

Density-dependent selection and the limits of relative fitness

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Abstract

Selection is commonly described in terms of constant relative fitnesses. Yet when selection is strong, the ecological view of selection in density-regulated populations seems to be incompatible with constant-density relative fitnesses. Here we analyze the population ecological limits of relative fitness using a novel [BLAH] in which population density depends dynamically on the demographic rates of the types present. Our model contains a “reproductive excess, and clearly distinguishes between density-dependent selection and selection-dependent density. These two effects are confounded in standard models of density-regulated population growth. Both effects are necessary, in combination with strong selection, for relative fitness to break down in populations close to demographic equilibrium. Remarkably, both effects are not sufficient: we give an example of strong selection on a density-regulating trait subject to density-dependent selection that conforms to the relative fitness description almost exactly. We reiterate the importance of reproductive excesses in many species, which allows even strong selection to have no effect on density. Our model also offers a possible alternative to relative fitness when the latter is untenable, as is likely the case far from demographic equilibrium.

(191 words)

Introduction

There are a variety of different measures of fitness. Some widely used examples are expected lifetime reproductive ratio R_0 , intrinsic population growth rate r , equilibrium population density/carrying capacity (often labeled “ K ”) (Benton and Grant, 2000), and invasion fitness (Metz et al., 1992). In addition, “relative fitness” is the standard in much of evolutionary biology, particularly evolutionary genetics, where the focus is relative genotypic proportions (Barton et al., 2007, pp. 468). The variety of fitness measures is not problematic in itself, because different measures have different uses. But it should be clear how these measures are connected to the processes of birth and death which ultimately drive selection (Metcalf and Pavard, 2007; Doebeli et al., 2017). While such a connection is fairly clear for absolute fitness measures like r , relative fitness is largely divorced from population ecology. It has even been proposed that relative fitness be justified from measure theory, abandoning population biology altogether (Wagner, 2010). Given the ubiquitous use of relative fitness, it is important that we understand its population ecological basis, both to clarify its domain of applicability, and as part of the broader challenge of synthesizing ecology and evolution.

Constant relative fitness values can be justified as an approximation which holds when selection is sufficiently weak and stable over time. Formally, these values are the “zeroth order” components of the actual relative fitnesses, which are not constant but depend on density, frequency, age structure, and so on (Ewens, 2004, pp. 277) (Charlesworth, 1994, Chap. 4). Yet strong, temporally-variable selection occurs widely in nature and the lab, including in wild *Drosophila*, where population density also varies by orders of magnitude each seasonal cycle (Messer et al., 2016; Bergland et al., 2014). The question is whether relative fitness can be used when selection is not vanishingly weak. In general, age-structured populations that reproduce by outcrossing do not permit strong selection to be represented in terms of type-specific relative-fitness constants (Charlesworth, 1994, Chap. 4). We will

therefore restrict our attention to asexual haploids with little or no age structure, where it is easier to evaluate how the success or failure of the relative fitness description is tied to the underlying population ecological assumptions.

In the absence of crowding, relative fitness simply represents differences in intrinsic population growth rate. In discrete time, the change in frequency of type i is $\Delta p_i = (\frac{W_i}{\bar{W}} - 1) p_i$, where W_i is the intrinsic absolute growth factor of type i , and $\bar{W} = \sum_i W_i p_i$ is the population mean W . The change in frequency depends only the relative ratio $\frac{W_i}{\bar{W}}$, not the absolute values of the growth factors W_i . Thus, we can replace the W_i with any set of values w_i that are proportional to the W_i ; these values are called “relative fitnesses”. The analogous formula in continuous time is $\frac{dp_i}{dt} = (r_i - \bar{r})p_i$, where W_i is replaced by the intrinsic exponential growth rate r_i (Crow et al., 1970, pp. 26), and the ratio $\frac{W_i}{\bar{W}}$ is replaced by the difference $r_i - \bar{r}$. In the particular case that there are two types present, a wildtype i and a mutant j for instance, then the continuous time equation takes the familiar form

$$\frac{dp_i}{dt} = sp_i(1 - p_i), \tag{1}$$

where $s = r_i - r_j$ is the selection coefficient.

The simple interpretation of relative fitness as a difference in intrinsic growth rates breaks down when we allow for population crowding. Since crowded and uncrowded conditions are so different, we expect that s will often depend on density (Travis et al., 2013). Eq. (1) is then no longer a complete description of selection — we would also need to specify a model for how density is changing. Note that frequency-dependent selection does not raise similar problems; Eq. (1) is still a complete description of selection even if its behavior is more complicated due to s depending on frequency. Population genetics traditionally evades the issue of density-dependent selection by simply assuming that total population density N has reached its equilibrium value, which is assumed to be a fixed constant. The selection coefficient s now

abstractly parameterizes the rate at which selection changes relative frequencies, and no longer corresponds to differences in intrinsic growth rates r .

