Report7

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1 Model assessment: LOO-CV for factory data with Stan

In this exercise, the aim is to assess the predictive performance of the pooled, separate and hierarchical Gaussian models developed for the factory dataset. The data provided contain quality control measurements from 6 machines in a factory and more specifically only 5 measurements were done for each machine.

1.1 To recap:

Three different models were used for modelling the data:

• Separate model: each of the i th machine (i = 1, ..., 6) is modelled with its own model, that is:

$$y_i \sim N(\mu_i, \sigma_i) \tag{1}$$

where μ_i and σ_i are the mean and standard deviation of the distribution associated with the ith machine and y_i represents the measurements of the i th machine.

• Pooled model: all the measurements are considered together, without making any difference between the machines. This means that the following model is considered:

$$y \sim N(\mu, \sigma)$$
 (2)

where y is a quality measurement from any machine, and μ and σ are the parameters characterizing the normal distribution.

• Hierarchical model: in this case, the following model is considered:

$$y_i \sim N(\mu_i, \sigma)$$
 (3)

and at the same time is assumed that the mean values μ i are drawn from a normal distribution $N(\mu_0, \sigma_0)$.

1.2 Some theory.

All the three models were implemented in Stan with default settings (i.e. 4 chains, 2000 iterations of which 1000 of warm-up and uniform priors).

The predictive performance of the three models were evaluated with the Pareto smoothed importance sampling (PSIS) leave-one-out (LOO) cross-validation. The PSIS-LOO is a particularly new implementation of the LOO scheme. If n observation are available, we fit n models to the data by leaving one of the data points out at each time. This data point is then used to estimate how

well the model is able in predicting it. The predictive accuracy for a fitted model is called log pointwise predictive density (lppd) and it is evaluated as:

$$lppd = \sum_{i=1}^{n} log \left(\frac{1}{S} \sum_{s=1}^{S} p(y_i | \theta^s) \right)$$
(4)

where S is the number of simulations drawn from the posterior probability and y_i are the observations.

In case of PSIS-LOO cross-validation, the estimate log pointwise predictive density is.

$$lppd_{llo-cv} = \sum_{i=1}^{n} log\left(\frac{\sum_{s=1}^{S} w_{i}^{s} p(y_{i} | \theta^{s})}{\sum_{s=1}^{S} w_{i}^{s}}\right)$$
(5)

Now the equation $p_{loo-cv} = lppd - lppd_{loo-cv}$ can be used to estimate the complexity of the used models

In the PSIS method, also the estimated shape k° of the generalized Pareto distribution can be used to assess the reliability of the estimate. High estimates of k° (generally > 1) indicate that the full posterior is not a good importance sampling approximation to the desired leave-one- out posterior, and thus the observation is surprising according to the model. In case of $k^{\circ} < 0.5$, model is considered good and in case of $0.5 < k^{\circ} < 1$, attention should be paid, but generally up to 0.7 the models are good.

1.3 Code base

1.3.1 import data

1.3.2 The 3 models (results follows)

```
In [3]: separate_mod = """
    data {
```

```
int<lower=0> N; // number of data points
    int<lower=0> K; // number of groups
    int<lower=1,upper=K> x[N]; // group indicator
    vector[N] y; // data
}
parameters {
    vector[K] mu; // group means
    vector<lower=0>[K] sigma; // group stds
}
model {
    for (n in 1:N)
    y[n] ~ normal(mu[x[n]], sigma[x[n]]);
}
generated quantities {
    vector[N] log_lik;
    for (n in 1:N)
    log_lik[n] <- normal_log(y[n], mu[x[n]], sigma[x[n]]);</pre>
}
\Pi^{\dagger}\Pi^{\dagger}\Pi
pool_mod = """
data {
    int<lower=0> N; // number of data points
    vector[N] y; // data
}
parameters {
    real mu; // group means
    real<lower=0> sigma; // group stds
}
model {
    y ~ normal(mu, sigma);
generated quantities {
    vector[N] log_lik;
    for (n in 1:N)
    log_lik[n] <- normal_log(y[n], mu, sigma);</pre>
}
0.000
hiera_mod = """
data {
    int<lower=0> N; // number of data points
    int<lower=0> K; // number of groups
    int<lower=1,upper=K> x[N]; // group indicator
    vector[N] y; // data
}
parameters {
    real mu0; // prior mean
    real<lower=0> sigma0; // prior std
```

```
vector[K] mu; // group means
    real<lower=0> sigma; // common std
}
model {
mu ~ normal(mu0, sigma0); // population prior with unknown parameters
for (n in 1:N)
y[n] ~ normal(mu[x[n]], sigma);
}
generated quantities {
vector[N] log_lik;
for (n in 1:N)
log_lik[n] <- normal_log(y[n], mu[x[n]], sigma);
}
"""</pre>
```

1.3.3 Compile models

1.3.4 Fit

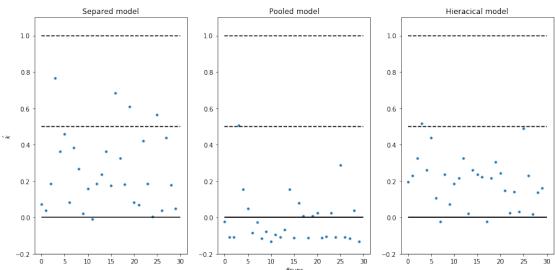
1.3.5 Extract estimats

1.3.6 Run psis-loo

1.4 Results

1.4.1 Plot \hat{k} for alle models

```
plt.scatter(np.arange(len(sm_ks)),sm_ks,s=10)
plt.ylim(-0.2,1.1)
plt.hlines(0,0,30)
plt.hlines(0.5, 0, 30, linestyles='dashed')
plt.hlines(1, 0, 30, linestyles='dashed')
plt.title('Separed model')
plt.ylabel('$\hat k$')
plt.subplot(1,3,2)
plt.scatter(np.arange(len(pm_ks)),pm_ks,s=10)
plt.ylim(-0.2,1.1)
plt.hlines(0,0,30)
plt.hlines(0,0,30)
plt.hlines(0.5, 0, 30, linestyles='dashed')
plt.hlines(1, 0, 30, linestyles='dashed')
plt.title('Pooled model')
plt.xlabel('#runs')
plt.subplot(1,3,3)
plt.scatter(np.arange(len(hm_ks)),hm_ks,s=10)
plt.ylim(-0.2,1.1)
plt.hlines(0,0,30)
plt.hlines(0,0,30)
plt.hlines(0.5, 0, 30, linestyles='dashed')
plt.hlines(1, 0, 30, linestyles='dashed')
plt.title('Hieracical model');
      Separed model
                                Pooled model
```



1.4.2 Calculate p_eff

```
In [93]: sm_lppd = np.sum(np.mean(sm_est['log_lik'], axis=0))
         pm_lppd = np.sum(np.mean(pm_est['log_lik'], axis=0))
         hm_lppd = np.sum(np.mean(hm_est['log_lik'], axis=0))
         sm_p_eff = sm_lppd - sm_loo
         pm_p_eff = pm_lppd - pm_loo
         hm_p_eff = hm_lppd - hm_loo
         print('The separet model: \n Effective number of parameters is ' + str(sm_p_eff) + '\n'
               '-2lppd and -2lppd_loo_cv is respectivly [' + str(-2*sm_lppd) + ', ' + str(-2*sm_
         print('The pool model: \n Effective number of parameters is ' + str(pm_p_eff) + '\n' +
               '-2lppd and -2lppd_loo_cv is respectivly [' + str(-2*pm_lppd) + ', ' + str(-2*pm_
         print('The Hierarchical model: \n Effective number of parameters is ' + str(hm_p_eff) +
               '-2lppd and -2lppd_loo_cv is respectivly [' + str(-2*hm_lppd) + ', ' + str(-2*hm_
The separet model:
Effective number of parameters is 4.58301003409
-21ppd and -21ppd_loo_cv is respectivly [261.128404557, 270.294424625]
The pool model:
Effective number of parameters is 1.13909919484
-21ppd and -21ppd_loo_cv is respectivly [259.740975956, 262.019174346]
The Hierarchical model:
Effective number of parameters is 2.43904932044
```

1.5 Comments

The obtained parameters make it possible to compare the models. When the estimated shape parameter kˆ is considered, it is possible to observe that the separate model has 4 parameters in the range 0.5-1, the hierarchical 2 and the pooled model 1. This means that the pooled model seems to be the most reliable according to this parameter.

-21ppd and -21ppd_loo_cv is respectivly [257.542473762, 262.420572403]

When the results in from the print out above are considered, it is possible to compare the models according to the parameters -2lppd and $-2lppd_{loo-cv}$ (lower values imply higher predictive accuracy). In this case, it is possible to observe that the hierarchical model has the highest predictive accuracy. Concerning the effective number of parameters, it can be seen that the pooled one has the lowest value, the hierarchical the middle and the separate model the highest.

This was expected because in the separate model 12 parameters (6 means and 6 standard deviations) are estimated, in the pooled model 2 parameters (common mean and standard deviation) are estimated, and in the hierarchical model 9 parameters (6 means, common standard deviation and the two parameters originating the distribution of the mean) are estimated. The effective number of parameters gives an idea of the complexity of the model and as expected the pooled one has the lowest complexity.

By taking into account all these aspects, it seems that the pooled model is the easiest and most reliable model, while the hierarchical one is the one with the highest predictive accuracy. Depending on the desired application one of these two can be chosen. On the other side, the separate model should be excluded because of its poor performances.