

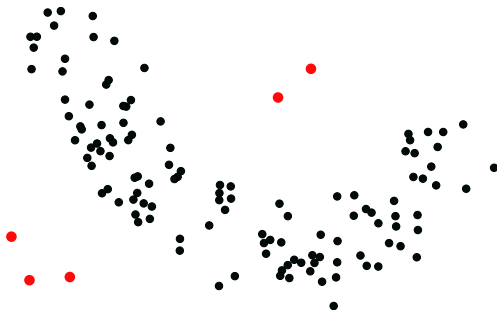
Machine Learning and Extremes for Anomaly Detection

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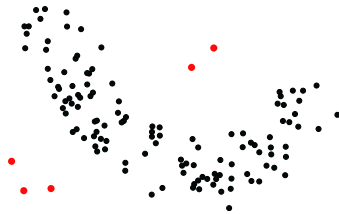
‘Finding patterns in the data that do not conform to expected behavior’



Applications: Network intrusions, credit card fraud detection, insurance, finance, military surveillance, predictive maintenance...

Different kinds of Anomaly Detection

- ▶ **Supervised AD** (not dealt with)
Labels available for both normal data and anomalies
(similar to rare class mining)
- ▶ **Novelty Detection** (our theoretical framework)
Synonym: one-class classification. The algorithm learns on normal data only
- ▶ **Outlier Detection** (extended application framework)
Training set (unlabeled) = normal + abnormal data
(assumption: anomalies are very rare)



- ▶ **Statistical AD techniques**

[Hawkins 1980, Liu and Weng 1991, Eskin 2000, Agarwal 2006]

- ▶ **K-nearest neighbors**

[Breunig *et al.* 2000, Tang *et al.* 2002, Papadimitriou *et al.* 2002, Hautamaki *et al.* 2004]

- ▶ **Support estimation**

[Einmahl and Mason 92, Polonik 97, Schölkopf *et al.* 2000, Vert and Vert 2006, Scott and Nowak 2006]

- ▶ **High-dimensional techniques**

[Aggarwal and Yu 2001, Shyu *et al.* 2003, Shi and Horvath 2012, Liu *et al.* 2008]

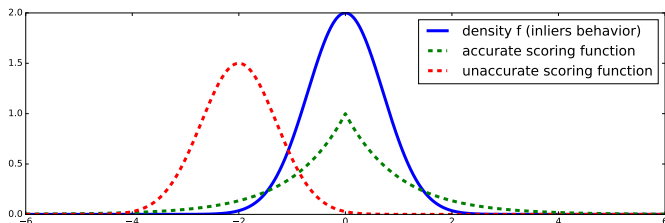
Background: scoring functions

Notation: Normal behavior \rightarrow density f .

AD algorithm returns a **scoring function** $s : \mathbb{R}^d \rightarrow \mathbb{R}$

- ▶ s defines a **pre-order** on \mathbb{R}^d = 'degree of normality'.
- ▶ s level sets are estimates of f level sets.
- ▶ s can be interpreted as a **continuum of level sets estimates** (at different levels).

Remark. Ideal scoring functions: $s = T \circ f$ any increasing transform of f .



Part I: Performance criterion for scoring functions

Part II: Learning accurate scoring functions on extreme regions

Part III: Heuristic contributions and perspectives

Part I: Performance criterion for scoring functions

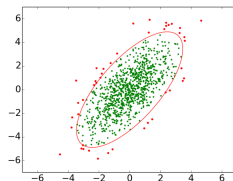
Part II: Learning accurate scoring functions on extreme regions

Part III: Heuristic contributions and perspectives

Existing criterion: Mass-Volume curve

Minimum volume set [Einmahl and Mason 1992, Polonik 1997]

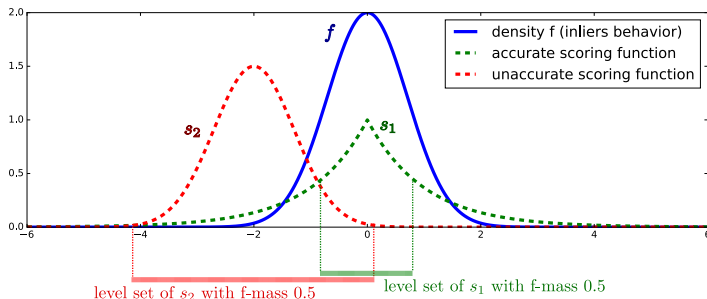
$$\Gamma_{\alpha}^* = \arg \min_{\Gamma \text{ borelian}} \text{Leb}(\Gamma) \quad \text{s.t.} \quad \mathbb{P}(\mathbf{X} \in \Gamma) \geq \alpha$$



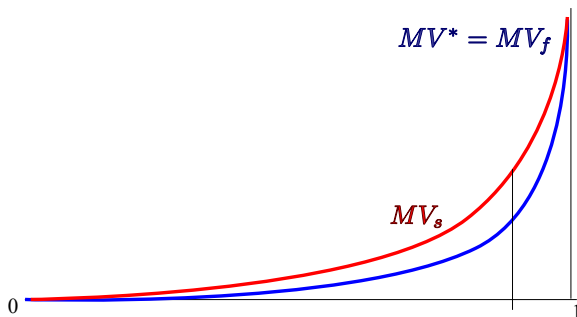
Mass Volume curve of a scoring function s [Cléménçon and Jakubowicz, 2013]:

$$MV_s(\alpha) := \inf_{\Gamma \text{ level-set of } s} \{ \text{Leb}(\Gamma) \quad \text{s.t.} \quad \mathbb{P}(\mathbf{X} \in \Gamma) \geq \alpha \}$$

$$MV^*(\alpha) := MV_f(\alpha) \stackrel{\text{prop}}{=} \min_{\Gamma \text{ borelian}} \{ \text{Leb}(\Gamma) \quad \text{s.t.} \quad \mathbb{P}(\mathbf{X} \in \Gamma) \geq \alpha \}$$



Existing criterion: Mass-Volume curve



Main drawbacks of MV:

- ▶ When optimized *w.r.t.* different levels α over a finite class, produces **not necessarily nested** empirical level sets.
- ▶ \rightarrow **low convergence rates** – of order $O(n^{-1/4})$.
- ▶ MV **diverges** in 1 in case of unbounded support.

Excess-Mass [Polonik 1995]

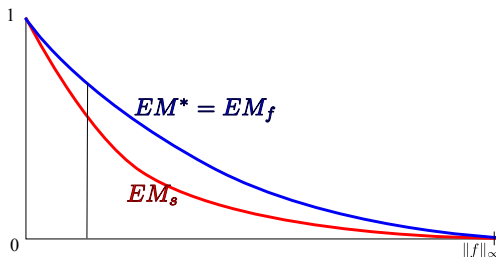
Excess-Mass curve

$$EM_s(t) := \sup_{\Omega \text{ level-set of } s} \{ \mathbb{P}(\mathbf{X} \in \Omega) - t \text{Leb}(\Omega) \}$$

$$EM^*(t) := EM_f(t) \stackrel{\text{prop}}{=} \max_{\Omega \text{ borelian}} \{ \mathbb{P}(\mathbf{X} \in \Omega) - t \text{Leb}(\Omega) \}$$

Property: Previous drawbacks are fixed with EM.

- ▶ Produces **nested** empirical level sets.
- ▶ \rightarrow **convergence rates** of order $O(n^{-1/2})$.
- ▶ EM curve **finite** even in case of unbounded support.



Learning a scoring function with M-estimation

\mathcal{G} : VC-class of sets.

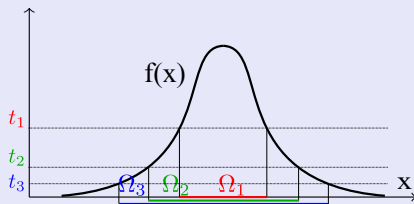
Procedure: Fix $t_0 > 0$

For $k = 1, \dots, N$,

$$t_{k+1} = \frac{t_k}{\left(1 + \frac{1}{\sqrt{n}}\right)}$$

$$\hat{\Omega}_{t_{k+1}} = \arg \max_{\Omega \in \mathcal{G}, \hat{\Omega}_{t_k} \subset \Omega} \mathbb{P}_n(X \in \Omega) - t_{k+1} \text{Leb}(\Omega)$$

$$s_N(x) := \sum_{j=1}^N (t_j - t_{j+1}) \mathbb{1}_{x \in \Omega_{t_j}}$$

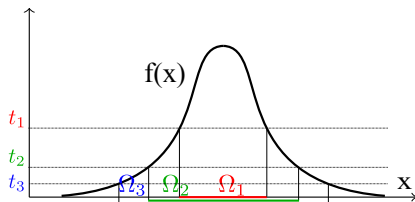


Learning a scoring function with M-estimation

Theorem

Assume the density f bounded, with compact support and without flat parts and \mathcal{G} VC-class. Then if $t_N = \mathcal{O}(n^{-1/2})$, with probability at least $1 - \delta$,

$$\sup_{t \in]0, t_1]} |EM^*(t) - EM_{s_N}(t)| \leq \left[A + \sqrt{2 \log(1/\delta)} \right] \frac{1}{\sqrt{n}} + \text{bias}(\mathcal{G}).$$



Part I: Performance criterion for scoring functions

Part II: Learning accurate scoring functions on extreme regions

Part III: Heuristic contributions and perspectives

General ideas:

- ▶ Extreme observations play a special role when dealing with outlying data.
- ▶ But no anomaly detection algorithm has **specific treatment for such multivariate extreme observations**. Univariate EVT: [Roberts 99, Lee and Roberts 2008, Clifton *et al.* 2011]
- ▶ Our goal:
 - ▶ Define a notion of sparsity for extremes observations.
 - ▶ Provide a method which can improve performance of standard AD algorithms by combining them with a **multivariate extreme analysis** of the **dependence structure**, using this notion of sparsity.

$$\mathbf{X} = (X_1, \dots, X_5)$$

Goal: find the groups of features which can be large together

ex: $\{X_1, X_2\}$, $\{X_1, X_3, X_4\}$, $\{X_5\}$

Namely: characterize the extreme dependence structure

→ Anomalies = points which violate this structure

- ▶ **Context**

- ▶ Random vector $\mathbf{X} = (X_1, \dots, X_d)$
- ▶ Margins: $X_j \sim F_j$ (F_j continuous)

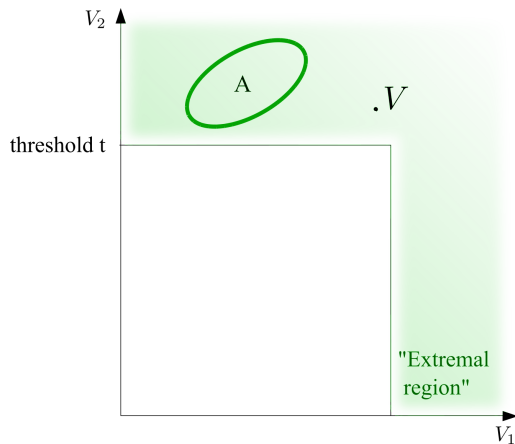
- ▶ **Preliminary step: Standardization of each marginal**

- ▶ Standard Pareto: $V_j = \frac{1}{1-F_j(X_j)}$ ($\mathbb{P}(V_j \geq x) = \frac{1}{x}, x \geq 1$)

Problematic of Extreme Value Theory

Describe \mathbf{V} 's distribution, when \mathbf{V} exceeds some large threshold.

$$\mathbb{P}(\mathbf{V} \in A) = ? \quad (A \text{ 'far from the origin'}).$$



Fundamental hypothesis and consequences

- ▶ Standard assumption: let A extreme region,

$$\mathbb{P}[\mathbf{V} \in tA] \simeq t^{-1} \mathbb{P}[\mathbf{V} \in A] \quad (\text{radial homogeneity})$$

- ▶ Formally:

regular variation (after standardization):

$$\text{If } 0 \notin \bar{A}, \quad t\mathbb{P}[\mathbf{V} \in tA] \xrightarrow[t \rightarrow \infty]{} \mu(A).$$

μ : exponent measure

Necessarily: $\mu(tA) = t^{-1}\mu(A)$

- ▶ \Rightarrow **angular measure** on sphere \mathbf{S}_{d-1} : $\Phi(B) = \mu\{tB, t \geq 1\}$

General model of multivariate EVT

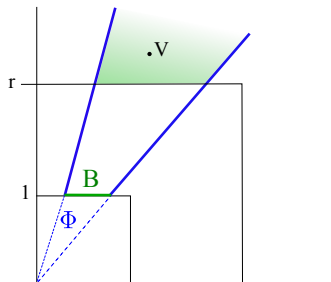
$\mathbb{P}[\mathbf{V} \in A] \simeq \mu(A)$, if A extreme region.

Model for excesses

For a large $r > 0$ and a region B on the unit sphere:

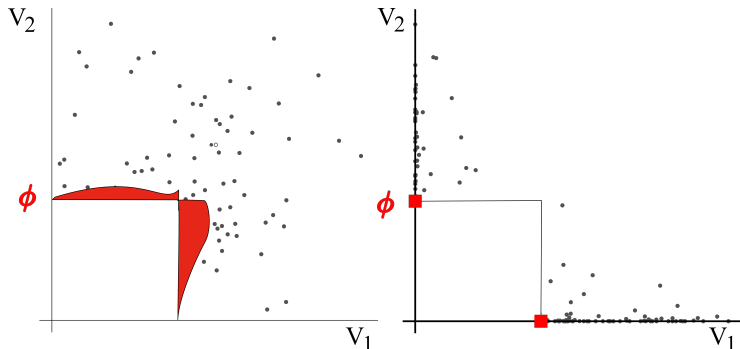
$$\mathbb{P} \left[\|\mathbf{V}\| > r, \frac{\mathbf{V}}{\|\mathbf{V}\|} \in B \right] \underset{r \rightarrow \infty}{\sim} \frac{1}{r} \Phi(B) = \mu(\{tB, t \geq r\})$$

$\Rightarrow \Phi$ (or μ) **rules the joint distribution of extremes** (if margins are known).



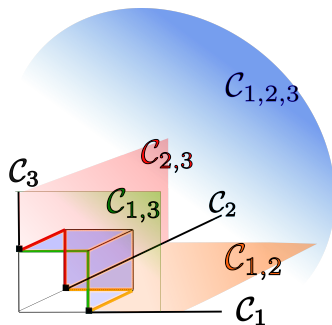
Angular distribution

Φ rules the joint distribution of extremes:



Asymptotic dependence:
(V_1 , V_2) may be large together.

Asymptotic independence:
Only V_1 or V_2 may be large.



- ▶ Sub-cones: $\mathcal{C}_\alpha = \{\|v\| \geq 1, v_j > 0 (j \in \alpha), v_j = 0 (j \notin \alpha)\}$
- ▶ Corresponding sub-spheres: $\{\Omega_\alpha, \alpha \subset \{1, \dots, d\}\}$ ($\Omega_\alpha = \mathcal{C}_\alpha \cap \mathbf{S}_{d-1}$)

- ▶ Natural decomposition of the angular measure :

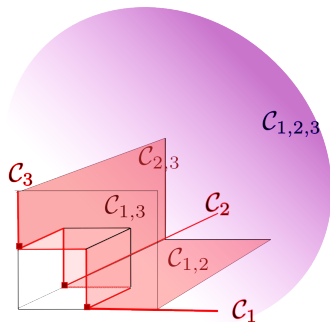
$$\Phi = \sum_{\alpha \subset \{1, \dots, d\}} \Phi_{\alpha} \quad \text{with } \Phi_{\alpha} = \Phi|_{\Omega_{\alpha}} \leftrightarrow \mu|_{\mathcal{C}_{\alpha}}$$

- ▶ \Rightarrow yields a representation

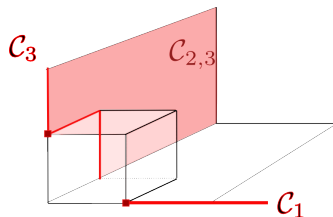
$$\begin{aligned} \mathcal{M} &= \left\{ \Phi(\Omega_{\alpha}) : \emptyset \neq \alpha \subset \{1, \dots, d\} \right\} \\ &= \left\{ \mu(\mathcal{C}_{\alpha}) : \emptyset \neq \alpha \subset \{1, \dots, d\} \right\} \end{aligned}$$

- ▶ Assumption: $\frac{d\mu|_{\mathcal{C}_{\alpha}}}{d\nu_{\alpha}} = O(1)$.

Sparse Representation ?



Full pattern :
anything may happen



Sparse pattern
(V_1 not large if V_2 or V_3 large)

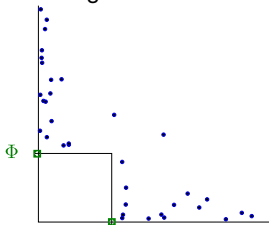
Estimation Problem: \mathcal{M} is an **asymptotic** representation

$$\mathcal{M} = \{ \Phi(\Omega_\alpha), \alpha \} = \{ \mu(\mathcal{C}_\alpha), \alpha \}$$

is the restriction of an asymptotic measure

$$\mu(A) = \lim_{t \rightarrow \infty} t\mathbb{P}[\mathbf{V} \in tA]$$

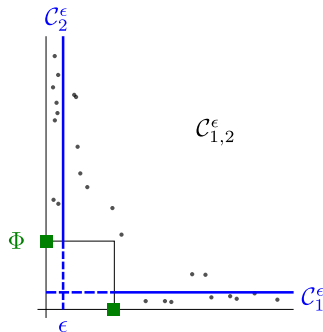
to a representative class of set $\{\mathcal{C}_\alpha, \alpha\}$, but only the central sub-cone has positive Lebesgue measure!



\Rightarrow Cannot just do, for large t :

$$\Phi(\Omega_\alpha) = \mu(\mathcal{C}_\alpha) \simeq \widehat{t\mathbb{P}}(t\mathcal{C}_\alpha)$$

Fix $\epsilon > 0$. Affect data ϵ -close to an edge, to that edge.



$$\mathcal{C}_\alpha \rightarrow \mathcal{C}_\alpha^\epsilon = \{\|v\| \geq 1, \quad v_j > \epsilon (j \in \alpha), \quad v_j \leq \epsilon (j \notin \alpha)\}.$$

New partition.

