

HW 1

Given:  $\vec{w}_{BN}$ ,  $\vec{w}_{RN}$ ,  $d\vec{w} = \vec{w}_{BN} - \vec{w}_{RN}$ , To find:  ${}^B d\vec{w}$

$$a) {}^B d\vec{w} = {}^B \frac{d}{dt} d\vec{w} = {}^B \frac{d}{dt} (\vec{w}_{BN} - \vec{w}_{RN}) = \frac{d}{dt} {}^B \vec{w}_{BN} - \frac{d}{dt} {}^R \vec{w}_{RN} = {}^B \dot{\vec{w}}_{BN} - {}^R \dot{\vec{w}}_{RN}$$

To get  ${}^B \dot{\vec{w}}$  (which is in B frame)  $\rightarrow {}^B \dot{\vec{w}} = {}^B \vec{w}_{BN} - [BR] {}^R \vec{w}_{RN}$

$$b) {}^B \dot{\vec{w}} = \vec{w}_{BN} - [BR] {}^R \vec{w}_{RN}$$

$$c) - {}^B \dot{\vec{w}} = \frac{B}{dt} \vec{w}_{BN} - \frac{B}{dt} ([BR] {}^R \vec{w}_{RN}) = {}^B \vec{w}_{BN} - [BR] \frac{B}{dt} {}^R \vec{w}_{RN} + [\vec{w}_{BN}] [BR] {}^R \vec{w}_{RN}$$

$$d) - {}^B \frac{d}{dt} {}^R \vec{w}_{RN} = {}^R \dot{\vec{w}}_{RN} + \vec{w}_{RN} \times {}^R \vec{w}_{RN} \quad ( \because [BR] = -[\vec{w}_{BN}] [BR] )$$

Plug b) in c)

$$\begin{aligned} {}^B \dot{\vec{w}} &= {}^B \vec{w}_{BN} - [BR] \left( {}^R \dot{\vec{w}}_{RN} + \vec{w}_{RN} \times {}^R \vec{w}_{RN} \right) + [\vec{w}_{BN}] [BR] {}^R \vec{w}_{RN} \\ &= {}^B \vec{w}_{BN} - [BR] {}^R \dot{\vec{w}}_{RN} - \cancel{\vec{w}_{RN} \times [BR] {}^R \vec{w}_{RN}} + \cancel{[\vec{w}_{BN}] [BR] {}^R \vec{w}_{RN}} \end{aligned}$$

$$e) {}^B \dot{\vec{w}} = {}^B \vec{w}_{BN} - [BR] {}^R \dot{\vec{w}}_{RN}$$

Now, vertical derivative of  $\vec{w}$   $\rightarrow \frac{N}{dt} d\vec{w}$ , use transport theorem

$$\frac{N}{dt} d\vec{w} = {}^B \frac{d}{dt} d\vec{w} + \vec{w}_{BN} \times d\vec{w} = {}^B \dot{\vec{w}} + \vec{w}_{BN} \times d\vec{w}$$

$$f) \frac{N}{dt} d\vec{w} = {}^B \vec{w}_{BN} - [BR] {}^R \dot{\vec{w}}_{RN} + \vec{w}_{BN} \times d\vec{w}$$

2) Define tensor  $T$  in A, B frames as: where  $B: \{\hat{b}_1, \hat{b}_2, \hat{b}_3\}$ ,  $A: \{\hat{q}_1, \hat{q}_2, \hat{q}_3\}$

$${}^A T = \begin{bmatrix} T_{11} \hat{q}_1 \hat{q}_1 & T_{12} \hat{q}_1 \hat{q}_2 & T_{13} \hat{q}_1 \hat{q}_3 \\ T_{21} \hat{q}_2 \hat{q}_1 & T_{22} \hat{q}_2 \hat{q}_2 & T_{23} \hat{q}_2 \hat{q}_3 \\ T_{31} \hat{q}_3 \hat{q}_1 & T_{32} \hat{q}_3 \hat{q}_2 & T_{33} \hat{q}_3 \hat{q}_3 \end{bmatrix} \quad \& \quad {}^B T = \begin{bmatrix} t_{11} \hat{b}_1 \hat{b}_1 & t_{12} \hat{b}_1 \hat{b}_2 & t_{13} \hat{b}_1 \hat{b}_3 \\ t_{21} \hat{b}_2 \hat{b}_1 & t_{22} \hat{b}_2 \hat{b}_2 & t_{23} \hat{b}_2 \hat{b}_3 \\ t_{31} \hat{b}_3 \hat{b}_1 & t_{32} \hat{b}_3 \hat{b}_2 & t_{33} \hat{b}_3 \hat{b}_3 \end{bmatrix}$$

where  $T_{xx}$  &  $t_{xx}$  are arbitrary values.

$$\text{Let } \begin{bmatrix} \hat{b}_1 \\ \hat{b}_2 \\ \hat{b}_3 \end{bmatrix} = \{\hat{b}\} \& \begin{bmatrix} \hat{q}_1 \\ \hat{q}_2 \\ \hat{q}_3 \end{bmatrix} = \{\hat{q}\}, \quad \{\hat{b}\} = [C] \{\hat{q}\} = [BA] \{\hat{q}\}$$

$\{\hat{b}\} \cdot \{\hat{b}\}^T = \text{coordinate set for tensor} \quad (\text{same goes for } \{\hat{q}\} \cdot \{\hat{q}\}^T)$

$$\{\hat{b}\} \cdot \{\hat{b}\}^T = [C] \{\hat{q}\} \cdot ([C] \{\hat{q}\})^T = [C] \{\hat{q}\} \{\hat{q}\}^T [C]^T$$

$$\therefore {}^B [T] = [C] [T] [C]^T$$

3] As seen in 2], tensors' coordinates are matrix multiplication of two vectors such as  $\rightarrow \{\hat{b}\} \cdot \{\hat{b}\}^T$ .

An element of a tensor has 3 components,  $\rightarrow T_{ij} \hat{b}_i \hat{b}_j^T$

so, a derivative of a tensor in a different frame would use the following

$$\text{transport theorem} \rightarrow {}^B[\mathbf{T}] = [C]^A[\mathbf{T}] [C]^T$$

$$\frac{d}{dt} ({}^A[C][\mathbf{T}][C]^T) = \frac{d}{dt} {}^B[\mathbf{T}] + \vec{w}_{BA} \times {}^B[\mathbf{T}]$$

$$\text{for a tensor} \rightarrow \vec{w}_{BA} \times T_{ij} \hat{b}_i \hat{b}_j^T = \cancel{\vec{w}_{BA} \times T_{ij}^0} + \vec{w}_{BA} \times \hat{b}_i T_{ij} \hat{b}_j^T + T_{ij} \hat{b}_i \hat{b}_j^T \times \vec{w}_{BA}^T$$

$$= [\vec{w}_{BA}]^B[\mathbf{T}] + {}^B[\mathbf{T}] [\vec{w}_{BA}]^T$$

$$[C] \frac{d}{dt} {}^A[\mathbf{T}][C]^T = \frac{d}{dt} {}^B[\mathbf{T}] + [\vec{w}_{BA}]^B[\mathbf{T}] + {}^B[\mathbf{T}] [\vec{w}_{BA}]^T$$

(skew-symmetric matrix)  $\rightarrow \vec{w}^T = -\vec{w}^T$

$$\therefore [C] \frac{d}{dt} {}^A[\mathbf{T}][C]^T = \frac{d}{dt} {}^B[\mathbf{T}] + [\vec{w}_{BA}]^B[\mathbf{T}] - {}^B[\mathbf{T}] [\vec{w}_{BA}]$$