

# Compilers

Topic: Local Optimizations

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# Optimization

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Compilers operate at many granularities or scopes

- Local techniques
  - Work on a single basic block
  - Maximal length sequence of straight-line code
- Regional techniques
  - Consider multiple blocks, but less than whole procedure
  - Single loop, loop nest, dominator region, ...
- Intraprocedural (or global) techniques
  - Operate on an entire procedure (but just one)
  - Common unit of compilation
- Interprocedural (or whole-program) techniques
  - Operate on  $> 1$  procedure, up to whole program
  - Logistical issues related to accessing the code (link time?)
- Link Time Optimizations

# Optimization

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At each of these scopes, the compiler uses different graphs

- Local techniques
  - Dependence graph (instruction scheduling)
- Regional Techniques
  - Control-flow graph (natural loops)
  - Dominator tree
- Intra-procedural (or global) techniques
  - Control-flow graph
  - Def-use chains, sparse evaluation graphs, SSA as graph
- Inter-procedural (or whole-program) techniques
  - Call (multi) graph

# Analysis versus Transformation

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We want to differentiate between analysis and transformation

- Analysis reasons about the code's behavior
  - Transformation rewrites the code to change its behavior
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- Local techniques can interleave analysis and transformation
    - Property of basic block: operations execute in defined order
  - Over larger regions, the compiler typically must complete its analysis before it transforms the code
  - Leads to confusion in terminology
    - Don't use “optimization” for both analysis & transformation

# Limitations of GCSE

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```
a ← b + c
b ← a - d
c ← b + c
d ← a - d
```

*Original Block*

```
a ← b + c
b ← a - d
c ← b + c
d ← b
```

*Rewritten Block*

```
a ← b × c
d ← b
e ← d × c
```

*Effect of Assignment*

# Value Numbering

$$\begin{array}{lcl} a^2 & \leftarrow & b^0 + c^1 \\ b^4 & \leftarrow & a^2 - d^3 \\ c^5 & \leftarrow & b^4 + c^1 \\ d^4 & \leftarrow & a^2 - d^3 \end{array}$$

Along with the Value Number Hash Table, maintain two other data structures.

1. Variable to Value Number Map
2. Value Number to Variables Map



for  $i \leftarrow 0$  to  $n-1$ , where the block has  $n$  operations    " $T_i \leftarrow L_i \text{ Op}_i R_i$ "

1. get the value numbers for  $L_i$  and  $R_i$
2. construct a hash key from  $\text{Op}_i$  and the value numbers for  $L_i$  and  $R_i$
3. if the hash key is already present in the table then  
    replace operation  $i$  with a copy of the value into  $T_i$  and  
    associate the value number with  $T_i$

else

    insert a new value number into the table at the hash key location  
    record that new value number for  $T_i$

# Value Numbering

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Original Code

```
a = x + y
b = x + y
a = 17
c = x + y
```

With VNs

```
a3 ← x1 + y2
b3 ← x1 + y2
a4 ← 174
c3 ← x1 + y2
```

```
a3 = x1 + y2
b3 = x1 + y2
a4 = 174
c3 = b3
```

# Value Numbering

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Original Code

$$a = x + y$$
$$a = 17$$
$$c = x + y$$

With VNs

$$a^3 = x^1 + y^2$$
$$a^4 = 17^4$$
$$c^3 = x^1 + y^2$$

- **Issue:** Although the computation in  $c=x+y$  is redundant, its value (VN-3) is not available in any variable
- **Possible Solution:** Introduce temporary variables

$$a^3 = x^1 + y^2$$
$$t^3 = a^3$$
$$a^4 = 17^4$$
$$c^3 = t^3$$



# Static Single Assignment Form(SSA)

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Original Code

```
a = x + y  
b = x + y  
a = 17  
c = x + y
```

SSA Form

```
a0 = x + y  
b0 = x + y  
a1 = 17  
c0 = x + y
```

- **Idea:** Each definition (or assignment) to a variable creates a new version of variable. A new name space would be created using this approach.

# Static Single Assignment (SSA)

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Original Code

```
a = x + y
b = x + y
a = 17
c = x + y
```

SSA Form

```
a0 = x + y
b0 = x + y
a1 = 17
c0 = x + y
```

- **Issue:** How to reconcile with the rest of the name space in other BBs?

