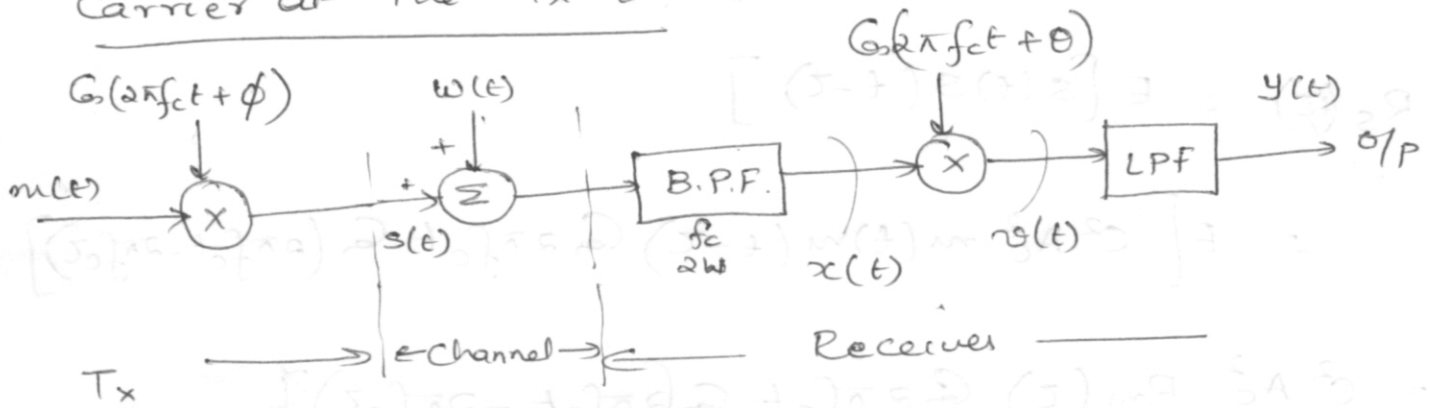


Analysis of DSB-SC ^{with} random phase in the carrier at the Tx & Rx!



Case-1 ϕ is random in the carrier.

$$s(t) = c A_c m(t) G(2\pi f_c t + \phi)$$

$$R(\tau) = c^2 A_c^2 E[s(t)s(t-\tau)]$$

$$= c^2 A_c^2 E[m(t)m(t-\tau) G(2\pi f_c t + \phi) G(2\pi f_c t + \phi - 2\pi f_c \tau)]$$

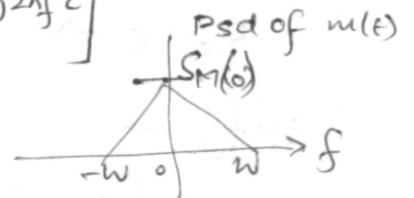
$$= c^2 A_c^2 R_m(\tau) E[G(2\pi f_c t + \phi) G(2\pi f_c t + \phi - 2\pi f_c \tau)]$$

ϕ = Uniformly distributed r.v. between 0 to 2π or $-\pi$ to π

$$= c^2 A_c^2 R_m(\tau) \left\{ \frac{1}{2} E[G(4\pi f_c t + 2\phi - 2\pi f_c \tau)] + E[G(2\pi f_c \tau)] \right\}$$

avg. over $\phi = 0$

$$= c^2 A_c^2 R_m(\tau) \frac{G(2\pi f_c \tau)}{2} = c^2 A_c^2 \frac{R_m(\tau)}{4} [e^{j2\pi f_c \tau} + e^{-j2\pi f_c \tau}]$$



P. Spectrum of P.S.D. of $s(t)$

Observation-1

PSD is ~~same~~ the same.

as that for a deterministic signal



Observation-2

$$P_{si} = \frac{R_m(0)}{2} \cdot c^2 A_c^2 = \frac{P_s c^2 A_c^2}{2}$$

Case-2

$\phi = 0$ or a constant

$$S(t) = CA_c m(t) \cos 2\pi f_c t$$

$$R_S(t, \tau) = E[S(t)S(t-\tau)]$$

$$= E[C^2 A_c^2 m(t)m(t-\tau) \cos 2\pi f_c t \cos(2\pi f_c t - 2\pi f_c \tau)]$$

$$= C^2 A_c^2 R_m(\tau) \cos 2\pi f_c t \cos(2\pi f_c t - 2\pi f_c \tau)$$

$$R_S(t, \tau) = \frac{C^2 A_c^2}{2} R_m(\tau) \left[\cos(4\pi f_c t - 2\pi f_c \tau) + \cos 2\pi f_c \tau \right]$$

Not a ~~sta~~ WSS process because it is a
~~comp~~ fn. of both t & τ . (Actually, Cyclostationary)

~~Q2 Find time-averaged~~

random process. In fact, whenever ϕ has any distribution other than uniform, the resulting process is cyclostationary.

For cyclostationary -

$$R_S(t, \tau) = R_S(t+T, \tau)$$

$$T = \frac{1}{2f_c}$$

Verify -

$$\therefore \cos(4\pi f_c t - 2\pi f_c \tau) = \cos(4\pi f_c t + 2\pi - 2\pi f_c \tau)$$

\therefore Compute

$$R_S(\tau) = \frac{1}{T} \int_{-T/2}^{T/2} R_S(t, \tau) dt$$

$$= \frac{C^2 A_c^2}{2} R_m(\tau) \cos 2\pi f_c \tau \rightarrow \text{Same as before.}$$

$$x(t) = s(t) + n(t)$$

$$= C A_c \cos(2\pi f_c t + \phi) m(t) + n_I(t) \cos 2\pi f_c t - n_Q(t) \sin 2\pi f_c t$$

$$v(t) = x(t) \cos(2\pi f_c t + \theta)$$

$$= C A_c \cos(2\pi f_c t + \phi) \cos(2\pi f_c t + \theta) m(t)$$

$$+ \boxed{\begin{aligned} & n_I(t) \cos 2\pi f_c t \cdot \cos(2\pi f_c t + \theta) \\ & - n_Q(t) \sin 2\pi f_c t \cdot \sin(2\pi f_c t + \theta) \end{aligned}}$$

$s_I(t)$
 noise
 $\leftarrow n_I(t)$

$$s_I(t) = C A_c \cos(2\pi f_c t + \phi) \cos(2\pi f_c t + \theta) m(t)$$

$$= \frac{C A_c m(t)}{2} \cos(\pi f_c t + \phi + \theta)$$

$$+ \frac{C A_c m(t)}{2} \cos(\phi - \theta)$$

$$y(t) = \text{LPF}(v(t)) = s_0(t) + n_0(t)$$

$$s_0(t) = \text{o/p at the filter}$$

$$= \frac{C A_c m(t)}{2} \cos(\phi - \theta)$$

Use of coherent detector

will nullify it

& hence, for the sake of simplicity, we

write $\phi = \theta = 0$

look at noise -

$$n_1(t) = n_I(t) \underbrace{\cos 2\pi f_c t}_{b} \underbrace{\cos(2\pi f_c t + \theta)}_a$$

$$- n_Q(t) \underbrace{\sin 2\pi f_c t}_{b} \underbrace{\cos(2\pi f_c t + \theta)}_a$$

Sub a

$$= \frac{1}{2} [\cos(a+b) - \cos(a-b)]$$

$$n_{I'}(t) = \frac{n_I(t)}{2} [\cos(4\pi f_c t + \theta) + \cos \theta]$$

$$- \frac{n_Q(t)}{2} [\sin(4\pi f_c t + \theta) - \sin \theta]$$

$$n_0(t) = \text{LPF} [n_1(t)]$$

$$= \frac{n_I(t)}{2} \cos \theta + \frac{n_Q(t)}{2} \sin \theta$$

Power in $n_{I'}(t) = \frac{n_I(t)}{2} \cos \theta = ?$

$$R_{n_{I'}}(t, t-\tau) = E \left[\frac{n_I(t)}{2} \cos \theta \frac{n_I(t-\tau)}{2} \cos \theta \right]$$

$$= \frac{1}{4} \times R_{n_I}(\tau) E[\cos^2 \theta]$$

$$= \frac{1}{8} R_{n_I}(\tau) E[1 + \cos 2\theta]$$

$$= \frac{1}{8} R_{n_I}(\tau) \quad \begin{matrix} \uparrow \\ E[\cos 2\theta] = 0 \end{matrix}$$

θ is uniformly distributed



$$R_{n_{I'}}(0) = \frac{1}{8} R_{n_I}(0) = \frac{1}{8} R_n(0) = \frac{1}{8} \times 2 \times 2W \times \frac{N_0}{2} = \frac{1}{4} W N_0$$

$$R_{no}(t, t-\tau) = E \left[\left(\frac{n_I(t)G_0\theta}{2} + \frac{n_Q(t)S_0\theta}{2} \right) \left(\frac{n_I(t-\tau)G_0\theta}{2} + \frac{n_Q(t-\tau)S_0\theta}{2} \right) \right] \quad (3)$$

$$= \frac{1}{4} E[n_I] \left\{ \frac{1}{4} R_{n_I}(\tau) E[G_0^2\theta] + R_{n_Q}(\tau) E[S_0^2\theta] \right.$$

$$+ E[n_I(t)n_Q(t-\tau)] E[G_0\theta S_0\theta]$$

$$\left. + E[n_I(t-\tau)n_Q(t)] E[G_0\theta S_0\theta] \right\}$$

$$= \frac{1}{4} R_{n_I}(\tau) \left\{ \frac{1 + E(G_0^2\theta)}{2} \right\}$$

$$+ \frac{1}{4} R_{n_Q}(\tau) \left\{ \frac{1 + E(S_0^2\theta)}{2} \right\}$$

$$+ \frac{1}{8} R_{n_I n_Q}(\tau) E(S_0\theta) + \frac{1}{8} R_{n_I n_Q}(\tau) E(S_0\theta)$$

$$R_{no}(\tau) = \frac{1}{8} R_{n_I}(\tau) + \frac{1}{8} R_{n_Q}(\tau)$$

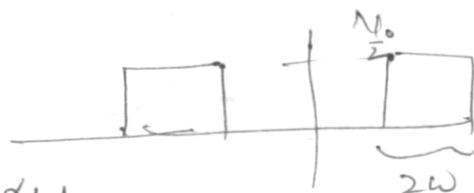
$$P_{no} = R_{no}(0) = \frac{1}{8} R_{n_I}(0) + \frac{1}{8} R_{n_Q}(0)$$

$$= \frac{1}{4} \left[\frac{1}{8} R_n(0) + \frac{1}{8} R_n(0) \right]$$

$$= \frac{1}{4} R_n(0)$$

$$= \frac{1}{4} \times 2 \times N_0 \times 2W$$

$$= \frac{1}{2} N_0 W$$



likewise for SSB —

Again, it is coherent detection —

∴ Signal power is same as was calculated earlier.

For noise power —

$$n(t) \sim n_I$$

$$v(t) = x(t) \cos(2\pi f_c t + \theta)$$

$$= (s(t) + n(t)) \cos(2\pi f_c t + \theta)$$

$$= s(t) \cos(2\pi f_c t + \theta) + n(t) \cos(2\pi f_c t + \theta)$$

Noise —

$$n(t) = n_I(t) \cos(2\pi f_c t + \theta)$$

$$= \left\{ n_I(t) \cos\left[2\pi\left(f_c - \frac{W}{2}\right)t\right] - n_Q(t) \sin\left[2\pi\left(f_c - \frac{W}{2}\right)t\right] \right\} \times \cos(2\pi f_c t + \theta)$$

$$2\pi f_c t = a$$

$$\pi W t = b$$

So

$$= \left[n_I(t) \cos(a-b) - n_Q(t) \sin(a-b) \right] \cos(a+\theta)$$

$$= \frac{1}{2} n_I(t) \left\{ \cos(2a-b+\theta) + \cos(b+\theta) \right\}$$

$$+ \frac{1}{2} n_Q(t) \left\{ \sin(2a-b+\theta) + \sin(-b-\theta) \right\}$$

So

$$= \frac{\sin(a+b) + \sin(a-b)}{2}$$

$$= \frac{\sin a \cos b + \cos a \sin b + \sin a \cos b - \cos a \sin b}{2}$$

$$y(t) = \text{LPP} \{ v(t) \}$$

$$= s_o(t) + n_o(t)$$

$$\therefore n_o(t) = \frac{1}{2} n_I(t) \cos(b + \theta) - \frac{1}{2} n_Q(t) \sin(b + \theta)$$

$$= \frac{1}{2} n_I(t) \cos(\pi W t + \theta) - \frac{1}{2} n_Q(t) \sin(\pi W t + \theta)$$

$$R_{n_o}(t, t-\tau) = \frac{1}{4} E \left[\left(n_I(t) \cos(b + \theta) - n_Q(t) \sin(b + \theta) \right) \right.$$

$$\left. \left(n_I(t-\tau) \cos(b - c + \theta) - n_Q(t-\tau) \sin(b - c + \theta) \right) \right]$$

$$= \frac{1}{4} R_{n_I}(\tau) E[\cos(b + \theta) \cos(b - c + \theta)]$$

$$+ \frac{1}{4} R_{n_Q}(\tau) E[\sin(b + \theta) \sin(b - c + \theta)]$$

$$- \frac{1}{4} E[n_I(t) n_Q(t-\tau)] E[\cos(b + \theta) \sin(b - c + \theta)]$$

$$- \frac{1}{4} E[n_I(t-\tau) n_Q(t)] E[\sin(b + \theta) \cos(b - c + \theta)]$$

Property - 7 — If a narrowband ^{noise} $n(t)$ is Gaussian with zero mean & a PSD $P_n(f)$ that is locally symmetric about the mid-band f_{nos} , $\pm f_c$, then the in-phase noise $n_I(t)$ & the quadrature noise $n_Q(t)$ are statistically independent.

$$R_{n_0}(t, t-z) = \frac{1}{8} R_{n_I}(z) E \left[G(2b + 2\theta - c) + G(c) \right] \\ + \frac{1}{8} R_{n_Q}(z) E \left[G(c) - G(2b + 2\theta - c) \right]$$

Subst = $\frac{G(a-b) - G(a+b)}{2}$
Avg over $\theta = 0$

$$= \frac{1}{8} R_{n_I}(z) G(c) + \frac{1}{8} R_{n_Q}(z) G(c)$$

$$R_{n_0}(z) = \frac{1}{8} R_{n_I}(z) G(\pi W z) + \frac{1}{8} R_{n_Q}(z) G(\pi W z)$$

$$R_{n_0}(0) = \frac{1}{8} R_{n_I}(0) + \frac{1}{8} R_{n_Q}(0)$$

$$= \frac{1}{4} R_n(0)$$

$$= \frac{1}{4} \times 2 \cdot \frac{N_0}{2} \times W$$

$$= \frac{N_0 W}{4}$$

