#### COMPUTER SYSTEMS ORGANIZATION

ARM ISA -- Spring 2012 -- IIIT-H -- Suresh Purini

#### ARM Processors – History

- □ First ARM Processor
  - Designed by: Acorn Computers Ltd.
  - Where: Cambridge, England.
  - □ Time: 1983-1985.
  - ARM stood for Acorn RISC Machine then.
- □ In 1990
  - Acorn Computers Ltd. became ARM Limited.
  - Acorn RISC Machine is renamed Advanced RISC Machine.

#### How ARM makes money?

- □ Not by selling processors like Intel.
- But by licensing its technology to a network of partners.
- A company that intends to use ARM core in its product
  - Have to pay an upfront licensee fee to gain access to the design.
  - Have to pay royalty for every chip that uses the licensed ARM design.

Homework: Read the web page at this link

http://ir.arm.com/phoenix.zhtml?c=197211&p=irol-homeprofile

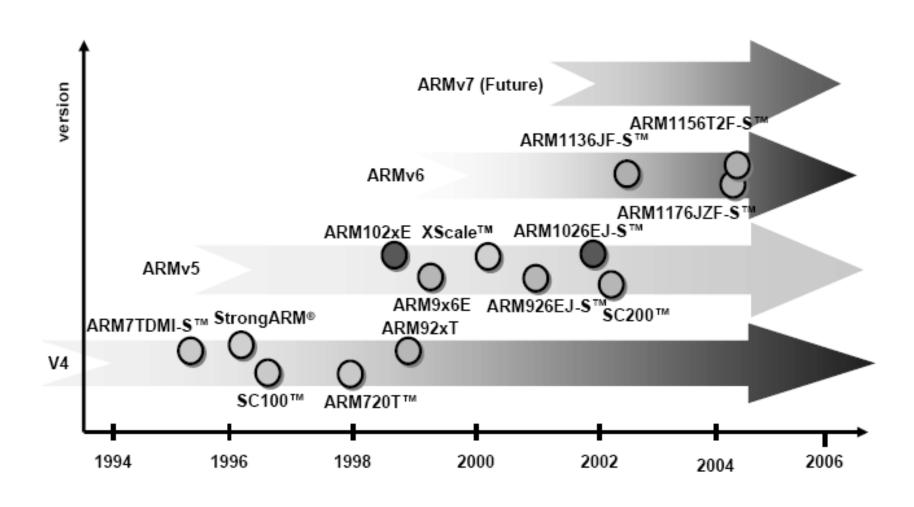
# **ARM Partnership Model**



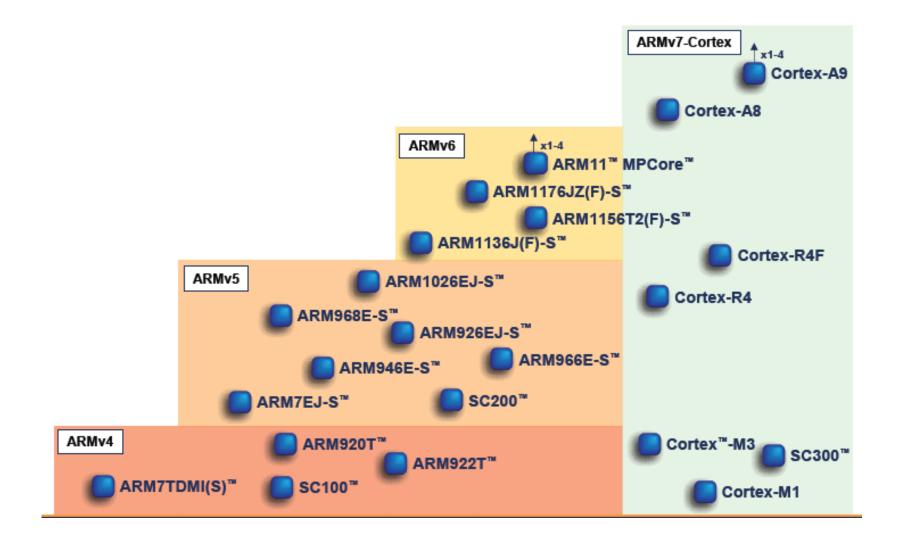
# **Applications**



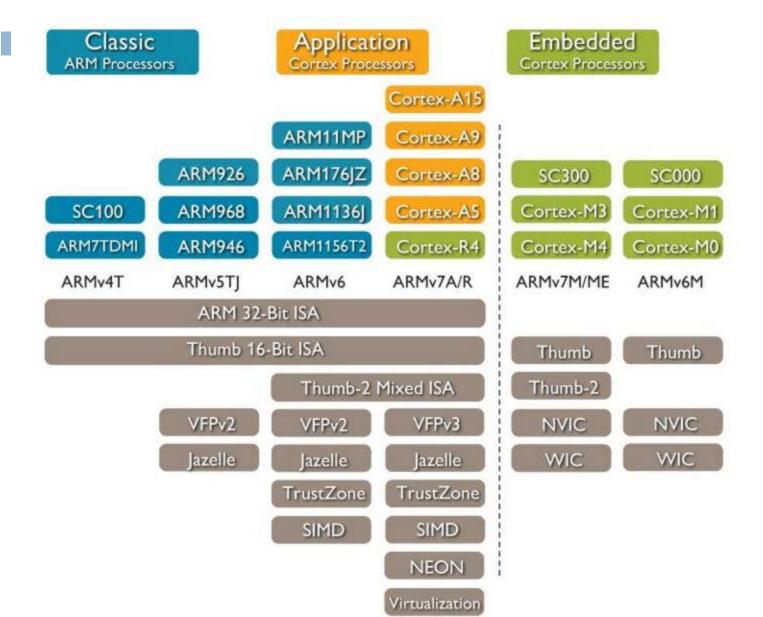
# **Architecture Revisions**



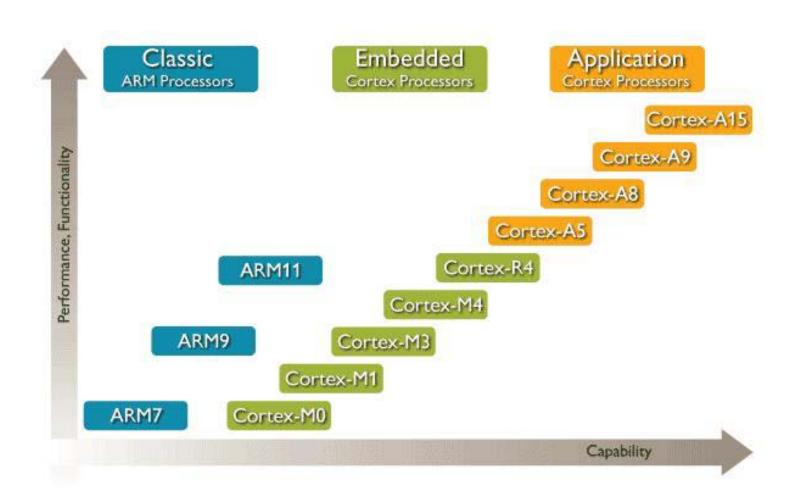
# Architecture Versions



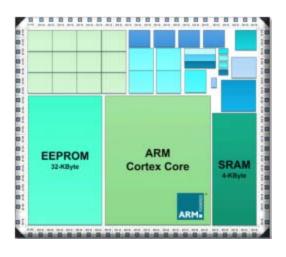
# Architecture Versions and ISAs

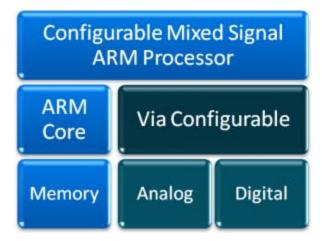


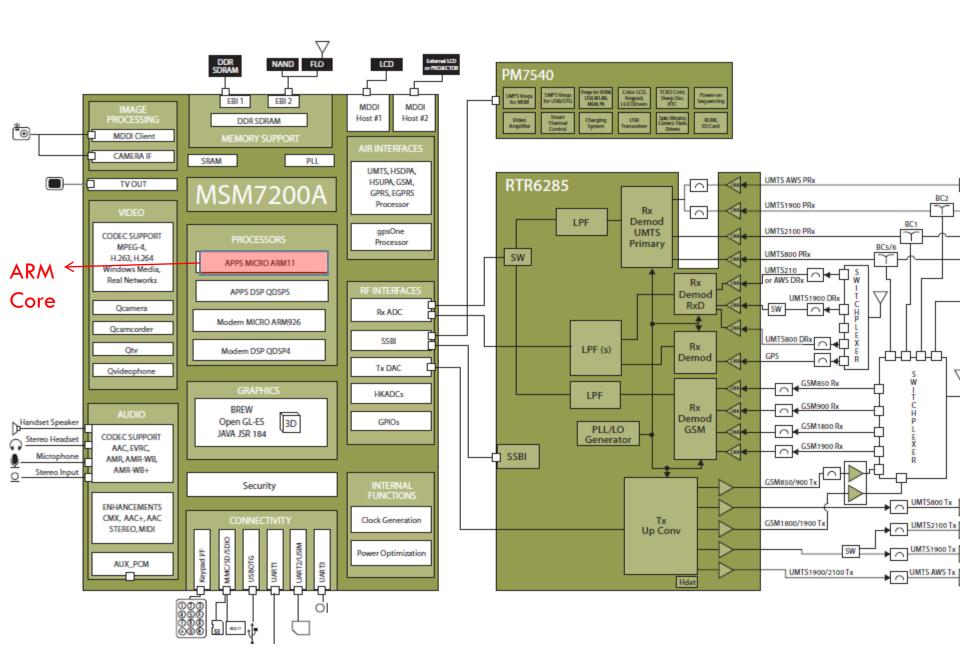
# **ARM Processors**



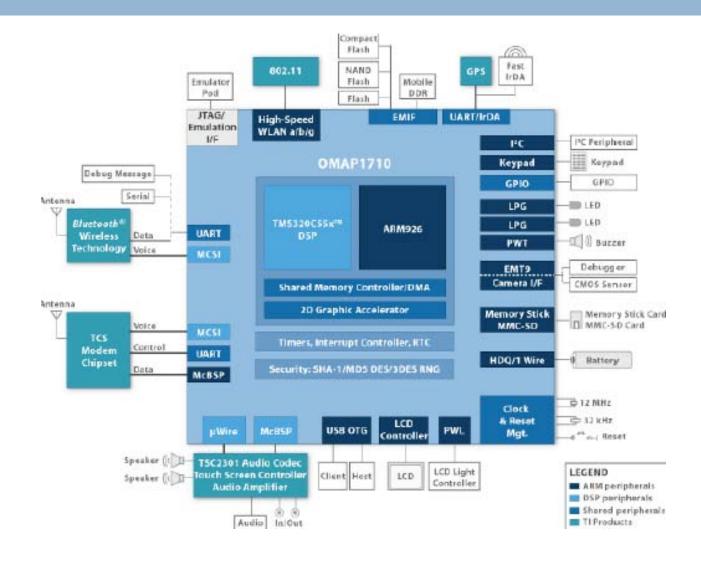
