

## Determinants and Matrices

## SET Self Evaluation Test - 9

[IIT Screening 2001]

1. If  $A = \begin{vmatrix} \sin\theta + \alpha & \cos\theta + \alpha & 1 \\ \sin\theta + \beta & \cos\theta + \beta & 1 \\ \sin\theta + \gamma & \cos\theta + \gamma & 1 \end{vmatrix}$ , then [Orissa JEE 2003]

- (a)  $A=0$  for all  $\theta$  (b)  $A$  is an odd Function of  $\theta$   
(c)  $A=0$  for  $\theta = \alpha + \beta + \gamma$  (d)  $A$  is independent of  $\theta$

2. If  $f(x) = \begin{vmatrix} 1 & x & x+1 \\ 2x & x(x-1) & (x+1)x \\ 3x(x-1) & x(x-1)(x-2) & (x+1)x(x-1) \end{vmatrix}$  then  $f(100)$  is equal to

[IIT 1999; MP PET 2000; Kerala (Engg.) 2005; DCE 2005]

- (a) 0 (b) 1  
(c) 100 (d) -100

3. The parameter on which the value of the

determinant  $\begin{vmatrix} 1 & a & a^2 \\ \cos(p-d)x & \cos px & \cos(p+d)x \\ \sin(p-d)x & \sin px & \sin(p+d)x \end{vmatrix}$  does not depend upon

[IIT (Re-Exam) 1997; Pb. CET 2000]

- (a)  $a$  (b)  $p$   
(c)  $d$  (d)  $x$

4. If  $1, \omega, \omega^2$  are the cube roots of unity, then

$\Delta = \begin{vmatrix} 1 & \omega^n & \omega^{2n} \\ \omega^n & \omega^{2n} & 1 \\ \omega^{2n} & 1 & \omega^n \end{vmatrix}$  is equal to

- (a) 0 (b) 1  
(c)  $\omega$  (d)  $\omega^2$

5. The value of the determinant  $\begin{vmatrix} 10! & 11! & 12! \\ 11! & 12! & 13! \\ 12! & 13! & 14! \end{vmatrix}$  is

[Orissa JEE 2003]

- (a)  $2(10!11!)$  (b)  $2(10!13!)$   
(c)  $2(10!11!12!)$  (d)  $2(11!12!13!)$

6. For all values of  $A, B, C$  and  $P, Q, R$ , the value of

$\begin{vmatrix} \cos(A-P) & \cos(A-Q) & \cos(A-R) \\ \cos(B-P) & \cos(B-Q) & \cos(B-R) \\ \cos(C-P) & \cos(C-Q) & \cos(C-R) \end{vmatrix}$  is [IIT 1994]

- (a) 0 (b)  $\cos A \cos B \cos C$   
(c)  $\sin A \sin B \sin C$  (d)  $\cos P \cos Q \cos R$

7. The number of distinct real roots of

$\begin{vmatrix} \sin x & \cos x & \cos x \\ \cos x & \sin x & \cos x \\ \cos x & \cos x & \sin x \end{vmatrix} = 0$  in the interval  $-\frac{\pi}{4} \leq x \leq \frac{\pi}{4}$

is

- (a) 0 (b) 2  
(c) 1 (d) 3

8. Let  $\Delta_1 = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$  and  $\Delta_2 = \begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix}$ , then

$\Delta_1 \times \Delta_2$  can be expressed as the sum of how many determinants

[Tamilnadu (Engg.) 2001]

- (a) 9 (b) 3  
(c) 27 (d) 2

9. If  $A = \begin{bmatrix} \cos^2 \theta & \sin \theta \cos \theta \\ \sin \theta \cos \theta & \sin^2 \theta \end{bmatrix}$ ,

$B = \begin{bmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{bmatrix}$

and  $\theta$  and  $\phi$  differs by  $\frac{\pi}{2}$ , then  $AB =$

- (a)  $I$  (b)  $O$   
(c)  $-I$  (d) None of these

10. If the multiplicative group of  $2 \times 2$  matrices of

the form  $\begin{pmatrix} a & a \\ a & a \end{pmatrix}$ , for  $a \neq 0$  and  $a \in R$ , then the

inverse of  $\begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}$  is

[Karnataka CET 1999]

(a)  $\begin{pmatrix} \frac{1}{8} & \frac{1}{8} \\ \frac{1}{8} & \frac{1}{8} \end{pmatrix}$