```
a0 = x + y
b0 = x + y
a1 = 17
c0 = x + y
a = a1
b = b0
c = c0
```

# Value Numbering – Static Single Assignment (SSA)

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Original Code

$$a = x + y$$
$$a = 17$$
$$c = x + y$$

SSA Form

$$a_0 = x + y$$
$$a_1 = 17$$
$$c_0 = x + y$$

SSA Form with VNs

$$a_0^3 = x^1 + y^2$$
$$a_1^4 = 17^4$$
$$c_0^3 = x^1 + y^2$$

Optimized Code

$$a_0^3 = x^1 + y^2$$
$$a_1^4 = 17^4$$
$$c_0^3 = a_0^3$$

# SSA Form

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A program is in SSA form when it meets two constraints

- Each definition has a distinct name
  - **Implication:** Names correspond to specific definition points in code
- Each use refers to a single definition

# Translating to SSA Form

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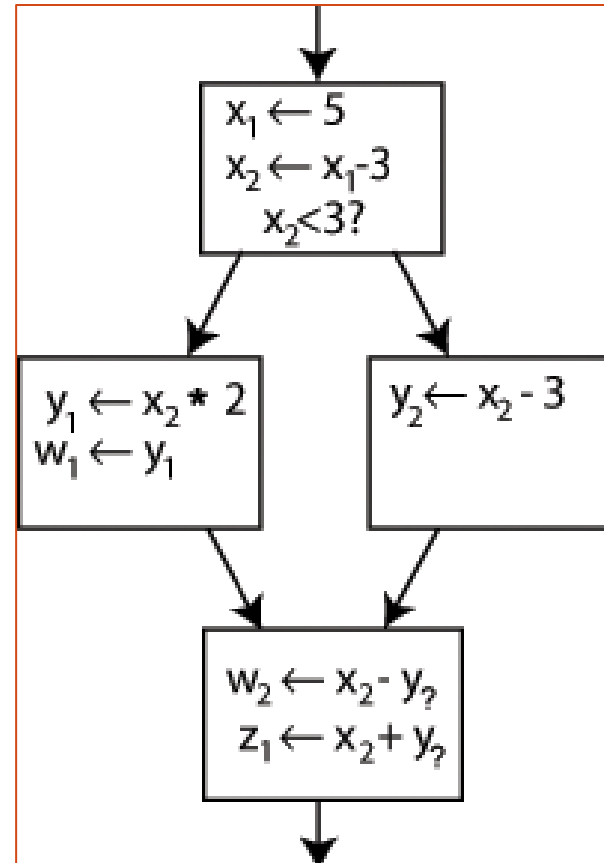
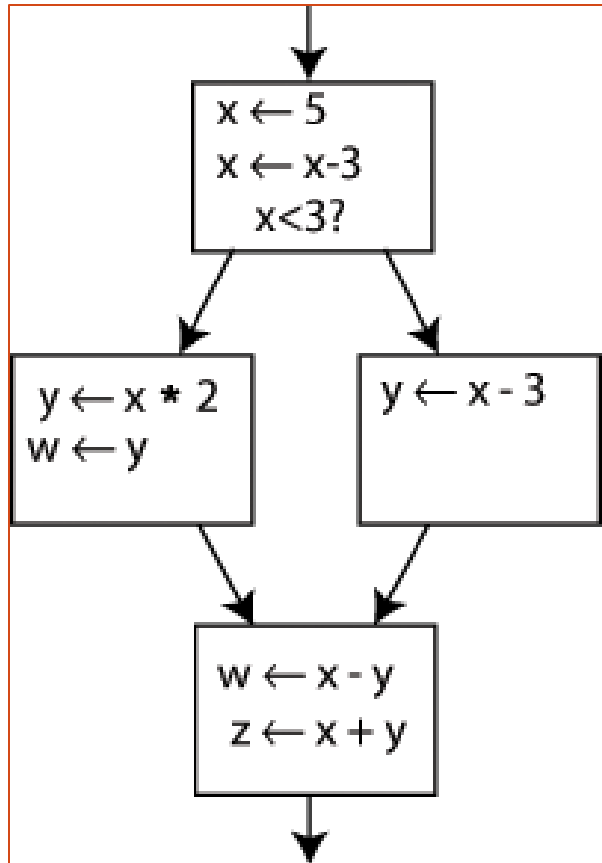
**Question:** How to translate IR into SSA form?

- Easy for straight line sequence of code
  - Each assignment to a variable is given a unique name
  - All of the uses reached by that assignment are renamed

