## Sequence models

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This document contains my personal notes on sequence models.

### 1. Embeddings

Embeddings are tensors. You interact with that tensor by indexing into it. It is often used to store encodings of collections of words. For example:

```
>>> nn.Embedding(vocab_sz, n_hidden)
```

creates a set of vocab\_sz tensors, each of size n\_hidden.

A common thing to do is to something like:

so you can see that the input is [sentence1, sentence2], where sentence 1 consists of words [1,2,4,5]. As an output, we get the corresponding 3-vectors for each word. So the output is:

```
[[[embedding_word_1,  # length 3 vector
  embedding_word_2,
  embedding_word_4,
  embedding_word_5],

[embedding_word_4,
  embedding_word_3,
  embedding_word_2,
  embedding_word_9]
]]
```

### 2. Linear layer

Applies a linear transformation to the incoming data:  $y = xA^T + b$ 

```
>>> m = nn.Linear(20, 30)
>>> input = torch.randn(128, 20)
>>> output = m(input)
>>> print(output.size())
torch.Size([128, 30])
```

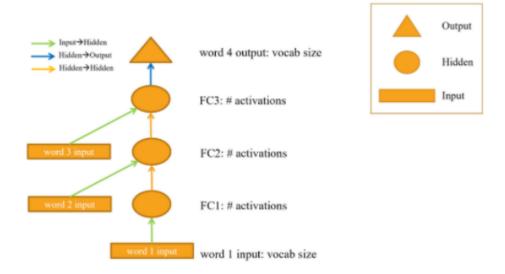


Figure 1. Graphical representation of RNN

#### 3. Recurrent neural network

Torch, by default, applies a multi-layer Elman RNN. This is defined as applying the following function to each element of the input sequence

$$h_t = \sigma_h(W_h x_t + U_h h_{t-1} + b_h) \tag{3.1}$$

$$y_t = \sigma_y(W_y h_t + b_y) \tag{3.2}$$

where  $x_t$  is an input vector,  $h_t$  is a hidden layer vector,  $y_t$  is an output vector, W,U,b are parameter matrices and vector,  $\sigma_h,\sigma_y$  are activation functions. Note that we don't actually retain the hidden state between lines – we throw it away after every complete training example (a line). We will typically initialize the hidden state to be  $h_{t=0}=0$ . Within a particular training instance, on a particular line, we may have different maximum values of t=T.

For example, in word classification, where we construct a character-level RNN, in each training loop we will

- 1. Get an input and target tensor
- 2. Create a zeroed initial hidden state
- 3. Read each letter in and:
  - Keep hidden state for next letter
  - ullet Feed the previous hidden state  $h_{t-1}$  in with the current input  $x_t$
- 4. Compare output at the end of the RNN loop to the target
- 5. Back-propagate

Then return the output and loss.

Bahdanau et al. (2014)

# References

Bahdanau, D., K. Cho, and Y. Bengio, 2014 Neural machine translation by jointly learning to align and translate. arXiv preprint arXiv:1409.0473.