(b)  $\begin{pmatrix} \frac{1}{4} & \frac{1}{4} \\ \frac{1}{4} & \frac{1}{4} \end{pmatrix}$

(c)  $\begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{pmatrix}$

(d) Does not exist

11. If for  $AX = B$ ,  $B = \begin{bmatrix} 9 \\ 52 \\ 0 \end{bmatrix}$  and

$A^{-1} = \begin{bmatrix} 3 & -\frac{1}{2} & -\frac{1}{2} \\ -4 & \frac{3}{4} & \frac{5}{4} \\ 2 & -\frac{1}{4} & -\frac{3}{4} \end{bmatrix}$ , then  $X$  is equal to

- (a)  $\begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$  (b)  $\begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 2 \end{bmatrix}$

(c)  $\begin{bmatrix} -4 \\ 2 \\ 3 \end{bmatrix}$  (d)  $\begin{bmatrix} 3 \\ 3 \\ 4 \\ -3 \\ 4 \end{bmatrix}$

12. Matrix  $A$  is such that  $A^2 = 2A - I$ , where  $I$  is the identity matrix. Then for  $n \geq 2$ ,  $A^n =$

- (a)  $nA - (n-1)I$  (b)  $nA - I$   
(c)  $2^{n-1}A - (n-1)I$  (d)  $2^{n-1}A - I$

13. Let  $p$  a non singular matrix  $1 + p + p^2 + \dots + p^n = O$  ( $O$  denotes the null matrix), then  $p^{-1} =$  [Orissa JEE 2004]

- (a)  $p^n$   
(b)  $-p^n$   
(c)  $-(1 + p + \dots + p^n)$   
(d) None of these

14. If  $P = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix} \begin{bmatrix} -1 & -2 \\ -2 & 0 \\ 0 & -4 \end{bmatrix} \begin{bmatrix} -4 & -5 & -6 \\ 0 & 0 & 1 \end{bmatrix}$  then  $P_{22} =$

[Orissa JEE 2004]

- (a) 40 (b) -40  
(c) -20 (d) 20

15. If  $C = 2\cos\theta$ , then the value of the determinant

$\Delta = \begin{vmatrix} C & 1 & 0 \\ 1 & C & 1 \\ 6 & 1 & C \end{vmatrix}$  is [Orissa JEE 2002]

- (a)  $\frac{\sin 4\theta}{\sin \theta}$   
(b)  $\frac{2\sin^2 2\theta}{\sin \theta}$   
(c)  $4\cos^2 \theta (2\cos \theta - 1)$   
(d) None of these

16. If  $\Delta_1 = \begin{vmatrix} x & b & b \\ a & x & b \\ a & a & x \end{vmatrix}$  and  $\Delta_2 = \begin{vmatrix} x & b \\ a & x \end{vmatrix}$  are the given determinants, then

[MNR 1986; Kurukshetra CEE 1998; UPSEAT 2000]

- (a)  $\Delta_1 = 3(\Delta_2)^2$  (b)  $\frac{d}{dx}(\Delta_1) = 3\Delta_2$   
(c)  $\frac{d}{dx}(\Delta_1) = 2(\Delta_2)^2$  (d)  $\Delta_1 = 3\Delta_2^{3/2}$

17. If  $a_1, a_2, a_3, \dots, a_n, \dots$  are in G.P. then the value of the

determinant  $\begin{vmatrix} \log a_n & \log a_{n+1} & \log a_{n+2} \\ \log a_{n+3} & \log a_{n+4} & \log a_{n+5} \\ \log a_{n+6} & \log a_{n+7} & \log a_{n+8} \end{vmatrix}$  is

- (a) -2 (b) 1  
(c) 2 (d) 0

18. In the determinant  $\begin{vmatrix} 0 & 1 & -2 \\ -1 & 0 & 3 \\ 2 & -3 & 0 \end{vmatrix}$ , the ratio of the co-factor to its minor of the element -3 is [MP PET 1992]

- (a) -1 (b) 0  
(c) 1 (d) 2

19. If value of a third order determinant is 11, then the value of the square of the determinant formed by the cofactors will be [Roorkee 1990; DCE 2000]

- (a) 11 (b) 121  
(c) 1331 (d) 14641

20. Consider the system of linear equations  $a_1x + b_1y + c_1z + d_1 = 0$ ,  $a_2x + b_2y + c_2z + d_2 = 0$  and  $a_3x + b_3y + c_3z + d_3 = 0$ . Let us denote by

$\Delta(a, b, c)$  the determinant  $\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$  if  $\Delta(a, b, c) \neq 0$ ,

then the value of  $x$  in the unique solution of the above equations is

[Ph. CET 2004]

- (a)  $\frac{\Delta(bcd)}{\Delta(abd)}$  (b)  $\frac{-\Delta(bcd)}{\Delta(abd)}$   
(c)  $\frac{\Delta(acd)}{\Delta(abd)}$  (d)  $-\frac{\Delta(abd)}{\Delta(abd)}$

21. If a matrix  $A$  is such that  $4A^3 + 2A^2 + 7A + I = O$ , then  $A^{-1}$  equals [MP PET 2001]

- (a)  $(4A^2 + 2A + 7I)$  (b)  $-(4A^2 + 2A + 7I)$   
(c)  $-(4A^2 - 2A + 7I)$  (d)  $(4A^2 + 2A - 7I)$

22. If  $F(\alpha) = \begin{bmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix}$  and

$G(\beta) = \begin{bmatrix} \cos \beta & 0 & \sin \beta \\ 0 & 1 & 0 \\ -\sin \beta & 0 & \cos \beta \end{bmatrix}$ , then  $[F(\alpha)G(\beta)]^{-1} =$

- (a)  $F(\alpha) - G(\beta)$  (b)  $-F(\alpha) - G(\beta)$   
(c)  $[F(\alpha)]^{-1}[G(\beta)]^{-1}$  (d)  $[G(\beta)]^{-1}[F(\alpha)]^{-1}$

23. If the points  $(x_1, y_1), (x_2, y_2)$  and  $(x_3, y_3)$  are

collinear, then the rank of the matrix  $\begin{bmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{bmatrix}$

will always be less than

[Orissa JEE 2003]

- (a) 3 (b) 2  
(c) 1 (d) None of these

24. For how many value (s) of  $x$  in the closed interval

$$[-4, -1] \text{ is the matrix } \begin{bmatrix} 3 & -1+x & 2 \\ 3 & -1 & x+2 \\ x+3 & -1 & 2 \end{bmatrix} \text{ singular}$$

[Karnataka CET 2002]

- (a) 2 (b) 0  
(c) 3 (d) 1

25. If 3, -2 are the Eigen values of a non-singular matrix  $A$  and  $|A|=4$ , then the Eigen values of  $adj(A)$  are

[Kurukshetra CEE 2002]

- (a)  $\frac{3}{4}, \frac{-1}{2}$  (b)  $\frac{4}{3}, -2$   
(c) 12, -8 (d) -12, 8

## Answers and Solutions

(SET - 9)

1. (d) Given  $A = \begin{bmatrix} \sin\theta + \alpha & \cos\theta + \alpha & 1 \\ \sin\theta + \beta & \cos\theta + \beta & 1 \\ \sin\theta + \gamma & \cos\theta + \gamma & 1 \end{bmatrix}$

Operate  $R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - R_1$

$$\therefore A = \begin{bmatrix} \cos\theta + \gamma - \cos\theta + \alpha & \sin\theta + \beta - \sin\theta + \alpha & 0 \\ \sin\theta + \beta - \sin\theta + \alpha & \cos\theta + \beta - \cos\theta + \alpha & 0 \\ \sin\theta + \gamma - \sin\theta + \alpha & \cos\theta + \gamma - \cos\theta + \alpha & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \sin(\beta - \gamma) & \sin(\beta - \alpha) & 0 \\ \sin(\gamma - \alpha) & \sin(\alpha - \beta) & 0 \\ \sin(\alpha - \beta) & \sin(\beta - \gamma) & 0 \end{bmatrix}$$

which is independent of  $\theta$ .

