

Announcements

- Quiz 2 due tonight at midnight!
- PA1 is due Sunday at midnight!
- PA2 and PA3 are SIGNIFICANTLY MORE WORK THAN PA0 and PA1
- Interview grading is <u>NEXT WEEK</u>
 - Schedule your place <u>TODAY</u> on Canvas Calendar
- Recitation materials: https://tinyurl.com/CSCI3753

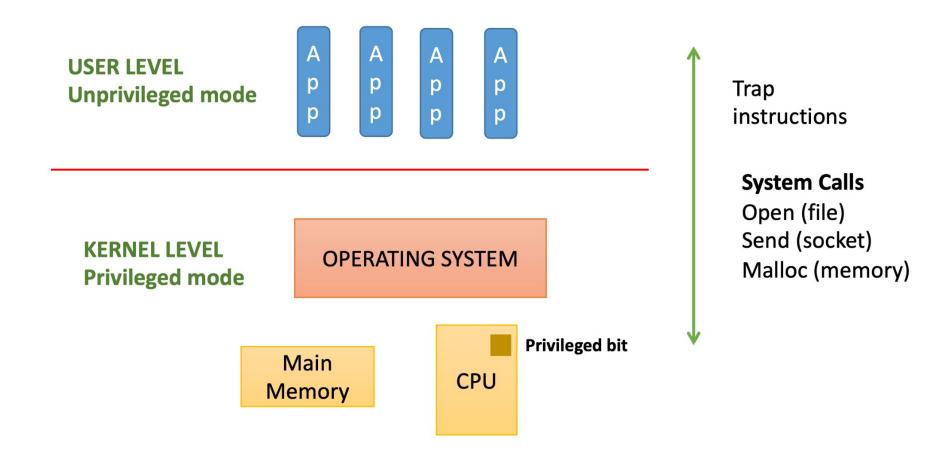
Recap

- Bootloader
- User/Kernel space
- System calls
 - Trap tables
- PA0

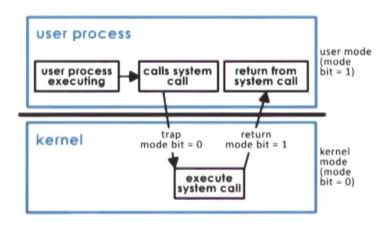


PA1 🔁

User/Kernel Protected Boundary



System Call Flow

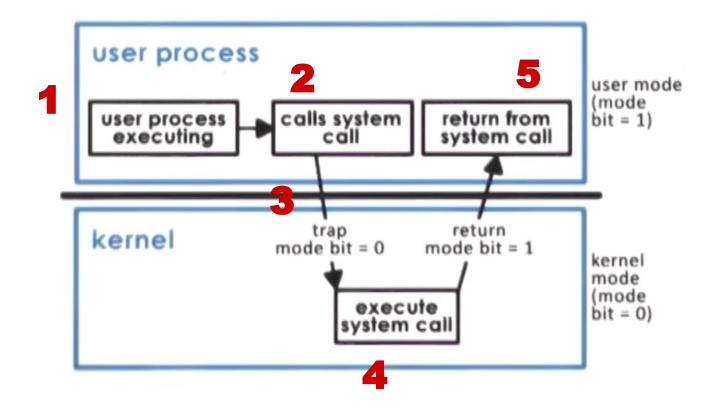


- To make a system call a program must:
 - write arguments
 - save relevant data to a defined location
 - make call using the specific system call number

Executing System Call

- A user space program invokes the syscall
- 2. A (usually) software interrupt is called and a trap is triggered (INT)
- 3. Mode bit is flipped from user to kernel (1 to 0)
- 4. The interrupt informs the kernel which syscall is needed
 - Requisite data is retrieved
 - Kernel verifies if all parameters are valid before executing the syscall
- 5. After execution, mode bit flips and user program resume

System Call Flow



- 1. Write the system call source code
- 2. Add the new syscall to the Makefile
- 3. Add the syscall to the syscalls table
- 4. Add the syscall prototype to the syscalls header file
- 5. Recomile, install, boot into mod'd kernel

1. Write the system call source code

```
#include <linux/kernel.h>
#include <linux/linkage.h>
#include <linux/syscalls.h>

SYSCALL_DEFINEO(helloworld)
{
   printk(KERN_ALERT "hello world\n");
   return 0;
}
```

