基於OpenCV DNN模塊給黑白老照片上色(附Python/C++源碼)

原創 Color Space OpenCV與AI深度學習 2022-02-16 08:05

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遵讀

本文給大家分享一個用OpenCV DNN模塊給黑白老照片上色的實例,並給出Python和C++版本源碼。

背景介紹

這個項目是基於在加利福尼亞大學,伯克利,Richard Zhang,Phillip Isola和Alexei A. Efros開發的研究工作--Colorful Image Colorization,對應論文地址:

https://arxiv.org/pdf/1603.08511.pdf,作者項目github地址:

https://github.com/richzhang/colorization/tree/caffe



正如在最初的論文中所解釋的,作者們接受了問題的潛在不確定性,將其作為一項分類任務,在訓練時使用類別再平衡來增加結果中的顏色多樣性。人工智能(AI)方法在測試時在CNN("卷積神經網絡")中作為前饋傳遞實現,並在100多萬張彩色圖像上進行訓練。

這個項目將使用的顏色空間模型是"Lab"。CIELAB顏色空間(也稱為CIE L*a*b*或有時簡稱為"Lab"顏色空間)是國際照明委員會(CIE)在1976年定義的顏色空間。它將顏色表示為三個數值,L*表示亮度,a*和b*表示綠色、紅色和藍黃色。

深度學習的過程:正如引言中所述,人工智能(AI)方法在測試時作為CNN("卷積神經網絡")中的前饋傳遞實現,並在100多萬張彩色圖像上進行訓練。換句話說,數百萬張彩色照片使用Lab模型進行分解,並用作輸入特徵("L")和分類標籤("a"和"b")。為了簡單起見,我們分成兩部分:"L"和"a+b",如方框圖所示:

有了經過訓練的模型(可以公開獲得),我們可以用它給一個新的黑白照片上色,這張照片
作為模型或組件"L"的輸入。模型的輸出將是其他組件"a"和"b",它們一旦添加到原始"L"
· 將返回一張完整的彩色照片· 如下所示:

简言之,使用ImageNet的130万张照片的广泛多样的对象和场景数据集,并应用深度学习算法(前馈CNN),生成了最终模型,可在以下网址获得:

https://github.com/richzhang/colorization/tree/caffe/models

效果展示

01:09

详细步骤与演示

OpenCV DNN模块可以直接使用Caffe训练好的模型,下面是加载模型测试步骤:

【1】下载模型和配置文件:

```
wget http://eecs.berkeley.edu/~rich.zhang/projects/2016_colorization/files/demc

(2) 准备测试图片--黑白老照片:
```

【3】代码测试:

Python OpenCV实现代码:

```
# 公众号:OpenCV与AI深度学习
# Importing Libraries
import numpy as np
import matplotlib.pyplot as plt
import cv2

print(cv2.__version__)

# Path of our caffemodel, prototxt, and numpy files
prototxt = "./model/colorization_deploy_v2.prototxt"
caffe_model = "./model/colorization_release_v2.caffemodel"
pts_npy = "./model/pts_in_hull.npy"

img_path = './imgs/11.jpg'
# Loading our model
net = cv2.dnn.readNetFromCaffe(prototxt, caffe_model)
```

```
17 pts = np.load(pts_npy)
19 layer1 = net.getLayerId("class8_ab")
20 print(layer1)
21 layer2 = net.getLayerId("conv8 313 rh")
22 print(layer2)
23 pts = pts.transpose().reshape(2, 313, 1, 1)
24 net.getLayer(layer1).blobs = [pts.astype("float32")]
25 net.getLayer(layer2).blobs = [np.full([1, 313], 2.606, dtype="float32")]
27 # Converting the image into RGB and plotting it
28 # Read image from the path
29 test_image = cv2.imread(img_path)
30 # Convert image into gray scale
31 test_image = cv2.cvtColor(test_image, cv2.COLOR_BGR2GRAY)
32 # Convert image from gray scale to RGB format
33 test_image = cv2.cvtColor(test_image, cv2.COLOR_GRAY2RGB)
34 # Check image using matplotlib
35 plt.imshow(test_image)
36 plt.show()
38 # Converting the RGB image into LAB format
39 # Normalizing the image
40 normalized = test_image.astype("float32") / 255.0
41 # Converting the image into LAB
42 lab_image = cv2.cvtColor(normalized, cv2.COLOR_RGB2LAB)
43 # Resizing the image
44 resized = cv2.resize(lab image, (224, 224))
45 # Extracting the value of L for LAB image
46 L = cv2.split(resized)[0]
47 L = 50 \# OR \text{ we can write } L = L - 50
49 # Predicting a and b values
50 # Setting input
51 net.setInput(cv2.dnn.blobFromImage(L))
52 # Finding the values of 'a' and 'b'
53 ab = net.forward()[0, :, :, :].transpose((1, 2, 0))
54 # Resizing
55 ab = cv2.resize(ab, (test_image.shape[1], test_image.shape[0]))
```

```
57 # Combining L, a, and b channels
58 L = cv2.split(lab_image)[0]
59 # Combining L,a,b
60 LAB_colored = np.concatenate((L[:, :, np.newaxis], ab), axis=2)
61 # Checking the LAB image
62 plt.imshow(LAB_colored)
63 plt.title('LAB image')
64 plt.show()
66 ## Converting LAB image to RGB
67 RGB_colored = cv2.cvtColor(LAB_colored,cv2.COLOR_LAB2RGB)
68 # Limits the values in array
69 RGB_colored = np.clip(RGB_colored, 0, 1)
70 # Changing the pixel intensity back to [0,255], as we did scaling during pre-pr
71 RGB_colored = (255 * RGB_colored).astype("uint8")
72 # Checking the image
73 plt.imshow(RGB_colored)
74 plt.title('Colored Image')
75 plt.show()
77 # Saving the colored image
78 # Converting RGB to BGR
79  RGB_BGR = cv2.cvtColor(RGB_colored, cv2.COLOR_RGB2BGR)
80 # Saving the image in desired path
   cv2.imwrite('result.jpg', RGB_BGR)
```

