

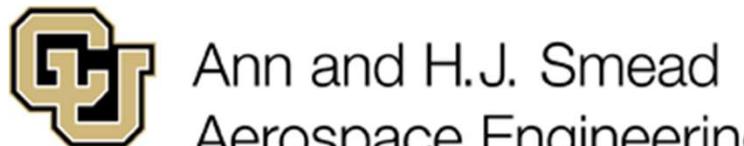
ASEN 5044, Fall 2024

Statistical Estimation for Dynamical Systems

Lecture 15: Mean Vectors and Covariance Matrices;
Multivariate Gaussian Density Functions and
Jointly Gaussian Random Vectors

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Tuesday 10/08/2024



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Announcements

- **Midterm 1: due Thurs 10/10 by 11:59 pm (Gradescope)**

- No office hours today or this week (b/c of exam)

- HW 5 to be posted Thurs 10/10 (to be due Fri 10/1⁸~~11~~)

- Quiz 5 out on Fri 10/11 (due Tues 10/15)

- Next advanced topic Lecture to be posted Fri 10/11

Last Time...

- Joint distributions for multiple random variables and operations
- Continuous multivariate expectations
 - means, cross-moment, covariance, correlation (normalized covariance)
 - examples for simple linear random function of Gaussian random variables

(last time) Useful (Scalar-Valued) Multivariate Moments and Expectations

- Expectation of XY (product of X and Y, i.e. "cross-moment"):

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy \cdot p(x,y) dx dy$$

If $X \perp\!\!\!\perp Y$: $E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy \cdot p(x) \cdot p(y) dx dy$

$$= (\int_{-\infty}^{\infty} x p(x) dx) (\int_{-\infty}^{\infty} y p(y) dy) = E[X] \cdot E[Y] = E[XY]$$

*Statement should read:
 $E[XY] = E[X] \cdot E[Y]$ IF X and Y are independent, i.e. it is sufficient
 (but NOT necessary) for X and Y to be independent for their
 cross-moment to split into the product of their means
 (this is actually different from the fact $p(x,y) = p(x) \cdot p(y)$ if and
 only if [iff] X and Y are independent)

$\underline{y} E[XY] = 0$
 Then we say
 that X & Y
 are
orthogonal RVs

- Covariance of X and Y: how linearly related X and Y are to each other

$$\text{cov}(x,y) \triangleq E[(x - \mu_x)(y - \mu_y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_x)(y - \mu_y) p(x,y) dx dy$$

Foil out:

$$E[XY - x\mu_y - \mu_x y + \mu_x \mu_y] = E[XY] - E[X]\mu_y - \mu_x E[Y] + \mu_x \mu_y = E[XY] - \mu_x \mu_y$$

- Correlation coefficient: covariance normalized by product of standard devs

$$\text{corr}(x,y) = \rho(x,y) \triangleq \frac{\text{cov}(x,y)}{\text{std dev}(x) \cdot \text{std dev}(y)} = \frac{E[(x - \mu_x)(y - \mu_y)]}{\sqrt{\text{var}(x)} \cdot \sqrt{\text{var}(y)}}$$