2. (a) Given determinant

$$= \begin{vmatrix} 1 & x & x+1 \\ 2x & x(x-1) & (x+1)x \\ 3x(x-1) & x(x-1)(x-2) & (x+1)x(x-1) \end{vmatrix}$$

$$= x(x+1) \begin{vmatrix} 1 & x & 1 \\ 2x & x-1 & x \\ 3x(x-1) & (x-1)(x-2) & x(x-1) \end{vmatrix}$$

$$= x(x+1)(x-1) \begin{vmatrix} 1 & 1 & 1 \\ 2x & x-1 & x \\ 3x & x-2 & x \end{vmatrix}$$

Applying  $C_1 - C_3$  and  $C_2 - C_3$

$$x(x+1)(x-1) \begin{vmatrix} 0 & 0 & 1 \\ x & -1 & x \\ 2x & -2 & x \end{vmatrix} = x(x+1)(x-1)[-2x+2x] = 0$$

$$\therefore f(x) = 0 \Rightarrow f(100) = 0.$$

3. (b)  $C_1 \rightarrow C_1 + C_3 - 2C_2$   $\cos dx$  gives

$$\Delta = \begin{vmatrix} 1+a^2-2a\cos dx & a & a^2 \\ 0 & \cos px & \cos(p+d)x \\ 0 & \sin px & \sin(p+d)x \end{vmatrix}$$

$= (1+a^2-2a\cos dx)\sin dx$ , (which is independent of  $p$ ).

4. (a)  $\Delta = 1(\omega^{3n}-1) + \omega^n(\omega^{2n}-\omega^{2n}) + \omega^{2n}(\omega^n-\omega^{4n})$

$$\Delta = [(\omega^3)^n - 1] + 0 + \omega^{2n}[\omega^n - (\omega^3)^n \cdot \omega^n]$$

$$\Delta = 1 - 1 + 0 + \omega^{2n}[\omega^n - \omega^n] = 0.$$

5. (c)  $\begin{vmatrix} 10! & 11! & 12! \\ 11! & 12! & 13! \\ 12! & 13! & 14! \end{vmatrix} = 10! \cdot 11! \cdot 12! \begin{vmatrix} 1 & 11 & 11 \times 12 \\ 1 & 12 & 12 \times 13 \\ 1 & 13 & 13 \times 14 \end{vmatrix}$

Applying  $R_2 \rightarrow R_2 - R_1$  and  $R_3 \rightarrow R_3 - R_1$

$$= 10! \cdot 11! \cdot 12! \begin{vmatrix} 1 & 11 & 11 \times 12 \\ 0 & 1 & 24 \\ 0 & 2 & 50 \end{vmatrix} = 2(10! \cdot 11! \cdot 12!).$$

6. (a) The determinant can be expanded as

$$\begin{vmatrix} \cos A \cos P + \sin A \sin P & \cos A \cos Q + \sin A \sin Q & \cos A \cos R + \sin A \sin R \\ \cos B \cos P + \sin B \sin P & \cos B \cos Q + \sin B \sin Q & \cos B \cos R + \sin B \sin R \\ \cos C \cos P + \sin C \sin P & \cos C \cos Q + \sin C \sin Q & \cos C \cos R + \sin C \sin R \end{vmatrix}$$

This determinant can be written as 8 determinants and the value of each of these 8 determinants is zero;

$$e.g., \cos P \cos Q \cos R \begin{vmatrix} \cos A & \cos A & \cos A \\ \cos B & \cos B & \cos B \\ \cos C & \cos C & \cos C \end{vmatrix} = 0$$

Similarly other determinants can be shown zero.

7. (c) Here,  $(2\cos x + \sin x) \begin{vmatrix} 1 & \cos x & \cos x \\ 1 & \sin x & \cos x \\ 1 & \cos x & \sin x \end{vmatrix} = 0$

or

$$(2\cos x + \sin x) \begin{vmatrix} 1 & \cos x & \cos x \\ 0 & \sin x - \cos x & 0 \\ 0 & 0 & \sin x - \cos x \end{vmatrix} = 0$$

$$\text{or } (2\cos x + \sin x)(\sin x - \cos x)^2 = 0$$

$$\therefore \tan x = -2, 1. \text{ But } \tan x \neq -2 \text{ in } \left[-\frac{\pi}{4}, \frac{\pi}{4}\right]$$

$$\therefore \tan x = 1. \text{ So, } x = \frac{\pi}{4}.$$

8. (c) Each term in  $\Delta_1 \times \Delta_2$  is the sum of three terms. So each entry in  $C_1$  or  $C_2$  or  $C_3$  in  $\Delta_1 \times \Delta_2$  is the sum of three terms. Hence,  $\Delta_1 \times \Delta_2$  can be

written as the sum of  $3 \times 3 \times 3 = 27$  determinants.