C++ OpenCV实现代码:

```
1 // ImgColorization_OpenCV_DNN.cpp : 此文件包含 "main" 函数。程序执行将在此处开始并
2 // 公众号:OpenCV与AI深度学习
3 #include "pch.h"
4 #include <iostream>
5 #include <opencv2/opencv.hpp>
6 #include <opencv2/dnn.hpp>
7
8 using namespace cv;
9 using namespace cv::dnn;
10 using namespace std;
```

```
// the 313 ab cluster centers from pts_in_hull.npy (already transposed)
  static float hull pts[] = {
    -90., -90., -90., -90., -90., -80., -80., -80., -80., -80., -80., -80.
    -70., -70., -60., -60., -60., -60., -60., -60., -60., -60., -60., -60., -60.
    -50., -50., -50., -50., -50., -50., -40., -40., -40., -40., -40., -40., -40.
    -30., -30., -30., -30., -30., -30., -30., -30., -30., -30., -30., -30.
    -20., -20., -20., -20., -20., -20., -20., -20., -20., -10., -10., -10., -10.
    20., 30., 40., 50., 60., 70., 80., 90., 0., 10., 20., 30., 40., 50., 60., 70
    60., 70., 80., 90., -30., -20., -10., 0., 10., 20., 30., 40., 50., 60., 70.,
    30., 40., 50., 60., 70., 80., 90., 100., -50., -40., -30., -20., -10., 0., 1
    -40., -30., -20., -10., 0., 10., 20., 30., 40., 50., 60., 70., 80., 90., 100
    30., 40., 50., 60., 70., 80., 90., 100., -70., -60., -50., -40., -30., -20.,
    100., -80., -70., -60., -50., -40., -30., -20., -10., 0., 10., 20., 30., 40.
    -40., -30., -20., -10., 0., 10., 20., 30., 40., 50., 60., 70., 80., 90., -90
    0., 10., 20., 30., 40., 50., 60., 70., 80., 90., -100., -90., -80., -70., -6
    40., 50., 60., 70., 80., 90., -100., -90., -80., -70., -60., -50., -40., -30
    80., -110., -100., -90., -80., -70., -60., -50., -40., -30., -20., -10., 0.
    -90., -80., -70., -60., -50., -40., -30., -20., -10., 0., 10., 20., 30., 40.
    -60., -50., -40., -30., -20., -10., 0., 10., 20., 30., 40., 50., 60., 70.,
    -20., -10., 0., 10., 20., 30., 40., 50., 60., 70., -90., -80., -70., -60.,
40 };
  int main()
  {
    string modelTxt = "./model/colorization_deploy_v2.prototxt";
    string modelBin = "./model/colorization_release_v2.caffemodel";
    string img path = "./imgs/10.jpg";
    Mat img = imread(img path);
    if (img.empty())
```

```
cout << "Can't read image from file: " << img_path << endl;</pre>
  return 2;
}
// fixed input size for the pretrained network
const int W in = 224;
const int H_in = 224;
Net net = dnn::readNetFromCaffe(modelTxt, modelBin);
// setup additional layers:
int sz[] = { 2, 313, 1, 1 };
const Mat pts_in_hull(4, sz, CV_32F, hull_pts);
Ptr<dnn::Layer> class8_ab = net.getLayer("class8_ab");
class8_ab->blobs.push_back(pts_in_hull);
Ptr<dnn::Layer> conv8_313_rh = net.getLayer("conv8_313 rh");
conv8_313_rh->blobs.push_back(Mat(1, 313, CV_32F, Scalar(2.606)));
// extract L channel and subtract mean
Mat lab, L, input;
img.convertTo(img, CV_32F, 1.0 / 255);
cvtColor(img, lab, COLOR BGR2Lab);
extractChannel(lab, L, ∅);
resize(L, input, Size(W_in, H_in));
input -= 50;
// run the L channel through the network
Mat inputBlob = blobFromImage(input);
net.setInput(inputBlob);
Mat result = net.forward();
// retrieve the calculated a,b channels from the network output
Size siz(result.size[2], result.size[3]);
Mat a = Mat(siz, CV_32F, result.ptr(0, 0));
Mat b = Mat(siz, CV_32F, result.ptr(0, 1));
resize(a, a, img.size());
resize(b, b, img.size());
// merge, and convert back to BGR
Mat color, chn[] = { L, a, b };
merge(chn, 3, lab);
cvtColor(lab, color, COLOR Lab2BGR);
imshow("color", color);
imshow("original", img);
waitKey();
return 0;
```

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91	}	
	4	
[4]	效果展示:	

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