

Jasdeep Dhillon

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<https://jasdeepdhillon13.github.io/website/>

Skillset

Assembly Language
C and C++
Java and Python
Keil RTX RTOS
Keil MCB1700 Evaluation Boards
FPGA and VHDL
Altera Cyclone II
Matlab and Simulink
Labview
PSIM, LTspice and EagleCad
PCB Design
Soldering & Circuit Assembly
Arduino and Raspberry Pi
AutoCAD and Unigraphics NX
SolidWorks
3D Printer and Milling Machine
Band saw and Drill Press
Oscilloscopes and DAQ
Digital Multimeter
CAN, I2C and SPI
Hardware & Design Prototyping
Material Selection & Fabrication

Work Experience

UAV Field Technician

Drone Delivery Canada

Sept 2017-Dec 2017

- Assembled a drone for training new pilots
- Simulated and created flight paths in MicroPilot Horizon and programmed drone to adjust speed around corners
- Integrated new sensors onto drones and field test drones

Research Assistant

University of Waterloo

May 2017-August 2017

- Assembly and testing of Spatial Atomic Layer Deposition (SALD) system
- Redesign of reactor stand in SolidWorks and machining of stand
- Designing thermoelectric cooling for the reactor stand

R&D Engineer

Magna International

Sept 2015 - Dec 2015

- Designed a PLC to monitor pressure and temperature data of paint booths
- Researched air balancing paint booths and controlling paint trajectory solutions

Projects

Autofuel (Capstone project)

- Designing and constructing a Cartesian robot to automate the vehicle refuelling process
- Responsible for mechanical and electrical assembly, SolidWorks design and machining

Search and Recovery Robot (University)

- Designed an automated vehicle to traverse and locate a base in a defined course

Light Painting Robot (University)

- Programmed a Fanuc robot to recreate a user's path to produce a light painting

Smart Lock System (Personal)

- Developed secure keyless entry lock and allows you to see who is at the door
- Schematic capture Pi based PCB to interface with low voltage peripherals and minimize power usage

Line Following Robot (University)

- Designed and soldered multiple circuits on PCB to create a line following and magnet sensing robot
- Programmed microcontroller in C

Bicycle Gloves (Personal)

- Gloves that provide direction to a cyclist through haptic feedback

Education

Bachelor of Applied Science Honors Mechatronics Engineering, University of Waterloo, Sept 2012 –May 2018

Interests

Design | Technology | Robots | Badminton | Hockey | Biking | Anime | Gaming