

INTRODUCTION

Our research aims to **automate state machine visualization directly from source code**. Automation of code visualization is valuable because it enables up-to-date diagrams with attendant verification, documentation, and understanding.

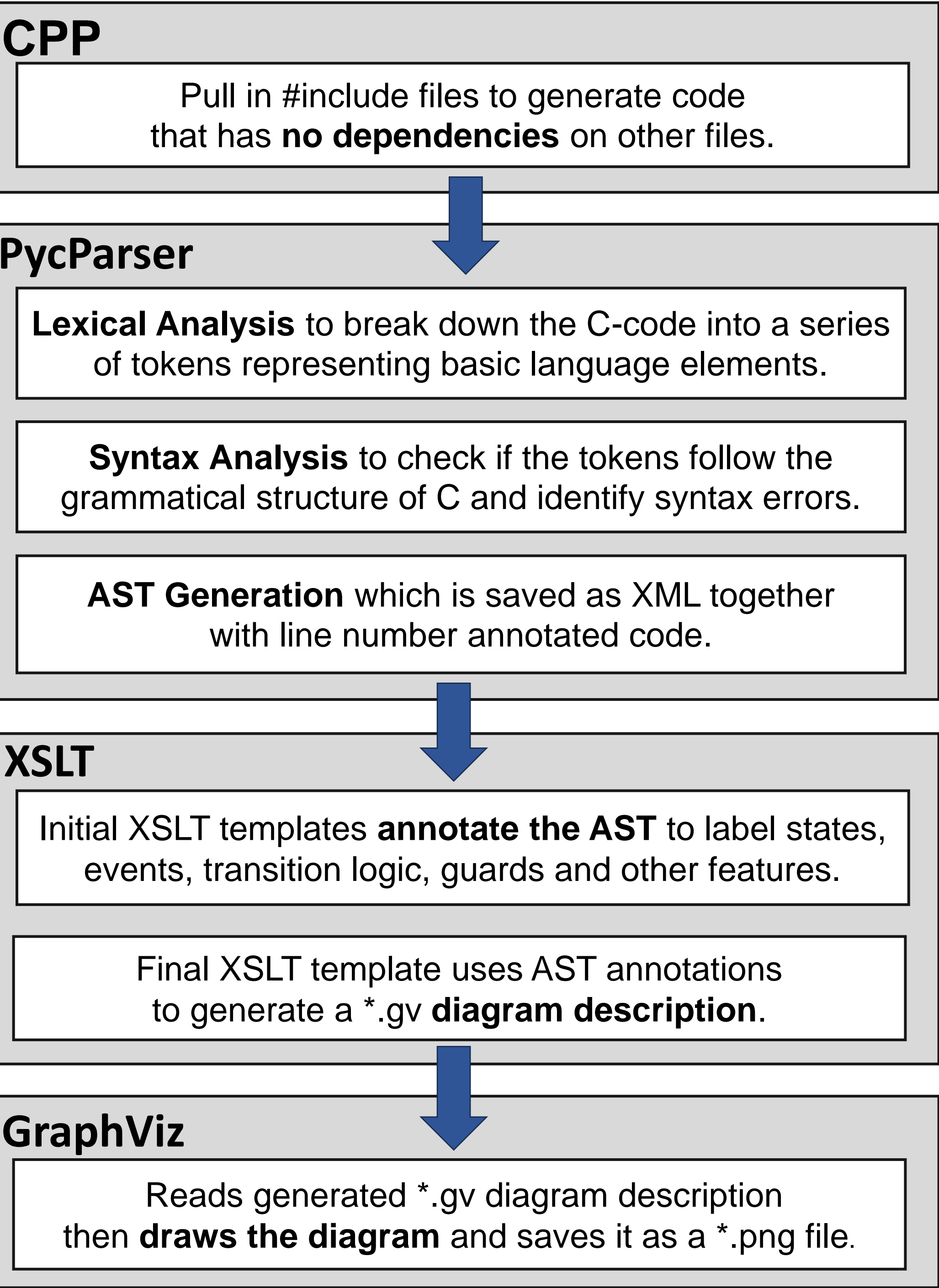
**Existing visualization tools** require extensive user input and manipulation for satisfactory results; no tool found runs fully automated. In contrast, our work uses **variable name conventions** and XSLT matching **Abstract Syntax Tree (AST)** patterns to generate state diagrams directly from source code.

