

Survey of Space Complexity and Connectivity

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Foundations

L Logspace decidable languages

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- Graph** We mean a directed graph unless stated otherwise

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Theorem 2.

STCONN is **NL**-complete

Savitch's Theorem

Theorem 3 [Savitch, 1970].

Let $s : \mathbb{N} \rightarrow \mathbb{N}$ be a space constructible function with $s(n) \geq \log n$. Then $\mathbf{NSPACE}(s(n)) \subseteq \mathbf{DSPACE}(s^2(n))$.

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It suffices to prove that $\mathbf{NL} \subseteq \mathbf{DSPACE}(\log^2(n))$ because for any $s(n)$ we can then show that reachability on the configuration graph ($O(c^{s(n)})$ nodes) can be solved in $O(\log^2(c^{s(n)})) = O(s^2(n))$ space.

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Corollary 4.

$\mathbf{PSPACE} = \mathbf{NPSPACE}$

Savitch's Algorithm

Algorithm 1 Find a directed path in a graph of length at most k

```
1: procedure FINDDIRECTEDPATH( $(V, E), s, t, k$ )
2:   if  $k == 0$  then return  $s == t$ 
3:   end if
4:   if  $k == 1$  then return  $s == t$  OR  $(s, t) \in E$ 
5:   end if
6:   for  $v \in V$  do
7:     if FINDDIRECTEDPATH( $(V, E), s, v, \lfloor \frac{k}{2} \rfloor$ ) AND
        FINDDIRECTEDPATH( $(V, E), v, t, \lceil \frac{k}{2} \rceil$ ) then
8:       return TRUE
9:     end if
10:  end for
11:  return FALSE
12: end procedure
```

Theorem 5 [Immerman, 1988, Szelepcsényi, 1988].

Let $s : \mathbb{N} \rightarrow \mathbb{N}$ be a function such that $s(n) \geq \log n$. Then

NSPACE($s(n)$) = **coNSPACE**($s(n)$) *(even if $s(n)$ is not space constructible).*

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Corollary 6.

$\mathbf{NL} = \mathbf{coNL}$

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- This is a major open question.
- One attempt at answering in the affirmative is efficient algorithms
- One attempt at answering in the negative is to show $USTCONN \notin L$
 - In a breakthrough result, Reingold showed this is a fruitless attempt

Theorem 7 [Reingold, 2008].

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A directed graph is said to be Eulerian if the indegree and outdegree of each vertex is the same. That is, there are the same number of arcs into and out of every vertex.

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Theorem 9 [Reingold et al., 2006].

There exists a logspace algorithm for deciding reachability in Eulerian directed graphs

Restricted Graphs

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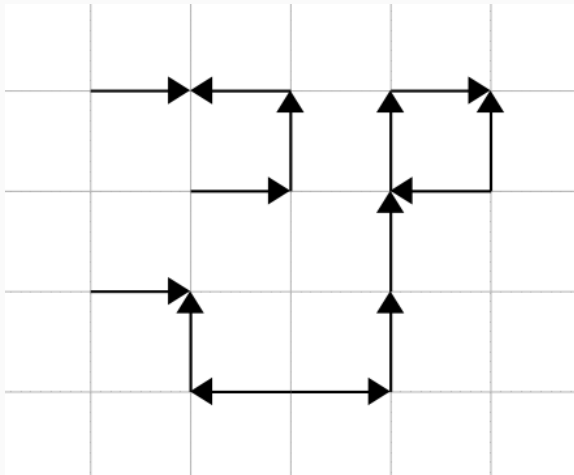
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Theorem 10 [Allender and Mahajan, 2000, Reingold, 2008].

Given an adjacency matrix of a graph, the problem of finding a combinatorial embedding is \mathbf{L} -complete

Grid Graphs



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Theorem 13 [Allender et al., 2005].

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Theorem 14 [Allender et al.,].

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- There is weak evidence that GGRB is not **NL**-complete [Allender et al.,]
 - There is a relatively simple reduction from GGRB to its complement $\overline{\text{GGRB}}$
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- Is LGGR easier than GGR?
 - Seems reasonable since a path can only progress southeast
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 - Next result shows that no more is known about LGGR than GGR

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Definition 20.

If G, H are graphs and G does not contain H as a minor, then G is called H -free

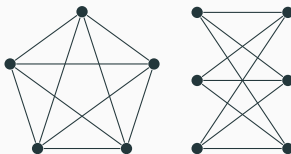
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Theorem 21 [Wagner, 1937].

A graph is planar if and only if it is both K_5 -free and $K_{3,3}$ free



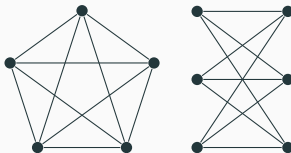
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Theorem 22 [Thierauf and Wagner, 2009].

Reachability for K_5 -free graphs and for $K_{3,3}$ -free graphs logspace reduces to PLANARREACH

Space and Time

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A trivial time bound is obtained from Savitch's algorithm

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Polynomial time, sublinear space algorithms also exist

Theorem 25 [Barnes et al.,].

$$\text{STCONN} \in \mathbf{TISP}(n^{O(1)}, \frac{n}{2^{O(\sqrt{\log n})}})$$

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- When considering time and space bounds together, planar graphs and grid graphs are not known to be equivalent because the known reductions from planar graphs to grid graphs result in a polynomial blowup in the size of the graph

Theorem 26 [Imai et al., 2013].

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The former result also holds for graphs that are almost planar

Theorem 28 [Chakraborty et al., 2014].

Reachability for a directed graph which is either K_5 -free or $K_{3,3}$ -free can be decided in $\mathbf{TISP}(n^{O(1)}, n^{1/2+\epsilon})$ for any $\epsilon > 0$

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Theorem 30 [Chakraborty et al., 2014].

Given a combinatorial embedding of a graph on a genus g surface, reachability can be decided in

TISP $(n^{O(1)}, n^{2/3} \log^{O(1)}(n) \cdot g^{1/3} \log^{O(1)}(g))$

Theorem 31 [Asano and Doerr, 2011].

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Conclusion

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 - Does \mathbf{FewL} equal \mathbf{UL}
 - $\mathbf{ReachFewL} = \mathbf{ReachUL}$

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