

Assignment2

May 3, 2024

```
[97]: import os
import pandas as pd
```

```
[98]: import autograd.numpy as np
```

```
[99]: import matplotlib.pyplot as plt
from matplotlib import gridspec
```

```
[100]: import autograd.numpy as np
from autograd import grad
```

1 Exercise 13.1. Two-class classification with neural networks

```
[108]: #data = pd.read_csv('/Users/jazz13/Desktop/2_eggs.csv', delimiter=',')
data = np.loadtxt('/Users/jazz13/Desktop/GitHub_Files/435-deep-learning/2_eggs.
↪csv', delimiter=',')
x = data[:2,:]
y = data[2,:][np.newaxis,:]

print(np.shape(x))
print(np.shape(y))
```

(2, 96)

(1, 96)

```
[109]: # Creating a network with 4 hidden layers with 10 units in each layer.
N    = 2 #dimension of input
C    = 1 #dimension of output
U_1 = 10
U_2 = 10
U_3 = 10
U_4 = 10
layer_sizes = [N, U_1, U_2, U_3,U_4,C]
```

```
[118]: # normalize the inputs first
def normlaize(x):
    # compute the mean and standard deviation of the input
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x_mean = np.mean(x)
x_std = np.std(x)
x_norm = (x - x_mean)/float(x_std)
return x_norm

```

```

[111]: # activation function
def activation(a):
    #return np.maximum(0,a)
    return np.tanh(a)

```

```

[112]: def softmax(x,y,w):
    cost = np.sum(np.log(1 + np.exp(-y*model(x,w).T)))
    return cost/float(np.size(y))

```

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[113]: def feature_transforms(a,w):
    for W in w: # loop through each layer
        a = W[0] + np.dot(a.T , W[1:])
        a = activation(a).T
    return a

```

```

[114]: def model (x, theta):
    # x is input (multiple input for every data sample)
    f = feature_transforms(x, theta[0])
    a = theta[1][0] + np.dot(f.T, theta[1][1:])
    return a

```

```

[115]: # create initial weights for a neural network model
def network_initializer(layer_sizes, scale):

    # container for all tunable weights
    weights = []

    # create appropriately -sized initial
    # weight matrix for each layer of network
    #print( len( layer_sizes ) -1)
    for k in range ( len( layer_sizes ) -1):

        # get layer sizes for current weight matrix
        U_k = layer_sizes[k]
        U_k_plus_1 = layer_sizes[k +1]

        # make weight matrix
        weight = scale* np.random.randn(U_k+ 1, U_k_plus_1 )
        weights.append(weight)

    # repackage weights so that theta_init [0] contains all
    # weight matrices internal to the network , and theta_init [1]

```

```

# contains final linear combination weights
theta_init = [ weights[: -1], weights[ -1]]

return theta_init

```

```

[116]: # gradient descent function
def gradient_descent (x,y,g, alpha , max_its, w):
    # compute gradient module using autograd
    gradient = grad(g)
    acc = accuracy(x, y, w)

    # gradient descent loop
    #weight_history = [w] # weight history container
    cost_history = [g(w)] # cost function history container
    accuracy_histroy = [acc]
    iters =[0]
    for k in range( max_its ):

        # evaluate the gradient
        grad_eval = gradient(w)

        for i in range(len(w[0])):
            w[0][i] = w[0][i] - alpha* grad_eval[0][i]

        w[1] = w[1] - alpha* grad_eval[1]

        acc = accuracy(x, y, w)
        # record weight and cost
        #weight_history.append(w)
        cost_history.append(g(w))
        iters.append(k+1)
        accuracy_histroy.append(acc)

    return iters, w, cost_history, accuracy_histroy

```

```

[124]: def accuracy(x,y,w):
    y_predict = np.sign( model(x,w))

    return np.sum( (y_predict == y.T) ) / float(np.size(y))

```

```

[123]: x_normalized = normlaize(x)

scale = 1

theta_init = network_initializer(layer_sizes,scale)

```

```

theta = theta_init

alpha = 0.01
max_its = 2000

g = lambda w: softmax(x_normalized,y,w)