Resulting estimation procedure

$$\hat{V}_i^j = \frac{1}{1 - \hat{F}_j(X_i^j)} \text{ with } \hat{F}_j(X_i^j) = \frac{\text{rank}(X_i^j) - 1}{n}$$

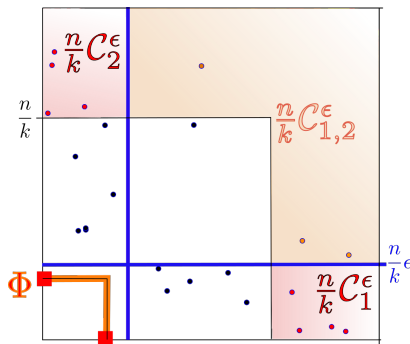
Recall that:

$$\mu(A) = \lim_{t \rightarrow \infty} t \mathbb{P}[\mathbf{V} \in t A]$$

\Rightarrow get an natural estimate of $\Phi(\Omega_\alpha)$

$$\hat{\Phi}(\Omega_\alpha) := \frac{n}{k} \mathbb{P}_n(\hat{V} \in \frac{n}{k} \mathcal{C}_\alpha^\epsilon)$$

($\frac{n}{k}$ large, ϵ small)



\Rightarrow we obtain

$$\hat{\mathcal{M}} := \{ \hat{\Phi}(\Omega_\alpha), \alpha \}$$

Theorem [Goix, Sabourin, Cléménçon 2016]

There is an absolute constant $C > 0$ such that for any $n > 0$, $k > 0$, $0 < \epsilon < 1$, $\delta > 0$ such that $0 < \delta < e^{-k}$, with probability at least $1 - \delta$,

$$\|\widehat{\mathcal{M}} - \mathcal{M}\|_{\infty} \leq Cd \left(\sqrt{\frac{1}{\epsilon k} \log \frac{d}{\delta}} + Md\epsilon \right) + \text{bias}(\epsilon, k, n)$$

Comments:

- ▶ $M \simeq \sum_{\alpha} \sup(\text{density on cones } \alpha)$
- ▶ Existing literature (for spectral measure) [Einmahl and Segers 09, Einmahl et al. 01]

$d = 2$, asymptotic behavior, rates in $1/\sqrt{k}$.

- ▶ Here: $1/\sqrt{k} \rightarrow 1/\sqrt{\epsilon k} + \epsilon$. Price to pay for biasing our estimator with ϵ .

Theorem's proof: key ingredient

Would like to use concentration inequality...

In our case: $\sup_{A \in \mathcal{A}} \frac{n}{k} \left| (\mathcal{P} - \mathcal{P}_n) \left(\frac{n}{k} A \right) \right|$

But usually: $\sup_{A \in \mathcal{A}} |(\mathcal{P} - \mathcal{P}_n)(A)|$

- ▶ scaling $\frac{n}{k}$
- ▶ classical VC-inequality: $\frac{n}{k}$ nice but not used !
→ high proba bound in

$$\frac{n}{k} \times \sqrt{\frac{1}{n} \log \frac{1}{\delta}} \rightarrow \infty !!$$

⇒ Needs to take into account that the proba of $\frac{n}{k} A$ is small.

Key: VC-inequality adapted to rare regions \rightarrow bound in

$$\sqrt{\mathbf{p}} \frac{n}{k} \sqrt{\frac{d}{n} \log \frac{1}{\delta}}$$

with p the probability to be in the union class $\cup_{A \in \mathcal{A}} A$.

$$\mathbf{p} \leq d \frac{k}{n}$$

\Rightarrow bound in

$$d \sqrt{\frac{1}{k} \log \frac{1}{\delta}}$$

$k \propto$ number of data considered as extreme (data used for estimation)

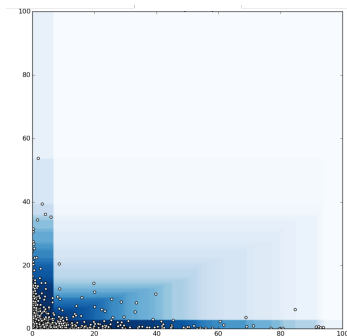
Application to Anomaly Detection

Recall that after standardization of marginals: $\mathbb{P}[R > r, \mathbf{W} \in B] \simeq \frac{1}{r} \Phi(B)$

→ scoring function = $\Phi_n^\epsilon \times 1/r$:

$$s_n(\mathbf{x}) := (1/\|\hat{T}(\mathbf{x})\|_\infty) \sum_{\alpha} \Phi_n^{\alpha, \epsilon} \mathbb{1}_{\hat{T}(\mathbf{x}) \in \mathcal{C}_\alpha^\epsilon}.$$

where $\hat{T} : \mathbf{X} \mapsto \mathbf{V}$ $(\hat{V}_j = \frac{1}{1-\hat{F}_j(X_j)})$



Part I: Performance criterion for scoring functions

Part II: Learning accurate scoring functions on extreme regions

Part III: Heuristic contributions and perspectives

EM and MV curves for model selection?

Practical motivations:

Most of the time, data come without any label.

→ no ROC or PR curves!

Estimation:

$$\widehat{MV}_s(\alpha) = \inf_{u \geq 0} \text{Leb}(s \geq u) \quad \text{s.t.} \quad \mathbb{P}_n(s \geq u) \geq \alpha$$

$$\widehat{EM}_s(t) = \sup_{u \geq 0} \mathbb{P}_n(s \geq u) - t \text{Leb}(s \geq u)$$

[Thomas et al. 2015]

Issue in large dimensions:

The volume $\text{Leb}(s \geq u)$ has to be estimated!

EM and MV curves for model selection?

Heuristic extension for large dimension:

Random projection and averaging [Goix 2016]

Inputs: AD algorithm \mathcal{A} , data set X size $n \times d$, feature sub-sampling size d' , number of draws m .

for $k = 1, \dots, m$ **do**

-randomly select a sub-group F_k of d' features

-compute the associated scoring function $s_k = \mathcal{A}((x_i^j)_{1 \leq i \leq n, j \in F_k})$

-compute $\widehat{C}_k^{EM} = \|\widehat{EM}_{s_k}\|_{L^1(I)}$ or $\widehat{C}_k^{MV} = \|\widehat{MV}_{s_k}\|_{L^1(J)}$

end for

Return performance criteria:

$$\widehat{C}_{high_dim}^{EM}(\mathcal{A}) = \frac{1}{m} \sum_{k=1}^m \widehat{C}_k^{EM} \quad \text{or} \quad \widehat{C}_{high_dim}^{MV}(\mathcal{A}) = \frac{1}{m} \sum_{k=1}^m \widehat{C}_k^{MV}.$$

Seems to work in practice but no statistical guaranties.

Random Forests for one-class classification

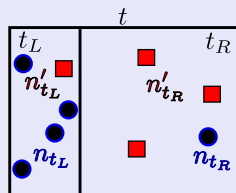
Two-class Random Forests [Breiman, 2001]

Two-Class impurity decrease

$$I_G(t_L, t_R) = \frac{n_{t_L} n'_{t_L}}{n_{t_L} + n'_{t_L}} + \frac{n_{t_R} n'_{t_R}}{n_{t_R} + n'_{t_R}}.$$

n_t : nb of observations with label 0 in node t .

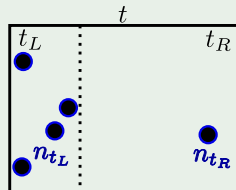
n'_t : nb of observations with label 1 in node t .



Random Forests for one-class classification

Two-Class: $I_G(t_L, t_R) = \frac{n_{t_L} n'_{t_L}}{n_{t_L} + n'_{t_L}} + \frac{n_{t_R} n'_{t_R}}{n_{t_R} + n'_{t_R}}.$

One-Class: $n'_{t_L}, n'_{t_R} = ?$



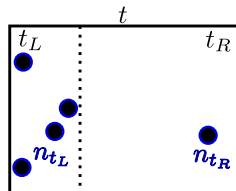
Existing literature: [Désir et al., 2013, Liu et al., 2008, Shi and Horvath, 2012].

Based on **second-class sampling**.

Random Forests for one-class classification

Two-Class: $l_G(t_L, t_R) = \frac{n_{t_L} n'_{t_L}}{n_{t_L} + n'_{t_L}} + \frac{n_{t_R} n'_{t_R}}{n_{t_R} + n'_{t_R}}.$

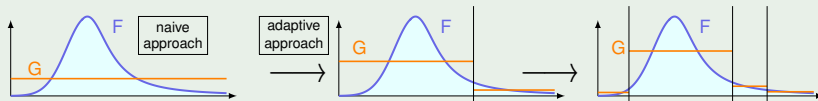
One-Class: $n'_{t_L}, n'_{t_R} = ?$



One-Class splitting criterion [Goix, Brault, Drougard, Chiapino 2016]:

Naive approach: $n'_{t_L} \rightarrow n \frac{\text{Leb}(t_L)}{\text{Leb}(t_0)}$ and $n'_{t_R} \rightarrow n \frac{\text{Leb}(t_R)}{\text{Leb}(t_0)}$ (t_0 root node)

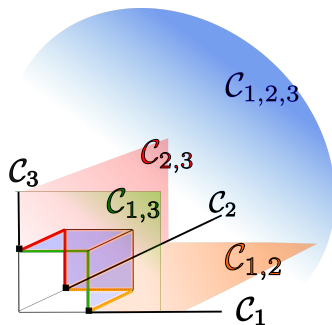
Adaptive approach: $n'_{t_L} \rightarrow n_t \frac{\text{Leb}(t_L)}{\text{Leb}(t)}$ and $n'_{t_R} \rightarrow n_t \frac{\text{Leb}(t_R)}{\text{Leb}(t)}$



F is the inliers distribution, G is the resulting outliers distribution.

Theoretical guaranties ? [Biau et al. 2008, Biau and Scornet, 2016]

Perspectives on AD with Extremes



- ▶ How to choose ϵ in practice?
- ▶ Refine our representation?
- ▶ An alternative notion of sparsity?

Some references:

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- ▶ Tang, Chen, Fu, and W.Cheung 2002. Enhancing effectiveness of outlier detections for low density patterns.
- ▶ Thomas, Feuillard and Gramford 2015, Calibration of One-Class SVM for MV set estimation.
- ▶ Thomas, Cléménçon, Feuillard and Gramford 2016, Learning Hyperparameters for Unsupervised Anomaly Detection.
- ▶ Vert and Vert 2006, Consistency and Convergence Rates of One-Class SVMs and Related Algorithms

DAMEX in $O(dn \log n)$

Input: parameters $\epsilon > 0$, $k = k(n)$

for $i = 1, \dots, n$ **do**

 # Standardize via marginal rank-transformation:

$$\hat{V}_i := (1/(1 - \hat{F}_j(X_i^j)))_{j=1, \dots, d}.$$

if $\hat{V}_i > \frac{n}{k}$ **then**

 # Assign to each \hat{V}_i the cone $\frac{n}{k}C_\alpha^\epsilon$ it belongs to:

$$\alpha = \alpha(V_i)$$

$$C_\alpha ++$$

end if

end for

$$\Phi_n^{\alpha, \epsilon} := \frac{n}{k} C_\alpha$$

Output: (sparse) representation of the dependence structure:

$\Phi_n^{\alpha, \epsilon} = \hat{\Phi}(\Omega_\alpha) = \frac{n}{k} \mathbb{P}_n(\hat{V} \in \frac{n}{k} C_\alpha^\epsilon)$, estimate of the α -mass of Φ for every α .

$$\widehat{\mathcal{M}} := (\Phi_n^{\alpha, \epsilon})_{\alpha \in \{1, \dots, d\}, \Phi_n^{\alpha, \epsilon} > \Phi_{\min}}$$

Does performance in term of EM/MV correspond to performance in term of ROC/PR?

- **Experiments:** 12 datasets, 3 AD algorithms (LOF, OCSVM, iForest) \rightarrow 36 possible pairwise comparisons:

$$\left\{ \left(A_1 \text{ on } \mathcal{D}, A_2 \text{ on } \mathcal{D} \right), A_1, A_2 \in \{\text{iForest, LOF, OCSVM}\}, \right. \\ \left. \mathcal{D} \in \{\text{adult, http, } \dots, \text{spambase}\} \right\}.$$

- **Results:** If we only consider the pairs *s.t.* ROC and PR agree on which algorithm is the best, we are able (with EM and MV scores) to recover it in 80% of the cases.

EM/MV random projection benchmark

Table: Results for the novelty detection setting. One can see that ROC, PR, EM, MV often do agree on which algorithm is the best (in bold), which algorithm is the worse (underlined) on some fixed datasets. When they do not agree, it is often because ROC and PR themselves do not, meaning that the ranking is not clear.

Dataset	iForest				OCSVM				LOF			
	ROC	PR	EM	MV	ROC	PR	EM	MV	ROC	PR	EM	MV
adult	0.661	0.277	1.0e-04	7.5e01	0.642	0.206	2.9e-05	4.3e02	0.618	0.187	1.7e-05	9.0e02
http	0.994	0.192	1.3e-03	9.0	0.999	0.970	6.0e-03	2.6	<u>0.946</u>	<u>0.035</u>	<u>8.0e-05</u>	<u>3.9e02</u>
pima	0.727	0.182	5.0e-07	1.2e04	0.760	0.229	5.2e-07	<u>1.3e04</u>	<u>0.705</u>	<u>0.155</u>	<u>3.2e-07</u>	2.1e04
smtp	0.907	<u>0.005</u>	<u>1.8e-04</u>	<u>9.4e01</u>	<u>0.852</u>	0.522	1.2e-03	8.2	0.922	0.189	1.1e-03	5.8
wilt	0.491	0.045	4.7e-05	<u>2.1e03</u>	<u>0.325</u>	<u>0.037</u>	5.9e-05	4.5e02	0.698	0.088	<u>2.1e-05</u>	1.6e03
annthyroid	0.913	0.456	2.0e-04	2.6e02	0.699	0.237	6.3e-05	2.2e02	0.823	0.432	6.3e-05	1.5e03
arrhythmia	0.763	0.487	1.6e-04	9.4e01	0.736	0.449	1.1e-04	1.0e02	<u>0.730</u>	<u>0.413</u>	<u>8.3e-05</u>	<u>1.6e02</u>
forestcov.	<u>0.863</u>	0.046	3.9e-05	<u>2.0e02</u>	0.958	0.110	5.2e-05	1.2e02	0.990	0.792	3.5e-04	3.9e01
ionosphere	<u>0.902</u>	<u>0.529</u>	<u>9.6e-05</u>	<u>7.5e01</u>	0.977	0.898	1.3e-04	5.4e01	0.971	0.895	1.0e-04	7.0e01
pendigits	0.811	0.197	2.8e-04	2.6e01	0.606	0.112	<u>2.7e-04</u>	<u>2.7e01</u>	0.983	0.829	4.6e-04	1.7e01
shuttle	0.996	0.973	1.8e-05	5.7e03	<u>0.992</u>	<u>0.924</u>	3.2e-05	2.0e01	0.999	0.994	7.9e-06	<u>2.0e06</u>
spambase	0.824	0.371	9.5e-04	4.5e01	<u>0.729</u>	0.230	4.9e-04	1.1e03	0.754	<u>0.173</u>	<u>2.2e-04</u>	<u>4.1e04</u>

Table: Results for the novelty detection setting (novelty detection framework).

Datasets	OneClassRF		iForest		OCRF _{sampl.}		OCSVM		LOF		Orca		LSAD		RFC	
	ROC	PR	ROC	PR	ROC	PR	ROC	PR	ROC	PR	ROC	PR	ROC	PR	ROC	PR
adult	0.665	0.278	0.661	0.227	NA	NA	0.638	0.201	0.615	0.188	0.606	0.218	0.647	0.258	NA	NA
annthyroid	0.936	0.468	0.913	0.456	0.918	0.532	0.706	0.242	0.832	0.446	0.587	0.181	0.810	0.327	NA	NA
arrhythmia	0.684	0.510	0.763	0.492	0.639	0.249	0.922	0.639	0.761	0.473	0.720	0.466	0.778	0.514	0.716	0.299
forestcover	0.968	0.457	0.863	0.046	NA	NA	NA	NA	0.990	0.795	0.946	0.558	0.952	0.166	NA	NA
http	0.999	0.838	0.994	0.197	NA	NA	NA	NA	NA	NA	0.999	0.812	0.981	0.537	NA	NA
ionosphere	0.909	0.643	0.902	0.535	0.859	0.609	0.973	0.849	0.959	0.807	0.928	0.910	0.978	0.893	0.950	0.754
pendigits	0.960	0.559	0.810	0.197	0.968	0.694	0.603	0.110	0.983	0.827	0.993	0.925	0.983	0.752	NA	NA
pima	0.719	0.247	0.726	0.183	0.759	0.266	0.716	0.237	0.700	0.152	0.588	0.175	0.713	0.216	0.506	0.090
shuttle	0.999	0.998	0.996	0.973	NA	NA	0.992	0.924	0.999	0.995	0.890	0.782	0.996	0.956	NA	NA
smtp	0.922	0.499	0.907	0.005	NA	NA	0.881	0.656	0.924	0.149	0.782	0.142	0.877	0.381	NA	NA
spambase	0.850	0.373	0.824	0.372	0.797	0.485	0.737	0.208	0.746	0.160	0.631	0.252	0.806	0.330	0.723	0.151
wilt	0.593	0.070	0.491	0.045	0.442	0.038	0.323	0.036	0.697	0.092	0.441	0.030	0.677	0.074	0.896	0.631
average:	0.850	0.495	0.821	0.311	0.769	0.410	0.749	0.410	0.837	0.462	0.759	0.454	0.850	0.450	0.758	0.385
cum. train time:	61s		68s		NA		NA		NA		2232s		73s		NA	

Datasets	nb of samples	nb of features	anomaly class
adult	48842	6	class '> 50K' (23.9%)
annthyroid	7200	6	classes \neq 3 (7.42%)
arrhythmia	452	164	classes \neq 1 (features 10-14 removed) (45.8%)
forestcover	286048	10	class 4 (vs. class 2) (0.96%)
http	567498	3	attack (0.39%)
ionosphere	351	32	bad (35.9%)
pendigits	10992	16	class 4 (10.4%)
pima	768	8	pos (class 1) (34.9%)
shuttle	85849	9	classes \neq 1 (class 4 removed) (7.17%)
smtp	95156	3	attack (0.03%)
spambase	4601	57	spam (39.4%)
wilt	4839	5	class 'w' (diseased trees) (5.39%)