

FINAL REPORT

AUTOMATIC TUNING OF DBMS USING MACHINE LEARNING

CMU 10-701: MACHINE LEARNING (FALL 2014)

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Abstract

Modern database systems are highly configurable and must support a wide variety of workloads. However, tuning these systems is challenging. Configuration assistants like Microsoft's AutoAdmin [1] allow administrators to use statistics and suggestions from the database system to guide the physical design of the database. However, these methods still require experienced administrators and prior knowledge about the workload. We apply machine learning methods to automate database system tuning with minimal user input and knowledge by mapping workloads to representative benchmarks and then estimating performance metrics using a machine learning model without actually running the workload. Our experiments show that a CART-based decision tree classifier achieves 91% accuracy on the classification problem. We also demonstrate that a Gaussian process regression estimator has a R-squared score of 0.9 for estimating the throughput of the DBMS while executing a SQL workload under a given DBMS configuration.

1. Introduction

1.1. Motivation

DBMS tuning is a niche skill that involves configuring the DBMS suitably for the underlying hardware as well as guiding the physical design of the database. Doing these tasks effectively requires a deep knowledge of the SQL workload to be run on the DBMS, extensive prior experience in DBMS tuning, as well as significant amounts of time-consuming experimentation with candidate configurations. This issue is prevalent across several widely used database management systems. For instance, Robert Hass, a core developer of PostgreSQL, stated that [6] :

“On one test, involving 32 concurrent clients, I found that wal_buffers = 64 MB doubled performance as compared with wal_buffers = 16 MB; however, on another system, I found that no setting I tried produced more than a 10 % improvement over the auto-tuning formula.”

We therefore propose applying machine learning methods to automate the process of tuning the DBMS for a particular workload on a specific machine.

1.2. Problem definition

We address two problems in this project. First, we try to map a given workload comprised of a set of SQL transactions to a standard database benchmark workload. This problem is independent of the underlying DBMS or hardware configuration. This will allow us to use prior knowledge about the standard benchmark gained from previous DBMS deployments.

We collect features that characterize the SQL workload as well as DBMS statistics. We then use unsupervised techniques like clustering and supervised techniques like decision-trees for mapping the workload. Performance analysis of the resulting classifier is done via cross-validation.

Second, we plan to estimate the DBMS performance given a DBMS configuration, hardware setup and SQL workload. This is done with supervised techniques like Gaussian process regression. We use the lasso regression estimator to identify key features that influence the throughput and average transactional latency of the DBMS. Performance analysis of the estimator is also done using cross-validation. We describe our progress on solving these problems in this report.

The goals of this project are the following :

- to create a workload mapper that maps an arbitrary SQL workload to a well-known standard benchmark
- to estimate the performance metrics of a DBMS given a workload and configuration pair

We first describe how we generate the dataset in Section 2. Then, we focus on the feature extraction problem in Section 3. We describe our experimental setup and dataset information in Section 4. The evaluation results obtained for the classification problem and the estimation problem are shown in Section 5 and Section 6 respectively. Finally, we present the conclusions of this project in Section 7.

2. Data Set

The dataset required for this project would ideally comprise of a collection of real world SQL workloads, DBMS configurations and performance metrics. Collecting and curating such a dataset is itself an interesting problem. However, in this project, we first want to experiment with a smaller dataset to better understand the features relevant for our learning problem. Therefore, we chose to generate the dataset using OLTP-Bench [5], an extensible DBMS benchmarking frame-

work. We use the SQL workloads of standard benchmarks already available in OLTPBench.

We generate more synthetic variants of these workloads for training and testing purposes. As we mentioned earlier, while this synthetic data will not be representative of real-world workloads, we feel it is a good starting point for evaluating viability of the approach outlined above. We extract several features from the workload such as types of database queries, distribution of query types, and table access patterns using a workload analyzer. We hook this analyzer into Postgres [11] to collect features from the DBMS.

The key reasons for why we use OLTP-Bench framework to generate the dataset are the following:

- It supports several relational DBMSs through the JDBC interface including Postgres, MySQL, and Oracle.
- It allows us to control the workload mixture in a benchmark. For instance, we can adjust the percent of read and update transactions in the YCSB [3] benchmark to generate different variants of the workload.
- It supports user-defined configuration of the rate at which the transaction requests are submitted to the DBMS. This allows us to emulate different world workloads with varying degrees of concurrency.
- It exposes statistics that are complementary to the internal statistics of the DBMS [4]. We extract features from these statistics.

We implemented a dataset generator that runs different benchmarks supported by OLTP-Bench on a Postgres DBMS. After every workload execution, we collect statistics from the DBMS as well as from the testbed. We alter the workload mixture in all the benchmarks to generate different variants and emulate real world workloads. The key characteristics of the benchmarks that we use for generating the dataset are presented in Table 1.

3. Feature Extraction

We collect three types of features from both the DBMS as well as the benchmarking framework.

3.1. Features from OLTP-Bench

After executing the benchmark, we obtain statistics about the latency and throughput delivered by the DBMS. This includes both temporal performance metrics as well as aggregate metrics. We also record the type of DBMS used. Although currently we focus only on Postgres[11], we anticipate this tool to be useful for other DBMSs as well. We also record the expected label i.e. the benchmark name. This is used for evaluating the accuracy of our classification algorithms.

3.2. Static parameters from Postgres

Static parameters are features that do not vary over every execution. This primarily includes the configuration parameters of the DBMS and the hardware setup. For example, these are

some of the static parameters that we use as features:

- Size of shared memory buffers: This impacts the performance of memory-intensive queries significantly.
- Background writer delay: The background writer issues writes of dirty shared buffers to disk. This increases the net overall I/O load but allows server processes to avoid waiting for writes to finish.
- Vacuum cost delay: The vacuum process performs garbage collection. Very short delays can impact the DBMS performance.
- WAL level: The type of write-ahead logging performed - minimal, archive, or hot standby - affects the logging overhead.
- fsync: Durability requirements of data.
- Sequential page cost: Used in the cost model of the DBMS' planner.
- Hardware features: CPU cache sizes, DRAM size, disk size, cache latency, DRAM latency and disk latency.

Overall, these metrics significantly impact the performance of the DBMS. A non-expert user might not be able to configure these parameters to obtain good performance. Our tuning tool can help such users by automatically identifying a good DBMS configuration for a given workload.

3.3. Dynamic parameters from Postgres

We also collect dynamic parameters from the DBMS during feature extraction. To do this, we implemented a Postgres driver that queries the DBMS's internal catalog tables like `pg_stat_database`, `pg_statio_user_indexes`, `pg_stat_activity` and `pg_stat_user_table` to obtain useful workload parameters. For instance, these are some of the dynamic parameters that we use as features :

- Number of transactions in this database that have been committed or rolled back.
- Number of disk blocks read in this database.
- Number of times disk blocks were found already in the DBMS's buffer cache.
- Number of rows returned, fetched, inserted, updated or deleted by queries in this database.
- Number of index and cache blocks hit.
- Status of different storage backends of the DBMS.
- Size of the tables and indexes in the DBMS.
- Number of sequential scans and index scans performed by the workload.

We normalize the relevant metrics by the number of transactions executed. Before the start of an execution, we reset all the statistics using our DBMS driver. Overall, this gives us a nice set of features about the workload.

After collecting all these features, we transform them to a metric space and normalize them to generate a feature matrix

Benchmarks	Tables	Columns	Pr. Keys	Indexes	Fr. Keys	Txn. Types	# of Joins	Application domain	Attributes
AuctionMark	16	125	16	14	41	10	10	Online Auctions	Non-deterministic heavy transactions
Epinions	5	21	2	10	0	9	3	Social Networking	Joins over many-to-many relationships
SEATS	10	189	9	5	12	6	6	Online Airline Ticketing	Secondary indices queries
TATP	4	51	4	5	3	7	1	Caller Location App	foreign-key joins
TPC-C	9	92	8	3	24	5	2	Order Processing	Short, read-mostly non-conflicting transactions
Twitter	5	18	5	4	0	5	0	Social Networking	Write-heavy transactions
Wikipedia	12	122	12	40	0	5	2	Online Encyclopedia	Client-side joins on graph data
YCSB	1	11	1	0	0	6	0	NoSQL store	Complex transactions large data, skew
									Key-value queries

Table 1: Key characteristics of the benchmarks used in our evaluation. “Pr. key” denotes primary key and “Fr. key” denotes foreign key.

and a label matrix. This is used by the classification algorithms that we describe in the next section.

4. Experimental Setup

We address two problems in our experiments :

- Mapping a SQL workload to a benchmark class.
- Estimating the performance of the DBMS using the features and the class model without actually executing the workload.

We first describe the experimental setup and later present information about the dataset. All our experiments are performed on a machine with 8-core Intel i7-3770 running at 3.7 GHz. The system has 16 GiB DRAM. The L2 and L3 cache sizes are 256 KiB and 8 MiB respectively. We deploy Linux kernel 3.2.0 on the machine and disable logical processor support. We use the Scikit [8] framework in Python 3 for evaluating different machine learning algorithms. Our auto-tuning framework currently only supports Postgres 9.5. We plan to extend it to support other database management systems like MySQL in future work.

The dataset consists of 10 benchmark classes. These include all the benchmarks described in Table 1. We consider 4 variants of the YCSB key-value store benchmark. These variants map to different read-write mixtures and are listed below :

- Read-only : 100% reads 0% writes
- Read-heavy : 80% reads 20% writes
- Balanced : 50% reads 50% writes
- Write-heavy : 20% reads 80% writes

We added these variants to stress-test the classifiers and estimators as these variants can overlap with other benchmark classes along some dimensions in high-dimensional space.

For each DBMS run, we first generate a configuration by picking values for 12 key configuration parameters listed in Table 2. We then select a random benchmark and alter the transaction mix of the benchmark i.e. the proportion of different types of transactions in the specific benchmark. After running the benchmark for atleast more than 1 minute, we halt the system, and collect the dynamic features from the DBMS and the benchmarking framework. We also collect the static features from the specific DBMS configuration. These features and metrics constitute one sample in the dataset. Each sample consists of 263 features and our dataset consists of 1000 such samples.

5. Classification

We approach the problem of mapping a workload to a standard benchmark class using two techniques.

5.1. Clustering

Clustering was our first approach as an unsupervised algorithm seemed to best fit the data at hand. We evaluated the following clustering algorithms in Scikit.

- **K-Means** : This algorithm clusters the samples into groups of similar variance by minimizing the within-cluster sum-of-squares. The number of clusters needs to be specified. The algorithms scales well to a large number of samples. Given a set of n samples X , the algorithm splits them into K disjoint clusters, wherein each cluster is defined by the mean μ_k of the samples in the cluster i.e. the centroids of the cluster. The algorithm minimizes the within-cluster sum-of-squares criterion:

$$\sum_{i=0}^n \min_{\mu_k \in C} (\|x_k - \mu_i\|^2)$$

Feature name	Feature meaning	Default value	Mutated value set
shared_buffers	Number of shared memory buffers used by the database server	128 MB	[4 MB, 32 MB, 128 MB, 512 MB]
bgwrite_delay	Delay between rounds for the background writer	100 ms	[100 ms, 1000 ms, 10000 ms]
wal_level	Type of logging	minimal	[minimal, archive, hot_standby, logical]
fsync	Forced synchronization to disk	on	[on, off]
synchronous_commit	Whether transaction commit will wait for WAL records to be flushed	on	[on, off, local, remote_write]
wal_buffers	Number of disk-page buffers in shared memory for WAL	-1	[-1, 4 MB, 32 MB, 128 MB]
wal_writer_delay	Specifies the delay between rounds for the WAL writer	200 ms	[100 ms, 200 ms, 1000 ms, 10000 ms]
commit_delay	Time delay between writing a commit record to the WAL buffer	0 μ s	[0 μ s, 1000 μ s, 1000 μ s, 10000 μ s]
track_activities	Collect query/index statistics	on	[on, off]
log_planner_stats	Log planner statistics	off	[on, off]
debug_print_plan	Print plans in log	off	[on, off]
autovacuum	Enable autovacuum subprocess	on	[on, off]

Table 2: Configuration attributes that we mutate in each DBMS run.

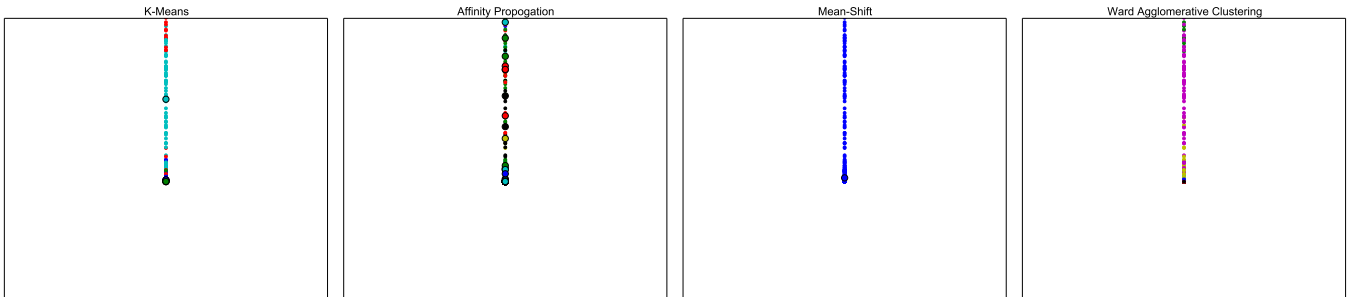


Figure 1: Clusters found by the clustering algorithms.

- **Affinity Propagation:** This algorithm creates clusters by passing messages between pairs of samples till it reaches convergence. The clusters are described using a small number of exemplars that are most representative of the dataset. The messages indicate the suitability of one sample to be the exemplar of the other and this gets updated over time for the entire dataset.

For a pair of samples i and k , the evidence that sample k should be the exemplar for sample i is defined by:

$$r(i, k) \leftarrow s(i, k) - \max_j [a(i, j) + s(i, j)] \forall j \neq k$$

Here, $s(i, k)$ is a similarity metric and availability $a(i, k)$ is the accumulated evidence that sample i should choose sample k as its exemplar. Thus, the exemplars chosen are similar enough to many samples and are chosen by many samples to be representative of themselves.

- **Mean-Shift :** This algorithm tries to identify blobs in a smooth density of samples. It works by first identifying candidates for centroids and then filtering them to eliminate near-duplicates.

For a candidate centroid x_i in iteration t , the algorithm updates the candidate effectively to be the mean of the samples within its neighborhood:

$$x_i^{t+1} = x_i^t + \frac{\sum_{x_j \in N(x_i)} K(x_j - x_i) x_j}{\sum_{x_j \in N(x_i)} K(x_j - x_i)}$$

Here, $N(x_i)$ depicts the neighborhood of samples within a given distance around x_i and the additive term is basically the mean shift vector computed for each centroid that points towards a region of the maximum increase in the density of points.

- **Agglomerative Clustering :** This algorithm is a type of hierarchical clustering algorithms that build nested clusters by merging or splitting them successively. The cluster hierarchy is represented as a tree, wherein the root is the unique cluster that gathers all the samples and the leaves are the clusters with only one sample. This particular algorithm uses a bottom up approach. Each samples starts in its own cluster, and over time the clusters are successively merged together based on a linkage criteria. We use the *ward* criteria that minimizes the sum of squared differences within all clusters that is effectively a variance-minimizing approach.

The clusters found by each algorithm in high-dimensional space are shown in Figure 1. We computed standard clustering metrics for each algorithm including the following :

- **Homogeneity:** Given a ground truth, this metric computes if all the clusters contain only data points which are members of a single class.
- **Completeness:** Given a ground truth, this metric computes if all the data points that are members of a given class are elements of the same cluster.
- **V-measure:** This metric is the harmonic mean between

Algorithm	Homogeneity	Completeness	V-Measure	# of clusters	Silhouette Coefficient
K-Means	0.607	0.592	0.600	10	0.106
Affinity-Propagation	0.654	0.317	0.427	88	0.082
Mean-Shift	0.012	0.368	0.024	2	0.517
Ward Agglomerative Clustering	0.589	0.635	0.611	10	0.097

Figure 2: Performance metrics of clustering algorithms.

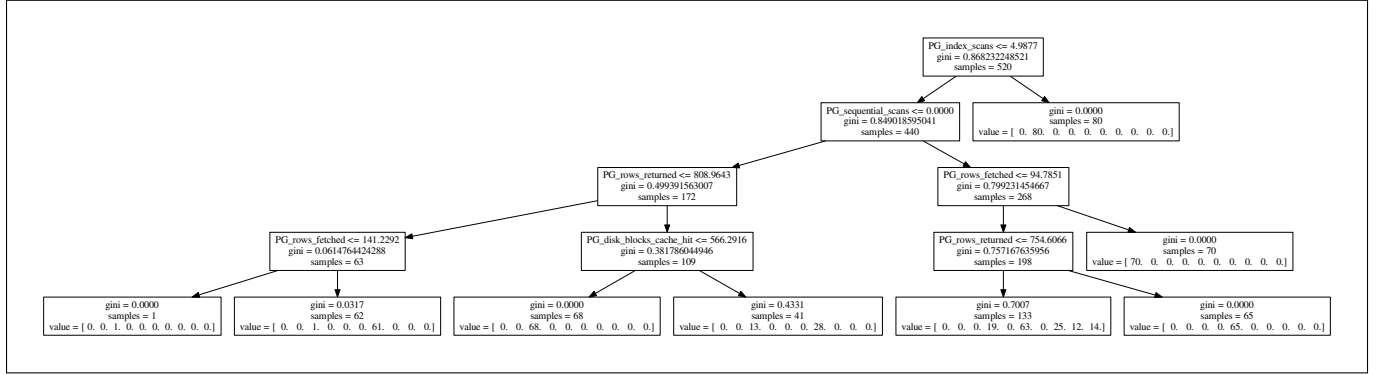


Figure 3: Decision tree with max depth set to 4.

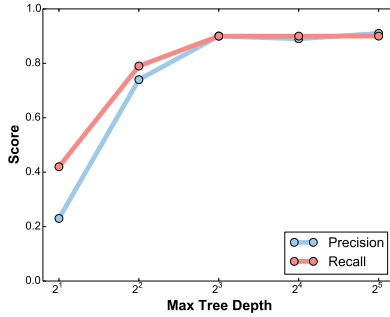


Figure 4: Impact of max depth on the accuracy of the decision tree.

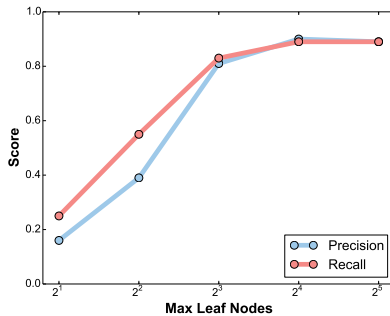


Figure 5: Impact of max leaf nodes on the accuracy of the decision tree.

homogeneity and completeness [10].

$$v = 2 * \frac{(\text{homogeneity} * \text{completeness})}{(\text{homogeneity} + \text{completeness})}$$

- **Silhouette coefficient:** This metric is computed using the mean intra-cluster distance a and the mean nearest-cluster distance b for each sample. It is defined for each sample as $(b - a) / \max(a, b)$.

These results are presented in Figure 2. We observe that the clustering algorithms work reasonably well with our dataset especially the K-Means and Ward Agglomerative Clustering algorithms. Both these algorithms require number of clusters as a parameter. However, this is not a restriction for our problem as we know the number of benchmarks - and hence the number of clusters - that we have. Algorithms like Affinity-Propagation and Mean-Shift give very high and very low estimates for the number of clusters in the dataset respectively. As we required higher classification accuracy and better intuition about the classifier, we also experimented with SVM classifiers and decision trees. We finally decided to use decision trees as they met both our accuracy and intuition requirements.

