

7/10/2022  
Tuesday

## MODULE :

Class Polynomial And Non-Polynomial {Class P & NP}

### NP Hard and NP Complete

Some computational problems are hard and difficult, for these problems no efficient algorithm exists. A concept known as NP completeness deals with finding of an efficient algorithm for certain problems.

The notion of efficient is used to describe that a problem's algorithm's running time is proportional to the polynomial function of its input size  $n$ . Thus for some constant  $k > 0$ , the algorithm is efficient, if it runs in  $O(n^k)$  times for input of size  $n$ .

### Class P

Class which contains all problems that are solvable in polynomial time. P is the set of decision problem with yes/no answer, i.e. polynomial bound.

An algorithm is said to be polynomial bounded, if its worst case complexity is bound by a polynomial function  $P$  of input size  $n$  in that case for each input of size  $n$ .



the algorithm terminates after at most  $PC(n)$  steps.

For example

$$n^2 + 13n + 10$$

7. Imps

### Decision Problem

The problems under this class have a single bit output which shows 0 or 1 i.e. the answer for the problem is either 0 or 1.

For example some decision problems are:

- i) Given 2 sets of strings  $S_1$  and  $S_2$ , then  $S_2$  is a substring of  $S_1$ .
- ii) Given 2 sets of elements  $S_1$  and  $S_2$ , then both the sets contain same no. of elements.

Any problem that involves the identification of an optimal value of a given cost function is known as an optimization problem.

For example:

Given a weighted graph  $G$ , and an integer  $i$ . Does  $G$  have a minimal spanning tree of weight at most  $i$ .

### Basic Concepts

Algorithms are divided into 2 groups based on their computing time. The first group consists of problems whose solution times are

bounded by polynomials of small degree  
eg: Order searching -  $O(\log n)$   
Polynomial Evaluation -  $O(n)$  etc..

The 2nd gp is made up of pblms whose best known algorithms are ~~known to~~ Non-Polynomial.

Eg: Travelling Salesperson pblm -  $O(n^2 2^n)$   
Knapsack Pblm -  $O(2^{n/2})$

Notes

There are 2 classes of pblms: NP hard and NP complete.

The pblm is NP complete, has the propy that it can be solved in polynomial time iff all other NP complete pblms can also be solved in ~~NP~~ polynomial time.

If an NP hard pblm can be solved in polynomial time. Then all NP <sup>complete</sup> pblms can be solved in polynomial time. All NP complete pblms are NP hard, but some NP hard pblms are not known to be NP complete.



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## Deterministic / Non-Deterministic

### Non-Deterministic Algorithm

Deterministic Algorithms are algorithms which have the property that the result of every operation is uniquely defined.

Non-deterministic algorithms are algorithms which contains operations whose outcomes are not-uniquely defined but are limited to specified set of possibilities.

To specify such algorithms 3 new functions are introduced:

i) Choice of  $S$

Arbitrarily chooses one of the elements of set  $S$

ii) Failure

Signals & unsuccessful completion

iii) Success

Signals a successful completion

Whenever there is a set of choices that leads to a successful completion, then one such set of choices is always made and the algorithm terminates successfully. A non-deterministic

algorithm terminates unsuccessfully iff  $\nexists$  no set of choices leading to a success signal

### Algorithm Non-Deterministic-Search

1  $j = \text{choice}(1, n)$

2 If  $a(j) = S$

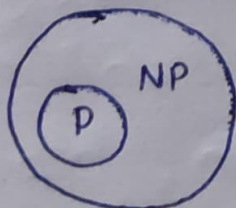
{ write  $C(j)$   
success;  
}

3 write  $C(n)$ ; failure

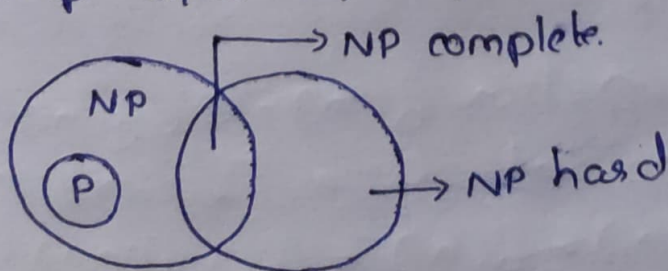
The classes NP hard & NP complete

P is the set of all decisions solvable by deterministic algorithms in polynomial time  
NP is the set of all decision problems solvable by non-deterministic algorithms in polynomial time. i.e.  $P \subseteq NP$ .

Relationship b/w P and NP



Relationship b/w P, NP, NP complete & NP hard





There are NP hard pblms, that are not NP complete. Only a decision pblm can be NP complete. An optimization pblm may be NP hard.

### Maximum Clique Problem

A maximal complete subgraph of a graph  $G = (V, E)$  is a clique, the size of the clique is the no. of vertices in it. The max clique pblm is an optimization pblm, that has to determine the size of largest clique in it.

The corresponding decision pblm is to determine whether  $G$  has a <sup>clique of</sup> size at least  $k$  for some given  $k$ .

