

EECS 510 Final Project

Andrew Huang and John Rader

May 2025

1. General Description

blah blah blah

testing doing this locally i guess if it compiles, it compiles

testing again

2. Grammar for the Language

Move Name for each State (Paired together for general buttons/functionality):

S is the initial variable for the beginning of a combo

State	Name
S	Neutral State
q_{ss}	Side Smash
q_{os1}	Overhead Smash I
q_{os2}	Overhead Smash II
q_u	Upswing
q_{bb1}	Big Bang I
q_{bb2}	Big Bang II
q_{bb3}	Big Bang III
q_{bb4}	Big Bang IV
q_{bbf}	Big Bang Finisher
q_{sb1}	Spinning Bludgeon (Time 0)
q_{sb2}	Spinning Bludgeon (Time 1)
q_{sb3}	Spinning Bludgeon (Time 2)
q_{c1}	Charge (Time 0)
q_{c2}	Charge (Time 1)
q_{c3}	Charge (Time 2)
q_{csb}	Charged Side Blow
q_{cu}	Charged Upswing
q_{cbb}	Charged Big Bang
q_{cfu}	Charged Follow-up
q_{mc1}	Mighty Charge (Time 0)
q_{mc2}	Mighty Charge (Time 1)
q_{mcu}	Mighty Charge Upswing
q_{mcs}	Mighty Charge Slam
q_{fben}	Focus Blow: Earthquake (No Wound)
q_{fbew1}	Focus Blow: Earthquake (Wound Option 1)
q_{fbew2}	Focus Blow: Earthquake (Wound Option 2)

$$\begin{aligned}
S &\rightarrow yq_{os1} \mid bq_{bb1} \mid r_2q_{c1} \mid (l_2r_1)q_{fben} \mid (l_2r_1)q_{fbew1} \mid (ly)q_{ss} \mid \lambda \\
q_{ss} &\rightarrow yq_{os2} \mid bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_{os1} &\rightarrow yq_{os2} \mid bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_{os2} &\rightarrow yq_u \mid bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_u &\rightarrow bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid (r_2yb)q_{mc1} \mid S \\
q_{bb1} &\rightarrow bq_{bb2} \mid r_2q_{c1} \mid S \\
q_{bb2} &\rightarrow bq_{bb3} \mid r_2q_{c1} \mid S \\
q_{bb3} &\rightarrow bq_{bb4} \mid r_2q_{c1} \mid S \\
q_{bb4} &\rightarrow bq_{bbf} \mid (r_2yb)q_{mc1} \mid r_2q_{c1} \mid S \\
q_{bbf} &\rightarrow r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_{sb1} &\rightarrow q_{sb2} \mid yS \\
q_{sb2} &\rightarrow q_{sb3} \mid yS \\
q_{sb3} &\rightarrow S? \mid yS? \\
q_{c1} &\rightarrow q_{c2} \mid r_2q_{csb} \mid yq_{csb} \mid bq_{cs1} \mid (l_2r_1)q_{fben} \mid (l_2r_1)q_{fbew1} \\
q_{c2} &\rightarrow q_{c3} \mid r_2q_{csu} \mid yq_{csu} \mid bq_{cs2} \mid (l_2r_1)q_{fben} \mid (l_2r_1)q_{fbew1} \\
q_{c3} &\rightarrow r_2q_{cbb} \mid yq_{cbb} \mid bq_{cs3} \mid (yb)q_{sb1} \mid (l_2r_1)q_{fben} \mid (l_2r_1)q_{fbew1} \\
q_{csb} &\rightarrow yq_{cfu} \mid bq_{ss} \mid r_2q_{c1} \mid S \\
q_{cu} &\rightarrow yq_{cfu} \mid bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_{cbb} &\rightarrow r_2q_{c1} \mid (yb)q_{sb1} \mid yq_{os1} \mid bq_{bb1} \mid (ly)q_{ss} \mid S \\
q_{cfu} &\rightarrow yq_{os1} \mid bq_{bb1} \mid r_2q_{c1} \mid (yb)q_{sb1} \mid S \\
q_{mc1} &\rightarrow q_{mc2} \mid l_2q_{mcu} \mid yq_{mcu} \\
q_{mc2} &\rightarrow l_2q_{mcs} \mid yq_{mcs} \\
q_{mcu} &\rightarrow yq_{os1} \mid (ly)q_{ss} \mid bq_{bb1} \mid (yb)q_{sb1} \mid S \\
q_{mcs} &\rightarrow (yb)q_{sb1} \mid yq_{os1} \mid (ly)q_{ss} \mid bq_{bb1} \mid S \\
q_{fben} &\rightarrow bq_{bb1} \mid r_2q_{c1} \mid S \\
q_{fbew1} &\rightarrow r_2q_{c1} \mid q_{fbew2} \\
q_{fbew2} &\rightarrow r_2q_{c1} \mid yq_{os2} \mid S
\end{aligned}$$

3. Automaton

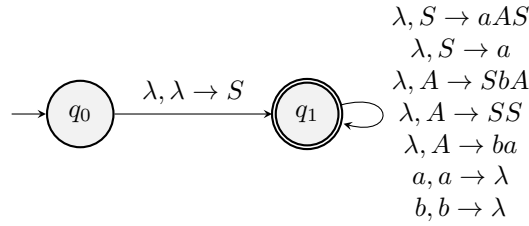


Figure 1: Automaton for language

4. Data Structure

5. Testing