5.2. Decision Trees

Decision trees are non-parametric supervised learning algorithms used for both classification and regression. It creates a model for predicting the class of a sample by learning simple decision rules inferred from the sample features[7]. These trees can be interpreted easily and visualised. We however need to be careful not to create overly complex trees that do not generalise the data well, i.e. we should avoid overfitting.

Given a set of training samples $x_i \in R^n$, $i = 1, \dots, l$ and the corresponding label vector $y \in R^l$, the decision tree partitions the space recursively so that samples with the same labels are grouped together. We denote the data at a node m in the decision tree as Q . For every candidate split $\theta = (j, t_m)$ that

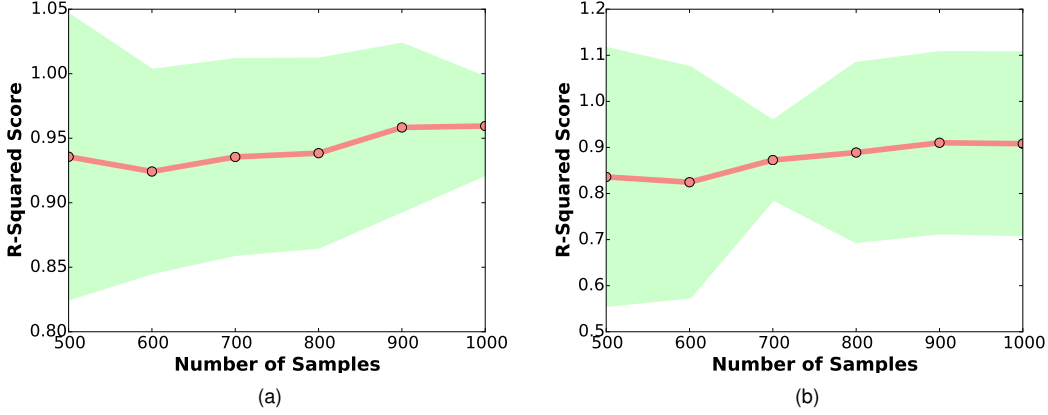


Figure 6: Per-benchmark gaussian processes to estimate (a) latency and (b) throughput

consists of a feature j and a feature-specific threshold t_m , the tree partitions the data into two subsets $Q_{left}(\theta)$ and $Q_{right}(\theta)$, wherein :

$$Q_{left}(\theta) = (x, y) | x_j \leq t_m$$

$$Q_{right}(\theta) = Q \setminus Q_{left}(\theta)$$

At each node m , we compute an impurity measure that we denote by H .

$$G(Q, \theta) = \frac{n_{left}}{N_m} H(Q_{left}(\theta)) + \frac{n_{right}}{N_m} H(Q_{right}(\theta))$$

We search for parameters that minimize H :

$$\theta^* = \operatorname{argmin}_{\theta} G(Q, \theta)$$

We then do the same process recursively for subsets $Q_{left}(\theta^*)$ and $Q_{right}(\theta^*)$ until we reach the maximum allowable depth or $N_m < \min_{samples}$ or $N_m = 1$. For the classification problem where the target is in $[0, K - 1]$ for node m , representing a region R_m with N_m observations, the proportion of class k observations in node m is given by :

$$p_{mk} = 1/N_m \sum_{x_i \in R_m} I(y_i = k)$$

We use the *Gini measure* as the impurity measure:

$$H(X_m) = \sum_k p_{mk}(1 - p_{mk})$$

The implementation uses an optimized version of the CART (Classification and Regression Trees) algorithm[2]. It basically constructs binary trees using the feature and threshold that yield the largest information gain at each node. The features need not be categorical as the algorithm dynamically defines a discrete attribute based on numerical variables that partitions the continuous attribute value into a discrete set of intervals. It does not compute rule sets unlike the C4.5 algorithm[9].

A sample decision tree with maximum depth limited to 4 is shown in Figure 3. We obtain 76% accuracy with this short

tree. The per-class accuracy metrics of the decision tree is shown in Table 3. The precision is the ratio $tp/(tp + fp)$ where tp is the number of true positives and fp the number of false positives. It is intuitively the ability of the classifier not to label as positive a sample that is negative. The recall is the ratio $tp/(tp + fn)$ where tp is the number of true positives and fn the number of false negatives. It is intuitively the ability of the classifier to find all the positive samples. The F1 score is a weighted average of the precision and recall and is defined as:

$$F1 = 2 * \frac{(precision * recall)}{(precision + recall)}$$

The support is the number of occurrences of each class in the true label vector y_{true} .

These are some interesting observations derived from the decision tree shown in Figure 3:

- Wikipedia benchmark performs a lot of index scans.
- SEATS benchmark involves fetching several rows per transaction.
- Epinions benchmark, on the other hand, involves returning several rows per transaction.
- Auctionmark benchmark has less locality of reference i.e. the number of disk block cache hits is low.
- Twitter benchmark also fetches several rows per transaction. However, it does not perform any sequential scans.

The accuracy increases quickly to 91% with a maximum depth of 8. The impact of maximum tree depth on the accuracy of the decision tree classifier is presented in Figure 4. Using three-way cross validation, we verified that the tree is able to classify the dataset accurately without overfitting. The impact of maximum number of leaf nodes on the accuracy of the decision tree classifier is presented in Figure 5. We observe that these parameters affect both precision and recall equally. The accuracy increases more steeply with increasing tree depth as expected.

