ASEN 5044, Fall 2018

Statistical Estimation for Dynamical Systems

Lecture 17 [Special Topic #3]: Multivariate Gaussian Conditional PDFs and Bayes' Rule for Gaussian Random Vectors

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Friday 10/12/2018





Today:

- Conditional expectations and expected values
 - Conditional mean and covariance
- Conditional multivariate Gaussian PDFs
 - \circ Given Gaussian p(x₁,x₂), what is p(x₁|x₂) or p(x₂|x₁)?
- Bayes' rule for multivariate Gaussian PDFs
 - \circ Given p(x,y)=p(x)p(y|x) in factored form, what is p(x|y=c) for Gaussians?

Conditional Expectations and Expected Values

Recall definition of conditional pdf for random variables x₁ and x₂

$$P(x_1|x_2=c) \stackrel{\triangle}{=} \frac{P(x_1,x_2=c)}{P(x_2=c)} = \frac{P(x_1,x_2=c)}{\sum_{i=0}^{\infty} p(x_1,x_2=c)dx_1}$$

$$P(x_2|x_1=d) \stackrel{\triangle}{=} \frac{P(x_1=d,x_2)}{P(x_1=d)} = \frac{P(x_1=d,x_2)dx_2}{\sum_{i=0}^{\infty} p(x_1=d,x_2)dx_2}$$

Concept of expected values naturally extends to conditional expected values

given some fxus f₁(x₁) & f₂(x₂):

$$E[f_1(x_1) | X_2 = c] \triangleq \int_{-\infty}^{\infty} f_1(x_1) \cdot p(x_1 | X_2 = c) \cdot dx_1 \qquad (= E[f_1(x_1)] p(x_1 | x_2 = c))$$

$$E[f_2(x_2) | x_1 = d] \triangleq \int_{-\infty}^{\infty} f_2(x_2) \cdot p(x_2 | x_1 = d) \cdot dx_2 \qquad (= E[f_2(x_2)] p(x_2 | x_1 = d))$$

Conditional Mean and Covariance

• For random vectors with some defined joint distribution, can thus also compute conditional mean vector and conditional covariance matrix

for
$$x_1 \in \mathbb{R}^{n_1}$$
 & $x_2 \in \mathbb{R}^{n_2}$ & $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^n$ ($n = n_1 + n_2$)

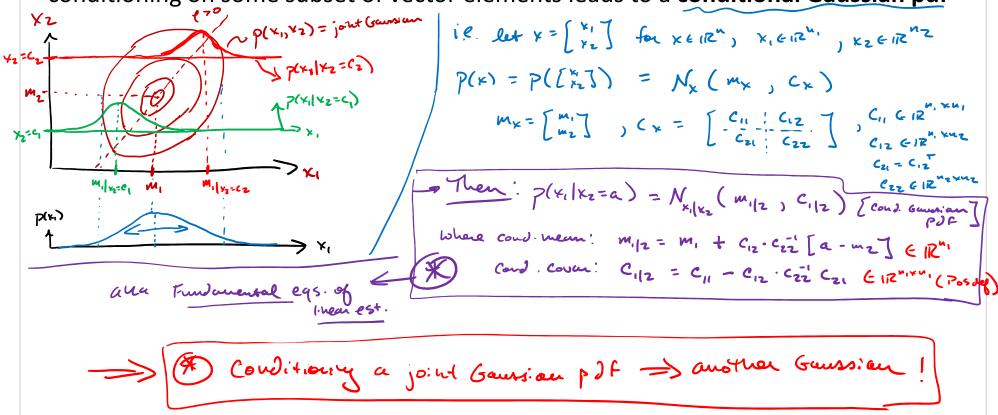
• Conditional Covariance matrix:
$$C_{1/2} \stackrel{\triangle}{=} E[(x_1 - m_{1/2})(x_1 - m_{1/2})^T | x_2 = c]$$

$$= \int_{-\infty}^{\infty} (x_1 - m_{1/2})(...)^T \cdot p(x_1 | x_2 = c) dx_1 \in \mathbb{R}^{n_1 \times n_1}$$

-> andlorgously can define mali & Cali for cond. wearn & cover. of Kz given xi=d

Conditional Gaussian PDFs

• For a Gaussian random vector with multivariate Gaussian joint pdf over its elements, conditioning on some subset of vector elements leads to a **conditional Gaussian pdf**



Derivation Sketch: Conditional Gaussian PDFs

 <u>Key idea:</u> start with definition of conditional pdf for vector random variables, then simplify and massage exponential term to look like multivariate Gaussian pdf over variables to left of conditioning sign (assuming conditioning vars are known/constant)

$$P(x_{1}|x_{2}=c) = \frac{P(x_{1}, x_{2}=c)}{P(x_{1}-c)} = \frac{N_{X}(m_{X}, C_{X})|_{x_{2}=c}}{N_{X_{2}}(m_{Z}, C_{ZZ})|_{x_{2}=c}}$$

$$= \frac{1}{(2\pi)^{N_{2}}|_{C_{Y}}|_{Y_{2}}} e_{X_{1}} \left\{ -\frac{1}{2} \left(\frac{x_{1}}{x_{2}} - \frac{1}{2} \frac{x_{2}}{x_{2}} - \frac{1}{2} \frac{x_{2}$$

Induction of Multivariate Gaussian PDFs

• Suppose we have random vectors x and y, where

• This is actually equivalent to knowing p(x,y) = p(x)p(y|x) (i.e. factorization of joint pdf), since we can "induce" p(y|x) from the given information

Note: Since
$$y = 14 \times 120$$
 $\frac{40 \times 1200}{200} = 14 \times 120$ $y = 14$

Induction of Multivariate Gaussian PDFs

• From knowing p(x) and p(y|x), we can further "induce" all required statistics for joint pdf:

$$P(x,y) = P(IJJ) = N(w,C), \quad m = \sum_{m_1}^{m_2} \sum_{m_2}^{m_2} C_{m_2}^{m_2} C_{m_2}^{m_2}$$

$$\Rightarrow \text{Already known} \quad m_1 \notin C_{KK} \text{ are from } P(K) = N_K(w_{Y},C_{KK})$$

$$\Rightarrow m_{Y} = E[y] = E[H_{X}+W] = E[H_{X}] + E[y] = H \cdot E[K] = H_{W_{X}} = m_{Y}$$

$$\Rightarrow C_{XY} = E[(x-m_{X})(y-m_{Y})] = E[(x-m_{X})(H_{X}+W-H_{W_{X}})]$$

$$= E[(x-m_{X})(H_{X}-m_{Y})] + E[(x-m_{Y})W]$$

$$= E[(x-m_{X})(x-m_{Y})] + E[(x-m_{Y})W]$$

$$= E[(x-m_{Y})(x-m_{Y})] + F[(x-m_{Y})W]$$

$$= E[(x-m_{Y})(x-m_{Y})] + F[(x-m_{Y})(x-m_{Y})]$$

$$= E[(x-m_{Y})(x-m_{Y})] + F[(x-m_{Y})(x-m$$

Upshot: Bayes' Rule for Multivariate Gaussian PDFs

• Thus, starting from p(x) and p(y|x), can immediately write down Bayes' posterior pdf p(x|y) using formulas for conditional Gaussian mean and covariance of x given y:

$$P(x|y) = M_{x|y} \left(m_{x|y}, C_{x|y} \right) \left(= \frac{P(x) \cdot P(y|x)}{S^{op} P(x) P(y|x) dx} \propto P(x) \cdot P(y|x) \right)$$

$$M_{x|y} = m_{x} + C_{xx} \cdot H^{T} \left[HC_{x} H^{T} + R \right]^{-1} \cdot \left(y - Hm_{x} \right)$$

$$C_{x|y} = C_{xx} - C_{xy} C_{yy}^{-1} \left(y_{x} = C_{xx} - C_{xx} H^{T} \left[HC_{x} H^{T} + R \right]^{-1} H \cdot C_{xx} \right)$$

$$P(x|y) = C_{xy} \cdot P(y|x) = C_{xy} \cdot P(y|x) = C_{xy} \cdot P(y|x) = C_{xy} \cdot P(x|y) = C_{x$$