```
function a = acceleration(pos)
a = - [pos(1)/(pos(1)^2+pos(2)^2)^(3/2); pos(2)/(pos(1)^2+pos(2)^2)^(3/2)];

end
```

```
Not enough input arguments.
Error in acceleration (line 2)
a = - [pos(1)/(pos(1)^2+pos(2)^2)^(3/2); pos(2)/(pos(1)^2+pos(2)^2)^(3/2)];
```

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