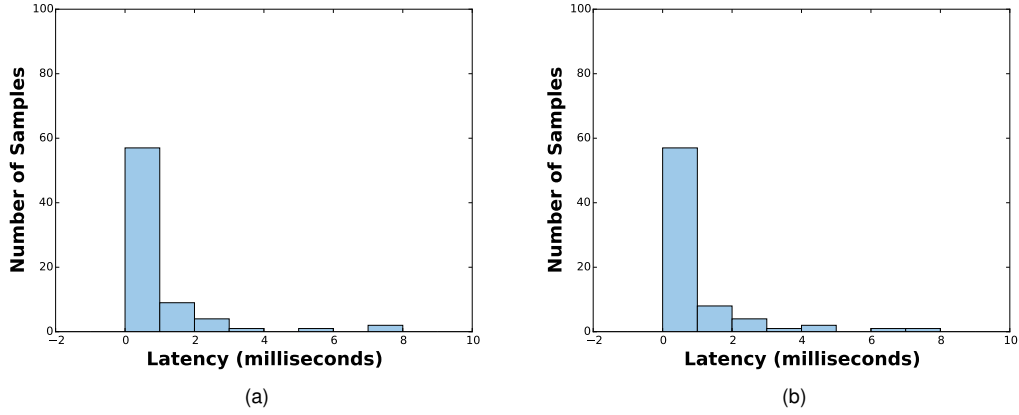


Figure 7: (a) Actual and (b) predicted latency distribution for the Wikipedia benchmark

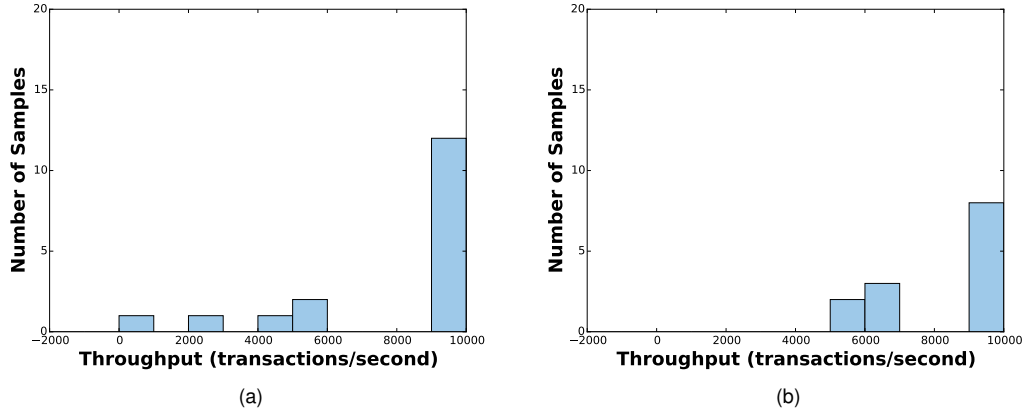


Figure 8: (a) Actual and (b) predicted throughput distribution for the balanced YCSB benchmark

Class	Precision	Recall	F1-score	Support
0.0	1.00	0.00	1.00	84
1.0	0.99	1.00	0.99	74
2.0	0.98	0.99	0.98	81
3.0	0.54	0.39	0.45	18
4.0	1.00	1.00	1.00	69
5.0	1.00	0.99	0.99	70
6.0	1.00	0.95	0.97	60
7.0	0.41	0.95	0.57	19
8.0	0.00	0.00	0.00	17
9.0	0.56	0.52	0.54	27
Avg / Total	0.90	0.91	0.90	519

Table 3: Per-class accuracy metrics of the decision tree with max depth = 8.

6. Estimation

We estimate expected performance of the DBMS on a given database configuration while executing each benchmark in the second part of our solution. In doing so, we hope to approxi-

mately estimate the performance of the target workload using the model for the benchmark that the classifier in Section 5 maps the workload to. As such, we train two estimators for each benchmark: one for database throughput and one for database latency.

6.1. Gaussian Process Regression

We chose to use Gaussian Process Regression, a supervised learning method, for this task as it works well for estimating regressions with no prior knowledge about distribution. It also gives a probabilistic estimation, allowing for further insight about bounds and probability of exceeding them. The Gaussian Process Regression models the data with the function

$$G(X) = f(X)^T \beta + Z(X)$$

where $f(X)^T \beta$ is a linear regression model and $Z(X)$ is a Gaussian process with zero mean. X is the input, represented as a vector of feature values. In this model, we try to find the “best linear unbiased prediction” (BLUP) of the process given the training data. That is, we try to find the best function for $\hat{G}(X) = G(X|\text{training data})$. Under the model, it can be