#### **ARM Cores**



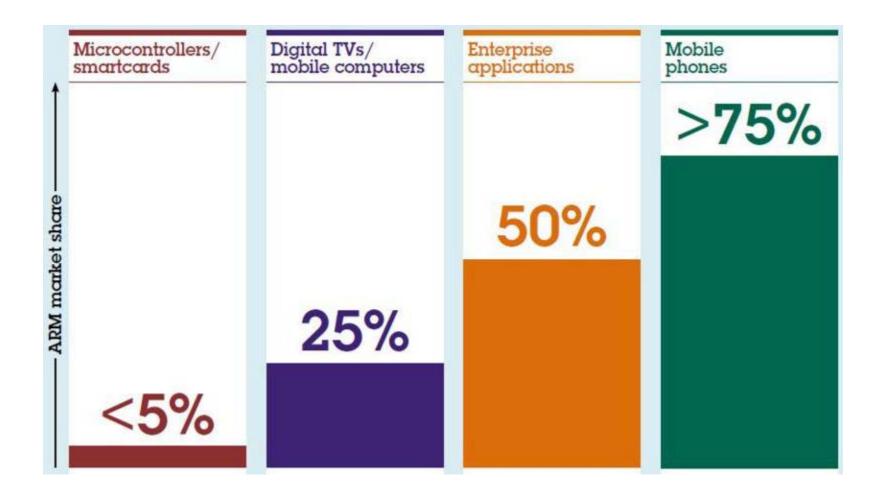




#### **ARM Cores**



# **ARM Market Share**



# ISA Design Philosophy

- Two ISA design philosophies
  - RISC Reduced Instruction Set Computer
  - □ CISC Complex Instruction Set Computer

# RISC versus CISC

RISC	CISC
Each instruction does one simple task.	Each instruction can do multiple tasks.
Amount of work done in each instruction is roughly the same.	Amount of work done in each instruction could have huge variance.
Fixed Length instruction format.	Variable length instruction format.
Load-Store Architecture. Instruction operands should always reside in registers.	Instruction Operands can reside in memory also.
Large bank of general purpose registers.	Many special purpose registers.
Simple Addressing Modes.	Can have complex addressing modes.
Few Data Types (typically integer and float)	Could provide support for more data types like Strings.
Berkeley RISC , Stanford MIPS, ARM, HP's PA-RISC	Intel x86 line of processors

## RISC or CISC – Which way should we go?

RISC	CISC
Simple, fast (pipelined) and power efficient hardware implementations.	Complex hardware, not so Power efficient, hard to come up with pipelined implementations.
Not so good for an Assemble Language Programmer when compared with CISC ISAs.	Good for an Assemble Language Programmer.
Good for compiler writer.	Compiler writer has to work hard to use the underlying CISC ISA features.
Less code density	Good code density

#### Principles of ISA Design

It is easy to see by formal-logical methods that there exist certain [instruction sets] that are in abstract adequate to control and cause the exception of any sequence of operations....The really decisive considerations from the present point of view, in selecting an [instruction set], are more of practical nature: simplicity of the equipment demanded by the [instruction set], and the clarity of its application to the actually important problems together with the speed of handling those problems.

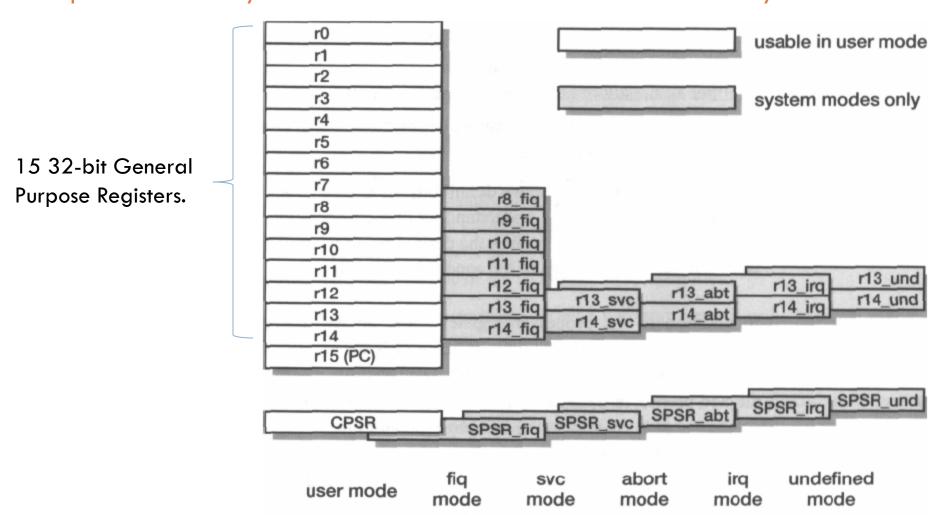
- Burks, Goldstine and Von Neumann, 1947

## ARM ISA

- Follows RISC Philosophy but borrows some CISC ideas.
- ARM ISA goal
  - Efficient ISA implementation in hardware (Good Performance)
  - Good Code Density
  - Low Power Consumption
- 32-bit ISA All instructions are encoded in 32-bits, 32-bit registers, Arithmetic on 32-bit values.
- 32-bit Address Space

#### ARM ISA – Register Set and Modes of Operation

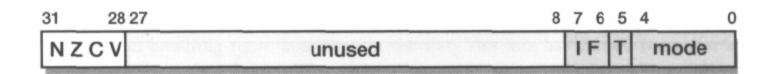
ARM processor always runs either in user mode or one of the 5 System Modes.



#### ARM ISA – Register Set

- All the registers are of length 32-bit.
- In the User Mode (Application Level Programs)
  - □ Registers r0 r15 are available to the programmer.
  - □ r13 sp (Stack Pointer)
  - □ r14 Ir (Link Register)
  - □ r15 pc (Program Counter)
  - □ CPSR Current Program Status Register is also accessible.
- Rest of the registers are used only in System-Level Programming and for handling Exceptions (like Interrupts)

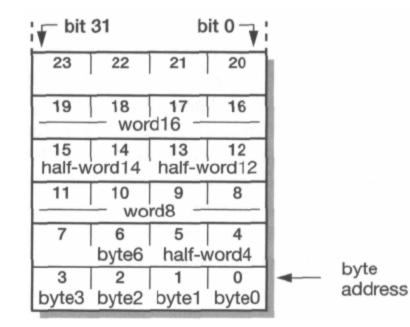
### **CPSR Register Format**



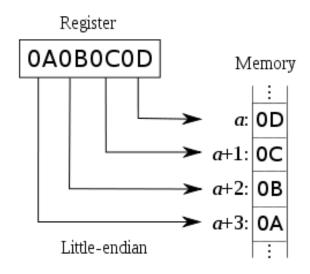
- N Negative; the last ALU operation which changed the flags produced a negative result.
- $_{\circ}$  Z Zero
- C Carry
- V Overflow
- I and F Interrupt enable flags (cannot be changed by programs running in User Mode)
- T Thumb mode
- Mode Mode bits indicates the Processor Mode.

### Memory System and Address Space

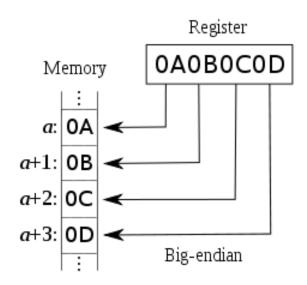
- □ Address Space Length:  $2^{32} 1$  bytes (4GB).
- ARM Instruction can access
  - Byte sized data items
  - Half-word sized data items
  - Word-sized data items
- Alignment Restrictions: Instructions and words should be 4-byte aligned and half-words should be 2-byte aligned.
- Follows Little-Endian Convention
- Can be configured to be Big-Endian



#### Big-Endian Versus Little-Endian

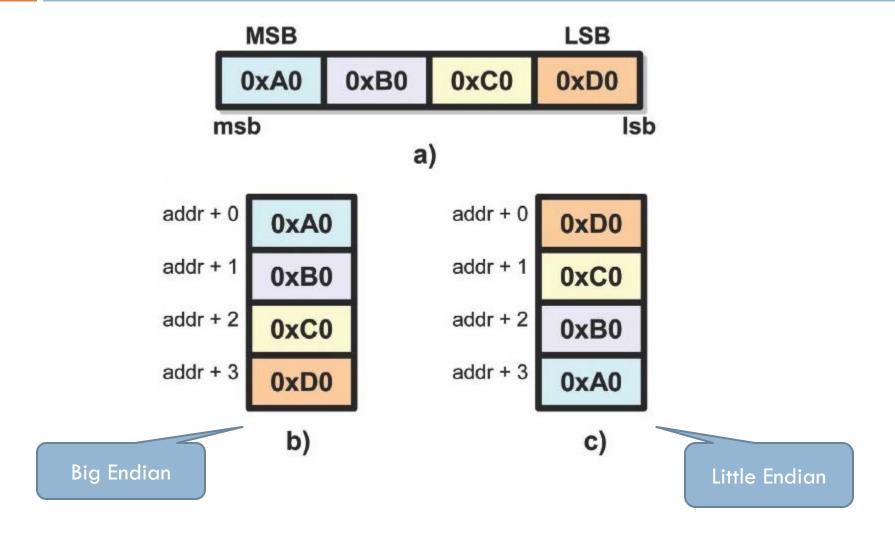


Little Endian: LSB goes to the smallest byte address.



Big Endian: MSB goes to the smallest byte address.

#### Big-Endian Versus Little-Endian



#### Big-Endian Versus Little-Endian

```
#include <stdio.h>
typedef unsigned char *byte_pointer;
void show bytes(byte pointer start, int len)
     int i;
     for (i = 0; i < len; i++)
                                                 Is the output of this program
          printf(" %.2x", start[i]);
                                               same irrespective of whether it is
     printf("\n");
                                               run on a Little Endian machine or
                                                    a Big Endian machine?
main()
     int num = 0xF1F2F3F4;
     show_bytes((byte_pointer) &num, 4);
```

#### Load-Store Architecture

#### In Load-Store Architectures

- Instructions process (ADD, SUB, ...) the data present only in the registers and result will also be placed in registers only.
- Only operations which apply to memory locations are ..
  - □ Load Load from the memory location to a register.
  - □ Store Store from the register to a memory location.

#### **ARM Instruction Set**

ARM Instructions can be classified into three categories.

- 1. Data Processing Instructions (like ADD, SUB, ...)
- Data Transfer Instructions (like LDR, STR, MOV, SWAP)
- 3. Control Flow Instructions

All Instructions are of 32-bit length.

## Data Processing Instructions

- Arithmetic operations
- Bit-wise logical operations
- Register movement operations

#### **Data Processing Instructions**

- Let variables a and b are unsigned integers.
- □ Also let  $r_0 \leftarrow a$ ,  $r_1 \leftarrow b$

#### C code

$$a = b + c$$

#### **ARM Code**

ADD r0, r1, r2; 
$$r0 = r1 + r2$$

r0 - Desitnation Operand (always a register, denoted as rd)

r1 - First Source Operand (always a register, denoted as rs)

r2 – Second Source Operand (Could be ....?)

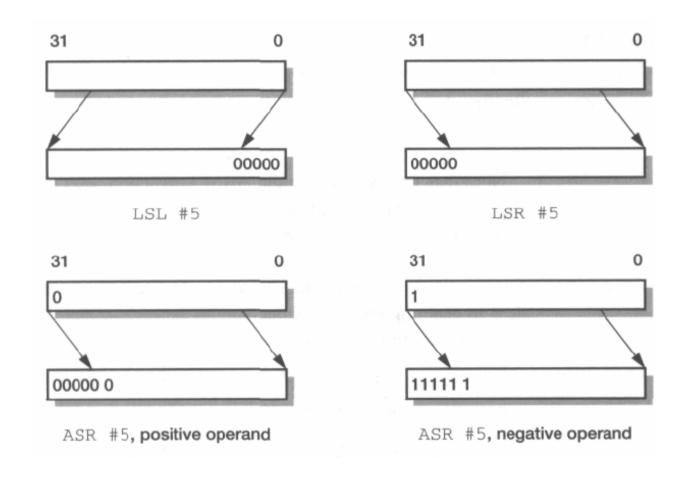
### Shifted Register Operands

 The second source operand in an ARM instruction can be subjected shift operation.

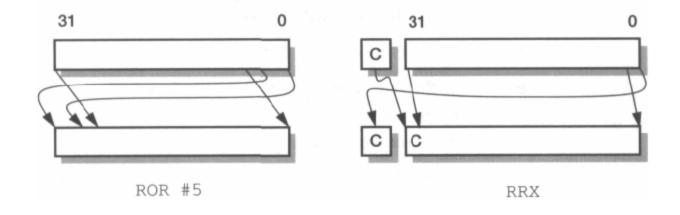
ADD r3, r2, r1, LSL #3; r3 = r2 + 8 \* r1  
ADD r3, r2, r1, LSL r0; r3 = r2 + r1 \* 
$$2^{r0}$$

- For shift operations using immediate values, the operation can execute still within a clock cycle.
- For shift operations involving a register, the operation takes an extra clock cycle.

## Shift Operations on the Second Source Operand



## Shift Operations on the Second Source Operand



#### Data Processing Instructions – Immediate Operands

Second Source Operand could be a constant

ADD r0, r0, 1; 
$$r0 = r0 + 1$$
  
ADD r2, r1, 8;  $r2 = r1 + 8$ 

Immediate operands should be of the form
immediate = (0 × 255) \* 22n 0 < n < 1</p>

immediate = 
$$(0 \rightarrow 255) * 2^{2n} 0 \le n \le 12$$

But why?

#### Data Processing Instructions – Immediate Operands

Immediate operands should be of the form

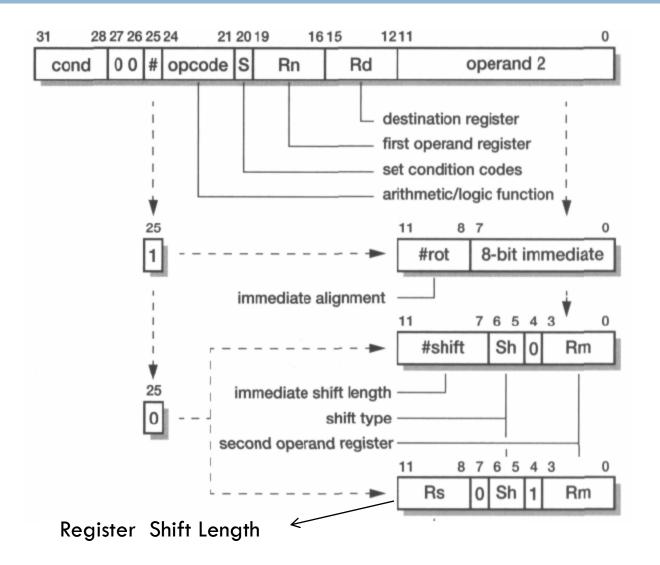
immediate = 
$$(0 \rightarrow 255) * 2^{2n} 0 \le n \le 12$$

Valid Immediate Operands: 010000001, 1000000100, ...

Invalid Immediate Operands: 100000010, 10000001000, ...

What if want to use a constant in an instruction which is not a valid immediate operand?

#### Data Processing Instructions Format



## Data Processing Instructions

Opcode 124:21)	Mnemonic	Meaning	Effect
0000	AND	Logical bit-wise AND	Rd:=RnANDOp2
0001	EOR	Logical bit-wise exclusive OR	Rd := Rn EOR Op2
0010	SUB	Subtract	Rd := Rn - Op2
0011	RSB	Reverse subtract	Rd := Op2 - Rn
0100	ADD	Add	Rd := Rn + Op2
0101	ADC	Add with carry	Rd := Rn + Op2 + C
0110	SBC	Subtract with carry	Rd := Rn - Op2 + C - 1
0111	RSC	Reverse subtract with carry	Rd := Op2 - Rn + C - 1
1000	TST	Test	ScconRnANDOp2
1001	TEQ	Test equivalence	Sec on Rn EOR Op2
1010	CMP	Compare	Sec on Rn - Op2
1011	CMN	Compare negated	Sec on Rn + Op2
1100	ORR	Logical bit-wise OR	Rd := Rn OR Op2
1101	MOV	Move	Rd := Op2
1110	BIC	Bit clear	Rd:=RnANDNOTOp2
1111	MVN	Move negated	Rd:=NOTOp2

## **Data Processing Instructions**

- Let variables a, b, c, d, e be 32-bit signed or unsigned integers.
- □ Also let  $r_0 \leftarrow a$ ,  $r1 \leftarrow b$ ,  $r2 \leftarrow c$ ,  $r3 \leftarrow d$ ,  $r4 \leftarrow e$

#### C code

$$a = b + c$$

$$d = a - e$$

#### ARM Code

ADD r0, r1, r2; 
$$r0 = r1 + r2$$

SUB r3, r0, r4; 
$$r3 = r0 - r4$$

ADD and SUB instructions here does not affect the flags in the CPSR register.

#### Data Processing Instructions

- Let variables f, g, h, i, j be 32-bit signed or unsigned integers.
- □ Also let  $r_0 \leftarrow f$ ,  $r_1 \leftarrow g$ ,  $r_2 \leftarrow h$ ,  $r_3 \leftarrow i$ ,  $r_4 \leftarrow i$

#### C code

$$f = (g + h) - (i + j)$$

#### ARM Code

ADD r5, r1, r2; 
$$r5 = g + h$$

ADD r6, r1, r2; 
$$r6 = i + j$$

SUB r0, r5, r6; r5 and r6 hold the temporary intermediate values

#### Data Processing Instructions

- Let variables a, b, c be 64-bit signed or unsigned integers.
- Also let
  - $\square$   $r_0 \leftarrow$  lower half of a ,  $r_1 \leftarrow$  upper half of a
  - $\square$  r<sub>2</sub>  $\leftarrow$  lower half of b , r3  $\leftarrow$  upper half of b
  - $\square$   $r_{A} \leftarrow$  lower half of c ,  $r5 \leftarrow$  upper half of c

#### C code

$$c = a + b$$

#### **ARM Code**

ADDS r4, r0, r2 ; 'S' will set the carry flag if there is a carryout bit

ADC 
$$r5$$
,  $r1$ ,  $r3$ ;  $r5 = r1 + r3 + C$ 

## Setting the Condition Code Flags

- Data processing instructions can set the condition codes (N, Z, C and V of CPSR) by adding the suffix 'S' to the instruction opcode.
  - ADDS, SUBS, ADCS, ....
- Comparison operations always set the condition codes even
   without the suffix 'S'

## Setting the Condition Code Flags

Always consult the ISA manual to check how the condition code flags are affected.

- $\Box$  The N flag is set if the result is negative (bit 31 of the result is set).
- Z flag is set if the result is zero, otherwise it is cleared.
- The C flag is set to carry-out from ALU when the operation is arithmetic (ADD, ADC, SUB, SBC, RSB, RSC, CMP, CMN)
  - Or to the carry-out from the shifter otherwise. If no shift is required, C is preserved.
- V flag is preserved in non-arithmetic operations. V flag is set if there is an overflow from bit 30 into bit 31 and cleared if no overflow occurs. V flag has significance only in signed arithmetic.

# ARM Condition Codes – Predicated Execution of Instructions

 The most significant bits of any instruction specifies a condition under which the instruction will be executed.

31 28	27	0
cond		

Opcode [31:28]	Mnemonic extension	Interpretation	Status flag state for execution
0000	EQ	Equal / equals zero	Zset
0001	NE	Not equal	Z clear
0010	CS/HS	Carry set / unsigned higher or same	Cset
0011	CC/LO	Carry clear / unsigned lower	C clear
0100	Ml	Minus / negative	Nset
0101	PL	Plus / positive or zero	N clear
0110	VS	Overflow	Vset
0111	vc	No overflow	V clear

# ARM Condition Codes – Predicated Execution of Instructions

 The most significant bits of any instruction specifies a condition under which the instruction will be executed.

31 28	27	0
cond		

Opcode [31:28]	Mnemonic extension	Interpretation	Status flag state for execution
1000	HI	Unsigned higher	C set and Z clear
1001	LS	Unsigned lower or same	C clear or Z set
1010	GE	Signed greater than or equal	N equals V
1011	LT	Signed less than	N is not equal to V
1100	GT	Signed greater than	Z clear and N equals V
1101	LE-	Signed less than or equal	Z set or N is not equal to V
1110	AL	Always	any
1111	NV	Never (do not use!)	none

```
C code: if (i==j) f = g+h; else f = g-h
Assume r0 \leftarrow f, r1 \leftarrow g, r2 \leftarrow h, r3 \leftarrow i, r4 \leftarrow j.
ARM code 1:
cmp r3, r4
addeq r0, r1, r2
                                             ARM code 3:
subne r0, r1, r2
                                                      cmp r3, r4
                                                       beq if
                                                       sub r0, r1, r2
ARM code 2:
                                                       b exit
     cmp r3, r4
                                             if: add r0, r1, r2
     bne else
                                             exit:
     add r0, r1, r2
     b exit
                                   Which of the 3 code sequences are good?
else: sub r0, r1, r2
exit:
```

```
C code: if (i \le j) f = g+h; else f = g-h (i, j are unsigned numbers)
Assume r0 \leftarrow f, r1 \leftarrow g, r2 \leftarrow h, r3 \leftarrow i, r4 \leftarrow j.
ARM code 1:
cmp r3, r4
addls r0, r1, r2
                                             ARM code 3:
subhi r0, r1, r2
                                                      cmp r3, r4
                                                       bls if
                                                       sub r0, r1, r2
ARM code 2:
                                                       b exit
     cmp r3, r4
                                             if: add r0, r1, r2
     bhi else
                                             exit:
     add r0, r1, r2
     b exit
                                   Which of the 3 code sequences are good?
else: sub r0, r1, r2
exit:
```

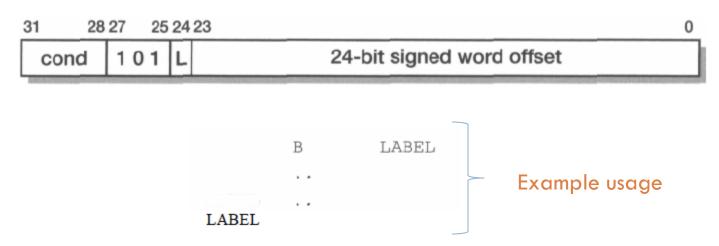
```
C code: if (i \le j) f = g+h; else f = g-h (i, j are signed numbers)
Assume r0 \leftarrow f, r1 \leftarrow g, r2 \leftarrow h, r3 \leftarrow i, r4 \leftarrow j.
ARM code 1:
cmp r3, r4
addle r0, r1, r2
                                             ARM code 3:
subgt r0, r1, r2
                                                      cmp r3, r4
                                                       ble if
                                                       sub r0, r1, r2
ARM code 2:
                                                       b exit
     cmp r3, r4
                                             if: add r0, r1, r2
     bgt else
                                             exit:
     add r0, r1, r2
     b exit
                                   Which of the 3 code sequences are good?
else: sub r0, r1, r2
exit:
```

```
C code: while (save[i] == k) i+=1;
r3 \leftarrow i \ r5 \leftarrow k \ r6 \leftarrow save
loop:
      add r12, r6, r3, LSL #2 ; r12 = &save[i]
        Idr r0, [r12, #0]
                                       ; r0 = save[i]
        cmp r0, r5
                                       ; branch if save[i] != k
        bne exit
        add r3, r3, #1
        b loop
exit:
```

#### Control Flow Instructions and PC-Relative Addressing

ARM provides two branch instructions

B (branch) and BL (branch and link)



Hey, but what is the contents of the register r15 (PC) now?

• PC = Address of the Branch Instruction + 8

Branch range: Approximately (-32MB to +32MB)

## **Conditional Branch Instruction Variants**

Branch	Interpretation	Normal uses
B BAL	Unconditional	Always take this branch
	Always	Always take this branch
BEQ	Equal	Comparison equal or zero result
BNE	Not equal	Comparison not equal or non-zero result
BPL	Plus	Result positive or zero
BMI	Minus	Result minus or negative
BCC	Carry clear	Arithmetic operation did not give carry-out
BLO	Lower	Unsigned comparison gave lower
BCS	Carry set Higher	Arithmetic operation gave carry-out
BHS	or same	Unsigned comparison gave higher or same
BVC	Overflow clear	Signed integer operation; no overflow occurred
BVS	Overflow set	Signed integer operation; overflow occurred
BGT	Greater than	Signed integer comparison gave greater than
BGE	Greater or equal	Signed integer comparison gave greater or equal
BLT	Less than	Signed integer comparison gave less than
BLE	Less or equal	Signed integer comparison gave less than or equal
BHI	Higher	Unsigned comparison gave higher
BLS	Lower or same	Unsigned comparison gave lower or same

```
mov r0, #0 ; initialize counter
loop:

add r0, r0, #1 ; increment loop counter
cmp r0, #10 ; compare with limit
bne loop ; repeat if not equal
; else fall through
```

```
CMP r0, #5

BEQ BYPASS ; if (r0 != 5) {

ADD r1, r1, r0 ; r1 := r1 + r0 - r2

SUB r1, r1, r2 ; }

BYPASS ...
```

#### Equivalent ARM Code Sequence

```
CMP r0, #5 ; if (r0 != 5) { ADDNE r1, r1, r0 ; r1 := r1 + r0 - r2 SUBNE r1, r1, r2 ; }
```

```
if ( r0 == r1 ) { r2 = r2 + 1; r3 = r3 + 1; r4 = r4 + 1; r5 = r5 + 1 } else { r6 = r6 + 1; r7 = r7 + 1; r8 = r8 + 1; r9 = r9 + 1 }
```

exit:

#### Code Sequence 3 Code Sequence 2 Code Sequence 1 cmp r0, r1 cmp r0, r1 cmp r0, r1 beg if bne else addeq r2, #1 add r6, #1 add r2, #1 addeq r3, #1 add r7, #1 add r3, #1 addeq r4, #1 add r8, #1 add r4, #1 addeq r5, #1 add r8, #1 add r5, #1 addne r6, #1 b exit b exit addne r7, #1 add r2, #1 if: add r6, #1 else: add r3, #1 addne r8, #1 add r7, #1 add r4, #1 addne r9, #1 add r8, #1 add r5, #1 add r9, #1

exit:

```
C code: if ((a==b) \&\& (c==d)) e++;
```

#### **ARM Code:**

```
cmp r0, r1
cmpeq r2, r3
addeq r4, r4, #1
```

## Base Plus Offset Addressing Modes

Indexed Addressing Mode with no write back

Idr r0, 
$$[r1, #4]$$
; r0 = mem<sub>32</sub>[r1+4]

