

# COMPUTER SYSTEMS ORGANIZATION

Subroutines in ARM -- Spring 2010 -- IIIT-H -- Suresh Purini

# Subroutines, Procedures and Functions

Subroutines, Procedures and Functions – Are they any different?

Why Procedures?

- ❑ Avoid duplication of code within the same program.
- ❑ Reuse of code across different programs (Libraries?)
- ❑ Decomposition of a Complex Program into a set of more manageable subroutines.
- ❑ Information Hiding.
- ❑ ....
- ❑ Any Disadvantages?

# Implementing Subroutine Abstraction in ARM

- ❑ **Question:** Can we implement subroutines in ARM using the instructions we have seen so far (ignoring the BL instruction)?

```
main()
{
    int i, sum = 0;
    for(i = 0; i < 100; ++i )
        sum = sum + sqr(i);
}

int sqr(int n )
{
    return n*n;
}
```

## Questions:

1. How to implement Control Transfer?
2. How to pass Parameters?
3. How to pass back Return Values?

# Subroutines – Implementing Control Transfer

main:

·  
·  
·

b sum

label:

·  
·  
·

sum:

·  
·  
·

b label

## Questions:

1. What is the problem with this approach?
2. How can it be resolved?

# Subroutines – Implementing Control Transfer

main:

```
.  
.   
.   
bl sum    ; branch to sum  
.          ; return here  
.   
.   
.   
sum:
```

sum:

```
.  
.   
.   
mov pc, lr ; return
```

Return address will be stored in the Link Register r14 (lr).

B and BL Instruction Format



# Subroutines – Implementing Control Transfer

```
main() {  
    int i, sum = 0;  
    for(i = 0; i < 100; ++i )  
        sum = sum + sqr(i);  
}
```

```
int sqr(int n ) {  
    return mult(n, n);  
}
```

```
int mult(int a, int b){  
    return a*b;  
}
```

```
main:  
    .  
    .  
    bl sum    ; branch to sum  
    .        ; return here  
    .
```

```
sum:                                Does this program work ?  
    .  
    bl mult   ; branch to mult  
    .  
    mov pc, lr ; return
```

```
mult:  
    .  
    .  
    mov pc, lr ; return
```

# Stacks and Subroutines – Implementing Control Transfer

main:

```
.  
:sub sp, sp, #4  
str lr, [sp]  
bl sum  
ldr lr, [sp]  
add sp, sp, #4  
:
```

sum:

```
.  
:sub sp, sp, #4  
str lr, [sp]  
bl mult ; branch to mult  
ldr lr, [sp]  
add sp, sp, #4  
:
```

mult:

```
mov pc, lr ; return  
:  
:  
mov pc, lr ; return
```

## Subroutine Calling Sequence:

1. Store the Link Register on the stack and adjust the stack Pointer
2. Call the Procedure
3. Pop the contents of the Link Register back from the stack and adjust the stack pointer.

**Agreement:** Callee promises Caller to preserve the lr, sp and also the stack contents.

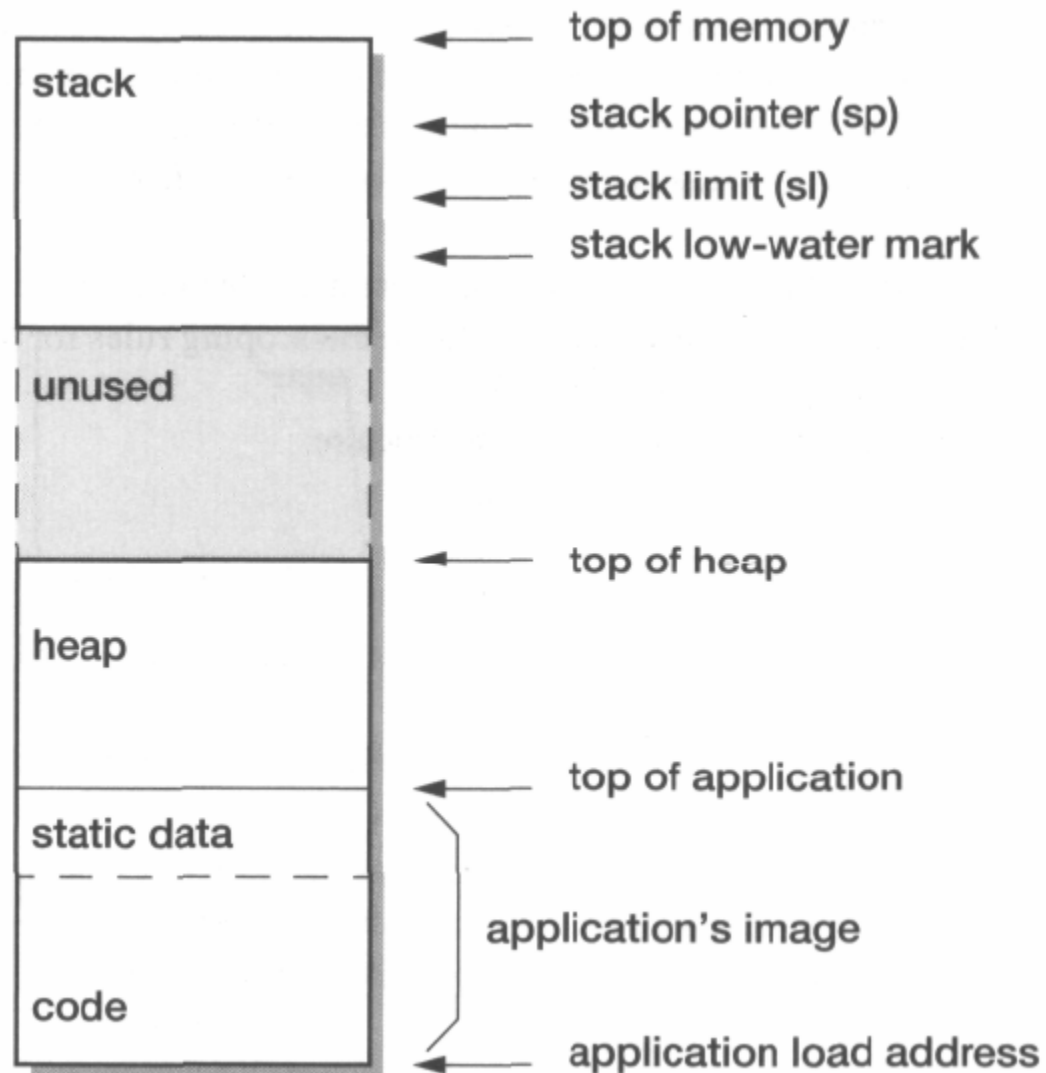
Caller

Callee

# Subroutines – Implementing Control Transfer

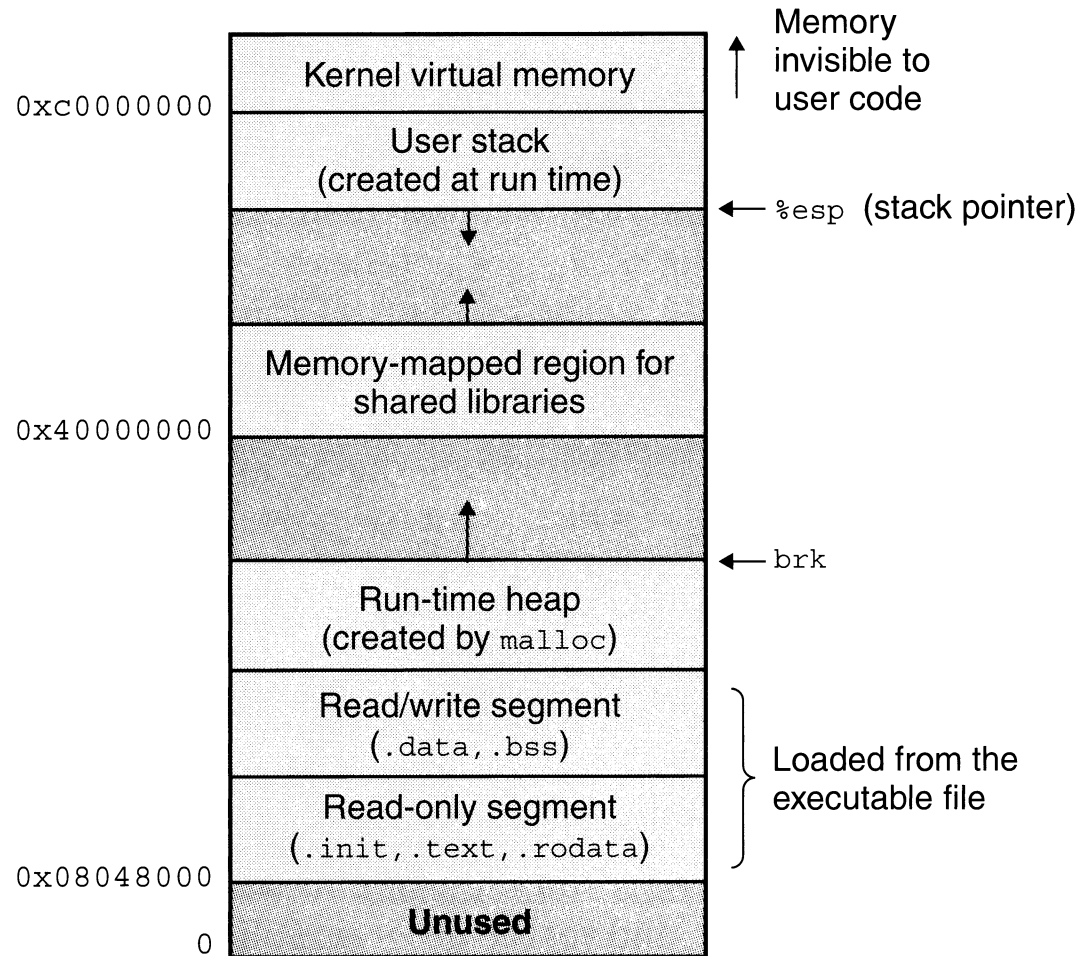
Hey, what's happening? Why are we decrementing the sp register when we want to push a return address onto the stack?

**Key Point:** Stack is growing from higher memory address to lower memory address. It is a convention.





# Linux Memory Image



# Subroutines – Implementing Control Transfer

```
main(){
    int n = getchar();
    computerSqrSum(&n);
}

int computerSqrSum(int *pn) {
    int i, sum = 0;
    for(i = 0; i < *pn; ++i )