```
1: a = x + y
2: a = a + 3
3: b = x + y
```

```
1: a1 = x0 + y0
2: a2 = a1 + 3
3: b1 = x0 + y0
```

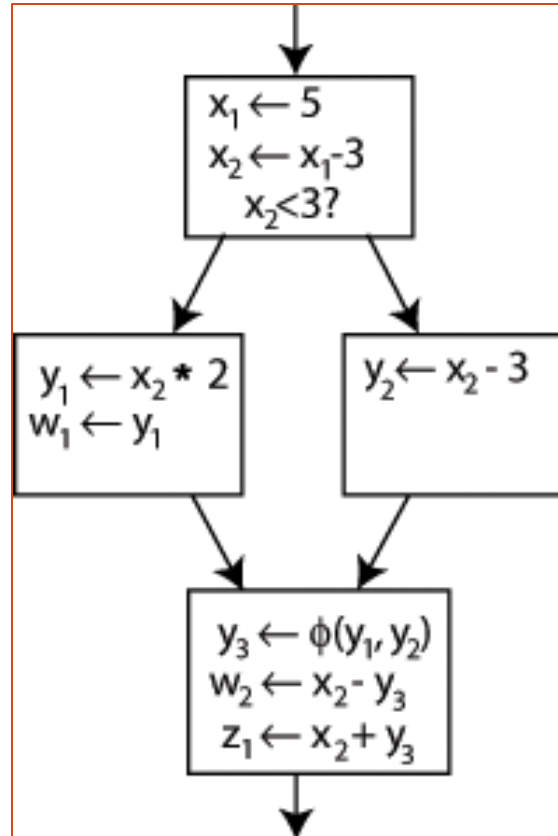
# Translating to SSA Form



- **What's easy:** Straight line sequence of codes, splits in CFGs
- **What's hard:** Joins in CFGs

# Translating to SSA Form

- Introduce Phi Functions to handle joins wherever necessary
- **Question:** Isn't a phi function necessary for the variable  $x$ ?



# SSA Variations

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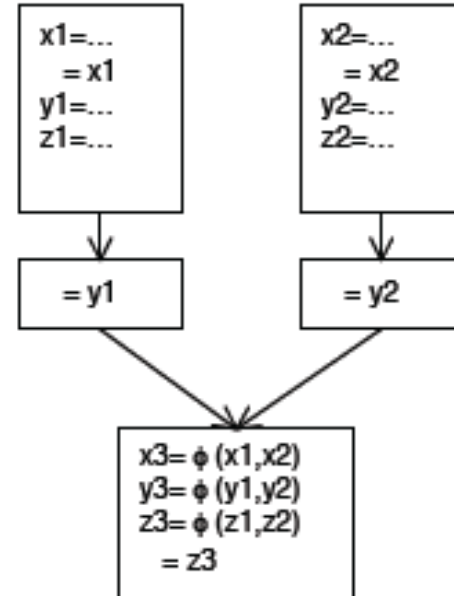
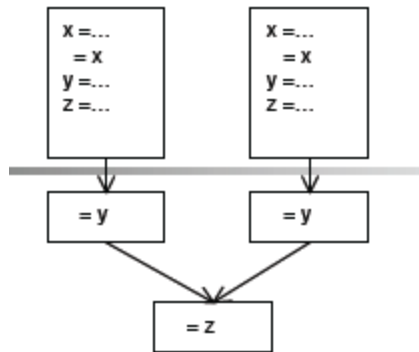
Many variations of SSA exist.

- Minimal SSA
- Pruned SSA
- Semi-pruned SSA
- .....



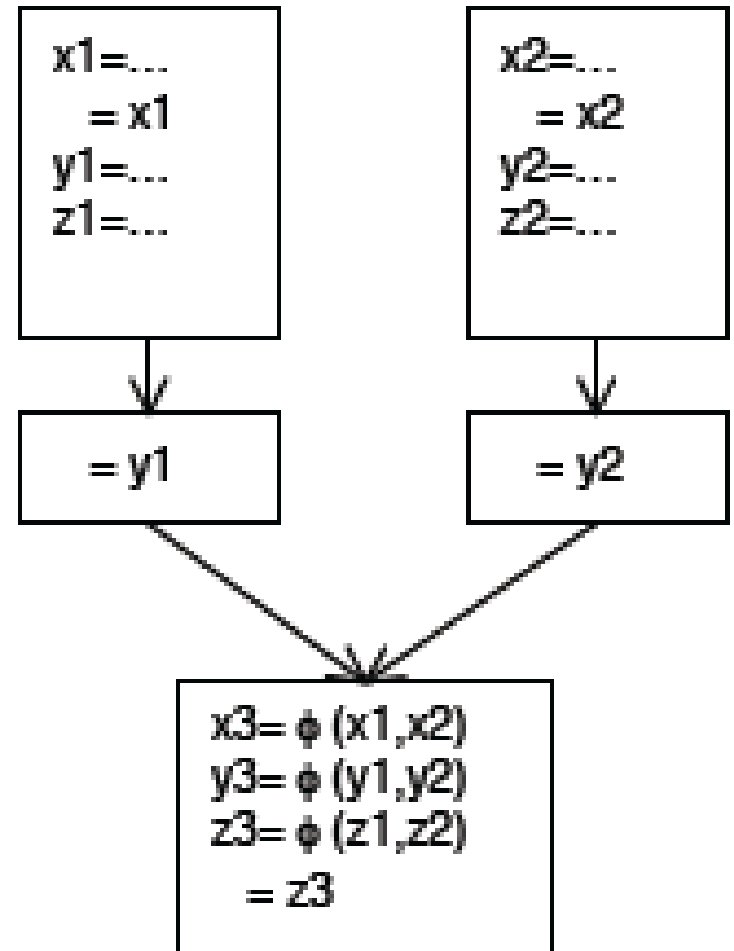
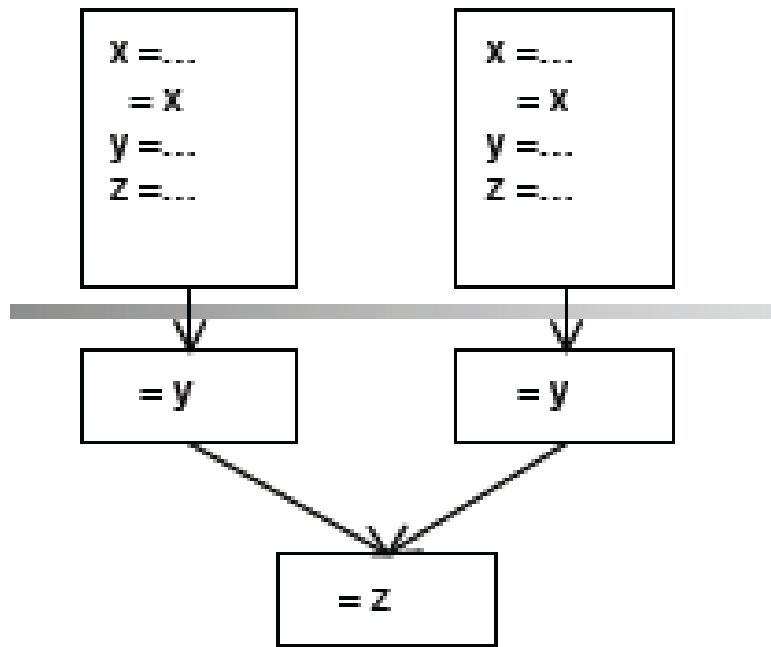
# Minimal SSA

- Insert a phi function at any join point where two distinct definitions for the same original name meet.
- The minimal number consistent with the definition of SSA
- Some of those phi functions may be dead



Minimal SSA form

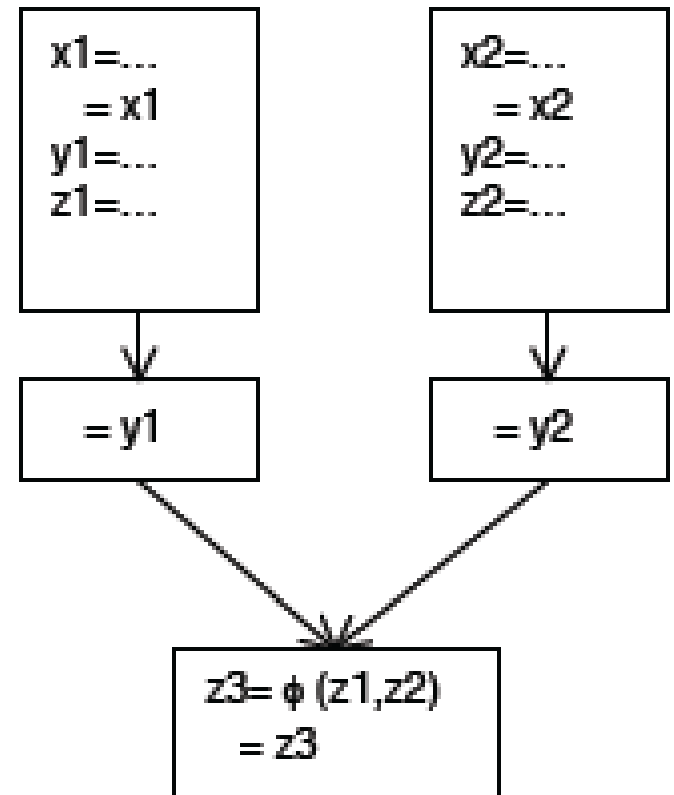
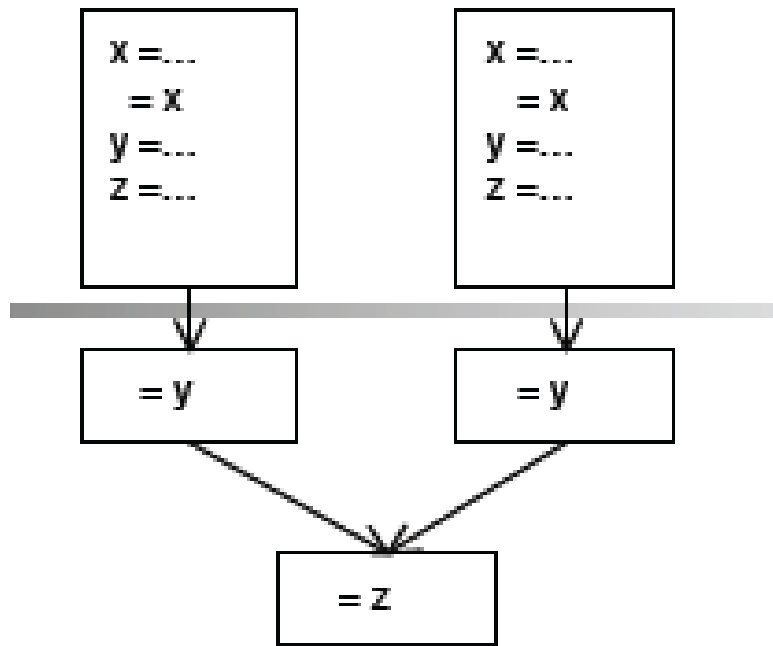
# Minimal SSA



Minimal SSA form

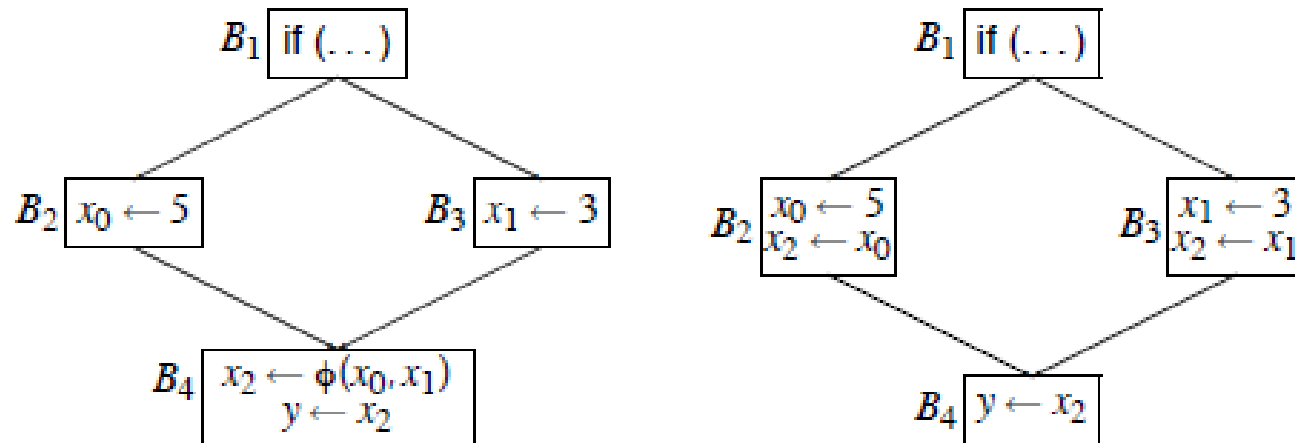
# Pruned SSA

- Same as minimal SSA
- Perform liveness analysis to drop dead phi functions

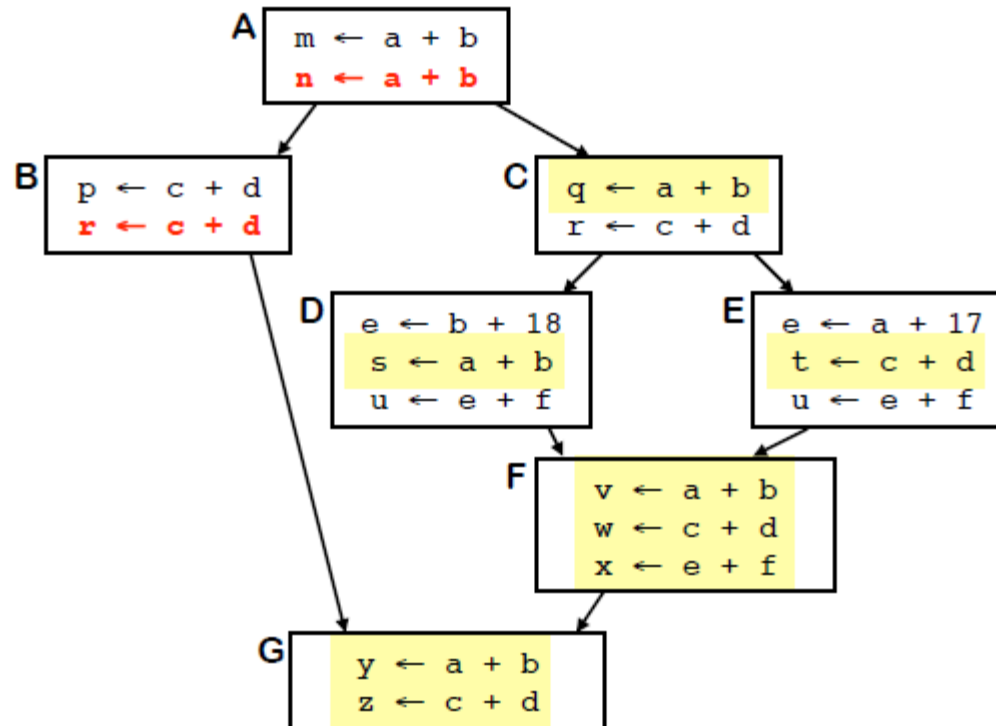


# Translating out of SSA Form

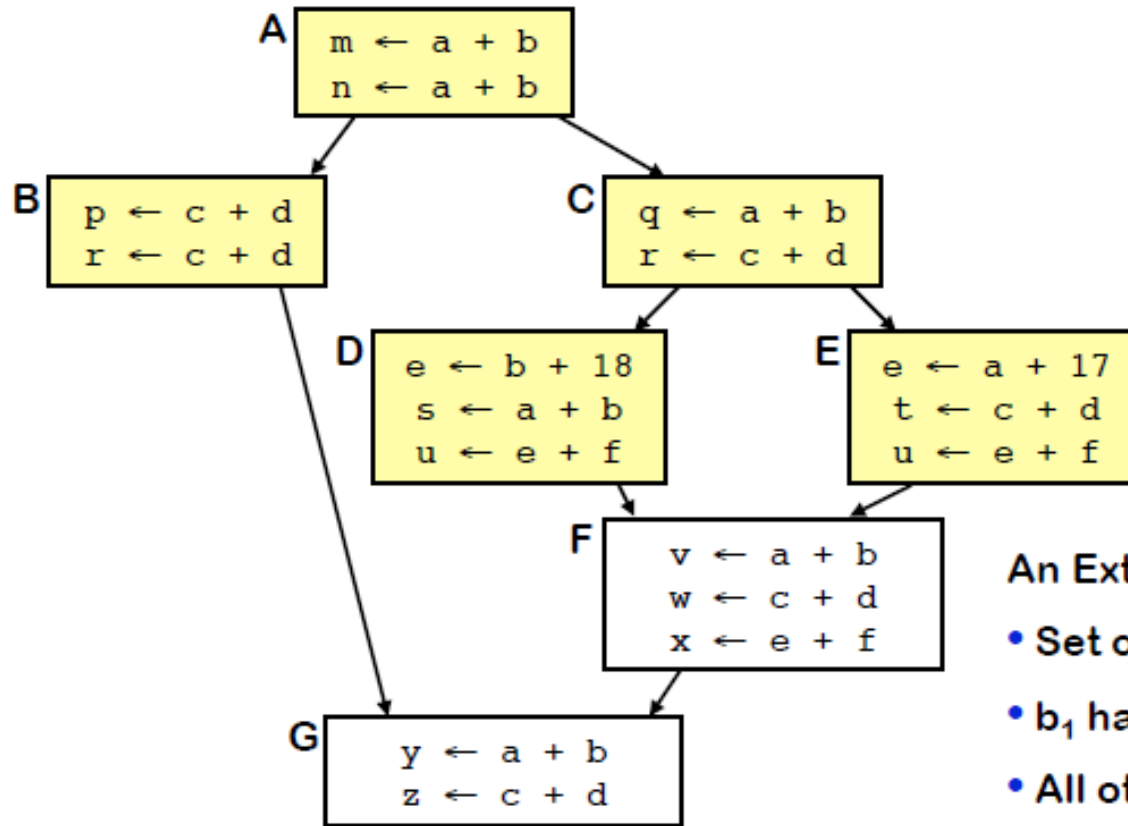
- Replace phi nodes with copy statements in the predecessors



# Superlocal Value Numbering



# Regional Optimization: Extended Basic Blocks



## An Extended Basic Block (EBB)

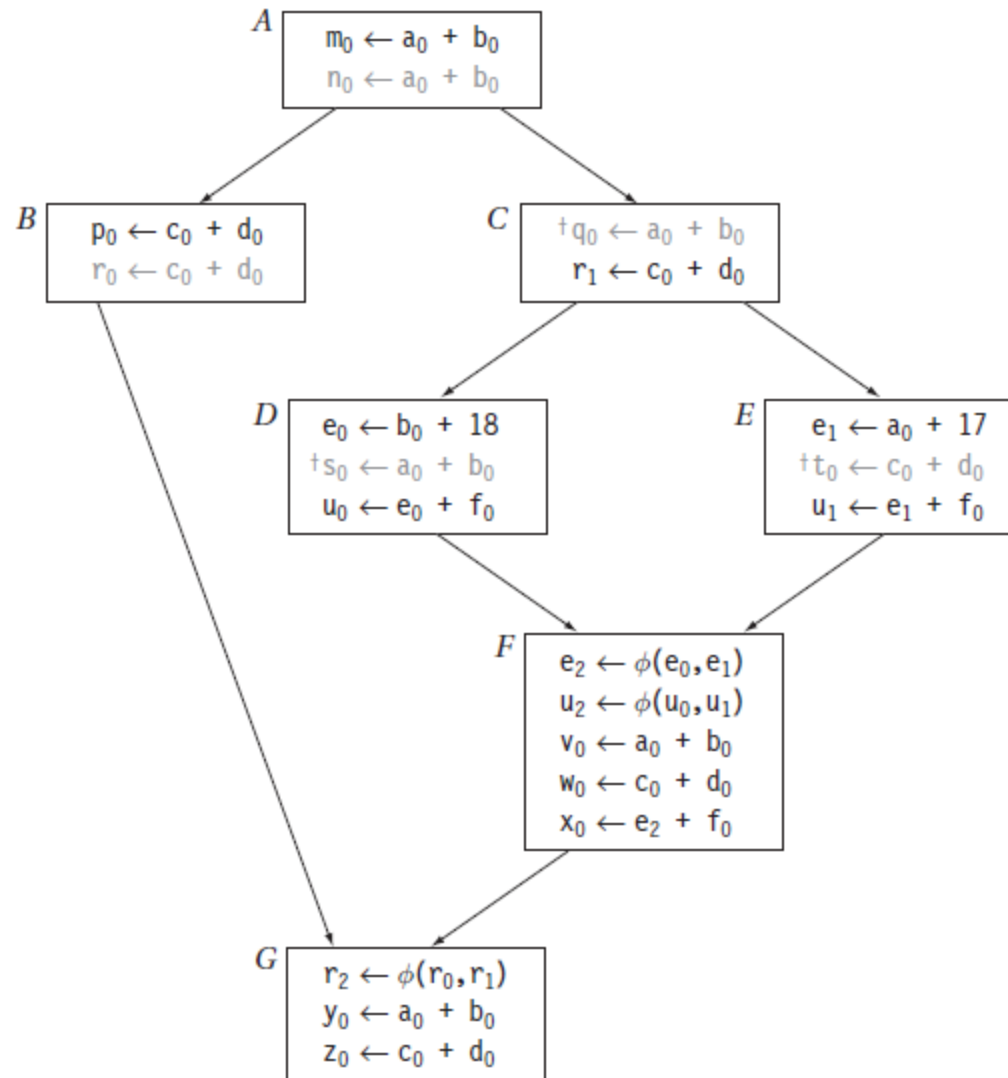
- Set of blocks  $b_1, b_2, \dots, b_n$
- $b_1$  has  $> 1$  predecessor
- All other  $b_i$  have 1 predecessor
- EBBs provide more context for optimization

# Extended Basic Blocks

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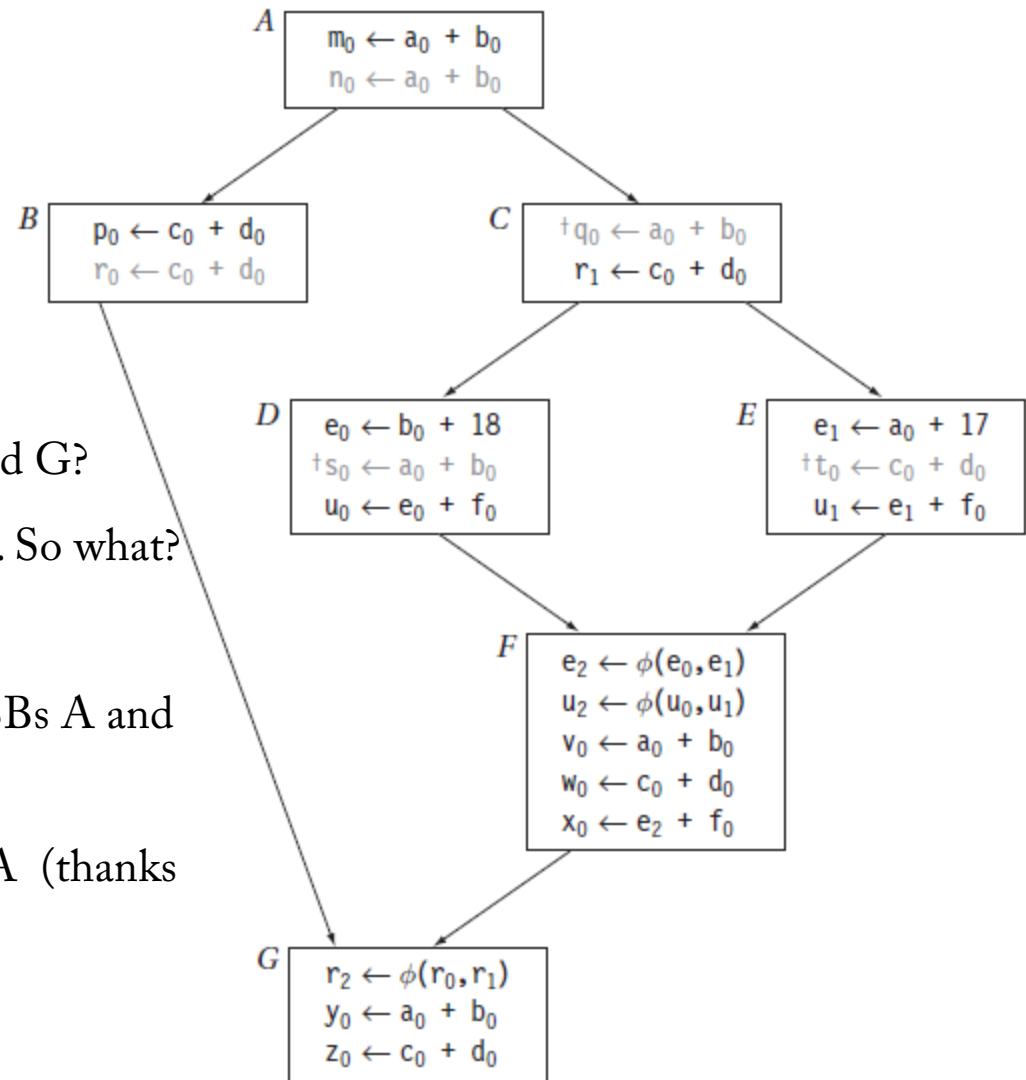
- An EBB can be seen as a tree with nodes having in-degree 1 (except for the root node) and arbitrary out degree
- Value Numbering Algorithm on an EBB
- **Key Idea:** While optimizing a BB, we can use the values generated in any of the ancestor Basic Blocks

# Supervalue Local Numbering





# Dominator-Based Value Numbering



- What about the redundancies in BBs F and G?
- **Problem:** They have multiple predecessors. So what?
- Observation
  - BB F can use the values computed in BBs A and C (thanks to SSA)
  - BB G can use the values computed in A (thanks to SSA)

# Dominators

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**Def:**  $x$  dominates  $y$  if and only if every path from the entry of the control-flow graph to the node for  $y$  includes  $x$ .

- By definition,  $x$  dominates  $x$
- We associate a Dom set with each node
- $|\text{Dom}(x)| \geq 1$

## Immediate dominators

- For any node  $x$ , there must be a  $y$  in  $\text{Dom}(x)$  closest to  $x$
- We call this  $y$  the immediate dominator of  $x$
- As a matter of notation, we write this as  $\text{IDom}(x)$

# Dominators

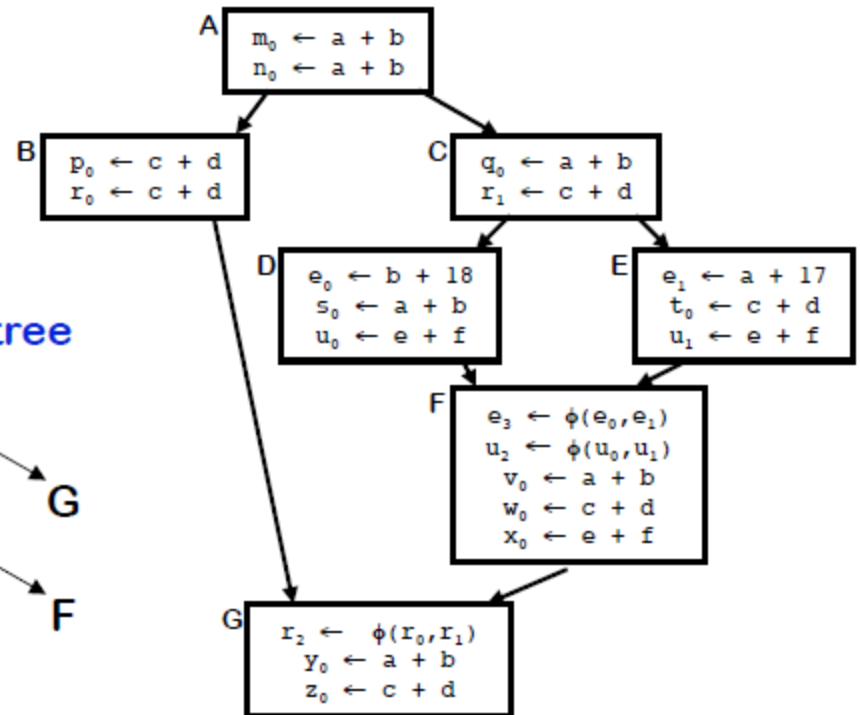
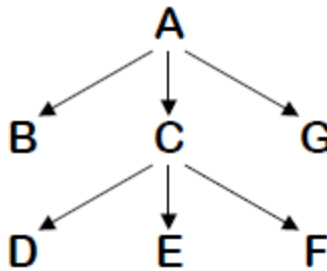
Dominators have many uses in analysis & transformation

- Finding loops
- Building SSA form
- Making code motion decisions

Dominator sets

Block	Dom	IDom
A	A	-
B	A,B	A
C	A,C	A
D	A,C,D	C
E	A,C,E	C
F	A,C,F	C
G	A,G	A

Dominator tree



# Dominator Based Value Numbering

- **Key Idea:** While Value Numbering a BB B, start with IDom(B)'s Value Number table
- While processing BB F, start with BB C's Value Number table (which includes BB A's also)
- Similarly for BB G, start with the Value Number table of BB A