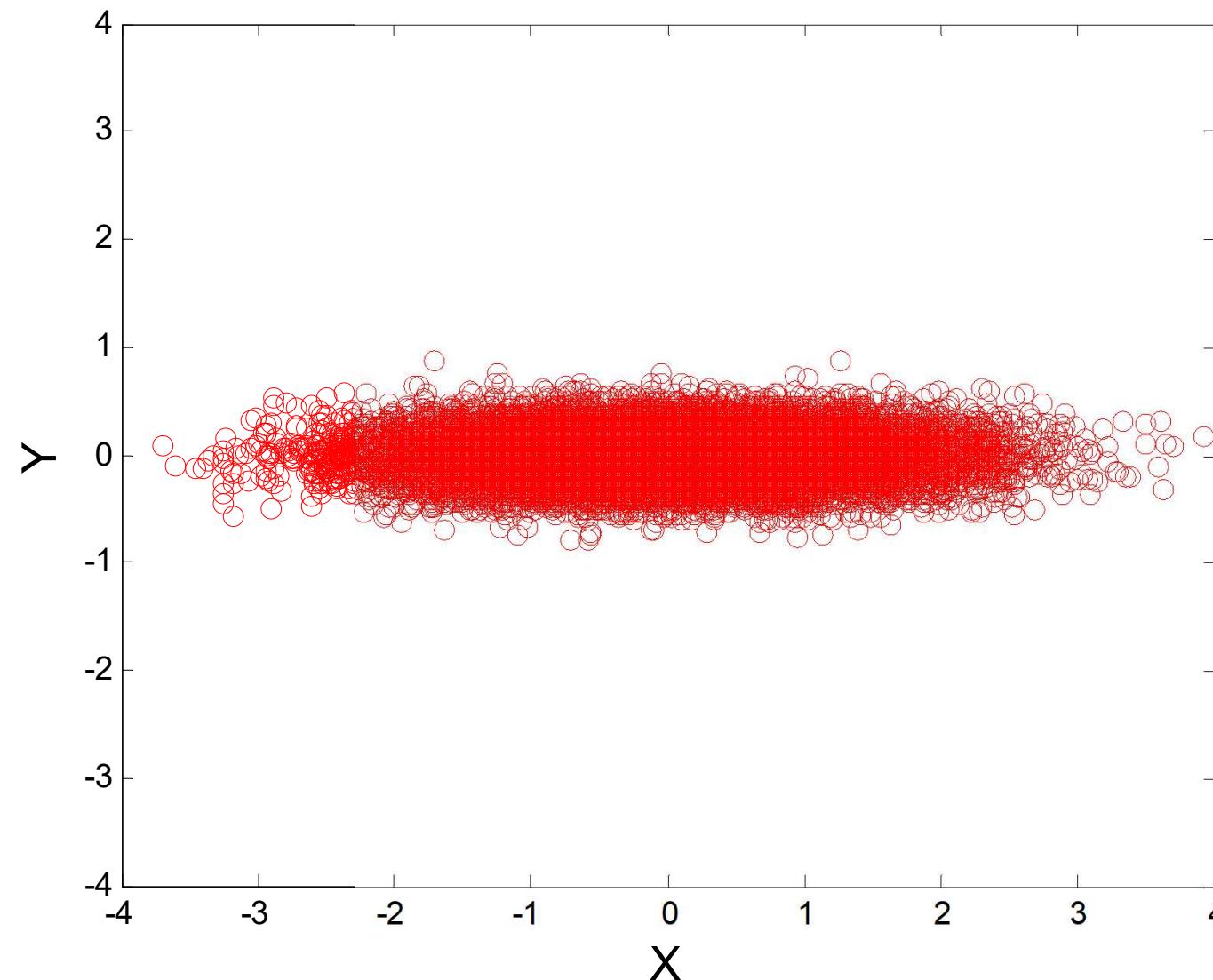
where $\rho \in [-1, 1]$

\downarrow
 "normalized covariance of x & y "

where $\text{var}(x) = E[(x - \mu_x)^2]$
 $\text{var}(y) = E[(y - \mu_y)^2]$

(last time) Example: Sample Covariances and Correlations

- Consider $x \sim N(0,1)$ with 20,000 samples
- Evaluate $y = 0^{\underline{x}} + 0.2^{\underline{e}}$, where error $e \sim N(0,1)$



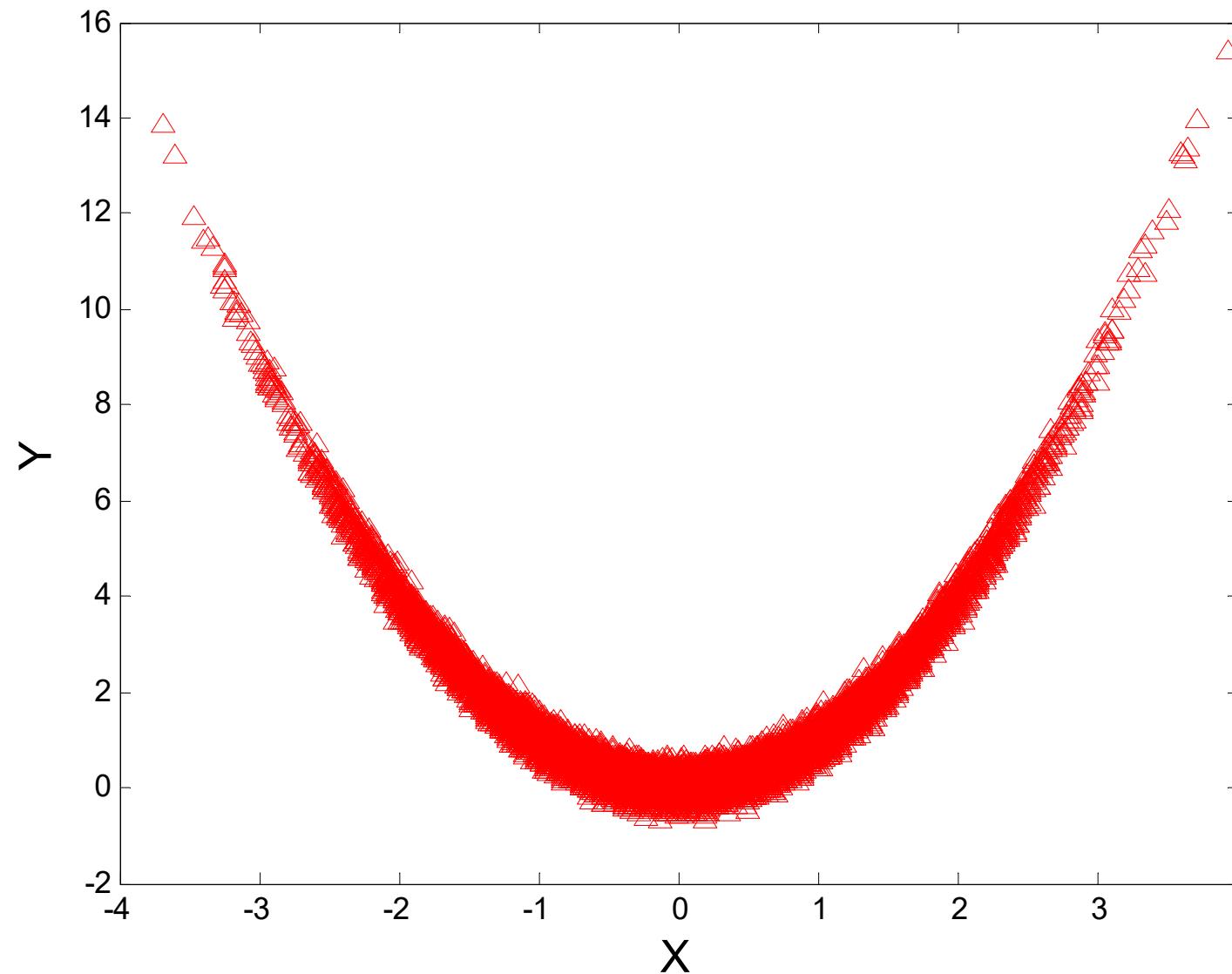
Sample values (Matlab)
 $cov(x, y) = 0.0016$
 $corr(x, y) = \rho = 0.0082$

No linear information between X and Y
(i.e. there is no linear dependence)

$\text{Cov} \& \text{corr} \rightarrow 0$ as $N \rightarrow \infty$
 \rightarrow no linear info b/w x & y
 $\rightarrow x \perp\!\!\!\perp y$

(last time) Example: Sample Covariances and Correlations

- Consider $x \sim N(0,1)$ with 20,000 samples
- Evaluate $y = x^2 + 0.2*e$, where error $e \sim N(0,1)$



Clarification from live lecture discussion: Since X is NOT independent of Y, $E[XY]$ does NOT equal a product of two separate integrals over X and Y (indeed: easy to show $E[XY] = E[X^3]$, which implies integral doesn't split). However, since $E[XY]=E[X^3]=0$ anyway, this gives the same result as $E[X]*E[Y]=0*1=0$ and hence $\text{cov}(X,Y)=0$, so X and Y are still uncorrelated, i.e. X and Y are still not linearly dependent, even though they are probabilistically dependent. This shows that X and Y being (probabilistically) independent is NOT a necessary condition for X and Y to be uncorrelated (even though it is a sufficient condition) - hence the directionality of the "if" statement in the definition of $E[XY]$ in slide 9 (i.e. "only if" does NOT apply, and so we can't say "iff")

Sample values (Matlab)

$$\text{cov}(x, y) = 0.0095$$

$$\text{std}(x) = \sqrt{0.9911}$$

$$\text{std}(y) = \sqrt{2.0119}$$

$$\text{corr}(x, y) = \rho = 0.0067$$

Covariance and correlation $\rightarrow 0$
as we get more and more samples...

