

```
In [1]: import numpy as np
        from scipy import linalg as la
```

Initializing variables

```
In [2]: matrix_a = np.array([[0, 3, -1],
                             [-1, 4, -2],
                             [1, 3, 1]])
        matrix_b = np.array([[2, -1, 2],
                             [-1, 0, 1],
                             [-1, 2, 2]])

        vector_v = np.array([2, -1, 4])
        vector_u = np.array([-2, 1, 5])

        scalar_a = -2
        scalar_b = 1
```

Question 1

```
In [3]: # Calculating  $\|v\|1v + au$ 
```

```
In [4]: result = la.norm(vector_v, 1) * vector_v + scalar_a * vector_u
        print('Result = ', result)
```

```
Result = [18. -9. 18.]
```

Question 2

```
In [5]: # Calculating the cos_theta between u and v
```

```
In [6]: cosine_theta = (vector_u.dot(vector_v)) / (la.norm(vector_u, 2) * la.norm(vector_v, 2))
        print('Cosine of Theta between vector u and vector v = ', round(cosine_theta, 4))
```

```
Cosine of Theta between vector u and vector v = 0.5976
```

Question 3

```
In [7]: # Calculating  $a(A \cdot v)$ 
```

```
In [8]: result = scalar_a * (matrix_a.dot(vector_v))
        print('Result = ', result)
```

```
Result = [14 28 -6]
```

Question 4

```
In [9]: # Calculating  $A \cdot B^T + tr(B) * L$ 
```

```
In [10]: matrix_b_transpose = matrix_b.T
         trace_of_matrix_b = matrix_b.trace()
         lower_triangular_b = la.tril(matrix_b)
```

```
result = matrix_a.dot(matrix_b.transpose) + trace_of_matrix_b * lower_triangular_b  
print('Result = \n', result)
```

```
Result =  
[[ 3 -1  4]  
 [-14 -1  5]  
 [-3  8 15]]
```

In []: