HUMBOLDT-UNIVERSITÄT ZU BERLIN



MATLAB-Programmcode zur Bachelorarbeit

Die Karhunen-Loève-Zerlegung

Beispiele und Optimalität bezüglich des mittleren quadratischen Fehlers

eingereicht von

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```
1 % This class is a collection of functions related to the ∠
Browni an %%
  2 %motion in the context of Karhunen-Loeve Expansion %%
 3 % written by Tim Jaschek as a part of %%
 4 %% a presentation about the Levy construction of Brownian Motion %%
  5 %% a presentation about the idea of Karhunen-Loeve Expansion%%
  6 % a part of his bachelor thesis %
  8 % This Programmis used to generate FIGURE 3 in the thesis %
  10
 11 classdef Br Mb
       properties (Constant)
 12
          steps = 1000;
 13
         time = linspace(1/BrMb.steps, 1, BrMb.steps);
 14
 15
       end
 16
       met hods (Static)
           f uncti on [Z, l ambda, psi] = compute_KLT_components(n)
 17
               %this function computes the analytically solved ∠
 18
eigenvalues and
               % eigenfunctions of a Brownian motion
 19
               steps = Br Mb. steps ;
 20
 21
               Z = randn(1, n);
               lambda = zeros(1, n);
 22
               psi = zeros(n, steps) ;
 23
               for j = 1:n
 24
                    lambda(j) = 1 / ((j-0.5) * pi);
 25
 26
                    for k = 1: steps
 27
                        psi(j,k) = sqrt(2) *sin((j-0.5) *pi *k/steps);
 28
                    end
 29
               end
 30
           end
 31
           function BM = BrownianMotion(n, steps)
 32
               %using the previous function, this function computes ∠
the n-th
               %partial sum of the Karhunen-Loeve Expansion of ∠
 33
Brownian motion
 34
               BM = zeros(1, steps);
 35
               [Z, lambda, psi] = Br Mb. compute KLT components(n);
               for j = 1: n
 36
 37
                    for k = 1: steps
                        BM(k) = BM(k) + Z(j)*lambda(j)*psi(j,k);
 38
 39
                    end
 40
               end
```

```
41
                %OPPORTUNITY to plot:
 42
                %figure
 43
                %plot(Br Mb. time, BM)
                %xlabel('time')
 44
 45
                %str=sprintf('Brownian Motion via Karhunen-Loeve ✓
Approx. for n = %d', n;
 46
                %title(str)
 47
            end
 48
            function plot Develop()
                %generates the first plot of FIGURE 3
 49
                BM = zeros(1, BrMb. steps);
 50
 51
                [Z, lambda, psi] = Br Mb. comput e_KLT_component s(80);
                figure
 52
 53
                subpl ot (1, 2, 1)
 54
                title('Brownian Motion via Karhunen-Loeve Approx. for ∠
different n')
 55
                hold on;
                for j = 1:80
 56
 57
                      for k = 1: Br Mb. steps
 58
                          BM(k) = BM(k) + Z(j)*lambda(j)*psi(j,k);
 59
                      end
 60
                      if j == 4 || j == 16 || j == 32 || j == 64
 61
                          plot (Br Mb. time, BM)
 62
                      end
 63
                end
 64
                legend('n = 4', 'n = 16', 'n = 32', 'n = 64')
 65
                hold off;
 66
            end
 67
            function plot Movie()
 68
                %an exciting movie that shows the behaviour of the ∠
partial sums
 69
                % of the Karhunen-Loeve Expansion is generated here
 70
                BM = zeros(1, BrMb. steps);
                [Z, lambda, psi] = Br Mb. comput e_KLT_component s(500);
 71
 72
                for j = 1:500
                      for k = 1: Br Mb. steps
 73
 74
                          BM(k) = BM(k) + Z(j)*lambda(j)*psi(j,k);
 75
                      end
 76
                      plot (Br Mb. time, BM)
 77
                      title('Animation of KLT Series');
 78
                      pause(0.01)
 79
                end
 80
            end
 81
            function LevyBase()
```

```
82
                %plots the Schauder base
                Bn = [0, 1];
 83
 84
                List = [0, 1];
 85
                figure
 86
                title('Schauder Base - Base from the Construction by ✓
L· vy');
                xlabel('time');
 87
 88
                hold on;
 89
                plot(List, Bn);
                for n = 1:4
 90
                      if n==1
 91
 92
                          Bn = [Bn, 0];
                          List = linspace(0, 1, 3);
 93
 94
                      else
 95
                          Bn = [Bn, 1, 0];
                          List = linspace(0, 1, length(Bn));
 96
 97
                      end
 98
                      plot(List, Bn);
 99
                end
100
                hold off;
101
            end
102
            function KLTBase()
103
                %plots the Karhunen-Loeve Eigenfunction base
104
                [Z, l ambda, psi] = Br Mb. comput e_KLT_component s(6);
105
                figure
                title('Fourier Base - Base from Karhunen-Lo·ve∠
106
Theorem);
107
                xlabel('time');
108
                hold on;
109
                for j = 1:6
110
                     plot(Br Mb. time, psi(j,:))
111
                end
112
                hold off;
113
            end
114
            function levy()
                %generates the second plot of FIGURE 3
115
                D_0 = linspace(0, 1, 2^0 + 1); % intervalls of dyadic \angle
116
poi nt s
117
                B 0 = [0, randn]; %approximation of Brownian Motin in \checkmark
step 0
118
                subpl ot (1, 2, 2);
119
                title('Brownian Motion via Levy Construction for ∠
different n')
120
                hold on;
```

```
121
                 for n=1:6
122
                      D_next = linspace(0, 1, 2^n+1);
123
                      B_next = zeros(1, length(D_next));
124
                      i = 1;
                      for i =1: 2^n+1
125
126
                           if mod(i, 2) == 0;
127
                               B_{next(i)} = sqrt(1/(2^{n+1})) *randn;
128
                           el se
129
                               B_next(i) = B_0(i);
130
                               j = j + 1;
131
                           end
132
                      end
133
                      for i =1: 2^n+1
134
                           if mod(i, 2) == 0;
135
                               B_next(i) = B_next(i) + (B_0(i/2) + B_0(i/2+1)) \checkmark
/2;
136
                           end
137
                      end
138
                      D_0 = D_next;
139
                      B_0 = B_next;
                      if n==2 || n==4 || n==5 || n==6
140
141
                           pl ot ( D_0, B_0)
142
                      end
143
                 end
                 legend('n = 4','n = 16', 'n = 32','n = 64')
144
145
                 hold off;
146
            end
147
            function CoV()
                 % plots the covariance function of Brownian motion
148
                 [X, Y] = meshgrid(0:.05:1);
149
                 Z = min(X, Y);
150
151
                 surf(X, Y, Z)
152
                 title('Kovarianzfunktion der Brownschen Bewegung')
                 xlable('time')
153
154
            end
            function KLTl ambda()
155
                 %plots the Eigenvalues
156
                 [Z, lambda, psi] = Br Mb. comput e_KLT_component s(10);
157
                 pl ot (linspace(1, 10, 10), lambda, '*')
158
                 title('KLT Coefficients')
159
                 xlabel('index')
160
161
                 yl abel ('lambda_i')
162
            end
163
            function CoVBB()
```

```
164
                %plots the covariancefunction of Brownian bridge
                [X, Y] = meshgrid(0:.05:1);
165
                Z = min(X, Y) - X.*Y
166
                surf(X, Y, Z)
167
168
                title('Kovarianzfunktion der Brownschen Bræcke')
169
            end
170
            function Mercer()
171
                %plots different approximations of the ✓
covariancefunction of
                %Brownian motion using Mercers theorem
172
                [Z, lambda, psi] = Br Mb. comput e_KLT_component s(10);
173
174
                figure
175
                A = zeros(20, 20);
176
                title('Mercers Theorem - covariance function of ✓
Brownian Motion');
                hold on;
177
                for n = 1:4
178
                    for i = 1 : 20
179
180
                          for j = 1:20
181
                              A(i,j) = A(i,j) + lambda(n)*psi(n,50*i) \checkmark
*psi(n, 50*j);
182
                          end
183
                    end
184
                end
185
                [X, Y] = meshgrid(0.05: 0.05: 1);
                surf(X, Y, A)
186
187
            end
188
            function value = mother(t)
189
                %%%Haar mother function%%%%%
                if ((t<0.5) \&\& (t >= 0))
190
191
                    value = 1;
192
                el sei f ((t \ge 0.5) \& (t < 1))
193
                    value = -1;
194
                el se
195
                    value = 0;
196
                end
197
            end
198
            function psi = Haar(N)
199
                steps = linspace(1/N, 1, N);
                %%Use the Haar Mother function%%%%
200
201
                psi(:, 1) = ones(1, N);
                psi(N, 1) = 0;
202
203
                n=0;
204
                k=0;
```

```
205
                count =2;
206
                while count < N+1
207
                    max = 2^n;
                    if k == max
208
209
                        n=n+1;
210
                        k=0;
211
                        cont i nue
212
                    end
                    for t=1: N
213
                         psi(t, count) = 2^{n} Br Mb. mot her (2^n
214
(t)-k);
215
                    end
216
                    count = count +1;
                    k=k+1;
217
218
                end
219
           end
220
       end
221 end
```

```
1 % This Programm generates a Plot eigenvalues and eigenfunctions of
 2 % the induced integral operators of different kernels
 3 % written by Tim Jaschek as a part of his bachelor thesis %
 4
 5 % This Programm is used to generate FIGURE 2 in the thesis %
 7
 8 % oad the class Kernels
9 Kernels;
10
11 %Parameter for accuracy
12 N=50;
13
14 figure
15 for i =1: 3;
16
       Mat = Kernels. KMat(i, N);
17
       [lambda, Phi] = Kernels.trapez Sceme(Mat);
       subplot(3, 3, [1+3*(i-1) 2+3*(i-1)]);
18
19
       for i = 1:6
20
           hold on;
21
           pl ot (linspace(0, 1, N+2), Phi(:, j));
22
       end
23
      if i ==1
24
           title('First 6 Eigenfunctions');
25
           yl abel (' K(s, t) = min(s, t)');
       elseifi == 2
26
27
           ylabel('K(s,t)=min(s,t)-st');
28
       else
29
           yl abel ( ' K(s, t) = \exp(-|s-t|) ');
30
       end
31
       hold off;
       subpl ot (3, 3, 3*i);
32
       pl ot (linspace(1, 10, 10), lambda(1:10), 'o', 'color', 'red');
33
       if i ==1
34
           title('First 10 Eigenvalues');
35
36
       end
37 end
38
39
40
41
```

