

ASEN 6060

ADVANCED ASTRODYNAMICS

Week 3 Discussion

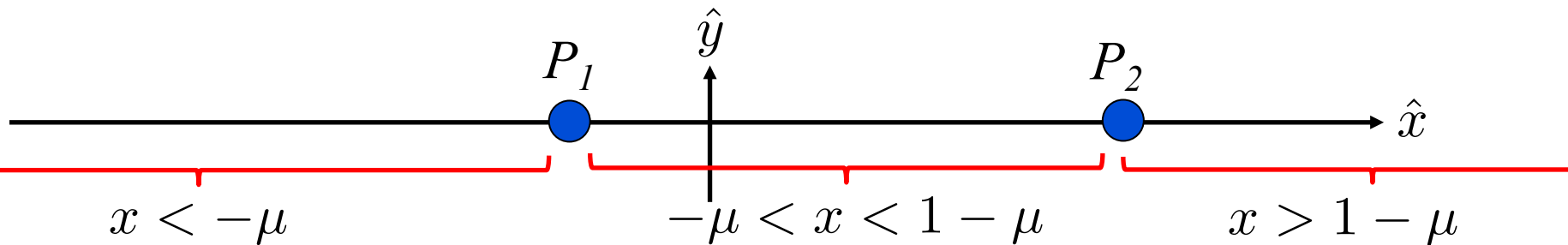
Objectives:

- Understand important considerations in numerically calculating equilibrium point locations
- Connect the evolution of ZVCs as a function of Jacobi constant to the itinerary and maneuvers performed along a trajectory

Questions 1 and 2

Numerically calculating the x -coordinates of the collinear equilibrium points

$$x - \frac{(1 - \mu)(x + \mu)}{(|x + \mu|)^3} - \frac{\mu(x - 1 + \mu)}{(|x - 1 + \mu|)^3} = 0$$



Question 1: How do you select a suitable initial guess along each of the three intervals?

Question 2: How do you verify if your solution corresponds to an equilibrium point?

Questions 1 and 2

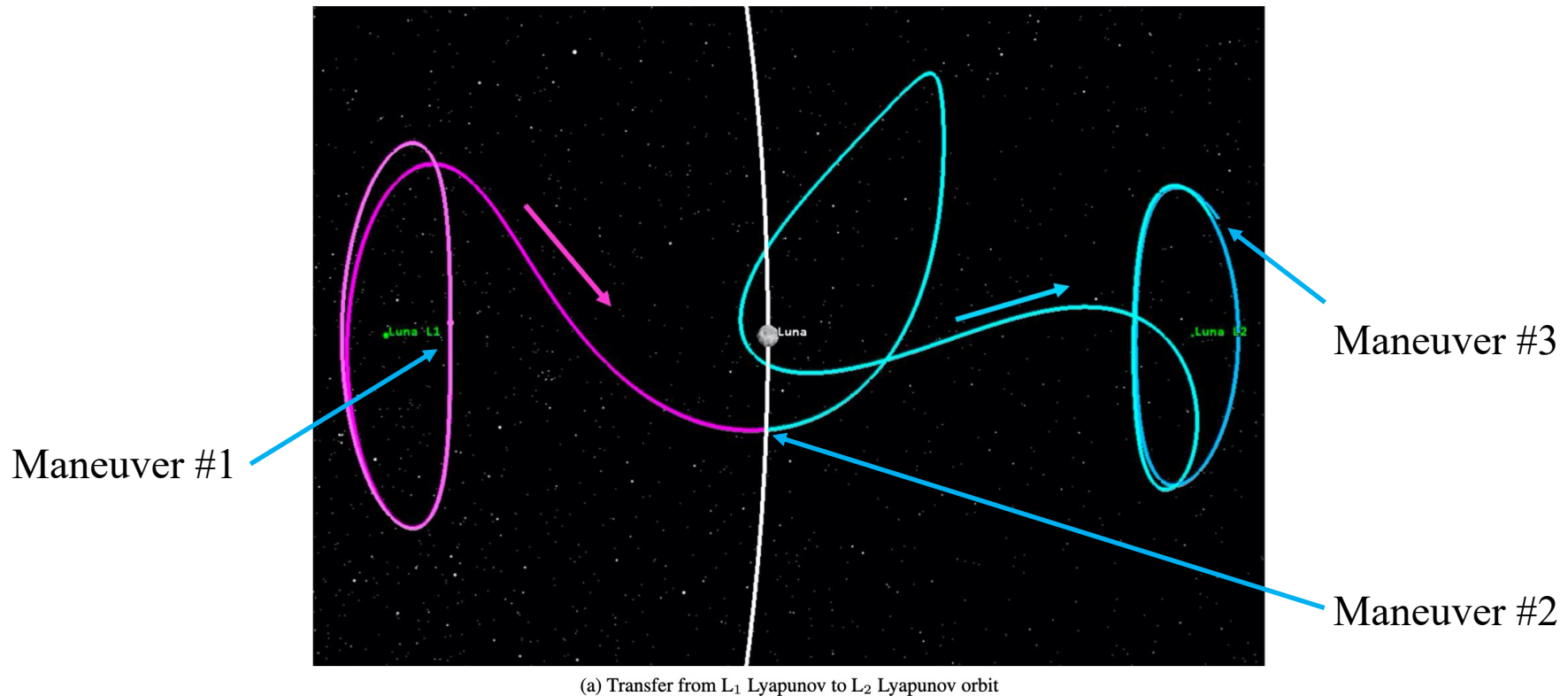
Question 1: How do you select a suitable initial guess along each of the three intervals?