$$\begin{aligned} 9. \quad (b) \quad AB &= \begin{bmatrix} \cos^2 \theta & \sin \theta \cos \theta \\ \sin \theta \cos \theta & \sin^2 \theta \end{bmatrix} \begin{bmatrix} \cos^2 \phi & \sin \phi \cos \phi \\ \sin \phi \cos \phi & \sin^2 \phi \end{bmatrix} \\ &= \begin{bmatrix} \cos \theta \cos \phi \cos \theta - \phi & \cos \theta \sin \phi \cos \theta - \phi \\ \cos \theta \sin \phi \cos \theta - \phi & \sin \theta \sin \phi \cos \theta - \phi \end{bmatrix} \\ &= \cos \theta - \phi \begin{bmatrix} \cos \theta \cos \phi & \cos \theta \sin \phi \\ \cos \theta \sin \phi & \sin \theta \sin \phi \end{bmatrix} \\ &= O, \quad \left( \because \theta - \phi = \frac{\pi}{2} \right). \end{aligned}$$

10. (d) Given, A multiplicative group of  $2 \times 2$  matrices of the form  $\begin{pmatrix} a & a \\ a & a \end{pmatrix}$ . Let  $A = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$  since  $|A| = 0$ , therefore inverse of A does not exist.

$$11. \quad (a) \quad AX = B \Rightarrow A^{-1} \cdot AX = A^{-1} B \Rightarrow X = A^{-1} B = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}.$$

$$\begin{aligned} 12. \quad (a) \quad \text{As we have } A^2 &= 2A - I \Rightarrow A^2 \cdot A = (2A - I)A \\ \Rightarrow A^3 &= 2A^2 - IA = 2(2A - I) - A \Rightarrow A^3 = 3A - 2I \\ &\quad \left\{ \because IA = A \text{ and } A^2 = 2A - I \right\} \end{aligned}$$

$$\text{Similarly, } A^4 = 4A - 3I, A^5 = 5A - 4I.$$

$$\text{Hence } A^n = nA - (n-1)I.$$

$$13. \quad (a) \quad 1 + p + p^2 + \dots + p^n = O$$

Pre-multiplying both sides by  $p^{-1}$

$$p^{-1} + I + Ip + \dots + p^{n-1}I = O \cdot p^{-1}$$

$$p^{-1} + I(1 + p + p^2 + \dots + p^{n-1}) = O$$

$$p^{-1} = -(1 + p + p^2 + \dots + p^{n-1})I$$

$$p^{-1} = -(-p^n) = p^n.$$

$$14. \quad (a) \quad P = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}_{3 \times 3} \begin{bmatrix} -1 & -2 \\ -2 & 0 \\ 0 & -4 \end{bmatrix}_{3 \times 2} \begin{bmatrix} -4 & -5 & -6 \\ 0 & 0 & 1 \end{bmatrix}_{2 \times 3}$$

$$P = \begin{bmatrix} -3 & -14 \\ -8 & -20 \\ -11 & -26 \end{bmatrix}_{3 \times 2} \begin{bmatrix} -4 & -5 & -6 \\ 0 & 0 & 1 \end{bmatrix}_{2 \times 3}$$

$$P = \begin{bmatrix} 12 & 15 & 4 \\ 32 & 40 & 28 \\ 44 & 55 & 40 \end{bmatrix}_{3 \times 3} \Rightarrow P_{22} = 40.$$

$$15. \quad (d) \quad \Delta = \begin{vmatrix} C & 1 & 0 \\ 1 & C & 1 \\ 6 & 1 & C \end{vmatrix} = C[C^2 - 1] - 1[C - 6]$$

$$\therefore C = 2 \cos \theta$$

$$\Delta = 2 \cos \theta (4 \cos^2 \theta - 1) - (2 \cos \theta - 6)$$

$$\Delta = 8 \cos^3 \theta - 4 \cos \theta + 6.$$

$$16. \quad (b) \quad \Delta_1 = \begin{vmatrix} x & b & b \\ a & x & b \\ a & a & x \end{vmatrix} = x^3 - 3abx \quad \frac{d}{dx} \Delta_1 = 3(x^2 - ab)$$

$$\text{and } \Delta_2 = \begin{vmatrix} x & b \\ a & x \end{vmatrix} = x^2 - ab \quad \frac{d}{dx} (\Delta_1) = 3(x^2 - ab) = 3\Delta_2.$$

17. (d) We have  $a_1, a_2, a_3, \dots, a_n$  in G.P.

$$\text{then } r = \frac{a_2}{a_1} \text{ i.e., } r = \frac{a_{n+1}}{a_n} = \frac{a_{n+2}}{a_{n+1}} = \dots$$

