

laplace Inverse :-

$$\textcircled{1} \quad f(s) = \frac{1}{s+a}, \quad \operatorname{Re}\{s\} > -a$$

$$f(t) = e^{-at} u(t)$$

$$\textcircled{2} \quad F(s) = \frac{10}{(s+b)^3}$$

$$\boxed{t^n e^{-at} u(t) \longleftrightarrow \frac{n!}{(s+a)^{n+1}}}$$

$$F(s) = 5 \times \frac{2!}{(s+b)^{2+1}}$$

$$\boxed{f(t) = 5 \cdot t^2 e^{-bt} u(t)}$$

$$\textcircled{3} \quad f(s) = \frac{8}{s^2 + 4s + 10} = \frac{8}{s^2 + 2 \cdot s \cdot 2 + (2)^2 + 6}$$

$$= \frac{8 \times \sqrt{6}}{(s+2)^2 + (\sqrt{6})^2} = \frac{8}{\sqrt{6}} \frac{\sqrt{6}}{(s+2)^2 + (\sqrt{6})^2}$$

$$f(t) = \frac{8}{\sqrt{6}} e^{-2t} \sin \sqrt{6} t u(t) .$$

e.g. $X(s) = \frac{2s^2 + 5s + 5}{(s+1)^2 (s+2)}$ find causal inverse $x(t)$

$$\text{let } X(s) = \frac{2s^2 + 5s + 5}{(s+1)^2 (s+2)} = \frac{A}{s+1} + \frac{B}{(s+1)^2} + \frac{C}{s+2}$$

$$\Rightarrow 2s^2 + 5s + 5 = A(s+1)(s+2) + B(s+2) + C(s+1)^2$$

At $s=-2$

$$8 - 10 + 5 = 0 + 0 + C$$

$C = 3$

$$\Rightarrow 2s^2 + 5s + 5 = A(s^2 + 3s + 2) + B(s+2) + C(s^2 + 2s + 1)$$

Comparing coeff of s^2 both side.

$$2 = A + C \quad \therefore A = 2 - C = 2 - 3$$

$A = -1$

Comparing coeff of s^0 both side.

$$5 = 2A + 2B + C$$

$$5 = -2 + 2B + 3 \Rightarrow 2B = 4 \Rightarrow B = 2$$

$$X(s) = \frac{-1}{s+1} + \frac{2}{(s+1)^2} + \frac{3}{s+2}$$

Taking causal Inverse Laplace.

$$x(t) = -e^{-t} u(t) + 2 \cdot t \cdot e^{-t} u(t) + 3e^{-2t} u(t)$$

$$x(t) = \left[-e^{-t} + 2t e^{-t} + 3e^{-2t} \right] u(t)$$

eg $X(s) = \frac{s(s-2)}{s^2(s+4)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s+4}$

$$s(s-2) = As(s+4) + B(s+4) + Cs^2$$

At $s=-4$

$$-30 = 16C$$

$C = -\frac{30}{16}$

comp. coeff of s^2

$$0 = A + C$$

$$A = -C$$

$A = \frac{30}{16}$

comp. coeff of s

$$5 = 4A + B$$

$$\Rightarrow$$

$B = \frac{50}{16}$

$$X(s) = \frac{30/16}{s} + \frac{50/16}{s+2} + \frac{(-30/16)}{s+4}$$

$$\Rightarrow x(t) = \frac{30}{16} u(t) + \frac{50}{16} t u(t) - \frac{30}{16} e^{-4t} u(t)$$

Minimum Phase system:

→ All poles & zeros must be located in L.H.S. of s -plane, so that the inverse of the system will also be causal & stable.

$$H(s) = \frac{(s+2)(s+3)}{(s+1)(s+4)(s+5)} \xrightarrow{-2, -3} \text{Minimum phase system}$$

$$H(s) = \frac{(s-2)(s+3)}{(s+1)(s+4)(s+5)} \xrightarrow{2, -3} \text{Mixed phase system}$$

$$H(s) = \frac{(s-2)(s-3)}{(s+1)(s+4)(s+5)} \xrightarrow{2, 3} \text{Maximum phase system.}$$

→ Total no. of poles = Total no. of zeros = 3

No. of zeros in finite s -plane $\gamma = 2$
 " poles " " " " " $p = 3$

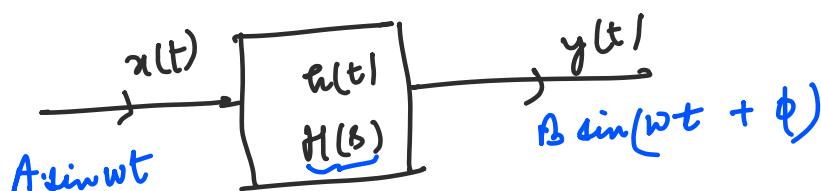
" zeros in infinite s -plane $= p - \gamma = 1$

$$\text{eg} \quad H(s) = \frac{(s+2)(s+3)}{(s+1)(s+4)(s+5)}$$

$$H(j\omega) = \frac{(j\omega+2)(j\omega+3)}{(j\omega+1)(j\omega+4)(j\omega+5)}$$

$$\begin{aligned} \angle H(j\omega) &= \left\{ \tan^{-1} \frac{\omega}{2} + \tan^{-1} \frac{\omega}{3} \right\} \\ &\quad - \left\{ \tan^{-1} \omega + \tan^{-1} \frac{\omega}{4} + \tan^{-1} \frac{\omega}{5} \right\} \end{aligned}$$

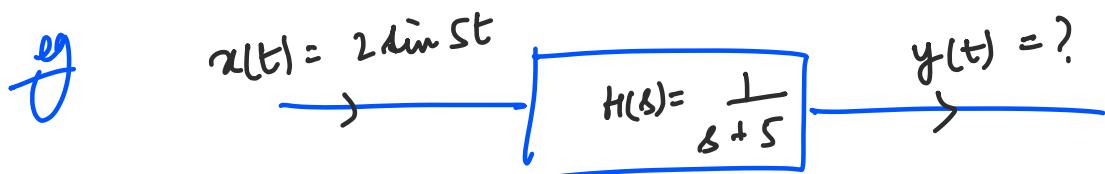
Steady State Response of an LTI system :-



$$\begin{aligned} H(s) &\approx H(j\omega) \\ H(j\omega) &\rightarrow |H(j\omega)| = X \quad B = AX \\ &\rightarrow \angle H(j\omega) = \phi \end{aligned}$$

If input to a LTI system is sinusoidal, then its response will also be sinusoidal in nature, having same freq. as input.

Amplitude & phase angle may vary!



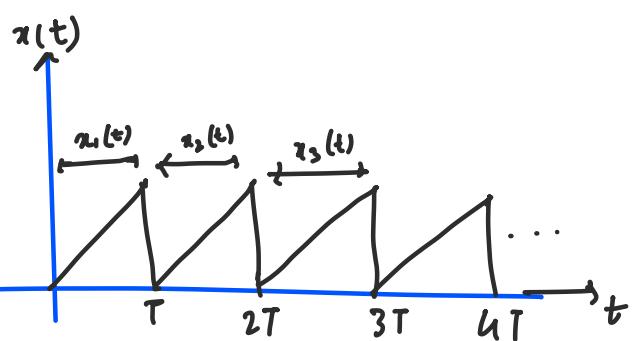
$$H(j\omega) = \frac{1}{j\omega + 5}$$

$$|H(j\omega)| = \frac{1}{\sqrt{\omega^2 + 25}} = \frac{1}{\sqrt{50}} = X$$

$$\angle H(j\omega) = -\tan^{-1} \frac{\omega}{5} = -45^\circ = \phi$$

$$y(t) = B \sin(st + \phi) = \frac{2}{\sqrt{50}} \sin(st - 45^\circ)$$

Laplace transform for causal repeating funcⁿ:



$$x(t) = x_1(t) + x_1(t-T) + x_1(t-2T) + x_1(t-3T) + \dots$$

$$x_1(t) \longleftrightarrow X_1(s)$$

$$x_1(t-T) \longleftrightarrow e^{-sT} X_1(s)$$

$$x_2(t-2T) \longleftrightarrow e^{-2sT} X_1(s)$$

$$\therefore X(s) = X_1(s) + e^{-sT} X_1(s) + e^{-2sT} X_1(s) + e^{-3sT} X_2(s) + \dots$$

$$= X_1(s) \left[1 + e^{-sT} + e^{-2sT} + e^{-3sT} + \dots \right]$$

$$= X_1(s) \left(\frac{1}{1 - e^{-sT}} \right)$$

Partial fraction :-

①

$$\frac{1}{x^2 - 4} = \frac{A}{x+2} + \frac{B}{x-2}$$

②

$$\frac{x-4}{x^2 + 2x - 15} = \frac{x-4}{(x+5)(x-3)} = \frac{A}{x+5} + \frac{B}{x-3}$$

③

$$\frac{x}{(x-1)(x-2)^2} = \frac{A}{x-1} + \frac{B}{x-2} + \frac{C}{(x-2)^2}$$

④

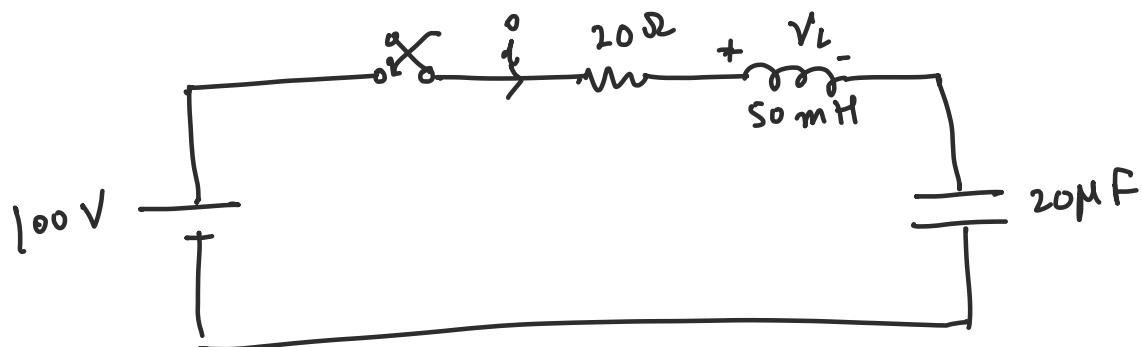
$$\frac{1}{(x-3)^3} = \frac{A}{x-3} + \frac{B}{(x-3)^2} + \frac{C}{(x-3)^3}$$

⑤

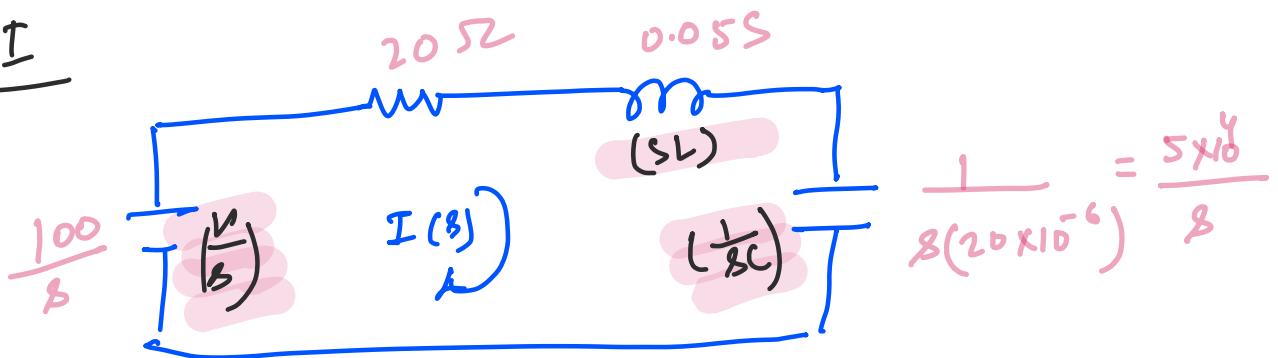
$$\begin{aligned}\frac{x^2 + 9}{(x^2 - 1)(x^2 + 4)} &= \frac{x^2 + 9}{(x+1)(x-1)(x^2 + 4)} \\ &= \frac{A}{x+1} + \frac{B}{x-1} + \frac{Cx + D}{x^2 + 4}\end{aligned}$$

Series RLC circuit Analysis :-

Ques :- The switch closes in the circuit of figure at $t=0$. Assuming a relaxed circuit at the time of switching, determine the current (i) for $t>0$. Also find the voltage V_L across the inductance for $t>0$.



Method I



By ohm's law

$$\boxed{V = IR}$$

$$\frac{100}{s} = I(s) \left[20 + 0.05s + \frac{5 \times 10^4}{s} \right]$$

$$\Rightarrow \boxed{I(s) = \frac{100/s}{20 + 0.05s + \frac{5 \times 10^4}{s}}}$$

Method 2 Using KVL .

On applying KVL - (Net potential drop in a closed circuit is 0)

$$100 - R i^*(t) - L \frac{di^*(t)}{dt} - \frac{1}{C} \int i^*(t) dt = 0$$

$$100 - 20 i^*(t) - 0.05 \frac{di^*(t)}{dt} - \frac{1}{20 \times 10^{-6}} \int i^*(t) dt = 0$$

on taking Laplace Transform

$$\frac{100}{s} - 20 I(s) - 0.05 \left[s I(s) \right] - \frac{1}{20 \times 10^{-6}} \left[\frac{I(s)}{s} \right]$$

$$\Rightarrow I(s) = \frac{\frac{100}{s}}{20 + 0.05s + \frac{5 \times 10^4}{s}}$$

$$\Rightarrow I(s) = \frac{\frac{100}{s}}{0.05s^2 + 20s + 5 \times 10^4} = \frac{\frac{2000}{s}}{s^2 + 400s + 10^6}$$

$$= \frac{\frac{2000}{s}}{(s+200)^2 + (979.79)^2}$$

$$\left[\because e^{-at} \sin \omega t = \frac{\omega}{(s+a)^2 + \omega^2} \right]$$

$$\left(\frac{\frac{2000}{s}}{979.79} \right) \frac{979.79}{(s+200)^2 + (979.79)^2}$$

on taking inverse Laplace transform

$$\Rightarrow i^*(t) = 2.04 e^{-200t} \sin (979.79 t)$$

Now voltage across the inductor -:

$$V_L(s) = I(s)(Ls)$$

$$\frac{2000}{(s+200)^2 + (979.79)^2} \times 0.05s$$

$$V_L(s) = \frac{100s}{(s+200)^2 + (979.79)^2}$$

$$\boxed{\therefore e^{-at} \cos wt = \frac{s+a}{(s+a)^2 + w^2}}$$

$$\therefore \frac{100(s+200) - 20000}{(s+200)^2 + (979.79)^2}$$

$$V_L(s) = \frac{100(s+200)}{(s+200)^2 + (979.79)^2} - \frac{20000}{(s+200)^2 + (979.79)^2}$$

$$= \frac{100(s+200)}{(s+200)^2 + (979.79)^2} - \left(\frac{20000}{979.79} \right) \left(\frac{-979.79}{(s+200)^2 + (979.79)^2} \right)$$

On taking inverse L.T.

$$V_L(t) = 100 \left\{ e^{-200t} \cos(979.79t) - 20.41 e^{-200t} \sin(979.79t) \right\}$$

Numericals → Initial Value Theorem :-

$$\lim_{t \rightarrow 0^+} x(t) = x(0^+) = \lim_{s \rightarrow \infty} s X(s) \quad \leftarrow \text{Property}$$

Eg $F(s) = \frac{4s+5}{s^2+8s+16}$, find initial value of $f(t)$

$$f(0^+) = \lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} \frac{s(4s+5)}{s^2+8s+16} = \lim_{s \rightarrow \infty} \frac{s^2 \left(4 + \frac{5}{s}\right)}{s^2 \left(1 + \frac{8}{s} + \frac{16}{s^2}\right)} = 4.$$

Eg $F(s) = \frac{6s+5}{2s+8}$ → not a proper fraction (degree are same)

$$\begin{array}{r} 2s+8 \end{array} \overbrace{\begin{array}{r} 6s+5 \\ -6s-24 \\ \hline -19 \end{array}}^{3} \Rightarrow F(s) = 3 - \frac{19}{2s+8}$$

$$\Rightarrow f(0^+) = \lim_{s \rightarrow \infty} s \left(-\frac{19}{2s+8} \right) = \lim_{s \rightarrow \infty} \frac{s(-19)}{s(2+\frac{8}{s})} = -\frac{19}{2} = -9.5 \quad \text{Ans}$$

Eg $F(s) = \frac{s^3+6s^2+8s+10}{s^2+4s+3}$

$$\begin{array}{r} s^2+4s+3 \end{array} \overbrace{\begin{array}{r} s^3+6s^2+8s+10 \\ -s^3-4s^2-3s \\ \hline 2s^2+5s+10 \\ -2s^2-8s-6 \\ \hline -3s+4 \end{array}}^{s+2}$$

$$f(s) = (s+2) + \frac{-3s+4}{s^2+4s+3}$$

$$\therefore f(0^+) = \lim_{s \rightarrow 0} s \cdot \frac{(-3s+4)}{s^2+4s+3}$$

$$\lim_{s \rightarrow 0} \frac{s^2 \left(-3 + \frac{4}{s} \right)}{s^2 \left(1 + \frac{4}{s} + \frac{3}{s^2} \right)} = -3$$

$f(0^+) = -3$

Numericals on final value theorem :-

$$\lim_{t \rightarrow \infty} x(t) = x(\infty) = \lim_{t \rightarrow \infty} s X(s)$$

- (1) poles of $s X(s)$ must lie in LHS of s -plane
- (2) Periodic signal & bounded signal not applicable

e.g. L.T. of $f(t)$ if $f(s) = \frac{5s^2 + 23s + 6}{s(s^2 + 2s + 2)}$

As $t \rightarrow \infty$, then $f(t)$ approaches to :-

a) 0

$$s f(s) = \frac{s \cdot 5s^2 + 23s + 6}{s(s^2 + 2s + 2)}$$

b) $\frac{5}{2}$

$$s f(s) = \frac{s^2 + 23s + 6}{s^2 + 2s + 2}$$

c) 17

d) ∞

$$\begin{aligned} \therefore \lim_{t \rightarrow \infty} f(t) &= \lim_{s \rightarrow 0} s \cdot f(s) = \lim_{s \rightarrow 0} \frac{s^2 + 23s + 6}{s^2 + 2s + 2} \\ &= \frac{6}{2} = 3 \end{aligned}$$

eg $\ddot{x}(t) + 3\dot{x}(t) + 2x(t) = 5$
 solⁿ of $x(t)$ approaches, when $t \rightarrow \infty$

$$\frac{d^2x(t)}{dt^2} + 3\frac{dx(t)}{dt} + 2x(t) = 5$$

$$s^2 X(s) + 3sX(s) + 2X(s) = \frac{5}{s}$$

$$X(s) [s^2 + 3s + 2] = \frac{5}{s}$$

$$\therefore X(s) = \frac{5}{s(s^2 + 3s + 2)}$$

$$sX(s) = \frac{5}{s^2 + 3s + 2}$$

$$\text{final value: } x(\infty) = \lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s) = \frac{5}{s^2 + 3s + 2} = \frac{5}{2}$$

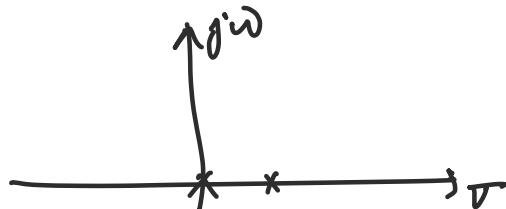
eg $X(s) = \frac{4}{s^2 + 4}$, then as $t \rightarrow \infty$, $x(t) = ?$

$$\sin \omega_0 t u(t) \xrightarrow{s^2 + \omega_0^2} \frac{\omega_0}{s^2 + \omega_0^2}$$

$x(t) = \sin 2t u(t)$ \leftarrow causal periodic signal
 \leftarrow final theorem not applicable.

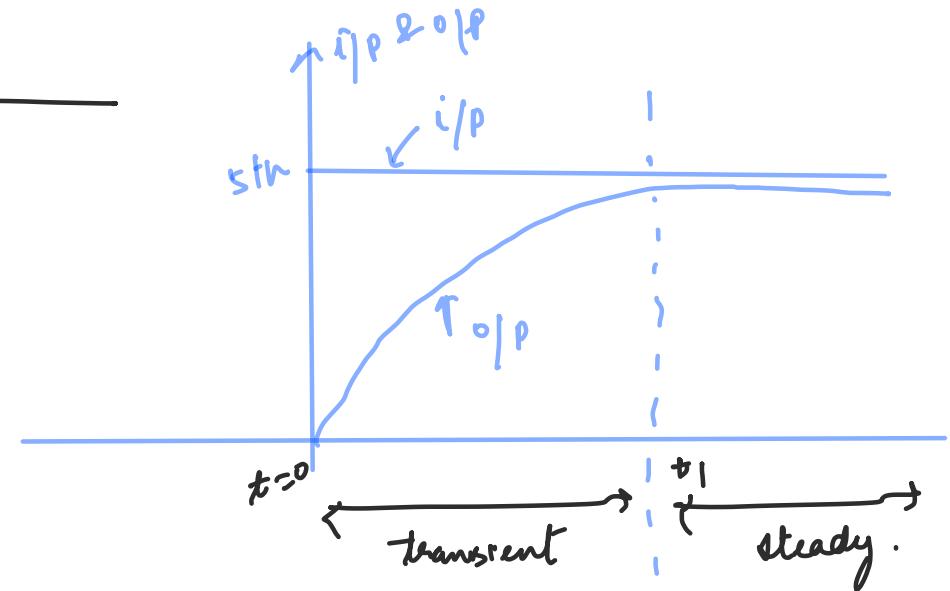
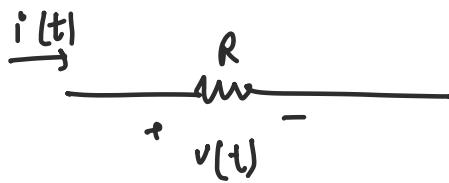
$$\underline{\text{eg}} \quad X(s) = \frac{1}{s(s-2)}$$

$$\text{poles of } X(s) = s=0, 2$$

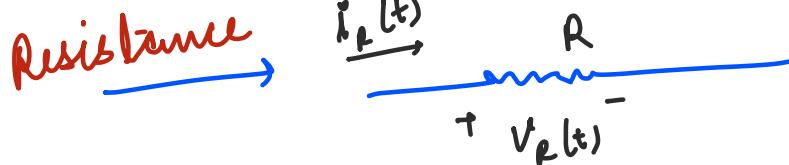
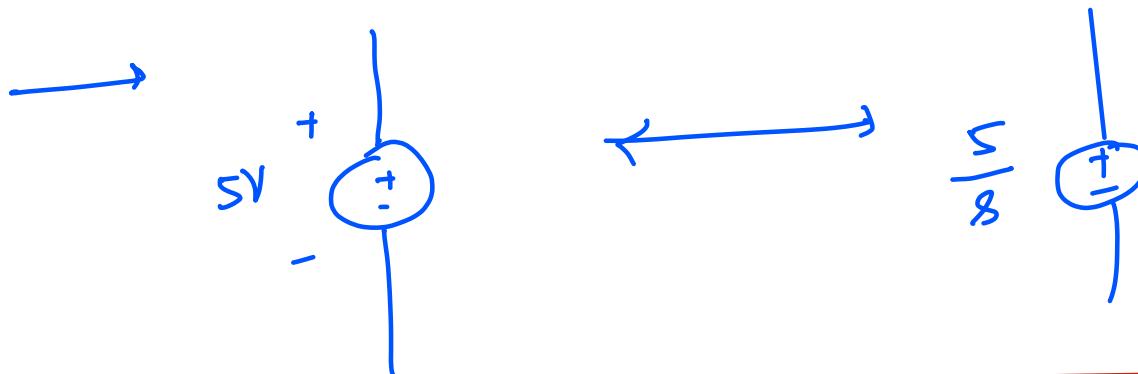
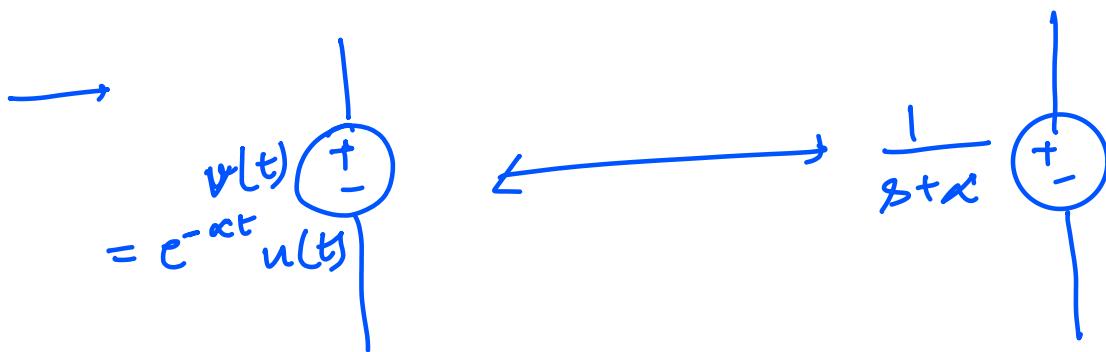


\rightarrow unbounded signal
 \rightarrow cannot be determined!

Application of L.T. in electrical Network :-



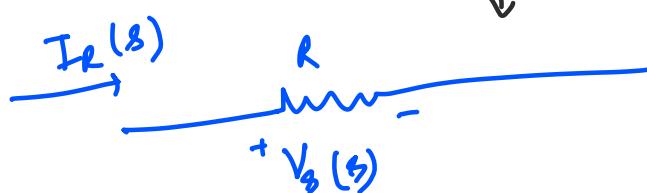
Transform Approach:-



$$v_R(t) = i_R(t) \cdot R$$

$$v_R(s) = R \cdot I_R(s)$$

$\downarrow L.T$

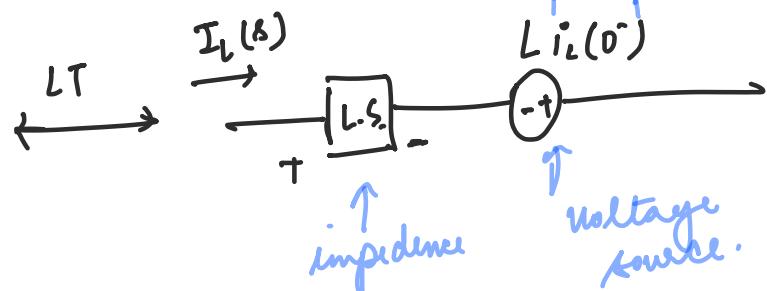
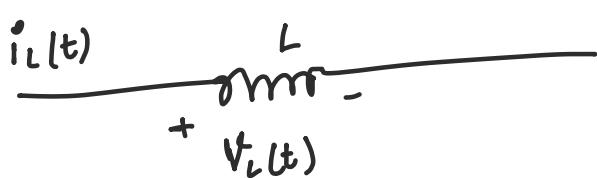
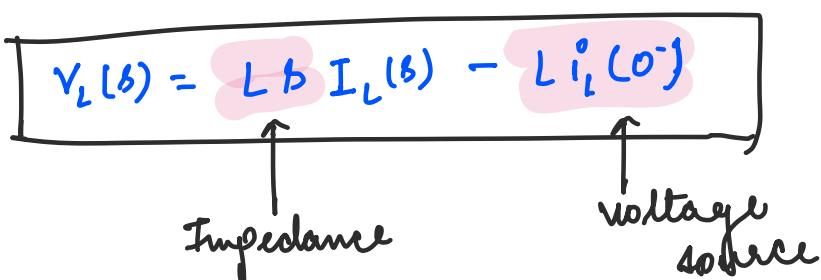


Inductor

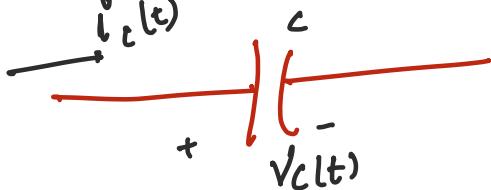
$$V_L(t) = L \frac{di_L(t)}{dt}$$

Taking L.T.

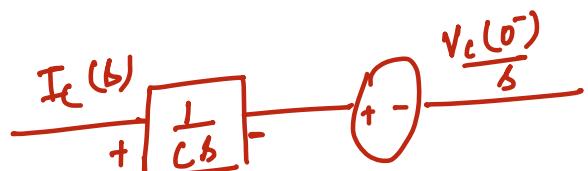
$$V_L(s) = L \left[s I_L(s) - i_L(0^-) \right]$$



Capacitor



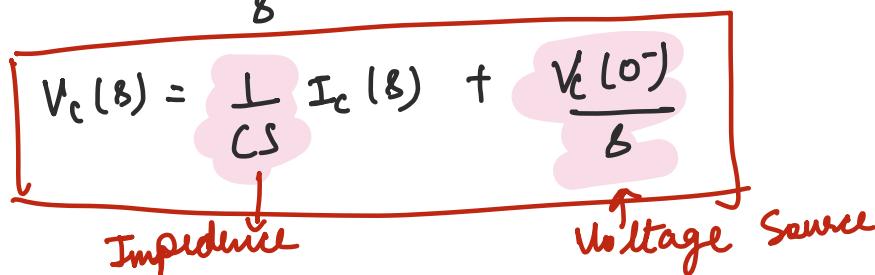
\xleftrightarrow{LT}



$$V_C(t) = \frac{1}{C} \int_{-\infty}^t i_C(t) dt = \underbrace{\frac{1}{C} \int_{-\infty}^0 i_C(t) dt}_{V_C(0^-)} + \frac{1}{C} \int_0^t i_C(t) dt$$

Voltage across capacitor before switching

$$V_C(s) = \frac{V_C(0^-)}{s} + \frac{1}{C} \left[\frac{I_C(s)}{s} \right]$$



$$z(t) \longleftrightarrow X(s)$$

$$\frac{dz(t)}{dt} \longleftrightarrow sX(s) - z(0^+)$$

$$\frac{d^2 z(t)}{dt^2} \longleftrightarrow s^2 X(s) - s z(0^+) - z'(0^+)$$

current through the inductor before switching

Inductor

$$V_L(t) = L \frac{di_L}{dt} \Big|_{t=0} \\ = 0$$

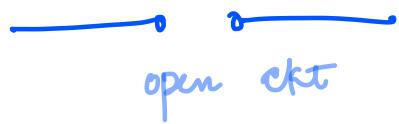


Steady

Short ckt

Capacitor

$$i_C(t) = C \frac{dV_C(t)}{dt} \\ = 0$$



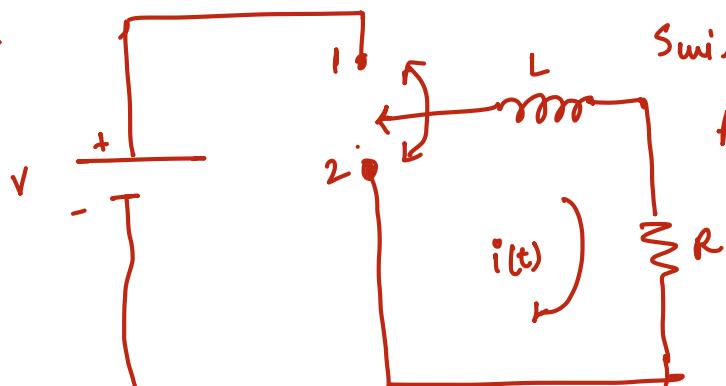
→ In inductor, current before switching
= current after switching.

$$i_L(0^-) = i_L(0^+)$$

→ In capacitor, voltage before switching =
voltage after switching.

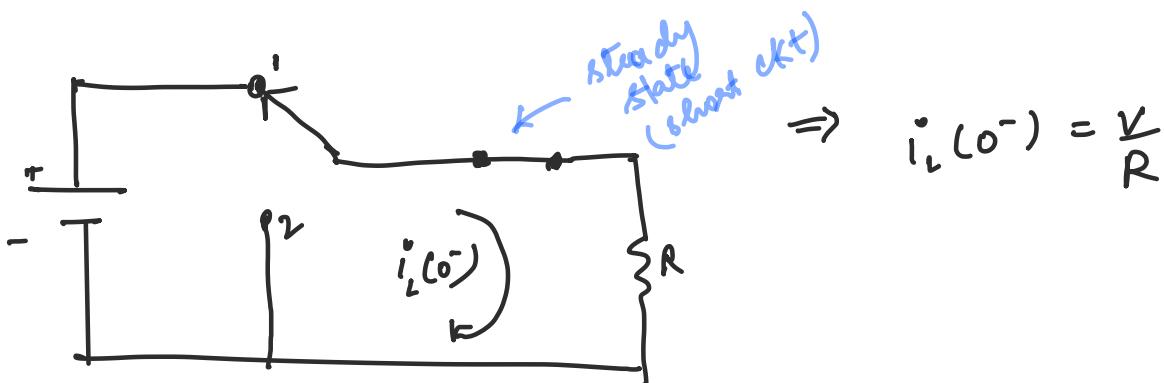
$$V_C(0^-) = V_C(0^+)$$

~~eg~~

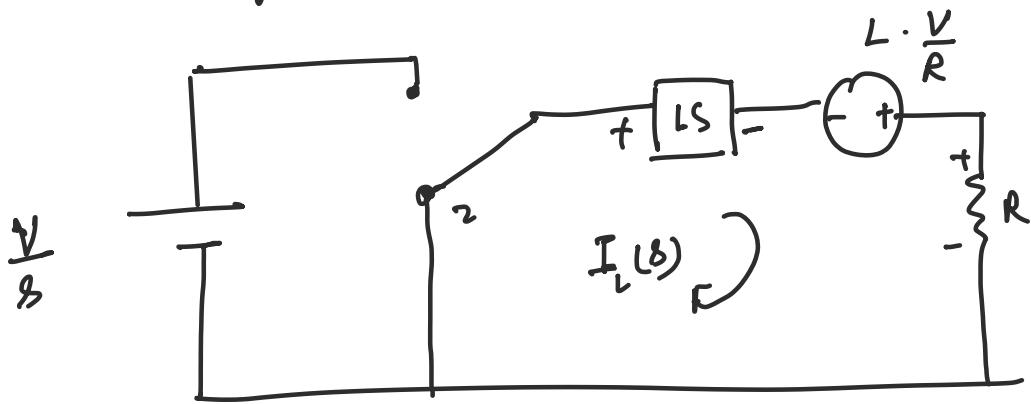


Switch is shifted from 1 → 2 at $t = 0^+$
At $t = 0^- \rightarrow$ steady state
Find $i(t)$ for $t \geq 0$

At $t = 0^-$



Transform Network for $t \geq 0$



$$I_L(s) \cdot LS - \frac{VL}{R} + I_L(s) R = 0$$

$$\Rightarrow I_L(s) [LS + R] = \frac{VL}{R}$$

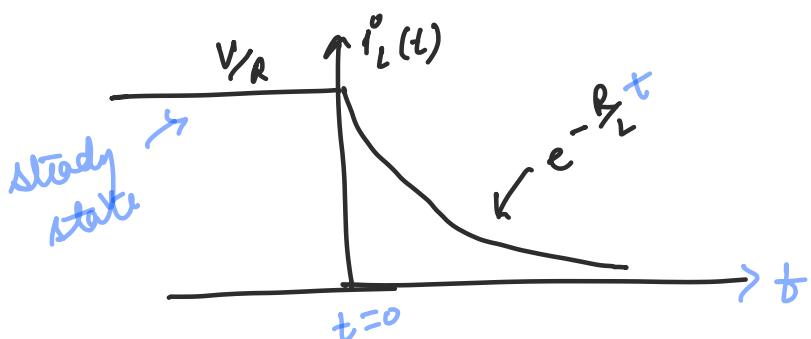
$$\Rightarrow I_L(s) = \frac{VL}{R(LS + R)} = \frac{\frac{VL}{s}}{R\left(s + \frac{R}{L}\right)}$$

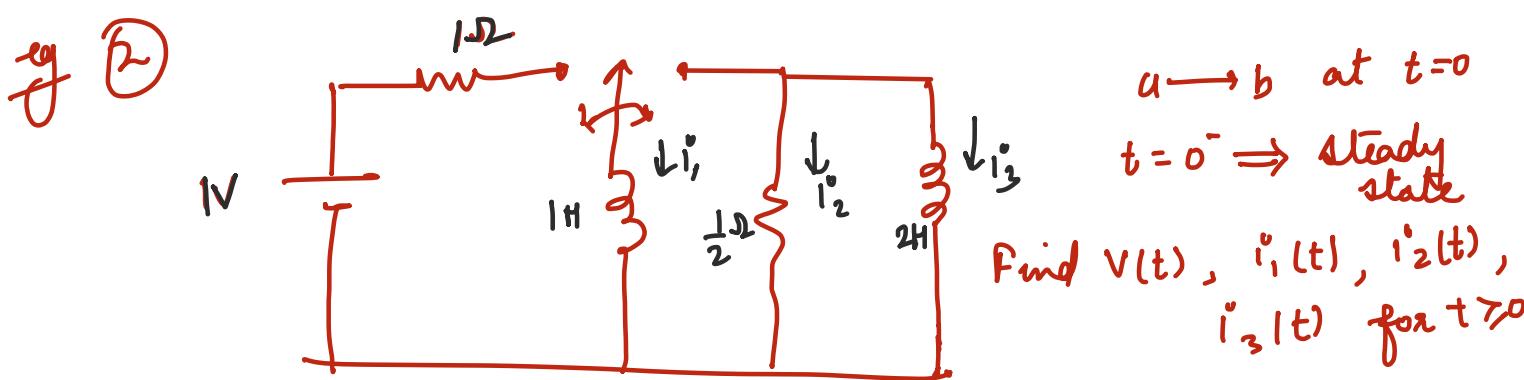
$$\therefore \boxed{i_L(t) = \frac{V}{R} e^{-\frac{R}{L}t}, t \geq 0}$$

To find $V_L(t)$

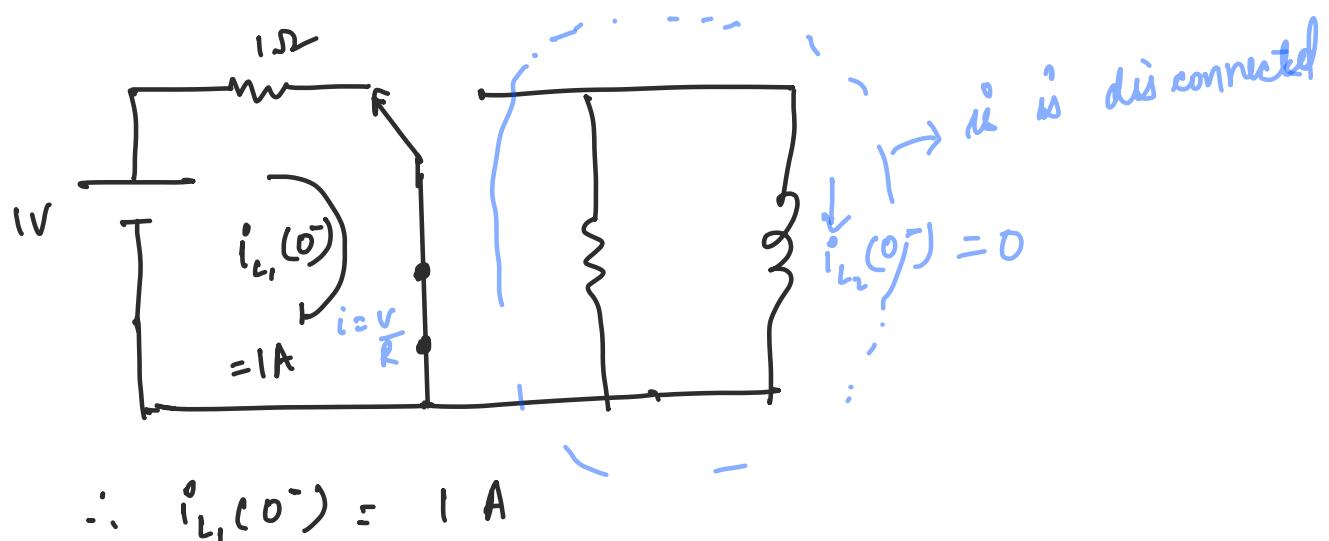
$$V_L(t) = I_L(s) LS - \frac{VL}{R} = \frac{VLs}{R\left(s + \frac{R}{L}\right)} - \frac{VL}{R}$$

$$\text{or } V_L(t) = L \frac{di}{dt} = L \frac{d}{dt} \left[\frac{V}{R} e^{-\frac{R}{L}t} \right]$$

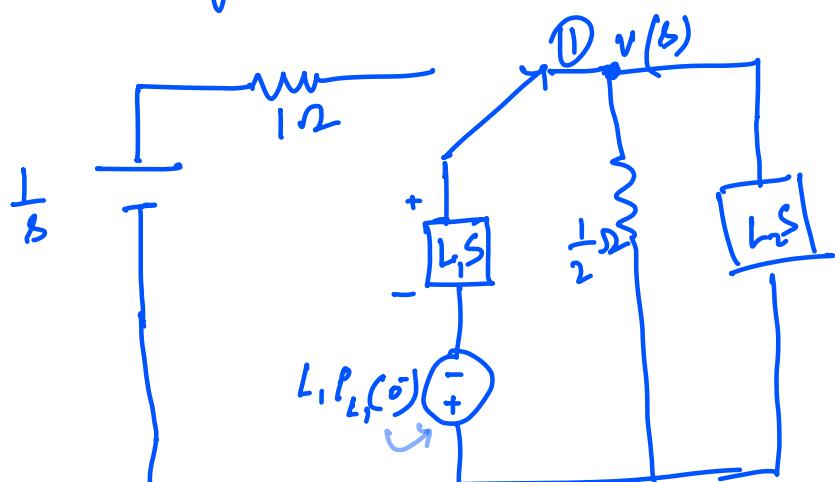




At $t=0^-$ (steady state)



Transform network for $t \geq 0$



KCL at ①

$$\frac{v(s) - (-1)}{s} + \frac{v(s)}{Y_2} + \frac{v(s)}{2s} = 0$$

$$2v(s) + 2 + 4s v(s) + v(s) = 0$$

$$\Rightarrow v(s)[4s + 3] = -2$$

$$v(s) = \frac{-2}{4\left(s + \frac{3}{4}\right)}$$

For $i_1(t)$

$$i_1(t) = \frac{1}{L} \int_{-\infty}^t v(t) dt = \frac{1}{L} \int_0^0 v(t) dt + \frac{1}{L} \int_0^t v(t) dt$$

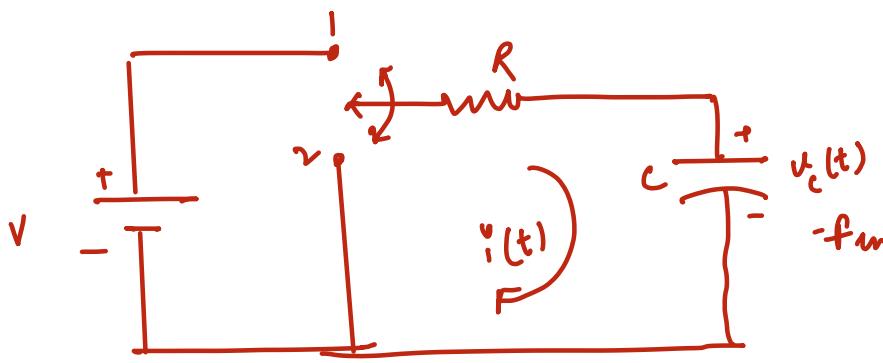
$v(t) = -\frac{1}{2} e^{-\frac{3}{4}t}$

 $t \geq 0$

$$i_1(t) = 1A + \int_0^t \left(-\frac{1}{2}\right) e^{-\frac{3}{4}t} dt$$

$$= \frac{1}{3} + \frac{2}{3} e^{-\frac{3}{4}t}$$

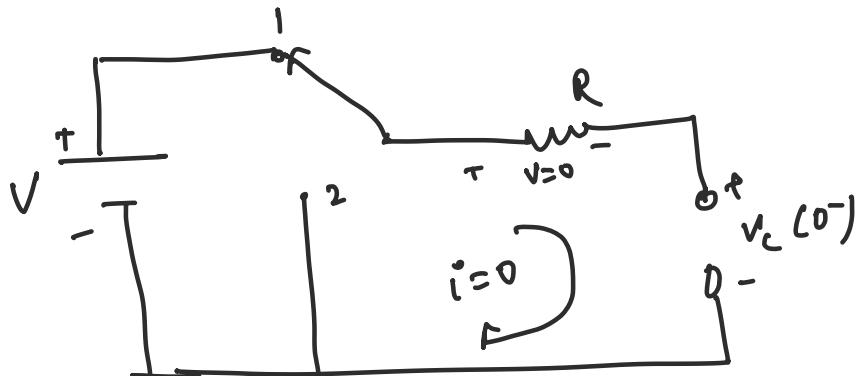
Ans.



$\overset{\text{eg}}{\text{Q}}$

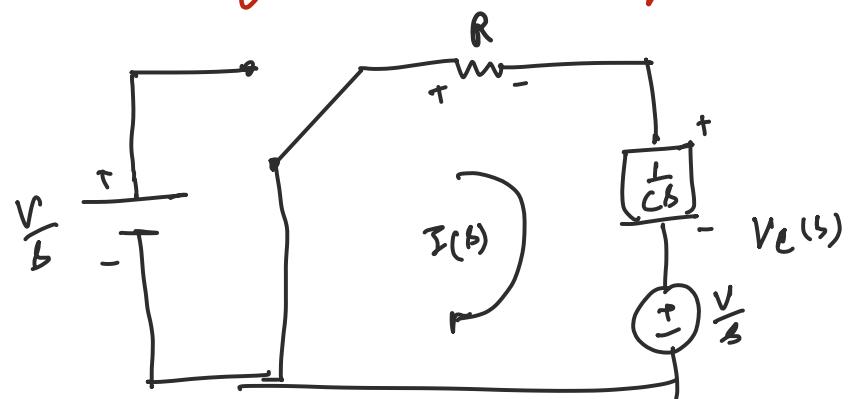
$1 \rightarrow 2$ at $t = 0^+$,
with $v_c(0^-) = \text{steady state}$
- find $i(t)$ & $v(t)$ for
 $t \geq 0$

At $t = 0^-$



$$\therefore v_c(0^-) = V$$

Transform network for $t \geq 0$



KVL

$$RI(s) + \frac{1}{Cs} I(s) + \frac{V}{s} = 0$$

$$I(s) \left[R + \frac{1}{Cs} \right] = -\frac{V}{s}$$

$$\Rightarrow I(s) = -\frac{V \cdot Cs}{s(RCs + 1)}$$

$$\Rightarrow I(s) = -\frac{VC}{RC(s + \frac{1}{RC})}$$

$$i(t) = -\frac{V}{R} e^{-\frac{1}{RC}t}$$

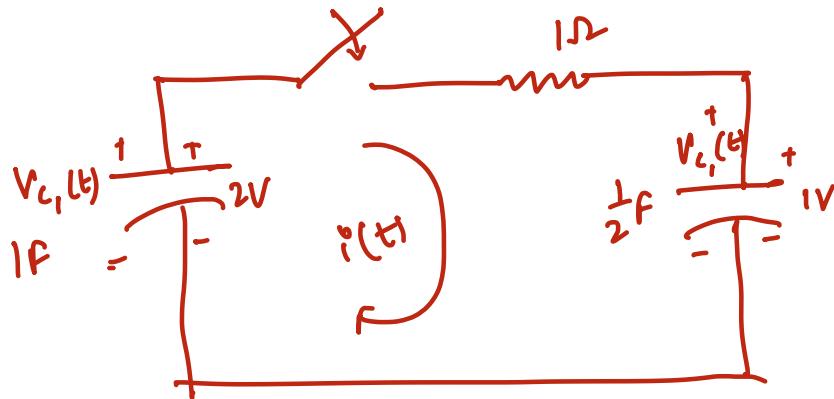
To find $v(t)$:-

$$iR + v(t) = 0$$

$$\therefore v(t) = -iR = \frac{V}{R} e^{-t/RC} \cdot R$$

$$v(t) = V \cdot e^{-t/RC}$$

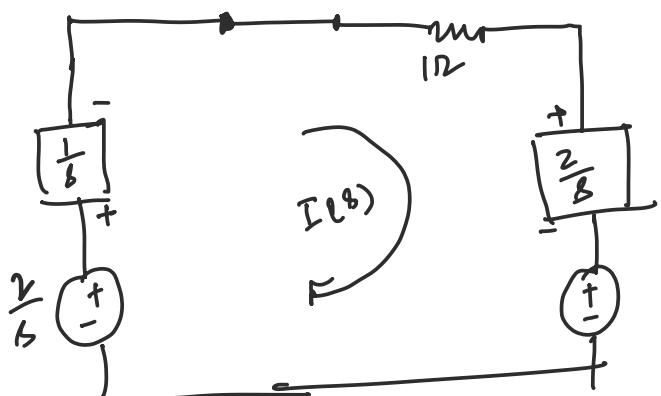
eg



find $P(t)$, $V_{C_1}(t)$,
 $V_{C_2}(t)$ for $t \geq 0$

$$V_{C_1}(0^-) = 2V, \quad V_{C_2}(0^-) = 1V$$

Transform network for $t > 0$



$$\begin{aligned} & \text{KVL} \\ & -\frac{2}{s} + I(s) \left(\frac{1}{s} \right) + 1 \cdot I(s) + \frac{2}{s} I(s) + \frac{1}{s} = 0 \\ & \Rightarrow I(s) \left\{ \frac{1}{s} + 1 + \frac{2}{s} \right\} = \frac{2}{s} - \frac{1}{s} \\ & \Rightarrow I(s) \left(\frac{1+s+2}{s} \right) = \frac{1}{s} \\ & \therefore I(s) = \frac{1}{s+3} \end{aligned}$$

$$\boxed{\therefore i(t) = e^{-3t}} \quad t \geq 0$$

To find $V_{C_1}(s)$:-

$$\begin{aligned} V_{C_1}(s) &= -I(s) \left(\frac{1}{s} \right) + \frac{2}{s} = -\frac{1}{s(s+3)} + \frac{2}{s} \\ &= -1 \cdot \frac{1}{3} \left\{ \frac{1}{s} - \frac{1}{s+3} \right\} + \frac{2}{s} = -\frac{1}{3} \left(\frac{1}{s} \right) + \frac{1}{3} \left(\frac{1}{s+3} \right) + \frac{2}{s} \end{aligned}$$

$$V_{C_1}(t) = -\frac{1}{3} + \frac{1}{3} e^{-3t} + 2 = \frac{5}{3} + \frac{1}{3} e^{-3t}, \quad t \geq 0$$

APPLICATION OF LAPLACE X-FORM

If a system is described by integral differential eqⁿ.

$$\frac{dy(t)}{dt} + 4y(t) + 10 \int_{-\infty}^t y(\tau) d\tau = 5x(t)$$

Find response $y(t)$ for input $x(t) = u(t)$ if initial conditions are $y(0^-) = 1$, $\int_{-\infty}^0 y(\tau) d\tau = 2$

We know,

$$\begin{aligned} x(t) &\longrightarrow X(s) \\ \frac{dx(t)}{dt} &\longrightarrow sX(s) - x(0^+) \\ \int_{-\infty}^t x(\tau) d\tau &\longleftrightarrow \frac{x(s)}{s} + \frac{\int_{-\infty}^0 x(\tau) d\tau}{s} \end{aligned}$$

$$sY(s) - y(0^-) + 4Y(s) + 10 \left[\frac{y(s)}{s} + \frac{\int_{-\infty}^0 y(\tau) d\tau}{s} \right] = 5X(s)$$

$$\Rightarrow Y(s) \left[s + 4 + \frac{10}{s} \right] = \frac{5}{s} + y(0^-) - 10 \frac{\int_{-\infty}^0 y(\tau) d\tau}{s}$$

$$\Rightarrow Y(s) \left[\frac{s^2 + 4s + 10}{s} \right] = \frac{5}{s} + 1 - \frac{10(2)}{s}$$

$$\Rightarrow Y(s) \left[\frac{s+4s+10}{s} \right] = 1 - \frac{15}{s} = \frac{s-15}{s}$$

$$\Rightarrow Y(s) = \frac{s-15}{s^2 + 4s + 10} = \frac{s-15}{s^2 + 4s + 4 + 6} = \frac{s-15}{(s+2)^2 + (\sqrt{6})^2}$$

$$\Rightarrow Y(s) = \frac{s-15}{(s+2)^2 + (\sqrt{6})^2} = \frac{s+2}{(s+2)^2 + (\sqrt{6})^2} - \frac{17 \times \sqrt{6}}{(s+2)^2 + (\sqrt{6})^2} \times \frac{1}{\sqrt{6}}$$

$$\Rightarrow y(t) = e^{-2t} \cos \sqrt{6} t + u(t) - \frac{17}{\sqrt{6}} e^{-2t} \sin \sqrt{6} t \quad \boxed{\text{Ans.}}$$

→ Total Response :-

$$\xrightarrow{\quad} c(t) = c(t)_{t.s} + c(t)_{s.s}$$

↙ transient state ↓ steady state

Zero input
response

$\rightarrow \text{input} = 0$

→ response is due to initial condition

→ responsible for transient response

→ Natural response

— T C.F.

Zero state response

→ when initial condition
 $= 0$

→ due to applied input

→ forced response

→ Steady State

→ PI

$$\rightarrow \text{Transfer func}^n = \left. \frac{Y(s)}{X(s)} \right|_{IC=0}$$

eg A system is described by a diff eqn

$$\frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 4y(t) = x(t)$$

System is initially relaxed and then excited by an input $x(t) = 10u(t)$. Find response $y(t)$

Initial conditions = 0 $\therefore y(0) = 0$

→ forced response due to $x(t) = 10u(t)$

$$\delta^2 Y(\delta) + 5\delta Y(\delta) + 4Y(\delta) = \frac{10}{\delta}$$

$$Y(\delta) [\delta^2 + 5\delta + 4] = \frac{10}{\delta}$$

$$\therefore Y(\delta) = \frac{10}{\delta(\delta+4)(\delta+1)} = \frac{A}{\delta} + \frac{B}{\delta+1} + \frac{C}{\delta+4}$$

$$Y(\delta) = \frac{10/4}{\delta} - \frac{10/3}{\delta+1} + \frac{10/12}{\delta+4}$$

$$y(t) = \left[\frac{10}{4} - \frac{10}{3} e^{-t} + \frac{10}{12} e^{-4t} \right] u(t)$$

steady state transient
[depends on 't']

eg find the response of the system represented by

$$\frac{d^2 y(t)}{dt^2} + 7 \frac{dy}{dt} + 10 y(t) = 3x(t)$$

where $x(t) = u(t)$ & initial conditions $y(0^-) = 1$
 $y'(0^-) = 2$

$$\{ \delta^2 Y(\delta) - \delta y(0^-) - y'(0^-) \} + 7 \{ \delta Y(\delta) - y(0^-) \} + 10 Y(\delta) = 3 X(\delta)$$

$$\Rightarrow Y(\delta) \left\{ \delta^2 + 7\delta + 10 \right\} - \underbrace{\delta y(0^-)}_1 - \underbrace{y'(0^-)}_2 - \underbrace{7y(0^-)}_1 = 3X(\delta)$$

$$\Rightarrow Y(\delta) [\delta^2 + 7\delta + 10] = 3X(\delta) + 6 + 2 + 7$$

$$\Rightarrow Y(\delta) (\delta^2 + 7\delta + 10) = 3X(\delta) + (\delta + 9)$$

$$Y(\delta) = \frac{3X(\delta)}{\delta^2 + 7\delta + 10} + \frac{\delta + 9}{\delta^2 + 7\delta + 10}$$

Forced resp. Natural resp.
→ due to input $X(\delta)$ → due to initial conditions.

$$= \frac{3}{s(s+2)(s+5)} + \frac{s+9}{(s+2)(s+5)}$$

$$Y(s) = \frac{A}{s} + \frac{B}{s+2} + \frac{C}{s+5} + \frac{D}{s+2} + \frac{E}{s+5}$$

$$Y(s) = \frac{A}{s} + \frac{B+D}{s+2} + \frac{C+E}{s+5}$$

$$Y(t) = [A + (B+D)e^{-2t} + (C+E)e^{-5t}] u(t)$$

↑ steady state transient response.

e.g. $X(s) = \log\left(\frac{s+4}{s+5}\right)$. Find inverse L.T $x(t)$.

We know,

$$t \cdot x(t) \longleftrightarrow X(s)$$

$$t \cdot x(t) \longleftrightarrow (-1) \frac{dX(s)}{ds}$$

$$X(s) = \log(s+4) - \log(s+5)$$

$$\frac{dX(s)}{ds} = \frac{1}{s+4} - \frac{1}{s+5}$$

$$\therefore -\frac{dX(s)}{ds} = \frac{1}{s+5} - \frac{1}{s+4}$$

Taking I.L.T both sides

$$t \cdot x(t) = e^{-st} u(t) - e^{-4t} u(t)$$

$$x(t) = \frac{1}{t} [e^{-st} u(t) - e^{-4t} u(t)]$$