#### Faculty of Mathematics, Physics and Informatics Comenius University in Bratislava



# **Neural Networks**

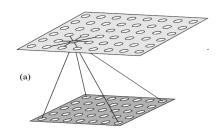
Lecture 7

# **Self-organizing map**

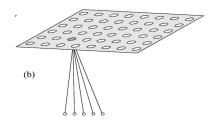
Igor Farkaš 2018

# Feature mapping

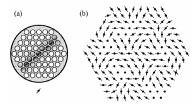
biologically motivated models



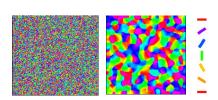
model with extracted features



e.g. mapping from retina to cortex -> orientation map



- introduced topology of neurons in the map
- winner-take-most due to neuron cooperation

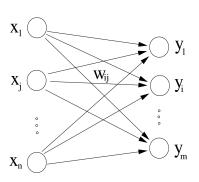


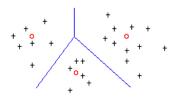
# Simple competitive learning

- · unsupervised learning
- linear neurons
- winner:  $y_{i*} = \max_i \{ \boldsymbol{w}_i^T . \boldsymbol{x} \}$ 
  - i.e. best matching unit i\*
- · winner-take-all adaptation:

$$\Delta w_{i*} = \alpha (x - w_{i*}) \qquad \alpha \in (0,1)$$
$$\|w_{i*}\| = 1$$

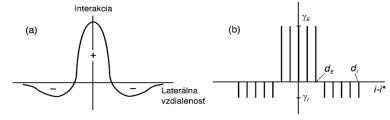
- · risk of "dead" neurons
- algorithm: in each iteration:
  - (1) find winner, (2) adapt its weights
- · useful for clustering





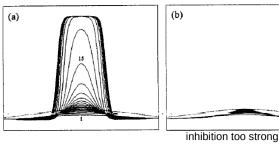
## Lateral interactions in the map

Mexican hat function (1D case)



$$y_i(t+1) = s(z_i + \sum_{k=-K}^{K} l_{ik}.y_{i+k}(t))$$

initial response  $z_i = w_i^T \cdot x$ 



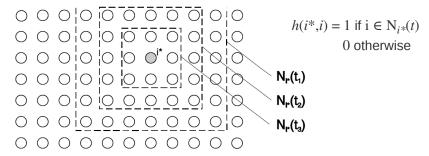


inhibition too weak

(Farkaš, 1997)

### Neighborhood function in SOM

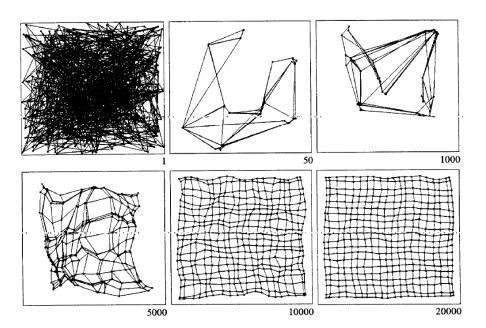
- computationally efficient substitute for lateral interactions
- neurons adapt only within the winner neighborhood
- neighborhood radius decreases in time
- rectangular neighborhood (below)



• alternative: gaussian neighborhood, e.g.

$$h(i^*, i) = \exp\left\{-\frac{d_E^2(i^*, i)}{\lambda^2(t)}\right\}$$
$$\lambda(t) = \lambda_i \cdot (\lambda_f/\lambda_i)^{t/t_{max}}$$

## Example: 2D random inputs, 20x20 neurons



### SOM algorithm (ED version\*)

(Kohonen, 1982)

• randomly choose an input x

Neighborhood size  $\lambda$ 

Ordering

• find winner *i*\* for *x* 

$$i^* = \operatorname{arg\,min}_i \| \mathbf{x} - \mathbf{w}_i \|$$

• update weights within the neighborhood

$$\mathbf{w}_{i}(t+1) = \mathbf{w}_{i}(t) + \alpha(t)h(i*,i)[\mathbf{x}(t) - \mathbf{w}_{i}(t)]$$