Hence

$$\log = \log a_{n+1} - \log a_n = \log a_{n+2} - \log a_{n+1} = \dots$$

$$\text{Now } \begin{vmatrix} \log a_n & \log a_{n+1} & \log a_{n+2} \\ \log a_{n+3} & \log a_{n+4} & \log a_{n+5} \\ \log a_{n+6} & \log a_{n+7} & \log a_{n+8} \end{vmatrix}$$

Operate  $C_2 \rightarrow C_2 - C_1$  and  $C_3 \rightarrow C_3 - C_2$

$$= \begin{vmatrix} \log a_n & (\log a_{n+1} - \log a_n) & (\log a_{n+2} - \log a_{n+1}) \\ \log a_{n+3} & (\log a_{n+4} - \log a_{n+3}) & (\log a_{n+5} - \log a_{n+4}) \\ \log a_{n+6} & (\log a_{n+7} - \log a_{n+6}) & (\log a_{n+8} - \log a_{n+7}) \end{vmatrix}$$

$$= \begin{vmatrix} \log a_n & \log r & \log r \\ \log a_{n+3} & \log r & \log r \\ \log a_{n+6} & \log r & \log r \end{vmatrix} = 0.$$

18. (a) Ratio of cofactor to its minor of the element  $a_{32}$ , which is in the 3rd row and 2nd column =  $(-1)^{3+2} = -1$ . \* \* \*

$$19. \quad (d) \quad \Delta^c = \Delta^{n-1} = \Delta^{3-1} = \Delta^2 = (11)^2 = 121.$$

But we have to find the value of the square of the determinant, so required value is  $(121)^2 = 14641$ .

$$20. \quad (b) \quad \text{From Cramer's rule, } x = \frac{D_x}{D} = \frac{\begin{vmatrix} -d_1 & b_1 & c_1 \\ -d_2 & b_2 & c_2 \\ -d_3 & b_3 & c_3 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}}$$

$$x = \frac{-\Delta(bcd)}{\Delta(abd)}.$$

$$21. \quad (b) \quad \text{Given } 4A^3 + 2A^2 + 7A + I = O$$

Pre-multiply with  $A^{-1}$

$$A^{-1}[4A^3 + 2A^2 + 7A + I] = O$$

$$4/A^2 + 2/A + 7/I + A^{-1}I = O \cdot A^{-1}$$

$$4(A^2 + 2A + 7) + A^{-1}I = O$$

$$A^{-1} = -(4A^2 + 2A + 7).$$

$$22. \quad (d) \quad \text{Since } (AB)^{-1} = B^{-1}A^{-1}.$$

23. (b) The given matrix is

$$\begin{bmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{bmatrix}, \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 - x_1 & y_2 - y_1 & 0 \\ x_3 - x_1 & y_3 - y_1 & 0 \end{vmatrix}$$

Using  $R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - R_1$

$$\begin{vmatrix} x_2 - x_1 & y_2 - y_1 \\ x_3 - x_1 & y_3 - y_1 \end{vmatrix} \neq 0$$

$\therefore$  The rank of matrix is always less than 2.

24. (d) For the given matrix to be singular, we must

$$\text{have, } \begin{vmatrix} 3 & -1+x & 2 \\ 3 & -1 & x+2 \\ x+3 & -1 & 2 \end{vmatrix} = 0$$

$$\begin{vmatrix} 3 & -1+x & 2 \\ 0 & -x & x \\ x & -x & 0 \end{vmatrix} = 0, \quad ,$$

$[R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - R_1]$

$$\begin{vmatrix} x+4 & -1+x & 2 \\ 0 & -x & x \\ 0 & -x & 0 \end{vmatrix} = 0, [C_1 \rightarrow C_1 + C_2 + C_3]$$

$$(x+4)(0+x^2) = 0 \Rightarrow x = -4, 0$$

Note that only  $-4 \in [-4, -1]$ .

25. (b) Since  $A^{-1} = \frac{\text{adj}A}{|A|}$  and if  $\lambda$  is eigen value of  $A$ ,

then  $\lambda^{-1}$  is eigen value of  $A^{-1}$ .

Thus for  $\text{adj}(A)X = (A^{-1}X)|A| = |A|\lambda^{-1}X$ .

Thus, eigen value corresponding to  $\lambda = 3$  is  $4/3$  and corresponding to  $\lambda = -2$  is  $4/-2 = -2$ .