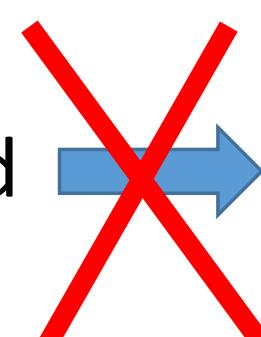
\rightarrow X and Y are not linearly related,
but they are not independent!!

(last time) Difference Between Dependence and Correlation

VERY IMPORTANT:

- If X and Y are independent  X and Y are uncorrelated

(Independence is sufficient for uncorrelatedness)

- If X and Y are uncorrelated  X and Y are independent

(Independence is NOT NECESSARY for uncorrelatedness)

Today...

- Mean vectors and covariance matrices
- Multivariate Gaussian PDFs
- Marginals of multivariate Gaussian PDFs
- Linear function with Gaussian noise sampling problem revisited
 - Empirical vs. Theoretical Expected Values

READ SIMON BOOK, CHAPTER 3.1

N-dimensional Random Vectors

- To deal with n-dimensional dynamic state vectors and state space models with noise, need to work with **random vectors**
- Stack continuous scalar random vars on top of each other with a well-defined joint pdf

Given n scalar random vars X_1, X_2, \dots, X_n , define the *random vector*

$$\vec{X} = \begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix} \text{ with realizations } \vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \text{ and (joint) pdf } p(\vec{X}) = p(X_1, \dots, X_n).$$

→ Define the *mean vector* as $\vec{m} = \begin{bmatrix} m_1 \\ \vdots \\ m_n \end{bmatrix} = E[\vec{X}] = \int_{-\infty}^{\infty} \vec{x} \cdot p(\vec{x}) d\vec{x}$

$$= \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \cdot p(x_1, \dots, x_n) dx_n \cdots dx_1,$$

where *marginal mean* of x_i is $m_i = \int_{-\infty}^{\infty} \cdots \int_{-\infty}^{\infty} x_i \cdot p(x_1, \dots, x_n) dx_n \cdots dx_1$.

Covariance Matrices

- Consider n-dimensional set of RVs X_1, X_2, \dots, X_n with joint pdf $p(X_1, X_2, \dots, X_n)$
- Can assemble all variances and covariances into the $n \times n$ **covariance matrix**

$$C \stackrel{\text{def. used as}}{=} E[(\vec{x} - \vec{m})(\vec{x} - \vec{m})^T] = \int_{-\infty}^{\infty} (\vec{x} - \vec{m})(\cdots)^T p(\vec{x}) d\vec{x} = E[\vec{x}\vec{x}^T] - \vec{m}\vec{m}^T$$

$$\rightarrow C = \begin{bmatrix} E[(x_1 - m_1)^2] & E[(x_1 - m_1)(x_2 - m_2)] & \cdots & E[(x_1 - m_1)(x_n - m_n)] \\ E[(x_2 - m_2)(x_1 - m_1)] & E[(x_2 - m_2)^2] & \cdots & E[(x_2 - m_2)(x_n - m_n)] \\ \vdots & \vdots & \ddots & \vdots \\ E[(x_n - m_n)(x_1 - m_1)] & E[(x_n - m_n)(x_2 - m_2)] & \cdots & E[(x_n - m_n)^2] \end{bmatrix}$$

$$= \begin{bmatrix} \sigma_{x_1}^2 & c_{12} & \cdots & c_{1n} \\ c_{21} & \sigma_{x_2}^2 & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \cdots & \sigma_{x_n}^2 \end{bmatrix}$$

where $\sigma_{x_i}^2 = \sigma_i^2 = \text{var}(x_i) = E[(x_i - m_i)^2]$ (=scalar)

and $c_{ij} = c_{ji} = E[(x_i - m_i)(x_j - m_j)]$ (=scalar)
 $= \underline{\underline{\rho_{ij}}} \cdot \sigma_{x_i} \cdot \sigma_{x_j}$ (=scalar)

(symmetric square positive (semi)definite matrix)

The Multivariate Normal (Gaussian) PDF

- Random vars X_1, \dots, X_n are said to be ***jointly normal (Gaussian)*** if their joint pdf is

$$p(\vec{X}) = \frac{1}{(2\pi)^{\frac{n}{2}} |C|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\vec{x} - \vec{m})^T C^{-1} (\vec{x} - \vec{m}) \right\}$$

Square of Mahalanobis distance = $\|(\vec{x} - \vec{m})\|_C^{-1}^2$
 [special case of a quadratic form that has many applications in statistics]

↓
Scalar output density
 from vector \vec{x}
 & mean vector \vec{m}
 & covariance C !