- update SOM parameters (neighborhood, learning rate)
- repeat until stopping criterion is met

fine-tuning

derived from a general Hebbian form:

$$\Delta w_i = \alpha y_i x - g(y_i) w_i$$

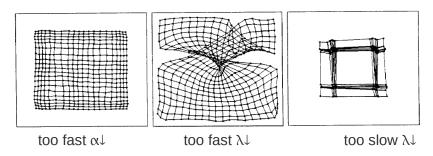
SOM as input-output mapping:

$$x \rightarrow \{1, 2, ..., m\}$$

$$\boldsymbol{x} \rightarrow \boldsymbol{y}, \quad \boldsymbol{y} = [y_1, y_2, ..., y_m]$$

where e.g.  $y_i = \exp(-\|x - w_i\|^2)$ 

## Special effects



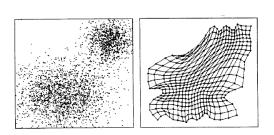


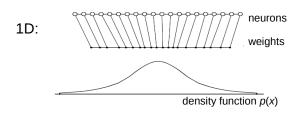
<sup>\*</sup> i.e. based on Euclidean distance

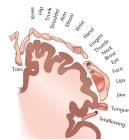
### Magnification property

• SOM roughly approximates input data distribution

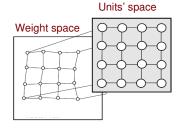
2D:







Somatosensory homunculus in the brain



Theory for 1D:  $w(x) \propto p(x)^{2/3}$  (Ritter, 1991)

## SOM simultaneously performs two tasks

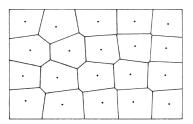
#### Vector quantization

(if number of inputs > number of neurons)

Voronoi compartments:

$$V_i = \{x \mid ||x - w_i|| < ||x - w_i||\}, \ \forall j \neq i$$

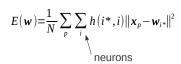
Quant. error:  $QE = \frac{1}{N} \sum_{p} ||\mathbf{x}_{p} - \mathbf{w}_{i*}||^{2}$ 



Voronoi tessellation

#### Topology preserving mapping

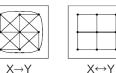
Cost function e.g. (Kohonen, 1991)











various measures of topology preservation proposed

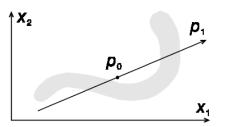
## Main properties of SOM

- Approximation of the input space (input data) by the grid of neurons → vector quantization theory
- Topological ordering preservation of similarities between input and output spaces
- Density matching reflecting the variations in the statistics of input distribution
- Feature selection via nonlinear mapping → principal curves or surfaces (Hastie and Stuetzle, 1989)
  - SOM as a nonlinear generalization of PCA

# Comparison of SOM to PCA

• feature extraction and mapping, difference in feature representation

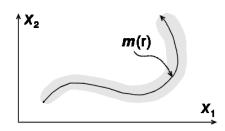
**PCA** 



(linear) principal components One unit represents 1 dimension

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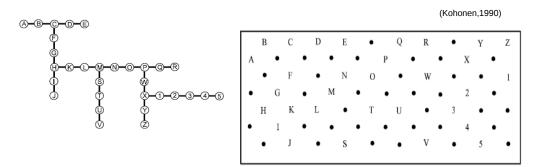
SOM



(nonlinear) principal manifold More units represent 1 dimension 10

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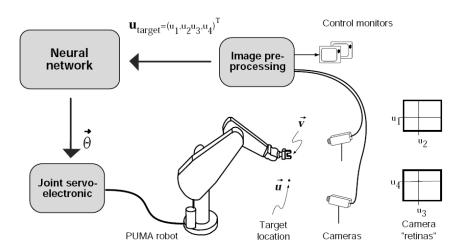
## Application: Minimum spanning tree



#### Input vector encoding:

Α	В	С	D	Е	F	G	Н	Ι	J	K	L	Μ	N	О	Р	О	R	S	Т	U	V	W	Х	Y	Z	1	2	3	4	5
1	2	3	4	5	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
0	0	0	0	0	1	2	3	4	5	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
																														6
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	2	3	4	1	2	3	4	2	2	2	2	2
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	2	3	4	5

# Application: Robotic arm control



$$\begin{split} \theta(\mathbf{u}) &= \theta_i + \mathbf{A}_i.(\mathbf{u} - \mathbf{w}_i) & \qquad \mathbf{w}_i \leftarrow \mathbf{w}_i + \varepsilon.h(i,i^*).(\mathbf{u} - \mathbf{w}_i) \\ \theta_i \leftarrow \theta_i + \varepsilon.h(i,i^*).\Delta\theta_i \\ \mathbf{A}_i \leftarrow \mathbf{A}_i + \varepsilon.h(i,i^*).\Delta\mathbf{A}_i \end{split}$$
 (Walter & Schulten 1993)