Group Brainstorming:

Question 2: How do you verify if your solution corresponds to an equilibrium point?

Group Brainstorming:

Transfer Example in Earth-Moon CR3BP



Question 3: Based on your knowledge of the CR3BP, what are the constraints on the value of C along the arcs comprising this transfer?

Image credit: Short, Haapala, Bosanac, 2020, “Technical Implementation of the Circular Restricted Three-Body Model in STK Astrogator”, AAS/AIAA Astrodynamics Specialist Conference.

Question 3

Question 3: Based on your knowledge of the CR3BP, what are the constraints on the value of C along the arcs comprising this transfer? What does this tell you about the solution space in general?

Group Brainstorming:

Question 4

Question 4: You and your colleague are each numerically generating a trajectory associated with the same initial state $[x_0, y_0, 0, \dot{x}_0, \dot{y}_0, 0]^T$ and integration time. You are each using your own code or using off-the-shelf software. Do you expect to recover the exact same state as your colleague after the integration time? Why/why not?

Question 4

Question 4: You and your colleague are each numerically generating a trajectory associated with the same initial state $[x_0, y_0, 0, \dot{x}_0, \dot{y}_0, 0]^T$ and integration time. You are each using your own code or using off-the-shelf software. Do you expect to recover the exact same state as your colleague after the integration time? Why/why not?

Question 5

Question 5: I would like to design a trajectory for a new spacecraft to leave a low Earth orbit (LEO) and rendezvous with another spacecraft in orbit near L_2 .

For a spacecraft in LEO,

$$C > C(L_1)$$

Use your knowledge of the ZVCs to describe a variety of possible itineraries for this trajectory and implications for any required maneuvers.

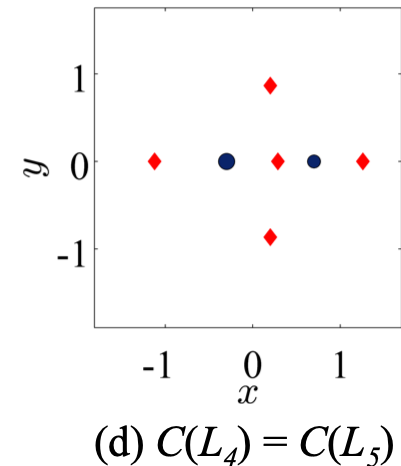
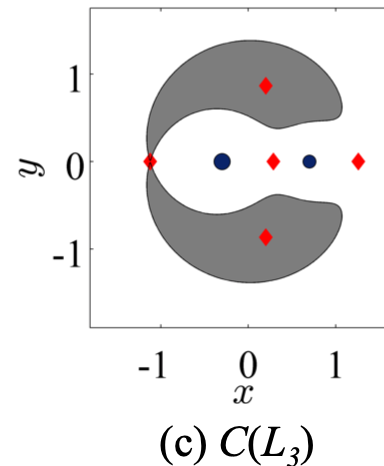
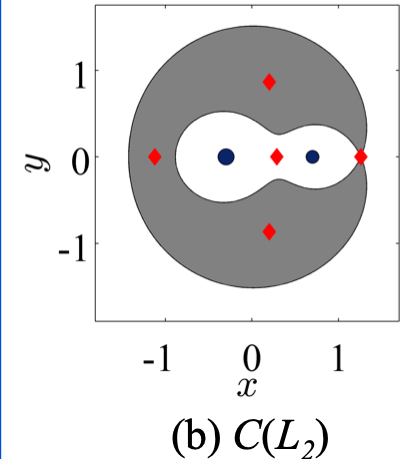
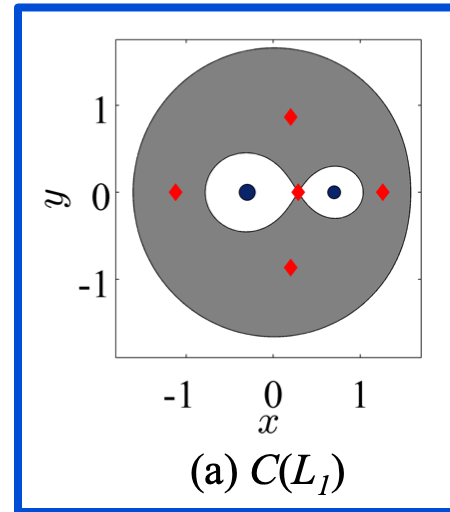


Image credit:
Bosanac, 2016

Question 5

Question 5: I would like to design a trajectory for a new spacecraft to leave a low Earth orbit and rendezvous with the original spacecraft in its final orbit near L_2 .

Use your knowledge of the ZVCs to describe possible itineraries for this trajectory and implications for any required maneuvers.

Group Brainstorming: