Jared Coleman

jaredraycoleman.com

EDUCATION

University of Southern California

Los Angeles, CA

Ph.D. in Computer Science; GPA: 4.0

Aug 2020 - May 2024

Dissertation: Dispersed Computing in Dynamic Environments

Advisor: Bhaskar Krishnamachari

California State University, Long Beach

Long Beach, CA

Master of Science in Computer Science; GPA: 4.0

Aug 2018 - May 2020

Bachelor of Science in Computer Science; GPA: 3.6

Aug 2013 - May 2018

Thesis: Minimizing The Maximum Distance Traveled To Form Patterns With Systems of Mobile Robots

Advisor: Oscar Morales-Ponce

Research Interests

Cooperative multi-agent systems, distributed computing, decentralized computing, online algorithms, distributed ledger technology, internet of things (IoT), artificial intelligence (AI), and large language models (LLMs) for endangered language revitalization.

EXPERIENCE

Coinbase Remote Jan 2024 - Present Consultant - Machine Learning Engineer Loyola Marymount University Los Angeles, CA Assistant Professor Aug 2024 - Present El Segundo, CA The Aerospace Corporation Mar 2020 - Jun 2024 Member of the Technical Staff Associate Member of the Technical Staff Sep 2018 - Mar 2020 InternJan 2018 - Aug 2018

- Designed software and algorithms for rapidly developing scalable, modular, and efficient analyses for launch vehicle verification in simulation, day-of-launch, and post-flight environments.

CSULB Research Foundation

Long Beach, CA

Student Research Assistant

Mar 2017 - May 2018

- Developed software and simulations for systems of cooperative robots.

PUBLICATIONS

[19] Evaluating Scheduling Algorithms for Adaptive Orchestration in Federated Tactical Edge Cloud Environments

Alessandro Amato, Harrie Bastiaansen, Jared Coleman, Willem Datema, Mattia Fogli, Johan van der Geest, Bhaskar Krishnamachari, Thomas Kudla, Pablo Sanchez, Niranjan Suri

To Appear at ICMCIS 2025 — International Conference on Military Communications and Information Systems

[18] Multimodal Search on a Line

Jared Coleman, Dmitry Ivanov, Evangelos Kranakis, Danny Krizanc, Oscar Morales-Ponce To Appear at SIROCCO 2025 — International Colloquium on Structural Information and Communication Complexity

[17] PISA: An Adversarial Approach To Comparing Task Graph Scheduling Algorithms

 ${\it Jared~Coleman,~Bhaskar~Krishnamachari}$

To Appear at IPDPS 2025 - The 39th International Parallel and Distributed Processing Symposium

[16] LLM-Assisted Rule Based Machine Translation for Low/No-Resource Languages Jared Coleman, Bhaskar Krishnamachari, Khalil Iskarous, Ruben Rosales AmericasNLP @ NAACL 2024 - 4th Workshop on NLP for Indigenous Languages of the Americas

[15] Linear Search for an Escaping Target with Unknown Speed

Jared Coleman, Dmitry Ivanov, Evangelos Kranakis, Danny Krizanc, Oscar Morales-Ponce IWOCA 2024 — 35th International Workshop on Combinatorial Algorithms

[14] Online Allocation of Sensing and Computation in Large Graphs

Xinlin Li, Merve Karakas, Osama A. Hanna, Mehrdad Kiamari, Jared Coleman, Christina Fragouli, Bhaskar Krishnamachari, Gunjan Verma

IEEE CIC 2023 — International Conference on Collaboration and Internet Computing

[13] DARSAN: A Decentralized Review System Suitable for NFT Marketplaces

Sulyab Thottungal Valapu, Tamoghna Sarkar, Jared Ray Coleman, Anusha Avyukt, Hugo Embrechts, Dimitri Torfs, Michele Minelli, Bhaskar Krishnamachari

ICBC 2023 — International Conference on Blockchain

[12] Search and Rescue on the Line

Jared Coleman, Lorand Cheng, Bhaskar Krishnamachari
SIROCCO 2023 — International Colloquium on Structural Information and Communication Complexity

[11] PhD Forum Abstract: Cooperative Problem-Solving with Systems of Constrained Mobile Agents

Jared Ray Coleman

IPSN 2023 — International Conference on Information Processing in Sensor Networks

[10] Graph Convolutional Network-based Scheduler for Distributing Computation in the IoRT

Jared Coleman, Mehrdad Kiamari, Lillian Clark, Daniel D'Souza, Bhaskar Krishnamachari MILCOM 2023 WS-7 — Workshop On The Internet Of Things For Adversarial Environments

[9] Delivery to Safety with Two Cooperating Robots

Jared Coleman, Evangelos Kranakis, Danny Krizanc, Oscar Morales-Ponce SOFSEM 2023 — International Conference on Current Trends in Theory and Practice of Computer Science

[8] The Snow Plow Problem: Perpetual Maintenance by Mobile Agents on the Line

Jared Coleman, Oscar Morales-Ponce

ICDCN 2023 — International Conference on Distributed Computing and Networking

[7] Line Search for an Oblivious Moving Target

Jared Coleman, Evangelos Kranakis, Danny Krizanc, Oscar Morales-Ponce OPODIS 2022 — International Conference on Principles of Distributed Systems

[6] Multi-Objective Network Synthesis for Dispersed Computing in Tactical Environments

Jared Coleman, Eugenio Grippo, Bhaskar Krishnamachari, Gunjan Verma SPIE Defense + Commercial Sensing 2022

[5] Network Synthesis for Tactical Environments: Scenario, Challenges, and Opportunities

Tzanis Anevlavis, Jonathan Bunton, Jared Coleman, Mine Dogan, Eugenio Grippo, Abel Souza, Christina Fragouli, Bhaskar Krishnamachari, Matthew Maness, Karl Olson, Prashant Shenoy, Paulo Tabuada, Gunjan Verma SPIE Defense + Commercial Sensing 2022

[4] Robotic Sorting on the Grid

Jared Coleman, Oscar Morales-Ponce

ICDCN 2022 — 23rd International Conference on Distributed Computing and Networking

[3] Message Delivery in the Plane by Robots with Different Speeds

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

SSS 2021 — 22rd International Symposium on Stabilization, Safety and Security

SSS 2021 — 23rd International Symposium on Stabilization, Safety, and Security of Distributed Systems

[2] The Pony Express Communication Problem

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Danny Krizanc

IWOCA 2021 — 32nd International Workshop on Combinatorial Algorithms

[1] Minimizing The Maximum Distance Traveled To Form Patterns With Systems of Mobile Robots

Jared Coleman, Evangelos Kranakis, Oscar Morales-Ponce, Jorge Urrutia, Birgit Vogtenhuber CCCG 2020, 32nd Canadian Conference on Computational Geometry, August 5-7, 2020