METHOD & TOOLS

Our **prototype** uses the following tools:

- **C++**: for macro expansion and file inclusion.
- **PycParser**: for Lexical Analysis, Syntax Analysis, and Abstract Syntax Tree (AST) generation from C code.
- **XSLT**: to express ASTs patterns to annotate ASTs represented in XML and describe diagrams.
- **GraphViz**: to create images from our generated diagram descriptions

To **generate a state diagram** from a \*.c file:



AUTOMATED VISUALIZATION FOR FLAT AND HIERARCHICAL STATE MACHINES

Autonomous Systems Lab @ UCSC

Jasmine Lesner | Gabriel Elkaim

{jlesner,elkaim}@ucsc.edu

```
ES_Event RunTemplateHSM(ES_Event ThisEvent)
{
    uint8_t makeTransition = FALSE;
    TemplateHSMState_t nextState;
    ES_Tattle();

    switch (CurrentState) {
    case InitPState:
        if (ThisEvent.EventType == ES_INIT)
        {
            InitLightSubHSM(); InitDarkSubHSM();
            InitJigSubHSM();
            ES_Timer_SetTimer(JIG_TIMER, JIG_TIME);
            nextState = InDark;
            makeTransition = TRUE;
            ThisEvent.EventType = ES_NO_EVENT;
        }
        break;

    case InLight:
        ThisEvent = RunLightSubHSM(ThisEvent);
        switch (ThisEvent.EventType) {
        case ES_ENTRY:
            ES_Timer_InitTimer(JIG_TIMER, JIG_TIME);
            break;

        case ES_EXIT:
            ES_Timer_StopTimer(JIG_TIMER);
            break;

        case LIGHT_TO_DARK:
            nextState = InDark;
            makeTransition = TRUE;
            ThisEvent.EventType = ES_NO_EVENT;
            break;

        case ES_TIMEOUT: //Go to jig
            nextState = Jig;
            makeTransition = TRUE;
            ThisEvent.EventType = ES_NO_EVENT;
            ES_Timer_SetTimer(JIG_SPIN_TIMER, JIG_SPIN
176
177
178
179
180
181
182
183
184
185
186
187
188
189
190
191
192
193
194
195
196
197
198
199
200
201
202
203
204
205
206
207
208
209
210
211
212
213
214
215
216
217
218
219
220
221
222
223
224
225
226
227
228
229
230
231
232
233
234
235
236
237
238
239
240
241
242
243
244
245
246
247
248
249
250
251

case ES_TIMEOUT: //Go to jig
    nextState = Jig;
    makeTransition = TRUE;
    ThisEvent.EventType = ES_NO_EVENT;
    ES_Timer_SetTimer(JIG_SPIN_TIMER, JIG
    break;

    default:
        break;
    }

    break;

case InDark:
    ThisEvent = RunDarkSubHSM(ThisEvent);
    switch (ThisEvent.EventType) {

case ES_ENTRY:
    StopMotors();
    break;

case DARK_TO_LIGHT:
    nextState = InLight;
    makeTransition = TRUE;
    ThisEvent.EventType = ES_NO_EVENT;
    break;

    default:
        break;
    }
    break;

case Jig:
    ThisEvent = RunJigSubHSM(ThisEvent);
    switch (ThisEvent.EventType) {

case JIG_FINISHED:
    nextState = InLight;
    makeTransition = TRUE;
    ThisEvent.EventType = ES_NO_EVENT;
    break;

    }

case JIG_FINISHED:
    nextState = InLight;
    makeTransition = TRUE;
    ThisEvent.EventType = ES_NO_EVENT;
    break;

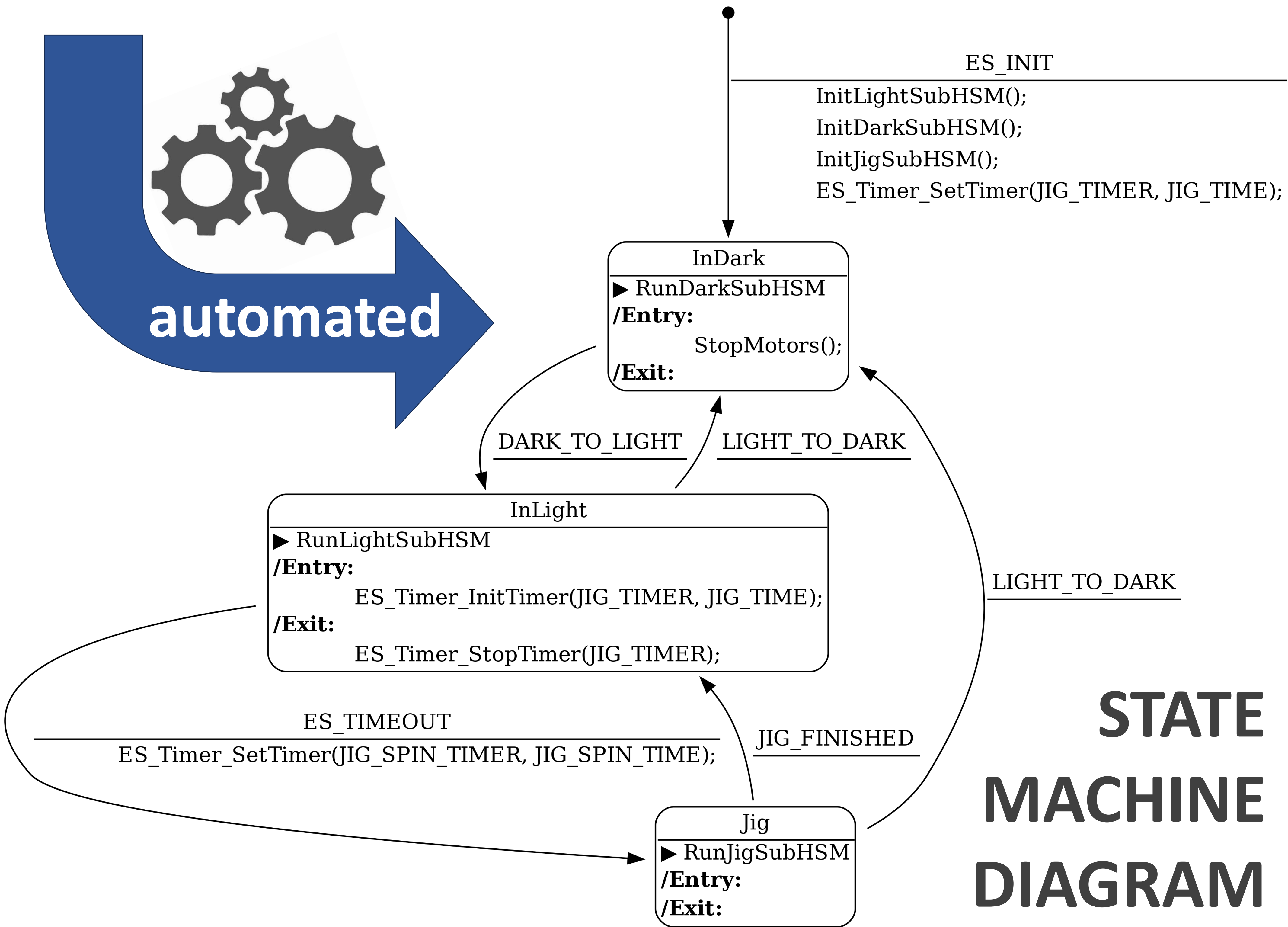
    }

    default:
        break;
    }

    if (makeTransition == TRUE) {
        RunTemplateHSM(EXIT_EVENT);
        CurrentState = nextState;
        RunTemplateHSM(ENTRY_EVENT);
    }

    ES_Tail();
    return ThisEvent;
}
```

ROBOT CODE



RESULTS

Given the myriad implementations of state machines in C-code, our prototype is implemented on top of **Abstract Syntax Trees (ASTs)** and supports:

- State machines implemented with **if-then-else** statements and **switch-and-default** statements
- **Case Cascades** inside switch statements: when fall through is to the same next state we simplify the diagram by combining transition labels together.
- **Event Parameters** so that the same event with a different parameter is treated as its own transition
- **onEntry** and **onExit** elements which show logic executed immediately on state entry/exit
- **onTransition** elements which show the logic executed for a specific transition
- **Guard Conditions** which show the logic that decides if a transition should occur.
- **Hierarchical State Machines (HSMs)** which allow new state machine logic to be isolated within a state

CONCLUSION

Our **prototype generates state diagrams directly from code** using naming conventions for variables and AST code patterns defined using XSLT. Moving forward, UCSC’s “ECE118: Introduction to Mechatronics” students will use our prototype so that broader usage will help us identify edge cases that require updates to our XSLT.

ACKNOWLEDGEMENTS

This project was initiated and funded by **CAHSI Undergraduates Program** and is supported by **National Science Foundation** Grants #2034030 and #1834620. **Bailen Lawson** supplied many ECE118 code samples enabling our testing. **One such code sample and its generated diagram are shown.**

