 2018

EXPERIENCE

The Aerospace Corporation

Casual Member of the Technical Staff

Member of the Technical Staff

Associate Member of the Technical Staff

Intern

El Segundo, CA

Aug 2020 – Present

Mar 2020 – Aug 2020

Sep 2018 – Mar 2020

Jan 2018 – Aug 2018

- Help build simulations for verifying flight software.
- Design software that helps Aerospace rapidly develop scalable, modular, and efficient analyses for launch vehicle verification in simulation, day-of-launch, and post-flight environments.

CSULB Research Foundation

Student Research Assistant

Long Beach, CA

Mar 2017 – May 2018

- Developed software and simulations for systems of cooperative robots.

PUBLICATIONS

Robotic Sorting on the Grid

Jared Coleman, Oscar Morales-Ponce

To Appear at ICDCN 2022 - 23rd International Conference on Distributed Computing and Networking

Message Delivery in the Plane by Robots with Different Speeds

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

To Appear at SSS 2021 - 23rd International Symposium on Stabilization, Safety, and Security of Distributed Systems

The Pony Express Communication Problem

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

In Proceedings IWOCA 2021 - 32nd International Workshop on Combinatorial Algorithms

Minimizing The Maximum Distance Traveled To Form Patterns With Systems of Mobile Robots

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Jorge Urrutia, Birgit Vogtenhuber

In proceedings CCCG 2020, 32nd Canadian Conference on Computational Geometry, August 5-7, 2020

PROJECTS

Secure IIoT

Using blockchain technology to secure industrial IoT systems

Autonomous Networks Research Group & Chevron

2021 – Present

Aerocube @ The Beach

Distributed robotics systems for space - a proof of concept

CSULB & The Aerospace Corporation

2017