```
1 % This class gives tools for image compressing via Principal %
  2 % Component Analysis (KLT) %
  3 % written by Tim Jaschek as a part of his bachelor thesis %
  4
  5 % Used to generate FIGURE 6 % %
  6 %%..to generate it, type the following in your MATLAB command:
  7 % mage;
  8 % mage. program();
  10
 11 classdef Image
 12
       properties (Constant)
       end
 13
       met hods (Static)
 14
           function X = load_space()
 15
               % oad an image
 16
 17
               X = i m ead('bl uemar bel. j pg');
               % show the image
 18
               figure
 19
 20
               image(X)
 21
           end
 22
           function B = blur BW(X)
 23
               %function to blur an B/Wimage
 24
               [m, n] = size(X);
               X = doubl e(X);
 25
               %%to 25%
 26
 27
               mm=m/2;
 28
               nn = n/2:
               B=zeros(mm, nn);
 29
               f or i = 1: mm
 30
 31
                   for j=1:nn
 32
                       B(i,i) = 1/4 *(X(2*i-1,2*i-1) + X(2*i,2*i-1) + \checkmark
X(2*i-1, 2*j) + X(2*i, 2*j);
 33
                   end
 34
               end
 35
               B = ui nt 8(B);
 36
           end
 37
           function Z = blur(X)
 38
               %function to blur an R/G/B image
               XR = X(:,:,1);
 39
               XG = X(:,:,2);
 40
               XB = X(:,:,3);
 41
               RN = I \text{ mage. bl ur BW(} XR);
 42
               GN = I mage. bl ur BW(XG);
 43
```

```
44
                 BN = I mage. bl ur BW(XB);
                 Z = cat(3, RN, GN, BN);
 45
 46
            end
 47
            function X_trans = PCA(X, k)
 48
                 %function for image compression via KLT of a B/Wimage
 49
                 [m, n] = size(X);
                 X = double(X);
 50
 51
                 X_hat = X;
                 mean = zeros(1, n);
 52
                 K = zeros(n, n);
 53
                 %%correct mean%%%
 54
 55
                 for i = 1: n
 56
                     mean(i) = sum(X(:,i))/m;
 57
                     X_{hat}(:,i) = X_{hat}(:,i) - mean(i);
 58
                 end
 59
                 %covariance matrix %%
 60
                 for i = 1: n
 61
                     for j=1:n
                           K(i,j) = (1/(n-1))*dot((X_hat(:,i)),(X_hat(:, \checkmark
 62
j)));
 63
                     end
 64
                 end
                 %Æigenvalues and Eigenvectors %%%
 65
                 [V, D] = eig(K);
 66
                 [lambda, ind] = sort(diag(D), 'descend');
 67
                 Phi = V(:, ind);
 68
 69
                 Phi = Phi(:, 1:k);
                 Phi T = Phi.';
 70
                 %%%Transform X %%%
 71
                 Y = Phi T*(X hat);
 72
                 X_{trans} = Phi *Y;
 73
                 for i = 1: n
 74
 75
                     X_{trans}(:,i) = X_{trans}(:,i) + mean(i);
 76
                 end
 77
                 X_trans = uint8(X_trans);
 78
            end
            function Z = PCA RGB(X, k);
 79
 80
                 %function for image compressing via KLT of an R/G/B∠
i mage
                 XR = X(:,:,1);
 81
                 XG = X(:,:,2);
 82
                 XB = X(:,:,3);
 83
                 RN = I mage. PCA(XR, k);
 84
 85
                 GN = I \text{ mage. PCA(} XG, k);
```

```
86
                 BN = I mage. PCA(XB, k);
 87
                 Z = cat(3, RN, GN, BN);
 88
            end
            function program()
 89
 90
               %generates FIGURE 6
               disp('loading image')
 91
               X = I mage. l oad_space();
 92
 93
               figure
 94
               set(gca, 'XTickLabel', [],'XTick',[])
 95
               h = subplot(2, 2, 1)
               i ms how(X)
 96
 97
               disp('data compressing...')
               Z = I \text{ mage. PCA}_RGB(X, 400);
 98
 99
               hh = subplot(2, 2, 2)
               imshow(Z)
100
               Z = I \text{ mage. PCA}_RGB(X, 200);
101
102
               hhh = subplot(2, 2, 3)
               imshow(Z)
103
               Z = I \text{ mage. PCA}_RGB(X, 100);
104
105
               hhhh = subplot(2, 2, 4)
               imshow(Z)
106
107
               p = get(h, 'pos');
108
               pp = get(hh, 'pos');
               ppp = get(hhh, 'pos');
109
110
               pppp = get(hhhh, 'pos');
111
               p([3, 4]) = p([3, 4]) + [0.1 0.1];
112
               set(h, 'pos', p);
113
               pp([3, 4]) = pp([3, 4]) + [0.1 0.1];
114
               set(hh, 'pos', pp);
115
               ppp([3, 4]) = ppp([3, 4]) + [0.1 0.1];
116
               set(hhh, 'pos', ppp);
117
               pppp([3, 4]) = pppp([3, 4]) + [0.1 0.1];
118
               set(hhhh, 'pos', pppp);
119
            end
120
       end
121 end
122
```

```
1 %%This class is a collection of different Kernels and integration ✓
met hods %%
  2 % o solve the Fredholmintegral equation. It also provides a %
 3 % Werverapproximation for the kernels. %
 4 % written by Timlaschek as a part of his bachelor thesis %
 5
  7 classdef Kernels
      properties (Constant)
 9
      end
      met hods (Static)
 10
          function K_st = Kernel(i, s, t)
 11
             %this is a collection of covariance functions%
 12
             if i == 1
 13
                 %Brownian Motion%
 14
 15
                 K st = min(s,t);
 16
             elseif i == 2
                  %Brownian Bridge%
 17
                  K st = min(s,t) - s*t;
 18
 19
             elseif i == 3
 20
                  %exponential kernel%
 21
                  K_st = exp(-abs(t-s));
 22
             else
 23
                  K_st = 0;
 24
             end
 25
          end
 26
          function Mat = KMat(i, N)
27
               %for given N and i, this function will generate an NxN∠
matrix
               % for the i-th kernel.
 28
               Mat = zeros(N+2, N+2);
 29
               for j = 1: N+2
 30
 31
                   for k = 1: N+2
                        %use symmetry to save operations
 32
 33
                       if k<j
                            Mat(j,k) = Mat(k,j);
 34
 35
                        el se
 36
                            Mat(j,k) = Kernels. Kernel(i,(j-1)/(N+1), \checkmark
(k-1)/(N+1);
37
                        end
38
                    end
 39
               end
40
          end
 41
          function [lambda, Phi] = uniform Sceme(K)
```

```
42
               %UNI FORM SCEME
43
               N = length(K) - 2;
44
               sqW = sqrt(1/(N+2))* eye(N+2);
               Mat = sqW^*K^*sqW
45
46
               [V, D] = ei g( Mat );
               [lambda, ind] = sort(diag(D), 'descend');
47
               E \ vectors = V(:, ind);
48
49
               Phi = sqrt(N+2)*E_vectors;
               %bring the EV in the right direction%%
50
               for i = 1: N+2
51
52
                     if Phi(2, i) < 0
53
                         Phi (:, i) =- Phi (:, i);
54
                     end
55
               end
56
           end
57
           function [lambda, Phi] = trapez_Sceme(K)
58
               %TRAPEZ SCEME
59
               N = length(K) - 2;
               sqW = sqrt(1/(N+1))* eye(N+2);
60
61
               sqW(1, 1) = sqrt(1/(2*(N+1)));
               sqW(N+2, N+2) = sqW(1, 1);
62
63
               qW = sqrt(N+2)*eye(N+2);
               qW(1, 1) = sqrt(2*(N+1));
64
65
               qW(N+2, N+2) = qW(1, 1);
66
               Mat = sqW^*K^*sqW
               [ V, D] = ei g( Mat );
67
               [lambda, ind] = sort(diag(D), 'descend');
68
69
               E \ vectors = V(:, ind);
               Phi = qW*E_vectors;
70
71
               %bring the EV in the right direction%%
               for i = 1: N+2
72
73
                     if Phi(2, i) < 0
74
                         Phi (:, i) =- Phi (:, i);
75
                     end
76
               end
77
           end
           function [lambda, Phi] = simpson_Sceme(K)
78
               %SIMPSON SCEME
79
80
               N = length(K) - 2;
               sqW = sqrt(1/(3*(N+1)))* eye(N+2);
81
82
               qW = sqrt(3*(N+1))*eye(N+2);
               for i = 2: N+1
83
84
                    sqW(i,i)=sqW(i,i)*sqrt(2);
85
                    qW(i,i) = qW(i,i) / sqrt(2);
```

```
86
                 end
 87
                 for i = 2: (N+1)/2+1
 88
                     i = 2*(i - 1);
 89
                      sqW(j,j)=sqW(j,j)*sqrt(2);
 90
                      qW(j,j) = qW(j,j) / sqrt(2);
 91
                 end
 92
                 Mat = sqW^*K^*sqW
 93
                 [ V, D] = ei g( Mat );
                 [lambda, ind] = sort(diag(D), 'descend');
 94
 95
                 E_{\text{vectors}} = V(:, i \text{ nd});
                 Phi = qW*E_vectors;
 96
 97
                 %%bring the EV in the right direction%%
                 for i = 1: N+2
 98
                       if Phi(2, i) < 0
 99
                            Phi(:,i) =- Phi(:,i);
100
101
                       end
102
                 end
103
            end
            function K = MercerApprox(lambda, Phi, n)
104
105
                 %INPUT: lambda - Eigenvalues,
                          Phi - Eigenfunctions,
106
107
                 %
                          n - summations
108
109
                 %OUTPUT: K as approximation of covariance matrix
110
                 N = length(lambda) - 2;
                 K=zeros(N+2, N+2);
111
112
                 for s=1: N+2
113
                     for t = 1: N+2
114
                           if t<s
115
                                K(s,t) = K(t,s);
116
                           el se
117
                               for i = 1: n
118
                                    K(s,t) = K(s,t) + lambda(i)*Phi(s,i) \checkmark
*Phi(t,i);
119
                               end
120
                           end
121
                      end
122
                 end
123
            end
124
125
        end
126 end
127
```

```
1 %%This Programm generates a Plot for different Kernels and ∠
partial %%
 2 ‰ sums of Mercer's series for the covariance function‰
 3 % written by Tim Jaschek as a part of his bachelor thesis %
 4
 5 % This Programmis used to generate FIGURE 1 in the thesis %
 7
 8 % oad the class Kernels
 9 Kernels;
10
11 %Parameter for accuracy
12 N=16;
13
14 figure
15 for i =1:3;
       Mat = Kernels.KMat(i, N);
16
       [lambda, Phi] = Kernels.trapez_Sceme(Mat);
17
       for i = 1: 3;
18
19
           K=Kernel s. Mercer Approx(lambda, Phi, j+(j-1)^2);
20
           subpl ot (4, 3, i + 3*(i - 1));
           surfc(linspace(0, 1, N+2), linspace(0, 1, N+2), ∠
21
K, ' edgeal pha' , ' 1' );
           if j == 1
22
23
               if i ==1
24
                   title('K(s,t)=min(s,t)');
25
                   zl abel ('n=1');
26
               elseif i ==2
                   title('K(s,t)=min(s,t) - st');
27
28
               else
29
                   title('K(s,t)=exp(-|s-t|)');
30
               end
31
           elseif j == 2
               if i == 1
32
                   zl abel ('n=3');
33
34
               end
35
           el se
36
               if i == 1
37
                   zl abel (' n=7');
38
               end
39
           end
       end
40
41
       subpl ot (4, 3, i + 9);
42
       surfc(linspace(0, 1, N+2), linspace(0, 1, N+2), Mat, 'edgeal pha', '1');
```

```
1 % This class is a collection of functions to expand a Brownian ✓
motion wrt.
  2 ‰to different orthonormal bases and compute the Total Mean∠
Squared Error
  3 % for the approximation with the n-th partial sum
 4 % written by Timlaschek as a part of his bachelor thesis %
  6 ‰Used to generate FIGURE 3 and the data for TABULAR 5.1 in this ∠
thesis %%
  9 classdef MSE
       properties (Constant)
 10
           %Parameter for the partial sum
 11
           n = 20;
 12
 13
 14
           %Parameter for the accuracy of the Kernels
 15
           N = 1000;
 16
       end
 17
       met hods (Static)
           function approximation()
 18
               % oad the classes BrMb and Kernels
 19
 20
               Br Mb;
 21
               Kernels;
               %%generate a Brownian Motion with N steps %%%%%
 22
               p = 10000; %parameter for the accuracy of the BM
 23
               X = Br Mo. Brownian Motion(p, MSE. N);
 24
               %%/get ORTHONORMAL BASES
 25
               %%/the analytic KLT Eigenfunctions
 26
               %% the Haar Wavelets
 27
               %%Æigenfunctions of Brownian Bridge
 28
               %%Eigenfunctions of Exponential Kernel
 29
               [Z, lambda, psi] = Br Mb. comput e_KLT_components(MSE. N);
 30
               psi = psi.';
 31
32
               Haar = Br Mb. Haar(1000);
               [lambda, Bridge] = Kernels.trapez_Sceme(Kernels.KMat(2, ∠
33
MSE. N));
               [lambda, Exp] = Kernels.trapez_Sceme(Kernels.KMat(3, MSE. ∠
 34
N));
35
               %%Compute the Approximations %%%%
               X_hat = MSE. Approx(X, psi(:, 1: MSE. n));
36
               X_{tilde} = MSE. Approx(X, Haar(:, 1: MSE. n));
 37
               X_bridge = MSE. Approx(X, Bridge(:, 1: MSE. n));
 38
               X_{exp} = MSE. Approx(X, Exp(:, 1: MSE. n));
 39
```

```
40
                %% pl ot bot h % %
                figure
41
42
                hold on;
43
                plot(linspace(1/MSE. N, 1, MSE. N), X)
44
                plot(linspace(1/MSE. N, 1, MSE. N), X_hat)
                plot(linspace(1/MSE.N, 1, MSE.N), X_tilde)
45
                plot(linspace(1/MSE.N, 1, MSE.N), X_bridge)
46
47
                %pl ot (linspace(1/MSE. N, 1, MSE. N), X_exp)
48
                hold off;
49
           end
           function meansquare()
50
                % oad the classes BrMb and Kernels
51
52
                Br Mb;
53
                Kernels;
54
55
                disp('Compute TMSE of Karhunen-Loeve-Base...')
56
                [Z, lambda, psi] = Br Mb. comput e_KLT_component s ( MSE. N);
                psi = psi.';
57
                Mse = zeros(1, MSE. N);
58
59
                for i =1: 30
                    X = Br Mb. Br owni an Mbt i on(5000, Mbe. N);
60
                    X_hat = MSE. Approx(X, psi(:, 1: MSE. n));
61
                    for i = 1: MSE. N
62
63
                         Mse(j) = Mse(j) + (X(j)-X_hat(j))^2;
64
                    end
65
                end
66
                Mse = Mse/30;
67
                TMse = 0:
68
                h=1/MSE. N;
                for j = 1: MSE. N- 1
69
70
                         TMse = TMse + h/2 * (Mse(j) + Mse(j+1));
71
                end
72
                TMs e
73
                %%%%%%%%%%Haar %%%%%%%%
                disp('Compute TMSE of Haar-Base...')
74
                Haar = Br Mb. Haar (1000);
75
76
                Mse = zeros(1, MSE. N);
77
                for i =1:30
78
                    X = BrMb. BrownianMotion(5000, MSE. N);
79
                    X_hat = MSE. Approx(X, Haar(:, 1: MSE. n));
80
                    for i = 1: MSE. N
                         Mse(j) = Mse(j) + (X(j)-X_hat(j))^2;
81
82
                    end
83
                end
```

```
84
                Mse = Mse/30;
 85
                TMse = 0;
 86
                h=1/MSE. N;
 87
                for j = 1: MSE. N- 1
 88
                         TMse = TMse + h/2 * (Mse(j) + Mse(j+1));
 89
                end
 90
                TMs e
 91
                %%%%%%%%Bridge%%%%%%%
 92
                disp('Compute TMSE of Brownian-Bridge-Base...')
                [lambda, Bridge] = Kernels.trapez_Sceme(Kernels.KMat(2, ∠
 93
MSE. N));
                Mse = zeros(1, MSE. N);
 94
                for i = 1:30
 95
 96
                     X = Br Mb. Br owni an Motion (5000, MSE. N);
                     X_hat = MSE. Approx(X, Bridge(:, 1: MSE. n));
 97
 98
                     for i = 1: MSE. N
 99
                         Mse(i) = Mse(i) + (X(i) - X_hat(i))^2;
100
                     end
101
                end
                Mse = Mse/30;
102
103
                TMse = 0:
104
                h=1/ MSE. N;
                for j = 1: MSE. N- 1
105
106
                         TMse = TMse + h/2 * (Mse(j) + Mse(j+1));
107
                end
                TMs e
108
109
                110
                disp('Compute TMSE of Exponential-Base...')
111
                [lambda, Exp] = Kernels.trapez_Sceme(Kernels.KMat(3, MSE. ∠
N));
112
                Mse = zeros(1, MSE. N);
113
                for i = 1:30
114
                     X = Br Mb. Br owni an Motion (5000, MSE. N);
115
                     X_hat = MSE. Approx(X, Exp(:, 1: MSE. n));
116
                     for j = 1: MSE. N
117
                         Mse(j) = Mse(j) + (X(j) - X_hat(j))^2;
118
                     end
119
                end
120
                Mse = Mse/30;
                TMse = 0;
121
122
                h=1/ MSE. N;
123
                for j = 1: MSE. N- 1
124
                         TMse = TMse + h/2 * (Mse(j) + Mse(j+1));
125
                end
```

```
126
                 TMs e
127
            end
128
            function X_hat = Approx(X, Phi);
                 % massume X has N steps on [0, 1] and we have at least n∠
129
Eigenvectors with N steps each %%%
                X_hat = zeros(1, MSE. N);
130
                A = zeros(1, MSE.n);
131
                h = 1/MSE.N;
132
                for i =1: MSE. n
133
134
                     %%compute the integrals via trapez sceme%%
                     for j = 1: MSE. N- 1
135
                          A(i) = A(i) + h/2 * (X(j)*Phi(j,i) + X(j+1) \checkmark
136
*Phi ( j +1, i ) );
                     end
137
138
                 end
                for i =1: MSE. N
139
140
                     X_hat(i) = dot(A, Phi(i, 1: MSE. n));
141
                 end
142
            end
143
       end
144 end
145
146
147
148
149
```

```
1 % This programm compares uniform, trapez and Simpson-Sceme for %
 2 % approximation of solutions to the Fredholmintegral equation. %
 3 % written by Tim Jaschek as a part of his bachelor thesis %
 4
 5 % Used to generate data for Tabular 6.1 and 6.2 %
 7
 8 %Import the class Kernels which contains some Kernels and
 9 % integration scemes.
10 Kernels;
11
12 %Parameter for the Number of approximation steps
13 N = 45;
14
15 %Generation of different Kernels
16 BrownianMotion = Kernels. KMat(1, N);
17 BrownianBridge = Kernels. KMat(2, N);
18 Exponential Ker = Kernels. KMat(3, N);
19
20 %BROWNI AN MOTION
21 % Solve Fredhol integral equality with different Scemes
22 [lambda1, Phi 1] = Kernels. uniform_Sceme(BrownianMbtion);
23 [lambda2, Phi 2] = Kernels.trapez_Sceme(BrownianMotion);
24 [lambda3, Phi 3] = Kernels.simpson_Sceme(BrownianMotion);
25 %Compute analytic solutions for first Eigenvalues
26 | ambda = [| ambda1(1) | ambda2(1) | ambda3(1)];
27 Phi = [Phi 1(:, 1) Phi 2(:, 1) Phi 3(:, 1)];
28 la = (2/pi)^2;
29 ph = zeros(N+2, 1);
30 for i = 1: N+2
      ph(i) = sqrt(2) * sin(0.5*pi*((i-1)/(N+2)));
31
32 end
33 %plot(linspace(0, 1, N+2), ph, linspace(0, 1, N+2), Phi(:, 1))
34 %Compute the error terms
35 absolute_error_lambda = abs(la(1)-lambda)
36 relative_error_lambda = abs(la(1)-lambda)/la(1)*100
37 absolute_error_phi = zeros(1,3);
38 relative_error_phi = zeros(1,3);
39 for i = 1:3
40
        absolute_error_phi(i) = max(abs(ph-Phi(:,i)));
        relative_error_phi(i) = absolute_error_phi(i)/max(abs(Phi(:, ∠
41
i)));
42 end
43 absolute_error_phi
```

```
44 relative_error_phi *100
45
46 %BROWNI AN BRI DGE
47 % Solve Fredhol integral equality with different Scemes
48 [lambda1, Phi 1] = Kernels. uniform Sceme(BrownianBridge);
49 [lambda2, Phi 2] = Kernels.trapez_Sceme(BrownianBridge);
50 [lambda3, Phi 3] = Kernels. simpson Sceme(BrownianBridge);
51 %Compute analytic solutions for first Eigenvalues
52 \cdot \text{lambda} = [\text{lambda}(1) \cdot \text{lambda}(1) \cdot \text{lambda}(1)];
53 Phi = [Phi 1(:,1) Phi 2(:,1) Phi 3(:,1)];
54 la = (1/pi)^2;
55 \text{ ph} = zeros(N+2, 1);
56 for i =1: N+2
57
      ph(i) = sqrt(2) * sin(pi*((i-1)/(N+2)));
58 end
59 plot(linspace(0, 1, N+2), ph, linspace(0, 1, N+2), Phi(:, 1))
60 %Compute the error terms
61 absolute_error_lambda = abs(la(1)-lambda)
62 relative_error_lambda = abs(la(1)-lambda)/la(1)*100
63 absolute_error_phi = zeros(1,3);
64 relative_error_phi = zeros(1,3);
65 for i =1:3
         absolute_error_phi(i) = max(abs(ph-Phi(:,i)));
66
         relative_error_phi(i) = absolute_error_phi(i)/max(abs(Phi(:, ∠
67
i)));
68 end
69 absolute_error_phi
70 relative_error_phi *100
71
72
73
74
```

```
1 % This class generates a plot of a Brownian sheet %
 2 % written by Tim Jaschek as a part of his bachelor thesis %
 3
 4 % Used to generate FIGURE 7 % %
 5 % ... to generate it, type the following in your MATLAB command:
 6 % Sheet;
 7 % Sheet. plotit();
 9
10 classdef Sheet
11
      properties (Constant)
12
          N = 500;
13
          n = 200;
14
      end
      met hods (Static)
15
16
          function lam = sqlambda(i, j)
              lam = 4 / ((2*i - 1)*(2*i - 1) * pi^2);
17
18
          end
          function ph = phi(i,j)
19
20
              ph = zeros(Sheet. N, Sheet. N);
21
              for k=1: Sheet. N
22
                  for I = 1: Sheet. N
23
                        ph(k, l) = 2*sin((i-0.5)*pi*k/Sheet. N)*sin((j- \checkmark
0. 5) *pi *l / Sheet . N);
24
                  end
25
              end
26
          end
27
          function plotit()
              BS = zeros(Sheet. N, Sheet. N);
28
29
              BS2 = zeros(Sheet. N, Sheet. N);
              xi = randn(1, Sheet. n^2);
30
31
              figure
              for i =1:5
32
33
                  for j = 1:5
                       lam = Sheet.sqlambda(i, j);
34
35
                       phi = Sheet.phi(i, j);
                       BS2 = BS2 + Iam*phi *xi(Sheet.n*(i-1)+j);
36
37
                  end
38
                  i
39
              end
40
              subpl ot (3, 1, 1);
              surf(linspace(1/Sheet.N, 1, Sheet.N), linspace(1/Sheet.N, 1, ∠
41
Sheet. N), BS2, 'edgeal pha', '0');
42
              color map jet
```

```
43
               tic;
44
               for i =1: Sheet.n
                    for j =1: Sheet. n
45
                        lam = Sheet.sqlambda(i,j);
46
                        phi = Sheet.phi(i,j);
47
                        BS = BS + lam*phi*xi(Sheet.n*(i-1)+j);
48
49
                    end
50
                    i
51
               end
52
               t oc
53
               subpl ot (3, 1, [2, 3])
               surf(linspace(1/Sheet.N, 1, Sheet.N), linspace(1/Sheet.N, 1, ∠
54
Sheet. N), BS, 'edgeal pha', '0');
               col or map jet
55
56
           end
57
      end
58 end
59
```

```
1 %%This class is a collection of functions related to signal ∠
detection via
  2 % Karhunen Loeve Transformation
 3 % written by Tim Jaschek as a part of his bachelor thesis %
 4
  5 % Used to generate FIGURE 5 %
 6 %%...to generate it, type the following in your MATLAB command:
 7 %% Signal;
 8 %% i gnal.compare2();
 10
 11 classdef Signal
      properties (Constant)
 12
 13
      end
 14
      met hods (Static)
           function tone = SinTone(toneFreq, sampleFreq)
 15
 16
               %build sine tone
 17
               t = (1: sampleFreq) / sampleFreq;
                                                            % bui I d∠
time steps of length 1 second
               tone = sin(2 * pi * toneFreq * t);
 18
sinusoidal modulation
 19
           end
20
           function playTone(tone, sampleFreq)
 21
               %play tone
22
               sound(tone, sampleFreq); % sound function from∠
Matlab
 23
                pause(1.5);
                                           % wait
 24
            end
           function spect = Spectrum(coeff)
 25
               spect = abs(coeff);
 26
               %know spectrum is two sided. Make it one sided:
 27
               spect = spect(1:length(coeff)/2+1);
 28
               spect(2: end-1) = 2*spect(2: end-1);
 29
 30
            end
 31
           function K = AutoCo(data)
               [M, N] = size(data);
 32
               K = zeros(N, N);
 33
               AK = zeros(N);
 34
 35
               for i = 1: N
                   f or | | =1: M
 36
 37
                       AK(j) = AK(j) + data(l, 1)*data(l, j);
 38
                    end
 39
                    AK(j) = AK(j) / M
 40
               end
```

```
41
                 for j = 1: N
42
                      for k=1: N
43
                          K(j,k) = AK(abs(j-k)+1);
44
                      end
                 end
45
46
            end
47
            function K = AutoCo2(data)
48
                [M, N] = size(data);
49
                K = zeros(N, N);
                for j = 1: N
50
51
                      for k = 1: N
52
                          %use symmetry to save operations
53
                          if k<j
54
                               K(j,k) = K(k,j);
55
                          el se
56
                               for I = 1: M
57
                                    K(j,k) = K(j,k) + data(l,k)*data(l,j);
58
                               end
59
                               K(j,k) = K(j,k) / M
60
                          end
61
                      end
62
                end
63
            end
64
            function coeff = KLT(K, E)
65
                 Kernels;
                 [lambda, Phi] = Kernels.trapez_Sceme(K);
66
                 Phi (:, 1) = s qrt ( | ambda(1) ) *Phi (:, 1);
67
68
                 %f \text{ or } i = 2:5
69
                 %
                       Phi (:, 1) = Phi (:, 1) + s qrt(| ambda(i)) * Phi (:, i);
70
                 %end
71
                 N = length(E);
72
                 A = zeros(1, N);
73
                 for j = 1: N
74
                     A(j) = Phi(j, 1) + E(j);
75
                 end
                 coeff = fft(A);
76
77
            end
78
            function compare()
79
                 %build measure values
80
                 N = 1400;
81
                 M = 40000;
82
                 figure
83
                 % different factor for the noise amplitude
                 for i = 1:4
84
```

```
85
                     data = zeros(M, N);
                     if i ==1
 86
 87
                          z=2;
                     elseif i ==2
 88
 89
                          z=4:
 90
                     elseif i == 3
 91
                          z = 10;
 92
                     else
 93
                          z = 100;
 94
                     end
 95
                     for j = 1:M
 96
                          %generate Mtimes tone + noise
                          tone = Signal. SinTone(300, N);
 97
                          noise = z*randn(1, N);
 98
 99
                          data(i,:) = tone + noise;
100
                     end
101
                     %first line is B
                     B = dat a(1, :);
102
                     % take the time
103
104
                     tic;
                     %build covariance matrix
105
106
                     K = Si gnal . Aut oCo( dat a);
107
                     %KARHUNEN-LOEVE TRANSFORMATION
                     %KLT returns first Eigenfunction in Fourier base
108
                     coeff = Signal.KLT(K, zeros(1, N));
109
                     spectrum_KLT = Signal.Spectrum(coeff);
110
111
                     t oc
112
                     tic:
113
                     %FAST FOURIER TRANSFORM
                     spectrum_FFT = Signal.Spectrum(fft(B));
114
115
                     t oc
116
                     subpl ot (4, 2, 1+2*(i-1));
117
                     plot(spectrum FFT);
                     if i == 1
118
                         title('SNR=0.5 - FFT');
119
                     elseifi == 2
120
                          title('SNR=0.25 - FFT');
121
                     elseif i == 3
122
123
                          title('SNR=0.1 - FFT');
124
                     elseif i == 4
125
                          title('SNR=0.01 - FFT');
126
                     end
127
                     xlabel('Frequenz in Hz');
128
                     yl abel (' Magni t ude');
```

```
129
                     subpl ot (4, 2, 2+2*(i-1));
                     plot(spectrum KLT);
130
131
                     if i == 1
132
                          title('SNR=0.5 - KLT');
133
                     elseifi == 2
134
                          title('SNR=0.25 - KLT');
                     elseif i == 3
135
                          title('SNR=0.1 - KLT');
136
                     elseif i == 4
137
                          title('SNR=0.01 - KLT');
138
139
                     end
140
                     xlabel('Frequenz in Hz');
                     yl abel (' Magni t ude');
141
142
                 end
143
             end
144
             function compare2()
145
                 %build measure values
                 N = 1400;
146
                 M = 300;
147
148
                 figure
                 %different factor for the noise amplitude
149
150
                 for i = 1:4
151
                     data = zeros(M, N);
152
                     if i ==1
153
                         z=2;
                     elseif i ==2
154
155
                          z = 4;
156
                     elseif i == 3
157
                          z = 10;
158
                     else
159
                          z = 50;
160
                     end
161
                     for j = 1: M
162
                          %generate Mtimes tone + noise
163
                          tone = Signal. SinTone(300, N);
                          noise = z*randn(1, N);
164
165
                          data(i,:) = tone + noise;
166
                     end
167
                     %compute Expectation
                     E = zeros(1, N);
168
169
                     for j = 1: N
170
                          E(j) = sum(data(:,j))/M
171
                     end
172
                     for j = 1: M
```

```
173
                          dat a(j,:) = dat a(j,:) - E;
174
                     end
175
                     %first line is B
                     B = data(1,:);
176
177
                     % take the time
178
                     tic;
179
                     %build covariance matrix
                     K = Signal. Aut oCo2( dat a);
180
181
                     %KARHUNEN-LOEVE TRANSFORMATION
                     %KLT returns first Eigenfunction in Fourier base
182
                     coeff = Signal.KLT(K, E);
183
184
                     spectrum KLT = Signal.Spectrum(coeff);
185
                     t oc
186
                     tic;
187
                     %FAST FOURIER TRANSFORM
188
                     spectrum FFT = Signal.Spectrum(fft(B+E));
189
                     t oc
                     subpl ot (4, 2, 1+2*(i-1));
190
191
                     plot(spectrum FFT);
192
                     if i == 1
                          title('SNR=0.5 - FFT');
193
194
                     elseif i == 2
195
                          title('SNR=0.25 - FFT');
196
                     elseif i == 3
                          title('SNR=0.1 - FFT');
197
                     elseifi == 4
198
199
                          title('SNR=0.02 - FFT');
200
                     end
201
                     xlabel('Frequenz in Hz');
                     yl abel (' Magni t ude');
202
                     subpl ot (4, 2, 2+2*(i-1));
203
204
                     pl ot (spectrum KLT);
205
                     if i == 1
206
                          title('SNR=0.5 - KLT');
207
                     elseifi == 2
                          title('SNR=0.25 - KLT');
208
                     elseif i == 3
209
                          title('SNR=0.1 - KLT');
210
211
                     elseif i == 4
                          title('SNR=0.02 - KLT');
212
213
                     end
                     xlabel('Frequenz in Hz');
214
                     yl abel (' Magni t ude');
215
216
                 end
```

217 end 218 end 219 end 220