$= \mathcal{N}(\vec{m}, C)$ → completely defined by $\vec{m} \in \mathbb{R}^{n \times 1}$ [mean vector]
 & $C \in \mathbb{R}^{n \times n}$ [covar. matrix]
 (sym, posdef)

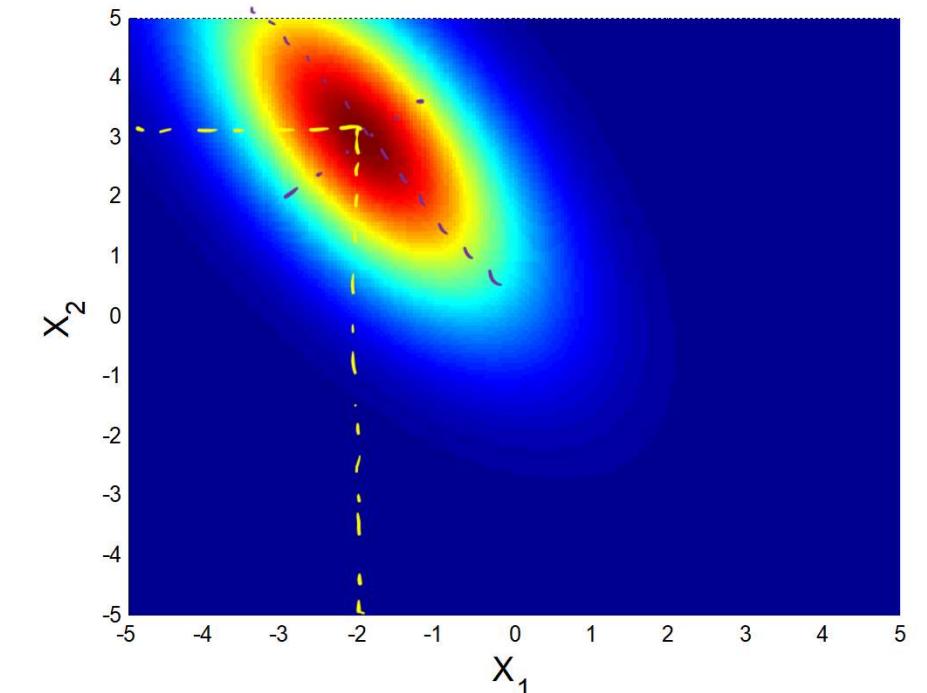
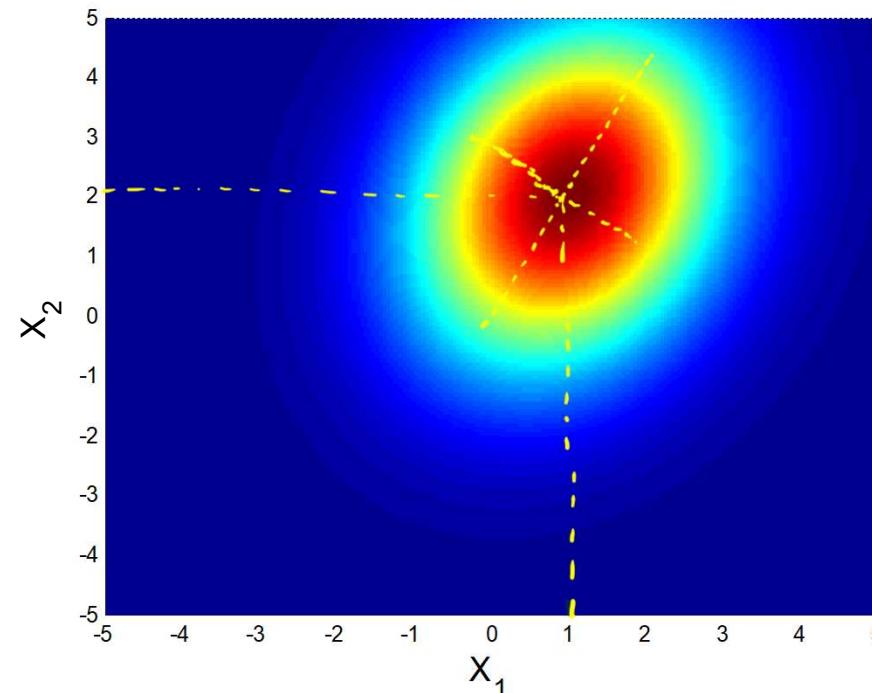
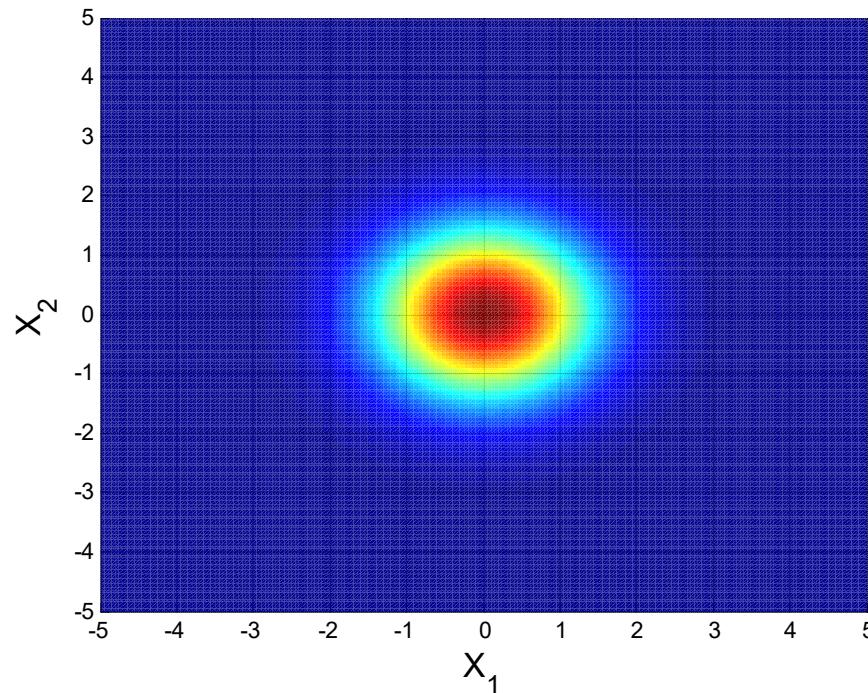
→ If $\vec{x} \sim \mathcal{N}(\vec{m}, C)$, then \vec{x} is said to be a Gaussian random vector

→ matlab: can compute $p(\vec{x})$ for any given \vec{x}, \vec{m} & C using "mvnpdf.m"

Example: 2D Multivariate Gaussian PDFs

- Special multivariate expectations: means, covariance, correlation
- Multivariate Normal (Gaussian) PDFs for random vectors

$$p(\vec{X}) = \frac{1}{(2\pi)^{\frac{n}{2}} |C|^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2} (\vec{x} - \vec{m})^T C^{-1} (\vec{x} - \vec{m}) \right\} = \mathcal{N}(\vec{m}, C)$$



$$\vec{m}_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad C_1 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\vec{m}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad C_2 = \begin{bmatrix} 2 & 0.6 \\ 0.6 & 4 \end{bmatrix}$$

$$\vec{m}_3 = \begin{bmatrix} -2 \\ 3 \end{bmatrix}, \quad C_3 = \begin{bmatrix} 2 & -1.8 \\ -1.8 & 4 \end{bmatrix}$$

Looking Inside the Multivariate Gaussian Terms

- Consider the expansion for a general bivariate normal pdf:

$$\vec{X} = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}, \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \vec{m} = \begin{bmatrix} m_1 \\ m_2 \end{bmatrix},$$

$$C = E[(x - \vec{m})(\dots)^T] = \begin{bmatrix} E[(x_1 - m_1)^2] & E[(x_1 - m_1)(x_2 - m_2)] \\ E[(x_2 - m_2)(x_1 - m_1)] & E[(x_2 - m_2)^2] \end{bmatrix} = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$$

→ easy to show: $|C| = (1 - \rho^2)\sigma_1^2\sigma_2^2$,

$$\text{and } C^{-1} = \begin{bmatrix} \frac{1}{(1-\rho^2)\sigma_1^2} & \frac{-\rho}{(1-\rho^2)\sigma_1\sigma_2} \\ \frac{-\rho}{(1-\rho^2)\sigma_1\sigma_2} & \frac{1}{(1-\rho^2)\sigma_2^2} \end{bmatrix}$$

→ plug $|C|$ and C^{-1} into the definition of $p(\vec{X}) = \mathcal{N}_{\vec{x}}(\vec{m}, C)$ from prev slides:

$$p(\vec{X}) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \cdot \exp \left\{ -\frac{1}{2(1-\rho^2)} \cdot \left[\underbrace{\frac{(x_1 - m_1)^2}{\sigma_1^2}}_{-\frac{1}{2} * \text{square of Mahalanobis distance for n=2 dims}} - \underbrace{\frac{2\rho(x_1 - m_1)(x_2 - m_2)}{\sigma_1\sigma_2}}_{x_1 \neq x_2 \text{ b/c of coupling when } \rho \neq 0} + \underbrace{\frac{(x_2 - m_2)^2}{\sigma_2^2}}_{\text{square of Mahalanobis distance for n=2 dims}} \right] \right\}$$

Marginal Distributions of Multivariate Gaussian PDFs

Suppose random vecs $\vec{x}_1 \in \mathbb{R}^{n_1}$ and $\vec{x}_2 \in \mathbb{R}^{n_2}$ are *jointly Gaussian*, such that

$$\vec{X} = \begin{bmatrix} \vec{X}_1 \\ \vec{X}_2 \end{bmatrix} \in \mathbb{R}^{(n_1+n_2) \times 1} \quad \text{and} \quad p(\vec{X}) = p\left(\begin{bmatrix} \vec{X}_1 \\ \vec{X}_2 \end{bmatrix}\right) = \mathcal{N}(\vec{m}, C),$$

where $\vec{m} = \begin{bmatrix} \vec{m}_1 \\ \vec{m}_2 \end{bmatrix} \in \mathbb{R}^{(n_1+n_2) \times 1}$ and $C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} \in \mathbb{R}^{(n_1+n_2) \times (n_1+n_2)}$

$$\vec{m}_1 \in \mathbb{R}^{n_1}, \vec{m}_2 \in \mathbb{R}^{n_2}$$

$$C_{11} = E[(\vec{x}_1 - \vec{m}_1)(\dots)^T] \in \mathbb{R}^{n_1 \times n_1} \text{ (posdef)}$$

$$C_{22} = E[(\vec{x}_2 - \vec{m}_2)(\dots)^T] \in \mathbb{R}^{n_2 \times n_2} \text{ (posdef)}$$

$$C_{12} = E[(\vec{x}_1 - \vec{m}_1)(\vec{x}_2 - \vec{m}_2)^T] \in \mathbb{R}^{n_1 \times n_2}$$

$$C_{21} = C_{12}^T = E[(\vec{x}_2 - \vec{m}_2)(\vec{x}_1 - \vec{m}_1)^T] \in \mathbb{R}^{n_2 \times n_1}$$



***FACT:** the vector marginal pdfs $p(\vec{X}_1)$ & $p(\vec{X}_2)$ are respectively given by:

$$p(\vec{X}_1) = \int_{-\infty}^{\infty} p(\vec{X}) d\vec{X}_2 = \mathcal{N}_{\vec{X}_1}(\vec{m}_1, C_{11})$$

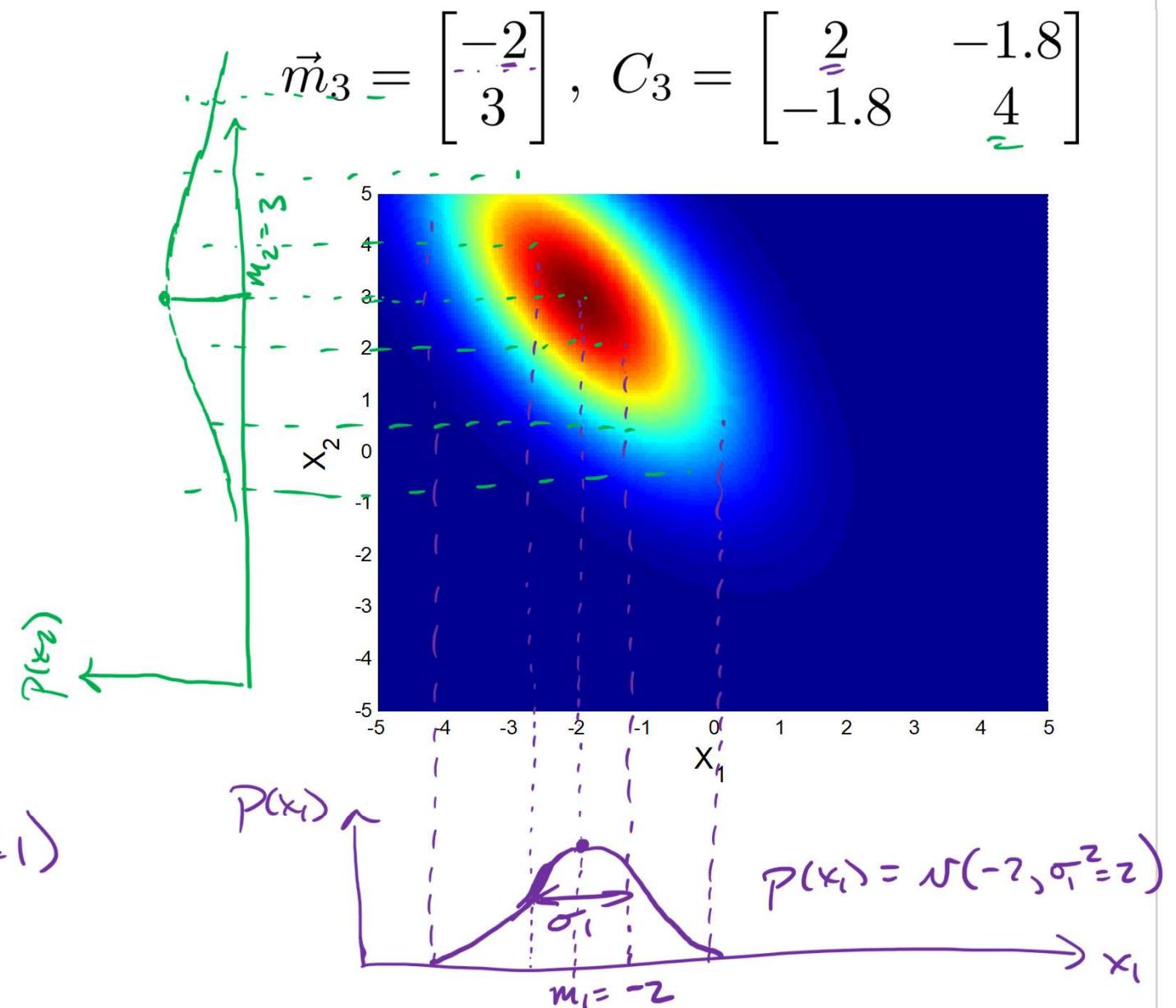
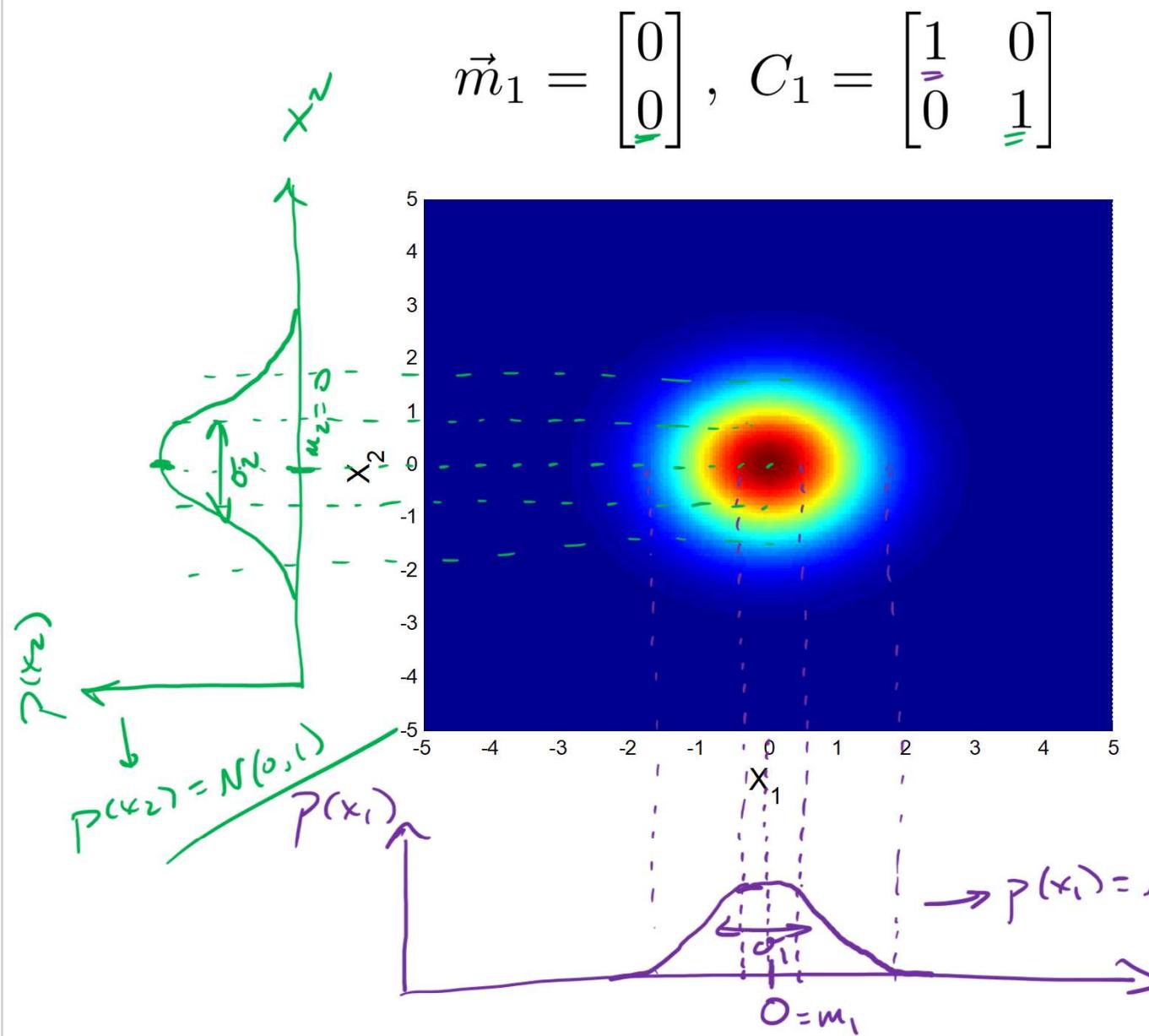
$$p(\vec{X}_2) = \int_{-\infty}^{\infty} p(\vec{X}) d\vec{X}_1 = \mathcal{N}_{\vec{X}_2}(\vec{m}_2, C_{22})$$

only keep rows of \vec{m} and rows/cols of C corresp. to \vec{x}_1 !

only keep rows of \vec{m} and rows/cols of C corresp. to \vec{x}_2 !

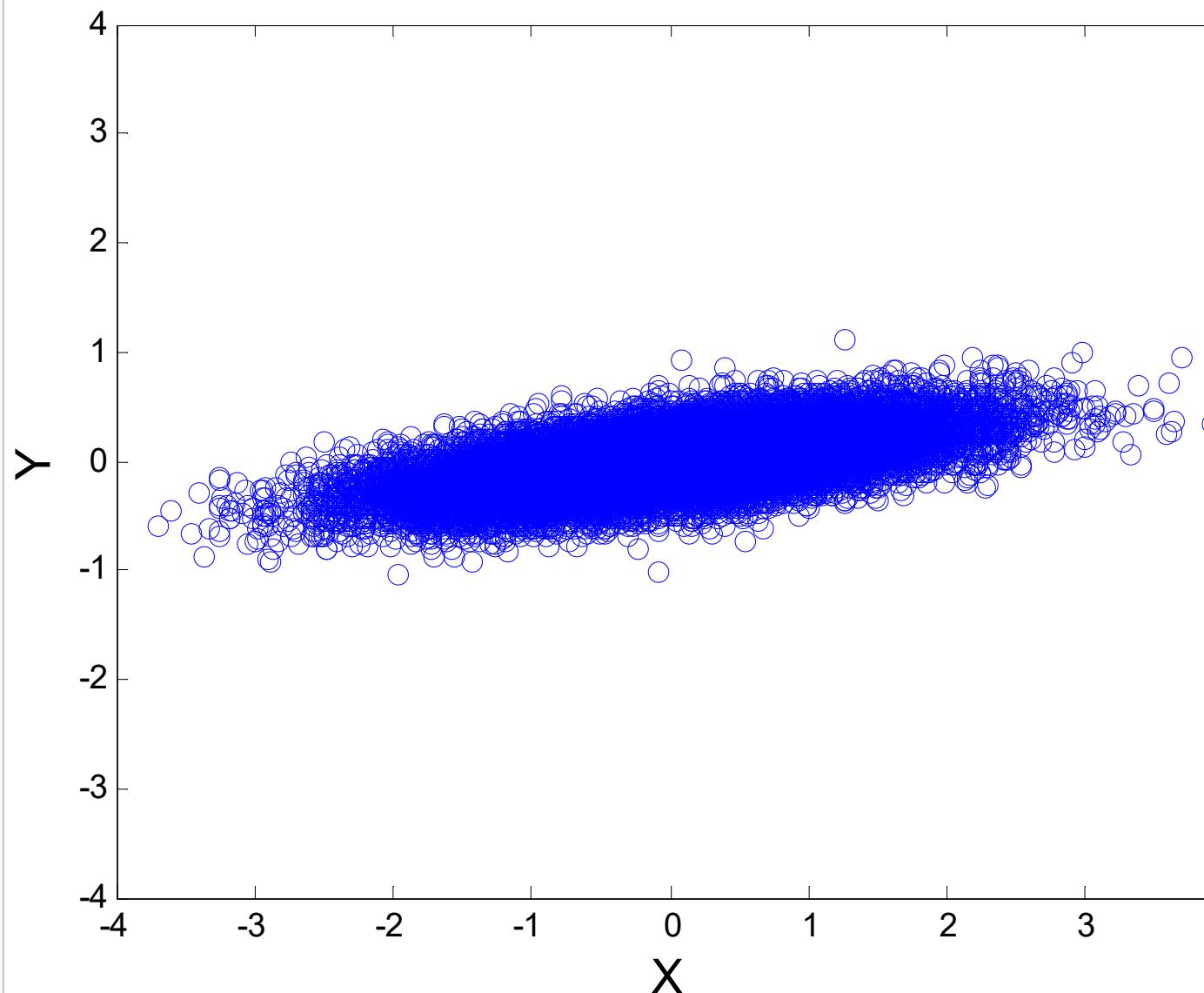
Example: Marginal PDFs of Multivariate Gaussian

- Consider the marginal distributions of two bivariate normal pdfs from before



Revisiting the Gaussian Sampling Experiment

- Consider $x \sim N(0,1)$ with 20,000 samples
- Evaluate $y = 0.15*x + 0.2*e$, where error $e \sim N(0,1)$



-Experimental sample expectation values:

$$\text{cov}(x,y) = 0.1509$$

$$\text{var}(y) = 0.2503$$

$$\text{var}(x) = 0.9955$$

$$\rho(x,y) = 0.6051$$

-If we are given nothing but $p(X)$ and equation for y in terms of x , how to compute theoretical expectations??:

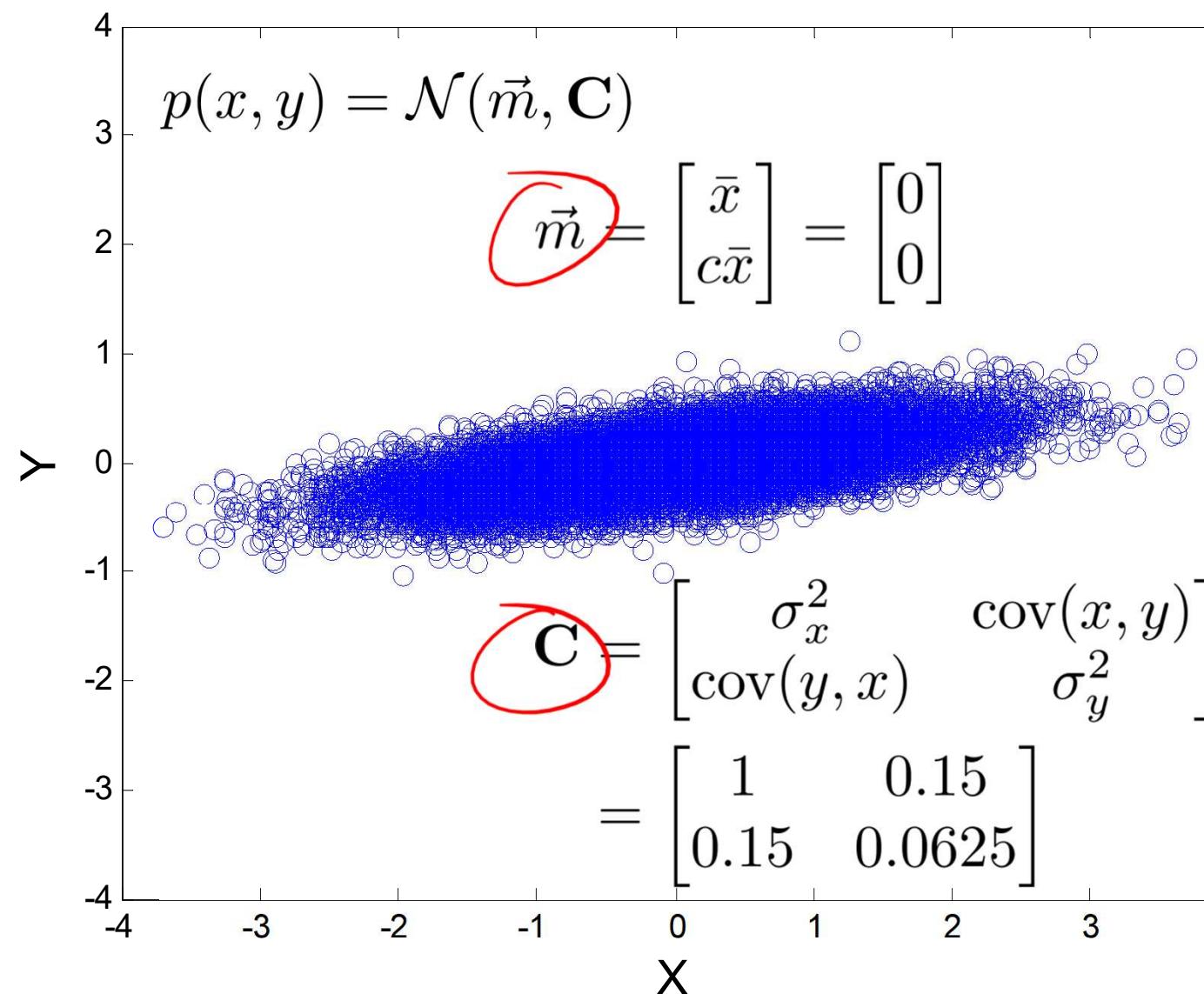
- $\text{cov}(x,y) = ???$
- $\text{var}(y) = ???$
- $\rho(x,y) = ???$
- $\text{mean}(y) = ???$

Revisiting the Gaussian Sampling Experiment

- Consider scalars $x \sim \mathcal{N}(\bar{x}, \sigma_x^2)$, $e \sim \mathcal{N}(0, \sigma_e^2)$, where x and e are indep., and $y = cx + de$ (c and d = constants)
- (i) $m_y = \bar{y} = E[y] = E[cx + de] = c \cdot E[x] + d \cdot E[e] = c\bar{x} + d \cdot 0 = c\bar{x} = \bar{y} = E[y]$
- (ii) $\text{cov}(x, y) = E[(x - \bar{x})(y - \bar{y})] = E[(x - \bar{x})(cx + de - \bar{y})]$
 $= E[x\{cx + de\} - x\bar{y} - \bar{x}\{cx + de\} + \bar{x}\bar{y}]$
 $= \text{linearity of } E \text{ & algebra (do in this)} \rightarrow \text{cov}(x, y) = E[xy] - \bar{x}\bar{y}$
- where $E[xy] = E[x\{cx + de\}] = E[cx^2 + d \cdot e \cdot x] = c \cdot E[x^2] + d \cdot \overline{E[e \cdot x]}$
 $= c \cdot E[x^2]$
 $\text{Var}(x) = E[x^2] - \bar{x}^2 \rightarrow E[x^2] = \text{Var}(x) + \bar{x}^2 = \sigma_x^2 + \bar{x}^2$
 $= c \cdot \{\sigma_x^2 + \bar{x}^2\} = E[xy] \Rightarrow \text{cov}(x, y) = c\sigma_x^2$
- Similarly: can show that $\sigma_y^2 = \text{Var}(y) = E[(y - \bar{y})^2] = c^2\sigma_x^2 + d^2\sigma_e^2$

Revisiting the Gaussian Sampling Experiment

- Consider $x \sim N(0,1)$ with 20,000 samples $\rightarrow \bar{x} = 0, \text{var}(x) = 1$
- Evaluate $y = 0.15x + 0.2e$, where error $e \sim N(0,1)$ $\rightarrow c = 0.15, d = 0.2$



Experimental sample expectation values:

$$\text{cov}(x, y) = 0.1509$$

$$\text{var}(y) = 0.0627$$

$$\text{var}(x) = 0.9955$$

$$\rho(x, y) = 0.6051$$

Exact theoretical expectation values:

$$\text{cov}(x, y) = c\sigma_x^2 = 0.15 * 1 = 0.15$$

$$\text{var}(y) = \sigma_y^2 = c^2\sigma_x^2 + d^2\sigma_e^2 = (0.15)^2 + (0.2)^2 = 0.0625$$

$$\text{var}(x) = \sigma_x^2 = 1$$

$$\rho(x, y) = \text{cov}(x, y) / [\text{stdv}(x) * \text{stdv}(y)] = 0.6$$