        sum = sum + sqr(i);
    *pn = sum;
    return sum;
}

int sqr(int n ) {
    return n*n;
}
```

# Subroutines – Implementing Control Transfer

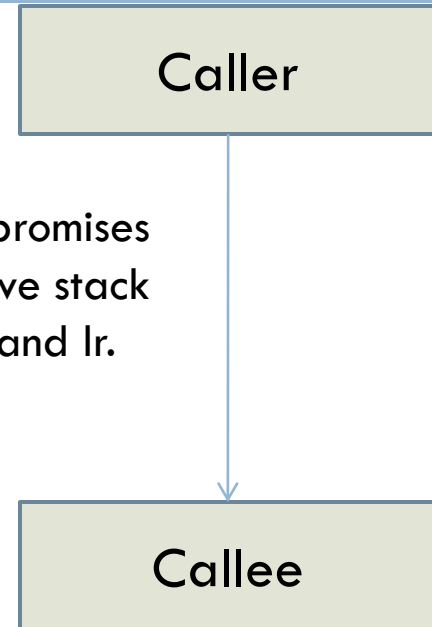
```
void printReverse(char *str) {  
    char *lstr;  
    if( *str) { return; }  
    else {  
        lstr = str + 1;  
        printReverse(lstr)  
    }  
    putchar(*str);  
}
```

# Stacks and Subroutines – Implementing Control Transfer

## Steps for calling a SubRoutine

1. Store the Link Register on the stack and adjust the stack Pointer.
2. Call the SubRoutine.
3. Pop the contents of the Link Register back from the stack and adjust the stack pointer.

**Agreement:** Caller promises callee to preserve stack contents, the sp and lr.



Instead of doing this for every Subroutine Call, why can't we store the link register at the beginning of the Caller code and Restore it at the end.

# Passing Parameters and Return Values

## How to pass Parameters and Return Values?

1. Pass parameters through registers. If there are more parameters than available registers, pass the rest of the parameters through the stack.
2. Return Values?

# Who should preserve the Registers?

- ❑ Subroutine **foo** wants to call Subroutine **fun**.
- ❑ **Strategy 1:** Before calling **fun**, **foo** stores all the registers it would like to preserve on the stack and restore them after the return from the function **fun**.
- ❑ **Strategy 2:** **fun** simply calls **foo** and **foo** saves all the registers it would like to use on the stack and restores them back before the return to **fun**.

What are the pros and cons of the two approaches?

Here comes the idea of caller saved registers and callee saved registers.

# ARM Procedure Call Standard

Register	Synonym	Special	Role in the procedure call standard
r15		PC	The Program Counter.
r14		LR	The Link Register.
r13		SP	The Stack Pointer.
r12		IP	The Intra-Procedure-call scratch register.
r11	v8		Variable-register 8.
r10	v7		Variable-register 7.
r9		v6 SB TR	Platform register. The meaning of this register is defined by the platform standard.
r8	v5		Variable-register 5.
r7	v4		Variable register 4.
r6	v3		Variable register 3.
r5	v2		Variable register 2.
r4	v1		Variable register 1.
r3	a4		Argument / scratch register 4.
r2	a3		Argument / scratch register 3.
r1	a2		Argument / result / scratch register 2.
r0	a1		Argument / result / scratch register 1.

# ARM Procedure Call Standard

Preserved	Not Preserved
Variable Registers: r4 – r11	Argument Registers: r0 – r3
Stack Pointer: sp	Intra-procedure-Call Scratch Register: r12
Link Register: lr	Stack below the stack pointer
Stack above the stack pointer	

1. You may not strictly care for these conventions within your assembly code.
2. However you should pay attention to these guidelines when making library function calls.



# Procedure Prologue and Epilogue Code

foo:

```
sub sp, sp, 16
str lr, [sp]
str r4, [sp, #4]
str r5, [sp, #8]
str r6, [sp, #12]
.
.
.
ldr r6, [sp, #12]
str r5, [sp, #8]
str r4, [sp, #4]
str lr, [sp]
add sp, sp, 16
```

Consider a subroutine foo which not only needs the registers r0-r3, r12, but also requires three additional registers r4, r5, r6 to do its computation.

Preserved	Not Preserved
Variable Registers: r4 – r11	Argument Registers: r0 – r3
Stack Pointer: sp	Intra-procedure-Call Scratch Register: r12
Link Register: lr	Stack below the stack pointer
Stack above the stack pointer	

# Procedure Prologue and Epilogue Code

foo:

stmfd sp!, {r4-r6, lr}

.

.

.

ldmfd sp!, {r4-r6, pc}

Did you see this block data transfer instruction?

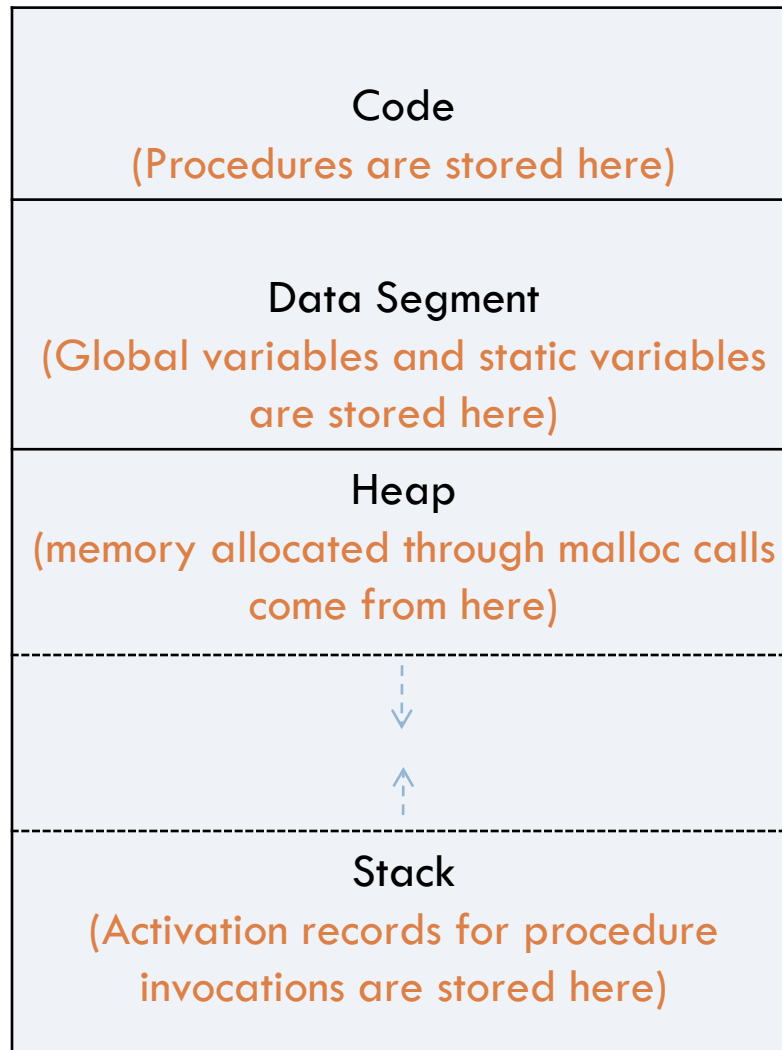
Preserved	Not Preserved
Variable Registers: r4 – r11	Argument Registers: r0 – r3
Stack Pointer: sp	Intra-procedure-Call Scratch Register: r12
Link Register: lr	Stack below the stack pointer
Stack above the stack pointer	

# Procedure Calling Sequences

- Procedure **main** wants to call **foo**. It passes its parameters through the registers r0 and r1. It is also using registers r2 and r3 for its local computation. So it has to make to sure the register contents r2 and r3 are preserved across the function call to foo. But how?

Preserved	Not Preserved
Variable Registers: r4 – r11	Argument Registers: r0 – r3
Stack Pointer: sp	Intra-procedure-Call Scratch Register: r12
Link Register: lr	Stack below the stack pointer
Stack above the stack pointer	

# Storage Lay-out of a Program



# Activation Records

- A program is a life-less entity at compile time and in general until it is invoked. It gains life when it is executed.
- Similarly a procedure in a program comes to life when it is invoked or activated.
- Each Live (or Active!) Procedure during a program execution has an associated Data-Structure called Activation Record.
- What does a Live Procedure need for it to carry out its business?

# Activation Records

- What does a Live Procedure need for it to carry out its business?
  - ▣ Space for its **parameters**
  - ▣ Space for the **return value**
  - ▣ Space for the **Local Variables**
  - ▣ Return address of the Calling Procedure.
  - ▣ Space to save the calling procedure context like registers etc.

Actual Parameters
Return Value
Saved Machine Status
Local Variables
Temporary Variables

Actual parameters and return values can be communicated through processor registers also.