Pre-Indexed Addressing Mode

Idr r0, 
$$[r1, #4]!$$
;  $r0 = mem_{32}[r1+4]$ ;  $r1 = r1 + 4$ 

Post-indexed Addressing Mode

Idr r0, [r1], #4 ; r0 := 
$$mem_{32}[r1]$$
  
; r1 := r1 + 4

## Indexed Addressing Mode

```
COPY ADR r1, TABLE1 ; r1 points to TABLE1

ADR r2, TABLE2 ; r2 points to TABLE2

LOOP LDR r0, [r1], #4 ; get TABLE1 1st word

STR r0, [r2], #4 ; copy into TABLE2

??? ; if more go back to LOOP

...

TABLE1 ; < source of data >

...

TABLE2 ; < destination >
```

ADR is not an ARM instruction. It is an Assembler Pseudo-op.

## Summary of ARM Addressing Modes

- Register-indirect addressing
  - □ LDR r0, [r1]
- Pre-indexed addressing
  - LDR r0, [r1, # offset]
- Pre-indexed, auto-indexing
  - LDR r0, [r1, # offset]!
- Post-indexed, auto-indexing
  - LDR r0, [r1], # offset
- PC relative addressing
  - ADR r0, address\_label

#### More Data Transfer Instructions

- Idrb Load an unsigned byte extended by 0
- Idrsb Load a sign extended byte
- Idrh Load an unsigned half word extended by 0
- Idrsh Load a sign extended half word.
- Idrd Load two consecutive words into a even register pair (like r12-r13 but not r11-r12)

## **Block Data Transfer Instructions**

- LDMIA r1, {r0, r2, r5}
  - $r0 = mem_{32}[r1]$
  - $r2 = mem_{32}[r1+4]$
  - $r5 = mem_{32}[r1+8]$
- □ LDMIB r1, {r0, r2, r5}
  - $r0 = mem_{32}[r1+4]$
  - $r2 = mem_{32}[r1+8]$
  - $r5 = mem_{32}[r1+12]$

- □ LDMIA r1!, {r0, r2, r5}
  - $r0 = mem_{32}[r1]$
  - $r2 = mem_{32}[r1+4]$
  - $r5 = mem_{32}[r1+8]$
  - r1 = r1 + 12
- □ LDMIB r1!, {r0, r2, r5}
  - $r0 = mem_{32}[r1+4]$
  - $r2 = mem_{32}[r1+8]$
  - $r5 = mem_{32}[r1+12]$
  - r1 = r1 + 12

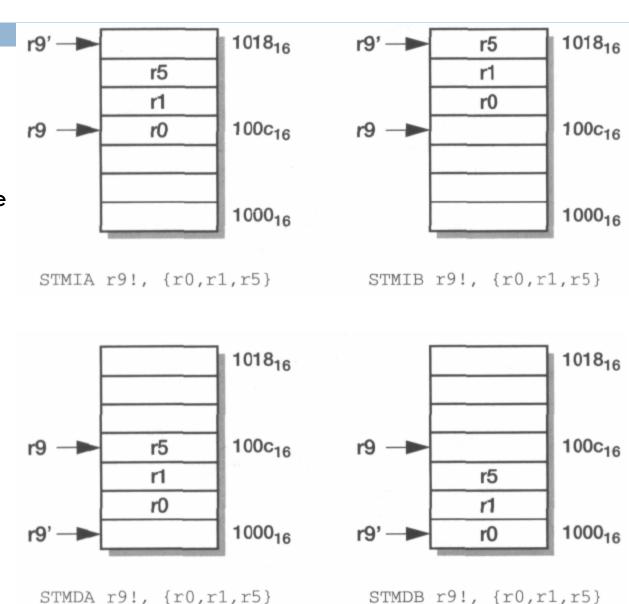
## **Block Data Transfer Instructions**

- LDMDA r1, {r0, r2, r5}
  - $r5 = mem_{32}[r1]$
  - $r2 = mem_{32}[r1 4]$
  - $r0 = mem_{32}[r1 8]$
- □ LDMDB r1, {r0, r2, r5}
  - $r5 = mem_{32}[r1 4]$
  - $r2 = mem_{32}[r1 8]$
  - $r0 = mem_{32}[r1 12]$

- □ LDMDA r1!, {r0, r2, r5}
  - $r5 = mem_{32}[r1]$
  - $r2 = mem_{32}[r1 4]$
  - $r0 = mem_{32}[r1 8]$
  - r1 = r1 12
- □ LDMDB r1!, {r0, r2, r5}
  - $r5 = mem_{32}[r1 4]$
  - $r2 = mem_{32}[r1 8]$
  - $r0 = mem_{32}[r1 12]$
  - r1 = r1 12

#### **Block Data Transfer Instructions**

- 1. There are analogous load instructions also.
- 2. These instructions take more than 3 cycles causing pipeline imbalance.
- 3. This breaks the RISC architecture principle of single cycle per instruction execution model.



3-Stage Pipelined implementation of ARM Processor