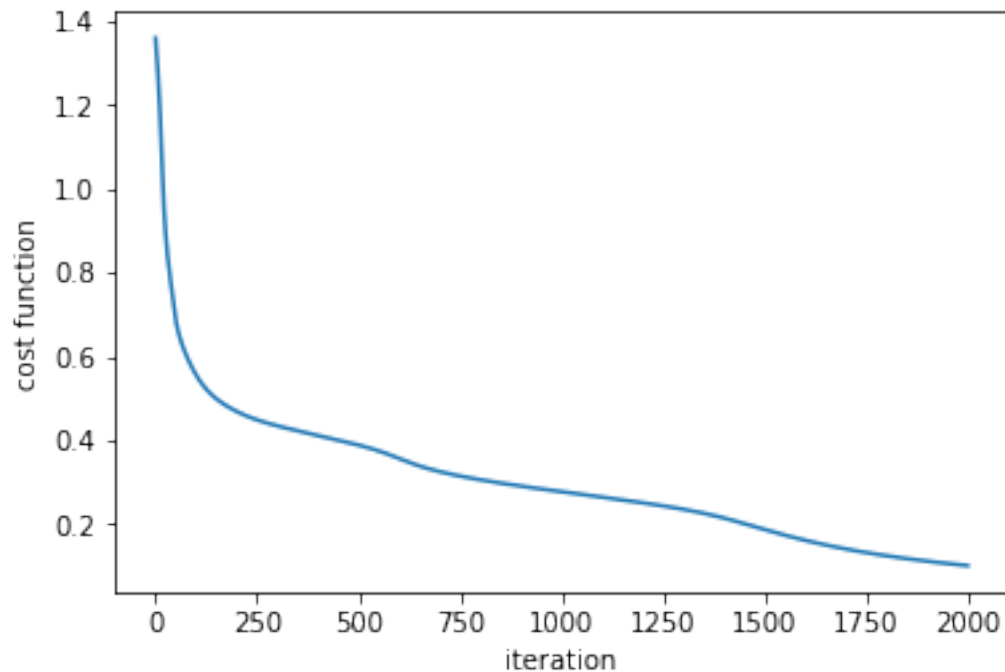
iters, theta, cost_history, acc_history = gradient_descent(x_normalized,y,g,
    ↪alpha , max_its, theta)
y_predict = (model(x_normalized, theta))

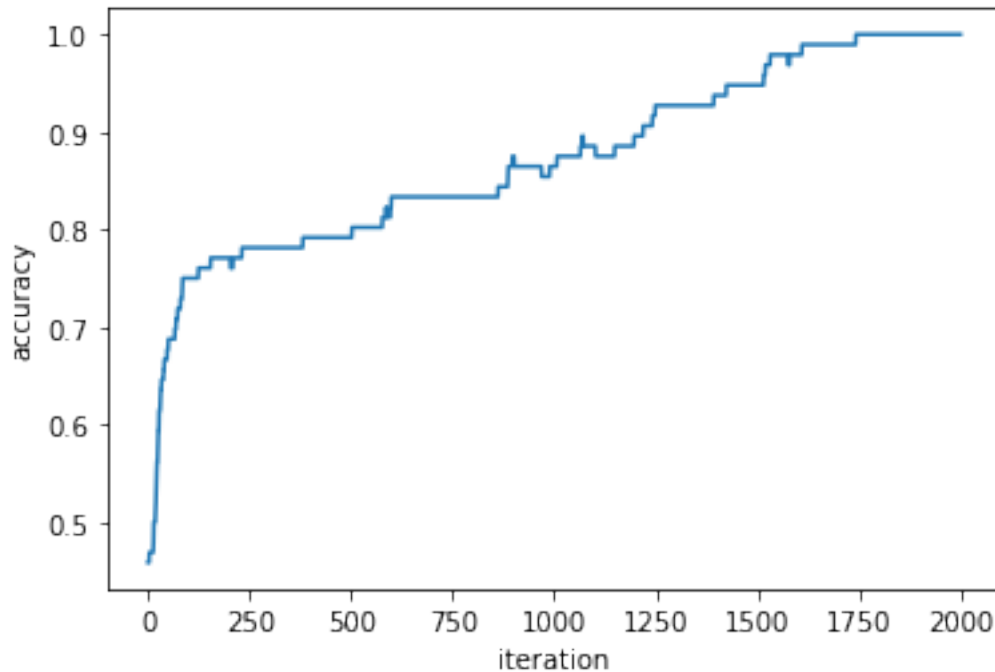
plt.figure(1)
plt.xlabel('iteration')
plt.ylabel('cost function')
plt.plot(iters, cost_history)

plt.figure(2)
plt.xlabel('iteration')
plt.ylabel('accuracy')
plt.plot(iters, acc_history)

```

[123]: [<matplotlib.lines.Line2D at 0x7fda6d9f9c70>]





2 Exercise 13.2 .Multi Class Classification Neural Networks

```
[126]: data = np.loadtxt('/Users/jazz13/Desktop/GitHub_Files/435-deep-learning/
↳ 3_layercake_data.csv', delimiter=',')
x = data[:,2,:]
y = data[:,2:][np.newaxis,:]

print(np.shape(x))
print(np.shape(y))
```

```
(2, 110)
```

```
(1, 110)
```

```
[144]: N    = 2 #dimension of input
C      = 3 #dimension of output
U_1    = 12
U_2    = 5
layer_sizes = [N, U_1, U_2, C]
```

```
[163]: def multiclass_softmax(w,x,y,iter):
        # get subset of points
        all_evals = model(x,w)
        # compute softmax across data points
        a = np.log(np.sum(np.exp(all_evals)))
```

```

# compute cost in compact form using numpy broadcasting
cost = np.sum(a - y.astype(int).flatten())

# return average
return cost/float(np.size(y))

```

```

[164]: x_normalized = normlaize(x)

scale = 0.1

theta_init = network_initializer(layer_sizes,scale)

theta = theta_init

alpha = 1
max_its = 1000

g = lambda w: multiclass_softmax(w,x,y,iter)

iters, theta, cost_history, acc_history = gradient_descent(x_normalized,y,g,
    ↪alpha , max_its, theta)
y_predict = (model(x_normalized, theta))

plt.figure(1)
plt.xlabel('iteration')
plt.ylabel('cost function')
plt.plot(iters, cost_history)

plt.figure(2)
plt.xlabel('iteration')
plt.ylabel('accuracy')
plt.plot(iters, acc_history)

```

```

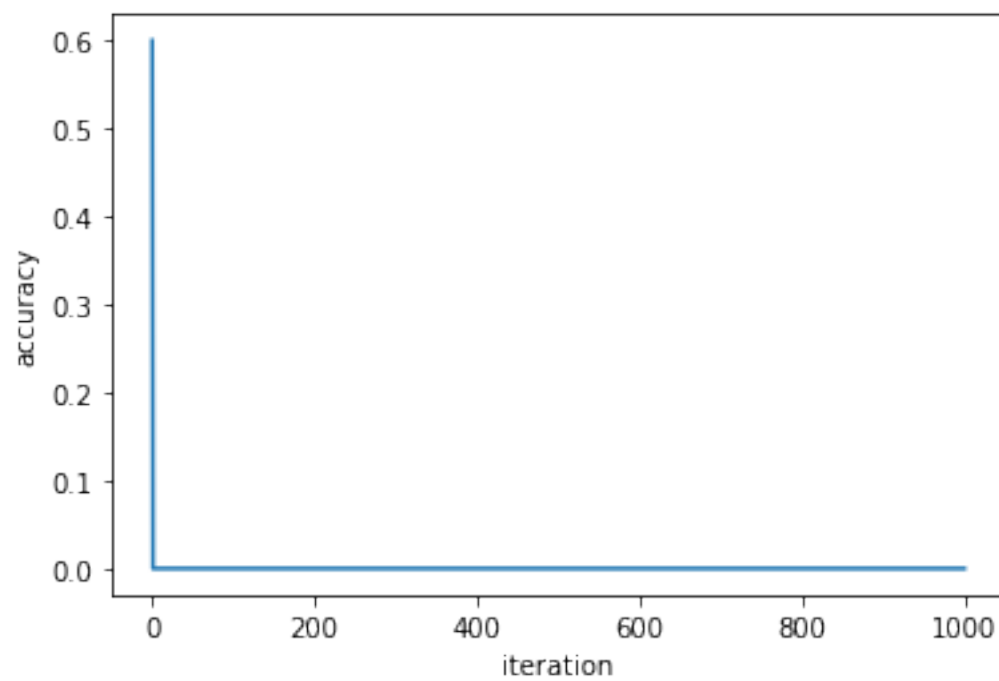
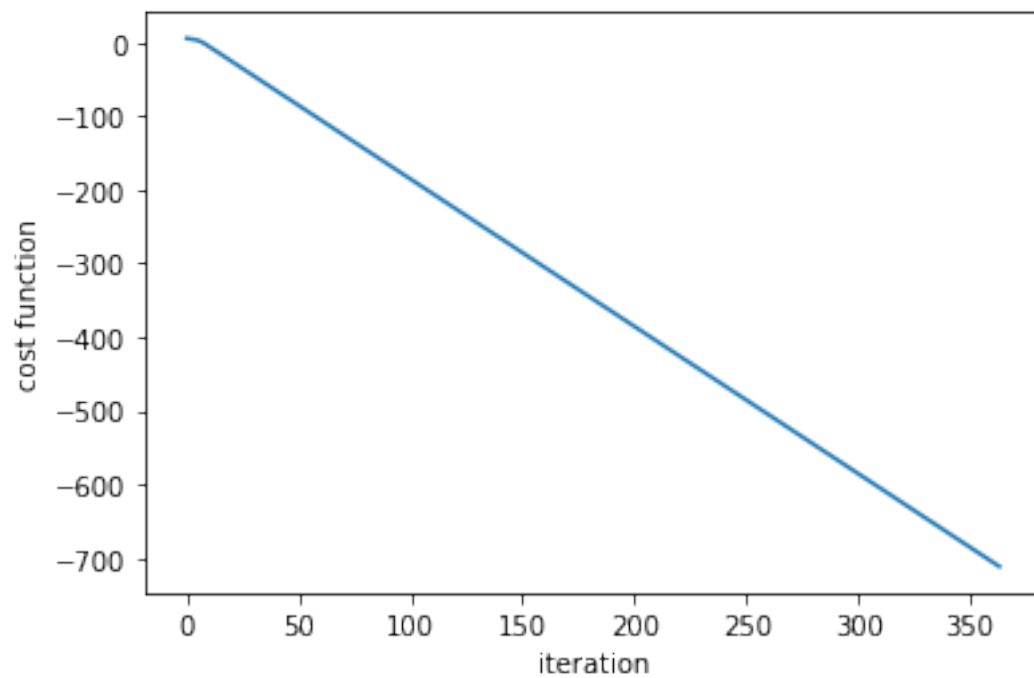
/var/folders/85/0qv3zvwx1r5_c57bw919zvpc0000gn/T/ipykernel_42252/575490115.py:3:
RuntimeWarning: invalid value encountered in add
    a = W[0] + np.dot(a.T , W[1:])

```

```

[164]: [<matplotlib.lines.Line2D at 0x7fda701540d0>]

```



3 Exercise 13.3. Number of Weights to Learn in a Neural Network

- (a) Find the total number Q of tunable parameters in a general L -hidden-layer neural network, in terms of variables expressed in the layer `_sizes` in Section 13.2.6

Total number of hidden layers $k = 1$ to L and there are U_k variables per k th hidden layer. The dimension of the input layer is N so let $U_0 = N$ and dimension of the output layer is $U_{L+1} = C$. Thus the total number of tunable parameters is

$$Q = \sum_{k=0}^L (1 + U_k) U_{k+1}$$

- (b) Based on your answer in part(a), explain how the input dimension N and number of data points P each contribute to Q . How is this different from what you saw with kernel methods in the previous chapter?

Rewriting the above expression for Q by taking out the $k = 0$ term, we get

$$Q = NU_1 + U_1 + \sum_{k=1}^L (1 + U_k) U_{k+1}$$

This shows that Q is directly proportional to N however it is independent with respect to the number of data points P

[]: