

Jase Branch

Fort Worth, TX | (817) 233-6836 | jase_branch4@outlook.com | linkedin.com/in/jase-branch | jasebranch.com

EDUCATION

University of Texas at Arlington

Arlington, TX

Bachelor of Science in Computer Science **GPA: 3.41/4.0**

2024

Relevant Coursework: Computer Architecture, Computer Vision, Neural Networks, Information Security

TECHNICAL SKILLS

Languages: C++, C, Rust, Python, Bash, Java

Robotics & Middleware: ROS2, Nav2, SLAM, Gazebo

Embedded Systems: STM32, ESP32, FreeRTOS, CAN, UART, SPI, I2C, MQTT

Graphics & Compute: OpenGL, GLSL, CUDA, Bullet Physics

Networking & Systems: Boost.Asio, UDP/TCP, real-time systems, sensor fusion

Tools: Git, CMake, Clang, Docker, Docker Compose, GitHub Actions

PROJECTS

Autonomous Drone Simulator (C++, OpenGL, Ada, Boost.Asio)

Spring – Summer 2025

- Built a real-time drone simulator integrating Bullet Physics and OpenGL
- Emulated five onboard sensors (IMU, GPS, etc.) with **10–100 Hz asynchronous** updates.
- Measured system throughput exceeding **260 messages/sec** across the sensor and networking pipeline.
- Developed a virtual flight controller in both Ada & Python communicating over UDP to simulation

Embedded Sensor Fusion Network (C++, Rust, FreeRTOS, STM32, ESP32)

Summer – Fall 2025

- Architected a multi-node embedded system streaming real-time IMU data over CAN and Wi-Fi.
- Tuned sensor pipeline sustaining **80–90 messages/sec** with low jitter.
- Reduced packet loss from **12% to under 3%** using multi-chunk CAN packetization and queue restructuring.
- Delivered reusable CAN serialization libraries and a Rust Embassy receiver sustaining **150–170 messages/sec**.

ROS2 Autonomous Navigation Benchmark (ROS2, Nav2, Gazebo, SLAM)

Fall – Winter 2025

- Built a reproducible benchmarking framework for autonomous navigation using ROS2 and Nav2.
- Automated **4 parallel** navigation trials using Docker Compose for consistent and repeatable testing.
- Collected and analyzed metrics including completion time, path length, and trajectory efficiency.

GPU Boid Simulation (C++, CUDA, OpenGL)

Spring – Summer 2025

- Implemented a GPU-accelerated Boid simulation using CUDA with OpenGL instanced rendering.
- Scaled performance from **600 to 20,000 agents** at **60 FPS**, achieving a **35–40×** speedup over CPU execution.
- Optimized GPU memory layout and kernel execution for large-population flocking behavior.

OpenGL 3D Renderer (C++, OpenGL, GLSL)

Summer 2024 – Winter 2024/25

- Developed a real-time 3D renderer achieving **90+ FPS** with **40+ objects** and **327k+ triangles**.
- Implemented Blinn-Phong lighting and shadow mapping using custom GLSL shaders.
- Built a scalable entity-component system (ECS) for efficient scene management.

EXPERIENCE

Team Member — UTA & Bell (Textron) Flight

Aug. 2023 – Dec. 2023

GPS-Denied Autonomous Drone Competition

Fort Worth, TX

- Collaborated with a 6-person multidisciplinary team and Bell engineers on a GPS-denied autonomous UAV system.
- Reproduced, diagnosed, and debugged intermittent MQTT communication failures observed during flight testing.
- Validated subsystem interfaces to ensure reliable end-to-end data flow across onboard and ground systems.

General Labor & Odd Jobs

May 2024 – Present

Various Jobs

Fort Worth, TX

- Provided general labor support for various tasks and family needs while working on technical projects