

Q.No-1) What is the correct vector space and corresponding dimensions of the four fundamental subspaces of the matrix M ($C(M)$, $R(M)$, $N(M)$, $L(M)$)? (Note: $C(M)$ is the column space of M , $N(M)$ is the null space of M , $R(M)$ is the row space of M , and $L(M)$ is the left null space of M . Dimension of a subspace is the number of basis vectors spanning the subspace)

$$M = \begin{bmatrix} 0 & 2 & 3 & 1 \\ -6 & -1 & -1 & 1 \\ 8 & 8 & 6 & 3 \end{bmatrix}$$

Reducing matrix M to row echelon form

$$R_1 \rightarrow R_3$$

$$M = \begin{bmatrix} 8 & 8 & 6 & 3 \\ -6 & -1 & -1 & 1 \\ 0 & 2 & 3 & 1 \end{bmatrix}$$

$$R_2 \rightarrow 4R_2 + 3R_1$$

$$M = \begin{bmatrix} 8 & 8 & 6 & 3 \\ 0 & 20 & 14 & 13 \\ 0 & 2 & 3 & 1 \end{bmatrix}$$

$$R_1 \rightarrow 5R_1 - 2R_2; R_3 \rightarrow 10R_3 - R_2$$

$$M = \begin{bmatrix} 40 & 0 & 2 & -11 \\ 0 & 20 & 14 & 13 \\ 0 & 0 & 16 & -3 \end{bmatrix}$$

$$R_1 \rightarrow 8R_1 - R_3; R_2 \rightarrow 8R_2 - 7R_3$$

$$M = \begin{bmatrix} 320 & 0 & 0 & -85 \\ 0 & 160 & 0 & 125 \\ 0 & 0 & 16 & -3 \end{bmatrix}$$

$\uparrow \quad \uparrow \quad \uparrow$

column space, $C(M)$ = linear combination of vectors corresponding to pivot columns

$$\therefore C(M) = \text{Span} \left(\begin{bmatrix} 0 \\ -6 \\ 8 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 8 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 6 \end{bmatrix} \right)$$

$$\dim(C(M)) = 3$$

To find Null space:

$$A\vec{x} = \vec{0}$$

$$\begin{bmatrix} 320 & 0 & 0 & -85 \\ 0 & 160 & 0 & 125 \\ 0 & 0 & 16 & -3 \end{bmatrix} \begin{bmatrix} u \\ v \\ w \\ x \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{aligned} 320u - 85x &= 0; & 160v + 125x &= 0; & 16w - 3x &= 0 \\ \Rightarrow u = \frac{85}{320}x = \frac{17}{64}x & & \Rightarrow v = \frac{-125}{160}x = \frac{-25}{32}x & & \therefore w = \frac{3}{16}x \end{aligned}$$

$$\therefore \text{Null space, } N(M) = \text{span} \left(\begin{bmatrix} 17/64 \\ -25/32 \\ 3/16 \\ 1 \end{bmatrix} \right); \dim(N(M)) = 1$$

$$\text{Row space, } R(M) = \text{span} \left(\begin{bmatrix} 0 \\ 2 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -6 \\ -1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 8 \\ 8 \\ 6 \\ 3 \end{bmatrix} \right); \dim(R(M)) = 3$$

To find left Null space:

$$M^T = \begin{bmatrix} 0 & -6 & 8 \\ 2 & -1 & 8 \\ 3 & -1 & 6 \\ 1 & 1 & 3 \end{bmatrix}$$

$$R_1 \rightarrow R_4$$

$$M^T = \begin{bmatrix} 1 & 1 & 3 \\ 2 & -1 & 8 \\ 3 & -1 & 6 \\ 0 & -6 & 8 \end{bmatrix}; \begin{aligned} R_2 &\rightarrow R_2 - 2R_1 \\ R_3 &\rightarrow R_3 - 3R_1 \end{aligned}$$

$$M^T = \begin{bmatrix} 1 & 1 & 3 \\ 0 & -3 & 2 \\ 0 & -4 & -3 \\ 0 & -6 & 8 \end{bmatrix}; \begin{aligned} R_1 &\rightarrow R_1 + \frac{1}{3}R_2 \\ R_3 &\rightarrow R_3 - \frac{4}{3}R_2 \\ R_4 &\rightarrow R_4 - 2R_2 \end{aligned}$$

$$M^T = \begin{bmatrix} 1 & 0 & 11/3 \\ 0 & -3 & 2 \\ 0 & 0 & -17/3 \\ 0 & 0 & 4 \end{bmatrix}; \begin{aligned} R_1 &\rightarrow R_1 + \frac{3}{17} \times \frac{11}{3} R_3 \\ R_2 &\rightarrow R_2 + \frac{3 \times 2}{17} R_3 \\ R_4 &\rightarrow R_4 + \frac{3 \times 4}{17} R_3 \end{aligned}$$

$$M^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -17/3 \\ 0 & 0 & 0 \end{bmatrix}$$

So no non trivial^{left} null space exist.

$$\therefore \text{Left Null space, } L(M) = \{\vec{0}\} =$$

$$\dim(L(M)) = 0$$

Q.No-4 Find the sum of the eigen values of the 3-dimensional matrix

$$A = \begin{bmatrix} -6 & -9 & 6 \\ -2 & 3 & -4 \\ 7 & -4 & -2 \end{bmatrix}$$

$$\rightarrow \text{sum of eigen values of } A = \text{trace of } A = -6 + 3 - 2 = -5$$

Q.No-5 Find the product of the eigen values of the 3-dimensional matrix

$$A = \begin{bmatrix} -8 & -4 & -9 \\ -5 & 5 & -4 \\ 2 & -4 & 1 \end{bmatrix}$$

$$\rightarrow \text{Product of eigen values} = \text{determinant of matrix} \\ = 10$$

```
>> A=[-8 -4 -9; -5 5 -4; 2 -4 1]
```

```
A =
```

```

-8    -4    -9
-5     5    -4
 2    -4     1

```

```
>> det(A)
```

```
ans =
```

```
10.0000 ←
```

```
>> L=eig(A)
```

```
L =
```

```

-8.8015
 6.9647
-0.1631

```

```
>> L(1)*L(2)*L(3)
```

```
ans =
```

```
10.0000
```

Q.No-6 Find the left eigen vector of the given matrix

$$M = \begin{bmatrix} -7 & -1.5 & 7 \\ -1.5 & 2 & -5 \\ 7 & -5 & 0 \end{bmatrix}$$

→ left eigen vector is a row vector \vec{x} such that

$$\begin{aligned} \vec{x}M &= \lambda \vec{x} \\ (\vec{x}M)^T &= (\lambda \vec{x})^T \\ M^T \vec{x}^T &= \lambda \vec{x}^T \end{aligned}$$

→ left eigen vector is a transpose of right eigen vector of M^T

left eigen vectors are

$$\begin{aligned} e_1 &= (-7 \quad -1.5 \quad 7) \\ e_2 &= (-1.5 \quad 2 \quad 5) \\ e_3 &= (7 \quad -5 \quad 0) \end{aligned}$$

```
>> M = [-7 -1.5 7; -1.5 2 -5; 7 -5 0]
M =
-7.0000 -1.5000 7.0000
-1.5000 2.0000 -5.0000
7.0000 -5.0000 0
>> A = transpose(M)
A =
-7.0000 -1.5000 7.0000
-1.5000 2.0000 -5.0000
7.0000 -5.0000 0
>> [E,D]=eig(A)
E =
-0.8257 -0.4232 -0.3731
0.1131 -0.7720 0.6254
0.5527 -0.4742 -0.6853
      ↑      ↑      ↑
D =
-11.4804 0 0
0 -1.8932 0
0 0 8.3736
```

Q.No-7 Compute the singular values of the given matrix

$$M = \begin{bmatrix} -4 & 2 & 4 & -8 \\ 1 & -5 & 5 & -5 \\ -6 & 3 & -1 & 8 \end{bmatrix}_{3 \times 4}$$

→ Singular values of M are square root of eigen values of MM^T or $M^T M$.

Singular values are 4.66, 8.23, 14.02

```
>> M = [-4 2 4 -8; 1 -5 5 -5; -6 3 -1 8]
M =
-4 2 4 -8
1 -5 5 -5
-6 3 -1 8
>> MT = transpose(M)
MT =
-4 1 -6
2 -5 3
4 5 -1
-8 -5 8
>> L=eig(M*MT)
L =
21.6793
67.7193
196.6014
>> S = [sqrt(L(1)) sqrt(L(2)) sqrt(L(3))]
S =
4.6561 8.2292 14.0215
```

Q.No-8 Compute the matrix M when M is rotated clockwise by 90 degree

$$M = \begin{bmatrix} -9 & -7 \\ 9 & 8 \end{bmatrix}$$

90° clockwise rotation matrix is $R = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

$$RM = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -9 & -7 \\ 9 & 8 \end{bmatrix} = \begin{bmatrix} 9 & 8 \\ -9 & -7 \end{bmatrix}$$

Q.No-10 M is a square matrix of dimension 3. Perform the eigen value decomposition of M and calculate the trace of the inverse of the eigen vectors of matrix M.

$$M = \begin{bmatrix} 101 & -2 & 14 \\ -2 & 25 & 26 \\ 14 & 26 & 76 \end{bmatrix}$$

$$D = \text{inv}E \times M \times E$$

E is a matrix of eigen vectors

invE is inverse of E

```
>> M = [101 -2 14; -2 25 26; 14 26 76]
```

```
M =
```

```
101    -2    14
   -2    25    26
   14    26    76
```

```
>> [E L] = eig(M)
```

```
E =
```

```
-0.0846   -0.4878   0.8689
-0.9132    0.3868   0.1282
 0.3986    0.7826   0.4782
```

```
L =
```

```
13.4653         0         0
         0  80.1249         0
         0         0 108.4098
```

```
>> invE = inv(E)
```

```
invE =
```

```
-0.0846   -0.9132   0.3986
-0.4878    0.3868   0.7826
 0.8689    0.1282   0.4782
```

```
>> D = invE*M*E
```

```
D =
```

```
13.4653    0.0000    0.0000
-0.0000   80.1249    0.0000
 0.0000    0.0000 108.4098
```

Q.No-2 State true/false for the following statements with reasoning.

If all entries of A are positive, then A is positive-definite matrix

→ False; suppose $A = \begin{bmatrix} 2 & 5 \\ 4 & 3 \end{bmatrix}$; $|A| = -14$ which is negative

If A is positive-definite matrix, then Inverse(A) is also a positive-definite matrix.

→ True

for positive definite matrix, eigen values (λ_i) are positive

We know eigen values of A^{-1} are reciprocal of eigen values of A

$$\text{i.e. } \lambda_i(A^{-1}) = \frac{1}{\lambda_i(A)}$$

$\Rightarrow \lambda_i(A^{-1})$ are positive

$\Rightarrow A^{-1}$ is positive-definite matrix

Q.No 9 For the given matrix (A), calculate $\exp(At)$ such that $f(x) = \exp(xt)$ is a characteristic polynomial of A. What is the expression for b_1 if $\exp(At) = b_0 + b_1A + b_2A^2$?

$$A = \begin{bmatrix} 3.5 & 0 & 0.5 \\ 1 & 2 & 1 \\ 0.5 & 0 & 3.5 \end{bmatrix}$$

$$e^{At} = L^{-1}[(sI - A)^{-1}]$$

$$(sI - A)^{-1} = \begin{bmatrix} \frac{s-3.5}{s^2-7s+12} & 0 & \frac{0.5}{s^2-7s+12} \\ \frac{s-3}{s^3-9s^2+26s-24} & \frac{1}{s-2} & \frac{s-3}{s^3-9s^2+26s-24} \\ \frac{0.5}{s^2-7s+12} & 0 & \frac{s-3.5}{s^2-7s+12} \end{bmatrix}$$

```
>> s = tf('s')
s =
s
Continuous-time transfer function.
>> A=[3.5 0 0.5; 1 2 1; 0.5 0 3.5]
A =
3.5000    0    0.5000
1.0000    2.0000    1.0000
0.5000    0    3.5000
>> sI = [s 0 0; 0 s 0; 0 0 s];
>> M=inv(sI-A)
```

```
M =
From input 1 to output...
s - 3.5
1: -----
s^2 - 7 s + 12
s - 3
2: -----
s^3 - 9 s^2 + 26 s - 24
0.5
3: -----
s^2 - 7 s + 12
From input 2 to output...
1
1: 0
2: -----
s - 2
3: 0
From input 3 to output...
0.5
1: -----
s^2 - 7 s + 12
s - 3
2: -----
s^3 - 9 s^2 + 26 s - 24
s - 3.5
3: -----
s^2 - 7 s + 12
Continuous-time transfer function.
```

```
>> syms s
>> M = [ (s-3.5)/(s^2 - 7*s + 12) (s-3)/(s^3 - 9*s^2 + 26*s - 24) 0.5/(s^2 - 7*s + 12); 0 1/(s-2) 0; 0.5/(s^2 - 7*s + 12) (s-3)/(s^3 - 9*s^2 + 26*s - 24) (s-3.5)/(s^2 - 7*s + 12)]

M =

[ (s - 7/2)/(s^2 - 7*s + 12), (s - 3)/(s^3 - 9*s^2 + 26*s - 24), 1/(2*(s^2 - 7*s + 12))]
[ 0, 1/(s - 2), 0]
[ 1/(2*(s^2 - 7*s + 12)), (s - 3)/(s^3 - 9*s^2 + 26*s - 24), (s - 7/2)/(s^2 - 7*s + 12)]

>> for i=1:3
for j=1:3
stM(i,j)=ilaplace(M(i,j));
end
end
>> stM

stM =

[ exp(3*t)/2 + exp(4*t)/2, exp(4*t)/2 - exp(2*t)/2, exp(4*t)/2 - exp(3*t)/2]
[ 0, exp(2*t), 0]
[ exp(4*t)/2 - exp(3*t)/2, exp(4*t)/2 - exp(2*t)/2, exp(3*t)/2 + exp(4*t)/2]
```

$$\therefore e^{At} = \begin{bmatrix} \frac{1}{2}(e^{3t} + e^{4t}) & 0 & \frac{1}{2}(e^{4t} - e^{3t}) \\ \frac{1}{2}(e^{4t} - e^{2t}) & e^{2t} & \frac{1}{2}(e^{4t} - e^{2t}) \\ \frac{1}{2}(e^{4t} - e^{3t}) & 0 & \frac{1}{2}(e^{3t} + e^{4t}) \end{bmatrix}$$

Q.No 3 For the given matrix (A), calculate $\exp(At)$ such that $f(x)=\exp(xt)$ is a characteristic polynomial of A. What is the expression for b3 if $\exp(At)$ is expressed as $[a_1 \ b_1 \ c_1; a_2 \ b_2 \ c_2; a_3 \ b_3 \ c_3]$?

$$A = \begin{bmatrix} 5 & 1 & 1 \\ -2 & 8 & 1 \\ 2 & -2 & 5 \end{bmatrix}$$

$$e^{At} = L^{-1}[(sI - A)^{-1}]$$

$$(sI - A)^{-1} = \begin{bmatrix} \frac{s^2 - 13s + 42}{s^3 - 18s^2 + 107s - 210} & \frac{s-7}{s^3 - 18s^2 + 107s - 210} & \frac{s-7}{s^3 - 18s^2 + 107s - 210} \\ \frac{-2s+12}{s^3 - 18s^2 + 107s - 210} & \frac{s^2 - 12s + 23}{s^3 - 18s^2 + 107s - 210} & \frac{s-7}{s^3 - 18s^2 + 107s - 210} \\ \frac{2s-12}{s^3 - 18s^2 + 107s - 210} & \frac{-2s+12}{s^3 - 18s^2 + 107s - 210} & \frac{s^2 - 13s + 42}{s^3 - 18s^2 + 107s - 210} \end{bmatrix}$$

```
>> s = tf('s')
s =
s
Continuous-time transfer function.
>> A=[5 1 1; -2 8 1; 2 -2 5]
A =
5 1 1
-2 8 1
2 -2 5
>> sI = [s 0 0; 0 s 0; 0 0 s];
>> M=inv(sI-A)

M =

From input 1 to output...
s^2 - 13 s + 42
1: -----
s^3 - 18 s^2 + 107 s - 210
-2 s + 12
2: -----
s^3 - 18 s^2 + 107 s - 210
2 s - 12
3: -----
s^3 - 18 s^2 + 107 s - 210
From input 2 to output...
s - 7
1: -----
s^3 - 18 s^2 + 107 s - 210
s^2 - 10 s + 23
2: -----
s^3 - 18 s^2 + 107 s - 210
-2 s + 12
3: -----
s^3 - 18 s^2 + 107 s - 210
From input 3 to output...
s - 7
1: -----
s^3 - 18 s^2 + 107 s - 210
s - 7
2: -----
s^3 - 18 s^2 + 107 s - 210
s^2 - 13 s + 42
3: -----
s^3 - 18 s^2 + 107 s - 210
```

```

>> syms s
>> M = transpose([ (s^2-13*s+42)/(s^3-18*s^2+107*s-210) (-2*s+12)/(s^3-18*s^2+107*s-210) (2*s-12)/(s^3-18*s^2+107*s-210); (s-7)/(s^3-18*s^2+107*s-210) (s^2-10*s+23)/(s^3-18*s^2+107*s-210) (-2*s+12)/(s^3-18*s^2+107*s-210); (s-7)/(s^3-18*s^2+107*s-210) (s-7)/(s^3-18*s^2+107*s-210) (s^2-13*s+42)/(s^3-18*s^2+107*s-210)])

M =

[ (s^2 - 13*s + 42)/(s^3 - 18*s^2 + 107*s - 210), (s - 7)/(s^3 - 18*s^2 + 107*s - 210), (s - 7)/(s^3 - 18*s^2 + 107*s - 210)]
[ -(2*s - 12)/(s^3 - 18*s^2 + 107*s - 210), (s^2 - 10*s + 23)/(s^3 - 18*s^2 + 107*s - 210), (s - 7)/(s^3 - 18*s^2 + 107*s - 210)]
[ (2*s - 12)/(s^3 - 18*s^2 + 107*s - 210), -(2*s - 12)/(s^3 - 18*s^2 + 107*s - 210), (s^2 - 13*s + 42)/(s^3 - 18*s^2 + 107*s - 210)]

>> for i=1:3
for j=1:3
stM(i,j)=ilaplace(M(i,j));
end
end
>> stM

stM =

[ exp(5*t), exp(6*t) - exp(5*t), exp(6*t) - exp(5*t)]
[ exp(5*t) - exp(7*t), exp(6*t) - exp(5*t) + exp(7*t), exp(6*t) - exp(5*t)]
[ exp(7*t) - exp(5*t), exp(5*t) - exp(7*t), exp(5*t)]
..

```

$$\therefore e^{At} = \begin{bmatrix} e^{5t} & e^{6t} - e^{5t} & e^{6t} - e^{5t} \\ e^{5t} - e^{7t} & e^{6t} - e^{5t} + e^{7t} & e^{6t} - e^{5t} \\ e^{7t} - e^{5t} & e^{5t} - e^{7t} & e^{5t} \end{bmatrix}$$