

Scope Graphs

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Scope graphs are an alternative approach for name resolution. A scope graph is an AST extended with:

- nodes representing scopes
- directed edges describing different relationships involving these scope nodes; including to other scope nodes and to original AST nodes. For example
 - a. parent/child scopes
 - b. declarations within a scope
 - c. imports

This reduces name resolution to reachability, and has some advantages over the lookup table approach:

- Paths are recoverable
- Ambiguity
- Incrementality

Language

The goal was to build a prototype of a scope graph for a small language, which Jonathan wrote a parser for. This language is a subset of Flix and has the following constructs:

- names (qualified and unqualified)
- accessibility modifiers
- expressions
 - literals, names, function application, sequencing, let binds
- types
 - base types, type application/vars
- defs
- modules
- uses/imports with aliases/renamings
- type aliases
- enums

Building the graph

AST

The AST is designed to distinguish **declarations** and **references**. Here, declarations refer to the entire AST node, so we also introduce **handles**.

- **Declaration** - refers to an entire AST node that introduces a new name into the current scope (module, enum, type alias, etc)
- **Handle** - the name introduced by a declaration, located within the declaration
- **Reference** - the name of a declaration, used to refer to the declaration from elsewhere within the AST

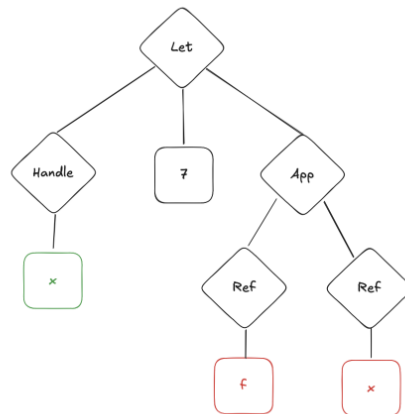
Thinking in terms of the IDE:

- If you ctrl click a reference, you should navigate to the matching handle.
- If you ctrl click a handle, you should get a drop down of references to it.

Every identifier in the AST is either a handle or a reference. And every declaration has a handle.

Example:

```
1 let x = 7;  
2 f(x)
```

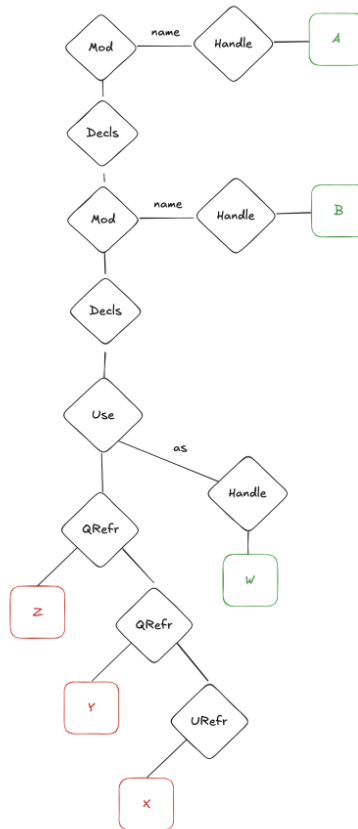


Qualifiers

- References are inductive types. If a reference has qualifiers, then every qualifier is itself a reference.
- Handles are just identifiers. If a module has qualifiers, then those qualifiers are desugared to multiple module declarations.

Example:

```
1 mod A.B {  
2   use X.Y.Z as W  
3 }
```



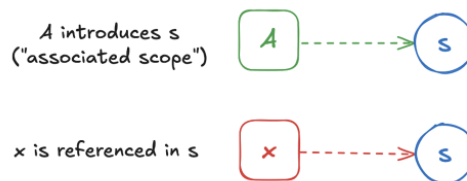
W is a handle 😊

type variables complicate things

Next we we add scope nodes and directed edges, which allow us to construct paths from references to handles/declarations.

Nodes

- **Declarations** introduce scopes
 - “associated scopes”
 - global vs local
 - global: associated scopes of `enum` s or `module` s, which can be accessed globally via a `use` statement.
 - local: associated scopes of other declarations, such as `def` or `let` , which can never be accessed outside of the declaration body.
- **References** are declared in scopes



Edges

s2 is the lexical
parent of s1



x is declared in s

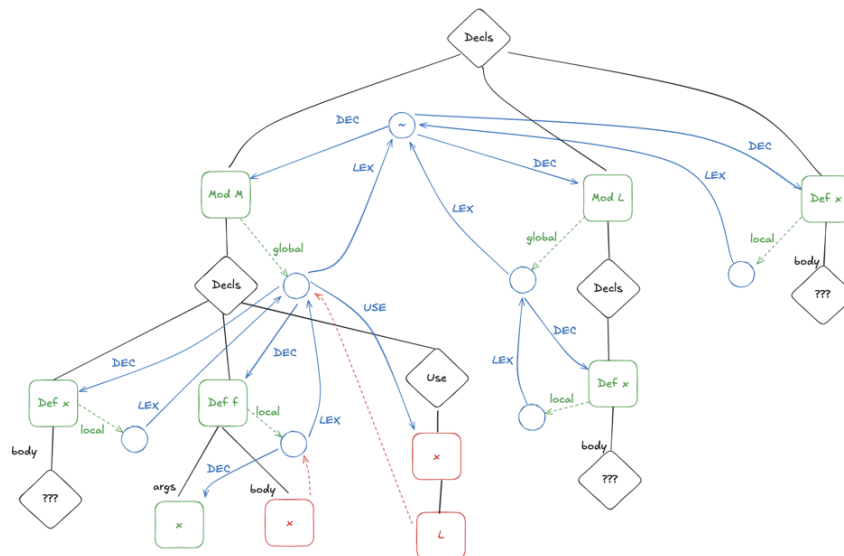


s uses (imports) A



Example:

```
1 def x(): Int = ???
2
3 mod L {
4   def x(): Int = ???
5 }
6
7 mod M {
8   use L.x
9
10  def x(): Int = ???
11  def f(x: Int): Int = x
12 }
```



Traversing the graph

Paths

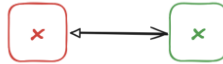
Once the graph has been built, we can resolve names by finding paths over the scope edges.

A path looks something like:



Note that the blue DEC / LEX / USE edges are the only “scope edges” that count in a path. The dotted arrows indicate relationships, but they are not officially part of the “path,” which is important once we look at regular expressions.

If such a path exists, then we can say “x refers to x” using this notation:



The path from s_1 to s_n might:

- be empty.
- be just some number of LEX edges.
- include a USE edge to something with a global scope (module or enum), in which case we recursively find a path to resolve the symbol in the `USE` statement, and then continue the search:



If we have a USE edge to a declaration with a local scope (def or enumCase), this can be the target, but we cannot continue the search:



Regex

There can be many declarations that “match” a reference, each with their own path. In order to formalize the scoping rules of a language, you need two things:

1. A regular expression (over the alphabet `{USE, DEC, LEX}`) that describes valid paths.
 - a. ex: `LEX* USE* DEC?` allows transitive imports, but not lexical parents of imported modules.
2. An ordering over `{USE, DEC, LEX}` to decide between multiple valid paths.
 - a. We are looking for the *shortest* matching path.
 - b. Note: two equal length paths may indicate a programmer error (ambiguous reference) or potentially something valid (importing an enum vs a mod).

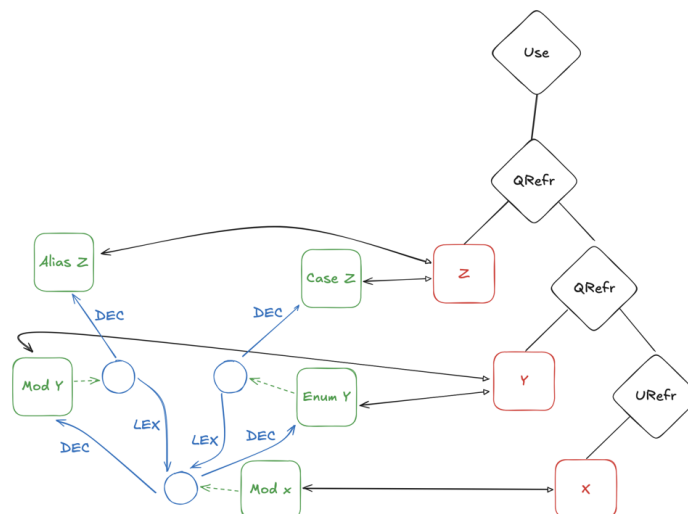
Qualifiers

When we encounter qualified references, we resolve the qualifier recursively, similar to a `USE`, then continue searching.

```

1 mod X {
2   enum Y {
3     case Z
4   }
5   mod Y {
6     type alias Z
7   }
8 }

```



Match

When we reach a declaration, how do we know if it matches?

1. The names have to be the same.
2. The “kind” (for lack of a better word) has to match.
 - a. If the reference appears in a type signature, then an enum or a type alias declaration could be a match.
 - b. If the reference appears in an expression, then a def or enum case declaration could be a match.
 - c. I have this half implemented in an ad hoc way. I don't think I've thought it through well enough.
 - d. If the reference appears in a qualifier or an import, it could be multiple things. (`Kind.Any` ?)
3. The visibility modifier has to be okay.
 - a. `private` declarations should not be accessible if we've crossed a `USE` edge.
 - b. I did not get to this.

Something I considered but didn't explore would be to have filters of type `Decl → Bool` that are accumulated during search. So, if we cross an import, we `and` in a filter that disallows `private` declarations. This could be an alternative way to represent “specific” imports.

Sources

These are the things I referenced while working on this:

- <https://drops.dagstuhl.de/storage/00lipics/lipics-vol313-ecoop2024/LIPIcs.ECOOP.2024.47/LIPIcs.ECOOP.2024.47.pdf>
- <https://drops.dagstuhl.de/storage/01oasics/oasics-vol109-evcs2023/OASIs.EVCS.2023.32/OASIs.EVCS.2023.32.pdf>
- <https://eelcovisser.org/talks/2017/2017-06-curryon/scope-graphs-curryon-2017-06-20.pdf>