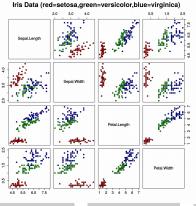
## Application: Data visualization

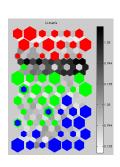
- 7x10 SOM with hexa grid
- trained on 4D Iris data
- 3 classes

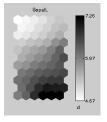
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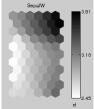
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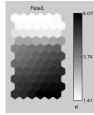
- · Neuron labels generated
- · according to votes
- Plots of component weights reveal an order

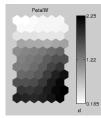






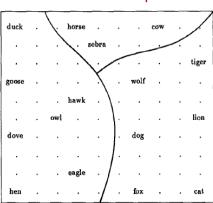






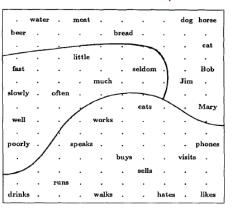
# Application: Semantic maps

#### Attribute map



Words  $\mathbf{x} = [\mathbf{x}_{symbol}; \mathbf{x}_{attr}]$ , i.e. concatenation of (16-dim) symbolic (one-hot) and binary attribute vectors (13-dim), of 3 categories (is, has, likes to). Testing done using  $\mathbf{x} = [\mathbf{x}_{symbol}; \mathbf{0}]$ .

#### Role-based map



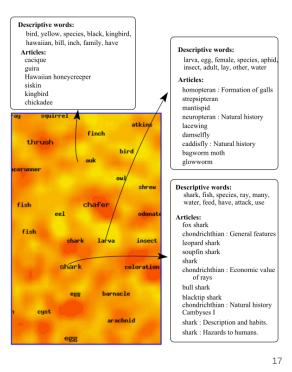
Words represented in contexts, i.e.  $x = [x_{symbol}; x_{context}]$ , using sentence templates [noun - verb - adverb/noun]. Symbol = 7-dim. vector (of unit length), (average L-R) context = 14-dim. (random projection used). Labeling based on  $x = [x_{symbol}; 0]$ .

(Ritter & Kohonen, 1989)

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## **Application: WEBSOM**

- e.g. collection of cca 12000 Encyclopaedia Britannica documents
- Used for information retrieval
- Random mapping (of word vectors) useful: preserves similarities
- Based on co-occurrence of 40000 words in documents
- SOM with cca 12000 nodes



(Kaski et al, 1998)

### **Dot-product version of SOM**

- randomly choose an input x
- find winner *i*\* for *x*

$$i^* = \operatorname{arg\,max}_i \{ \boldsymbol{x}^T \cdot \boldsymbol{w}_i \}$$

· update weights within the neighborhood

$$w_{i}(t+1) = \frac{w_{i}(t) + \alpha(t) \cdot h(i^{*}, i) \cdot x(t)}{\|w_{i}(t) + \alpha(t) \cdot h(i^{*}, i) \cdot x(t)\|}$$

- update SOM parameters (neighborhood, learning rate)
- repeat until stopping criterion is met

Example: DP-SOM map trained on 3D vectors  $\mathbf{s} = [s_1, s_2, s_3]$  created from 2D  $\mathbf{x} = [x_1, x_2]$  as

$$s_1 = 1 \cdot \cos(x_1) \cdot \cos(x_2)$$

$$s_2 = 1 \cdot \sin(x_1) \cdot \cos(x_2)$$

$$s_3 = 1 \cdot \sin(x_2)$$

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(a) (b) (c) (c) (1000 10000

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· Weight vector ordering independent of the input vectors' norms

## Related self-organizing NN algorithms

• Can be viewed as unsupervised data approximation with undirected graph G = (V,C),  $V = \{\mathbf{w}_i\}$  ~ vertices,  $C[m \times m]$  ~ (symmetric) connection matrix

#### Examples:

- Topology-Representing network (Martinetz & Schulten 1994)
  - Flexible net topology, fixed number of units
- Growing Cell Structures (Bruske & Sommer, 1995)
  - Flexible topology and number of units (they can be removed or added based on max. quantization error)
- useful for non-stationary data distributions

## Summary

- self-organizing map a very popular algorithm
  - principles of competition and cooperation, unsupervised learning
  - performs vector quantization and topology-preserving mapping
- · useful for data clustering and visualization
- theoretical analysis of SOM limited to simple cases
- · various self-organizing algorithms developed
  - main purpose: data clustering
  - not all implement dimensionality-reducing mapping
  - flexible architectures possible

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