- 1. Add the new syscall to the Makefile
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- 1. Write the system call source code
- 2. Add the new syscall to the Makefile
 - a. within './arch/x86/kernel/Makefile' add the line:

obj-y+=helloworld.o

- 1. Add the syscall to the syscalls table
- 2. Add the syscall prototype to the syscalls header file
- 3. Recomile, install, boot into mod'd kernel

- 1. Write the system call source code
- 2. Add the new syscall to the Makefile
- 3. Add the syscall to the syscalls table
 - a. Within file './arch/x86/entry/syscalls/syscall_64.tbl' add:

447	common	helloworld	sys_helloworld
	Common	HELLOWOI LU	Sys_Herroworra

- 1. Add the syscall prototype to the syscalls header file
- 2. Recomile, install, boot into mod'd kernel

- 1. Write the system call source code
- 2. Add the new syscall to the Makefile
- 3. Add the syscall to the syscalls table
- 4. Add the syscall prototype to the syscalls header file
 - a. Within the file './include/linux/syscalls.h' add the line:

```
asmlinkage long sys_helloworld(void);
```

1. Recomile, install, boot into mod'd kernel

- 1. Write the system call source code
- 2. Add the new syscall to the Makefile
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- 5. Recomile, install, boot into mod'd kernel

```
cd /home/kernel/linux-hwe-5.13-5.13.0
make -j10
sudo make modules_install
sudo make install
sudo reboot now
```

Loadable Kernel Module (LKM)

- LKM is a chunk of code we add to the Linux kernel while it is running
- Most often we do this with these modules:
 - Device drivers
 - Filesystem drivers
 - System calls

Loadable Kernel Module (LKM)

- LKMs are part of the kernel, once loaded
 - The part of the kernel bound to the machine image on boot is "base kernel"
- LKMs communicate with the base kernel

- 1. Write LKM code
- Add module to Makefile
- 3. Compile the module to get the .o file
- 4. Insert the mod into the running kernel

Write LKM code

Create a directory, /home/kernel/modules, and edit a new file named helloModule.c. Populate this file with the following code:

```
#include<linux/init.h>
#include<linux/module.h>

MODULE_AUTHOR("Your Name");
MODULE_LICENSE("GPL");
int hello_init(void) {
   printk(KERN_ALERT "inside %s function\n",__FUNCTION__);
   return 0;
}

void hello_exit(void) {
   printk(KERN_ALERT "inside %s function\n",__FUNCTION__);
}

module_init(hello_init);
module_exit(hello_exit);
```

- Add module to Makefile
- 2. Compile the module to get the .o file
- 3. Insert the mod into the running kernel

- 1. Write LKM code
- 2. Add module to Makefile

obj-m:=helloModule.o

- 1. Compile the module to get the .o file
- 2. Insert the mod into the running kernel

- 1. Write LKM code
- 2. Add module to Makefile
- 3. Compile the module to get the .o file

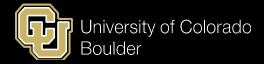
```
make -C /lib/modules/$(uname -r)/build M=$PWD
```

1. Insert the mod into the running kernel

- 1. Write LKM code
- 2. Add module to Makefile
- 3. Compile the module to get the .o file
- 4. Insert the mod into the running kernel

```
user@csci3753:/home/kernel/modules$ sudo insmod helloModule.ko user@csci3753:/home/kernel/modules$ lsmod | grep hello helloModule 16384 0
```

Much faster!



Why Use LKMs?

- We DON'T have to rebuild the kernel
- Help diagnose system problems
 - A device driver bug could bring down the kernel/entire system
- Save memory
 - Only load kernels when necessary
- Much faster to maintain, debug, and deploy

LKM Utilities

- insmod insert LKM into kernel
- rmmod remove LKM from kernel
- Ismod list currently loaded LKMs
- kernels kernel daemon program (for automation)
- modprobe ins/rm one or multiple LKMs intelligently
 - e.g., if mod A must be loaded before mod B, modprobe will automatically load mod A if you request mod B
- depmod determine mod interdependency
- ksyms display symbols exported for the new LKM
- modinfo displays LKM info from .modinfo section of LKM obj file

Passing Data Safely Between User/Kernel Space

- copy_from_user
- copy_to_user
- strnlen_user
- strncpy_from_user
- get_user
- put_user

Where are we getting this from? Kernel Memory Access PDF on Canvas

PA₁

- What questions do you all have?
- How many people have already finished?
- What has been the hardest part to complete?