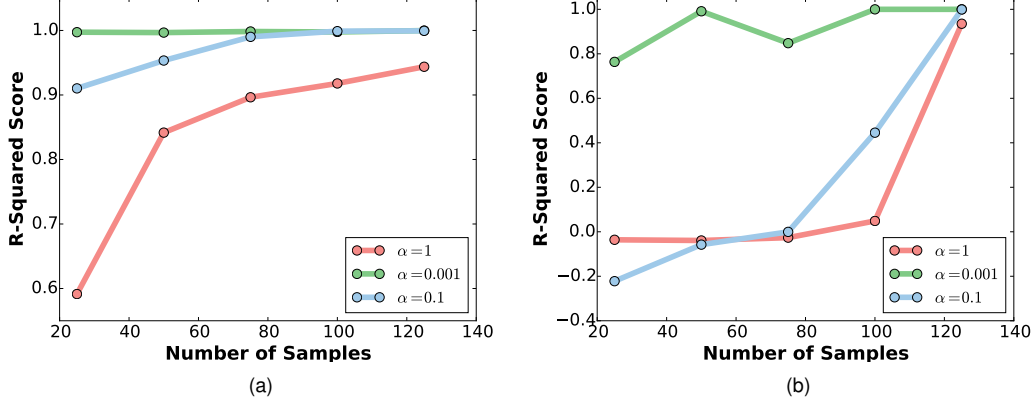


Figure 9: Performance of Lasso for various α values for (a) latency and (b) throughput on the Wikipedia benchmark

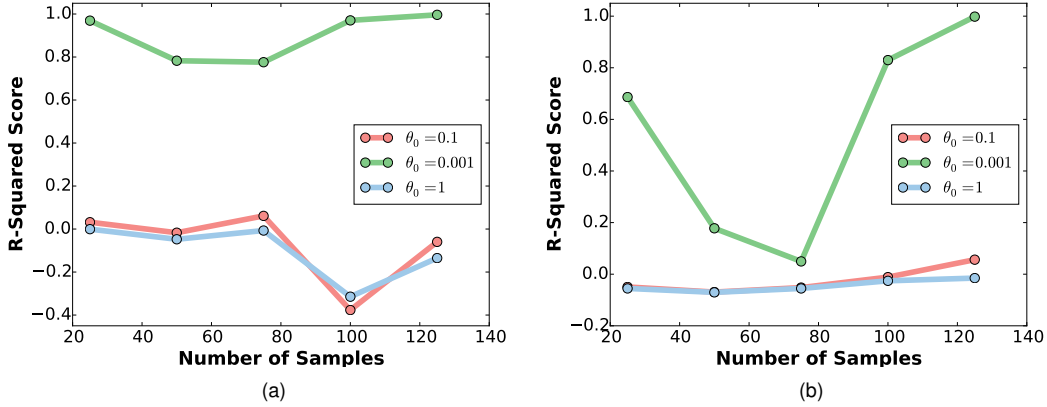


Figure 10: Performance of Gaussian Process Regression with absolute exponential autocorrelation for various θ_0 values for (a) latency and (b) throughput on the Wikipedia benchmark

shown that $\hat{G}(X) = a(X)^T y$ where $a(X)$ is the product of the weights with the feature values. From this model, we can find the BLUP by solving the following optimization problem:

$$a(X)^* = \arg \min_{a(X)} \mathbb{E}[(G(X) - a(X)^T y)^2]$$

subject to the constraint $\mathbb{E}[G(X) - a(X)^T y] = 0$. Gaussian Processes are amenable to kernels, although they are used as correlations in this model. We use the absolute exponential autocorrelation model in our experiments. This covariance model calculates autocorrelation of a vector X as:

$$\exp \left(\sum_{i=1}^n -\theta_0 |\Delta X_i| \right)$$

where θ_0 is the autocorrelation parameter and ΔX is the component-wise distances at which the correlation should be calculated. We experimented with various values of θ_0 and settled on $\theta_0 = 0.001$ as it exhibited the best performance, as seen in Figure 10.

One way to measure the performance of a regression model is the R^2 score defined as:

$$R^2 \equiv 1 - \frac{SS_{res}}{SS_{tot}}$$

In this definition, $SS_{res} = \sum_i (y_i - f_i)^2$ where y_i is the true value and f_i is the predicted value. This term is also known as the residual sum of squares. The other term in the definition is $SS_{tot} = \sum_i (y_i - \bar{y})^2$ where y_i is the true value and \bar{y} is the mean of all the true values. This is proportional to the variance of the true values. From this definition of the R^2 score, we see that the maximum value is 1 and that it indicates that the model perfectly predicted the observed data. A score less than 1 indicates that the model was not perfect and a score of zero indicates that the model is no better at predicting the values than the mean of the true values. Figure 6 shows the median R^2 score across the estimators for all benchmarks as a red line. The shaded green region indicates a single standard deviation spread. We infer from the figures that we can train a good estimator with as few as 600 samples. In

Feature Name	Feature Meaning
PG_Cache_Hits	Number of buffer hits in this table
PG_Index_Hits	Number of buffer hits in all indexes on this table
PG_Index_scans	Number of index scans initiated on this table
PG_rows_inserted	Number of rows inserted by queries in this database
PG_rows_returned	Number of rows returned by queries in this database
PG_rows_updated	Number of rows updated by queries in this database
PG_sequential_scans	Number of sequential scans initiated on this table
PG_transactions_committed	Number of transactions in this database that have been committed
PG_transactions_rolled_back	Number of transactions in this database that have been rolled back
autovacuum	Number of times the autovacuum daemon vacuumed this table
commit_delay	Time delay before a transaction attempts to flush the WAL buffer
fsync	Enable making sure that updates are physically written to disk
shared_buffers	Amount of memory the database server uses for shared memory buffers
track_activities	Enable the collection of information on the executing commands
wal_buffers	Amount of shared memory used for WAL data
wal_level	Determine how much information is written to the WAL
wal_writer_delay	Specify the delay between activity rounds for the WAL writer

Table 4: Some of the influential features for throughput estimation.

Feature Name	Feature Meaning
PG_index_scans	Number of index scans initiated on this table
PG_sequential_scans	Number of sequential scans initiated on this table
fsync	Enable making sure that updates are physically written to disk
synchronous_commit	Whether transaction commit will wait for WAL records to be flushed

Table 5: Influential features for latency estimation.

addition, the estimators become collectively better as more data is provided, as evidenced by the shrinking green region as number of samples increases.

One example of a highly accurate performance estimator is the latency estimator for the Wikipedia benchmark. This estimator has a high R^2 score of 0.9734. Looking at the actual and predicted latency values in Figure 7, we find that the predicted distribution mimics the actual one very closely, with only a slight dip into negative latency predictions. We believe this estimator can be even stronger if we encode constraints for possible predictions, such as positive values only.

One example of a less accurate performance estimator is the throughput estimator for the balanced YCSB benchmark. This estimator has a lower R^2 score of 0.7090. Looking at the actual and predicted throughput values in Figure 8, we see that the estimator fails to handle the holes in throughput seen in the actual values. We believe these isolated throughput values are due to environmental factors that are not reflected in the feature set such as load on the machine and other processes’ resource usages. A more “global” set of features across the whole system rather than just pertaining to the database may help train better estimators.

6.2. Lasso Regression

To gain more insight about what parameters affected performance the most, we performed Lasso Regression to determine the most influential features. Lasso regression encourages sparse coefficients in its solution, so it is a good method for finding the most important features for a particular problem. It works by optimizing this objective function :

$$\min_w \frac{1}{2n_{\text{samples}}} \|Xw - y\|_2^2 + \alpha \|w\|_1$$

which is a simple least squares linear regression with the lasso constraint added under weight α . A higher value for α encourages sparser solutions while a lower value relaxes this constraint. We experimented with different values of alpha and settled on using $\alpha = 0.001$ as it exhibited the best performance, as seen in Figure 9.

These features are summarized in Table 4 and Table 5. Confirming general intuition, throughput seems to be greatly affected by all operation types along with options that add delays (e.g. bgwriter_delay, commit_delay) or constrain how relaxed the database can be about transaction execution (e.g. fsync, synchronous_commit). It is, however, very interesting to note that latency seems primarily affected only by operations that take a long time to complete and not the type of operations or

hard delays introduced into the system.

In a practical implementation of our estimator, we will not be able to collect performance statistics while estimating performance for a specific configuration as we do not actually execute the workload in that configuration. So, we eliminated the features pertaining to throughput and latency from consideration while estimating performance metrics. However, these features are available in the training dataset. We believe that we can use graphical models to infer these missing throughput and performance features in the test data before estimation. We plan to explore this technique in future work.

7. Conclusion

DBMS performance tuning is a niche skill that requires much experience and experimentation to get right. Machine learning techniques can help automate this process by using prior knowledge to estimate the performance of the DBMS on a particular SQL workload without having to actually execute it. To achieve this goal, we have taken a two-step approach where we first map a workload to a well-known benchmark. Armed with this information, we then use a benchmark-specific regression estimator to obtain performance estimates under different DBMS configurations.

Using decision trees, we find that we can classify workloads using a few defining features. Our experiments show that a CART-based decision tree classifier achieves 91% accuracy on the classification problem. Thus, the decision trees learned to effectively discriminate between the different benchmark classes. We use Gaussian Process Regression estimators for predicting the throughput and latency of the DBMS while executing a SQL workload under a particular configuration. We demonstrate that this estimator achieves a R-squared score of 0.9. Furthermore, these highly accurate estimators can be trained with as few as 600 samples. Our analysis using Lasso Regression estimators provided key insights into the features that are most influential in determining throughput and latency.

In our experiments, we generate synthetic variants of the benchmarks in OLTPBench to emulate real-world workloads as we felt that it is a good starting point for evaluating the viability of our techniques. We plan to continue our evaluation using a larger real-world dataset that includes more realistic samples. We note that we leave the problem of using the performance estimator to find an optimal DBMS configuration for a given workload for future work. The estimator allows us to obtain inexpensive estimates without actually running the workload under a specific configuration. In addition, we will extend our auto-tuning framework to support other DBMSs like MySQL, and more hardware profiles. We anticipate that this larger and more realistic dataset will help us obtain additional insights about how best to tune the DBMS configuration

to maximize performance on arbitrary SQL workloads.

10 References

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