However, MacArthur famously argued that when population growth is density-regulated, selection in crowded populations is intimately connected to the ability to keep growing at higher densities than other types can tolerate (MacArthur and Wilson, 1967). The classic example is the logistic model, where the type with the greatest equilibrium population density “ K ” excludes the others (Fig. 1a). Similarly, the “ R^* rule”, a central tenet of resource competition theory, states that when growth is limited by a single homogeneous consumable resource, the type able to deplete the resource to the lowest equilibrium density R^* excludes the others (Grover, 1997). Differences in R^* will often entail differences in equilibrium density. The Lotka-Volterra competition model also couples selection in crowded populations to density except in special cases (Smouse, 1976; Mallet, 2012). In these examples, both N and s change during, and as a result of, adaptive sweeps. It would therefore seem that the ubiquitous constant- N , relative fitness description of selection is incompatible with a huge class of population ecological processes driving selection (Fig. 1b), even in the absence of age-structure and mating.

In light of this difficulty, the relative fitness description has been justified in broadly two different ways for crowded populations (we do not discuss Wagner’s [2010] measurement-theoretical justification, which is independent of population biology). The first is to simply assume that selection is density-independent but relax the assumption of constant N by allowing density to change as a result of selective sweeps (Barton et al., 2007, pp. 468) (Prout, 1980). Obviously this does not address the problem that s can, in reality, depend on density. Type-specific responses to density are at the center of MacArthur’s argument and the density-dependent selection literature that grew out of it (e.g. (Roughgarden, 1979)).

The second justification, which primarily grew out of a controversy over Haldane’s “cost of selection”, is to appeal to the existence of a “reproductive excess” of juveniles that are more



Figure 1: Selection in crowded environments shown as a phase diagram for the densities of two types n_1 and n_2 . (a) The logistic model $\frac{dn_1}{dt} = r_1(1 - \frac{n_1+n_2}{K_1})n_1$ and $\frac{dn_2}{dt} = r_2(1 - \frac{n_1+n_2}{K_2})n_2$ with $r_1 = r_2$ and $K_1 > K_2$. (b) The constant- N , relative fitness description of selection.

fragile than their adult counterparts (Turner and Williamson, 1968; Kimura and Crow, 1969; Nei, 1971). Selection can then be concentrated at the juvenile phase, uncoupling selection from population density at the adult phase unless it is so strong that the reproductive excess is depleted. This justifies Eq. (1) because, for a population in demographic equilibrium, selective sweeps do not affect density, and so the density-dependence of selection does not matter. Unfortunately this reproductive excess literature is also poorly integrated with population ecology. Kimura and Crow (1969) took constant N as a requirement and then derived some variants of the logistic model that satisfy this requirement. Nei (1971) proposed a model with an explicit representation of reproductive excess, but used an unusual model of competition based on pair-wise interactions which was only defined for at most two different types. As a result, the role of reproductive excesses in justifying Eq. (1) is still largely verbal.

Here we study the population ecology of relative fitness using a novel model of density-dependent population growth based on territorial contests. Rather than attempting to make

sense of relative fitness in existing standard models of population growth (e.g. (Kimura and Crow, 1969; Mallet, 2012)), we instead do the reverse, and attempt to make population ecological sense [BLAH]. Our starting point is the classic lottery model of territorial contest (Sale, 1977; Chesson and Warner, 1981). The classic lottery assumes a saturated population with constant N , and fitness involves a product of fertility and juvenile viability (Crow et al., 1970, pp. 185), [BLAH] generations can overlap. Our first task is to generalize the lottery model to create a variable-density version [BLAH] (sections “Model” and “Analytical approximation of the variable-density lottery”).

Equipped with this new model, we turn to the evaluation of Eq. (1). We first discuss selection on the ability to contest territories, which behaves like a pure constant- N , relative fitness trait, and discuss how this fits with MacArthur’s analysis of selection in crowded populations (section “ K -selection and selection-dependent density”). We then consider selection on density-regulating traits (section “Density-regulating traits and the threat of strong selection”), and conclude by contrasting the classical density-dependent selection literature with our results (“Discussion”).

Model

Assumptions and definitions

We assume that reproductively mature individuals (“adults”) require their own territory to survive and reproduce. All territories are identical, and the total number of territories is T . Time advances in discrete iterations, each representing the time from birth to reproductive maturity. In a given iteration, the number of adults of the i ’th type will be denoted by n_i , the total number of adults by $N = \sum_i n_i$, and the number of unoccupied territories by $U = T - N$. We assume that the n_i are large enough that stochastic fluctuations in the n_i (“drift”) can be ignored (with T also assumed large to allow for low type densities n_i/T).

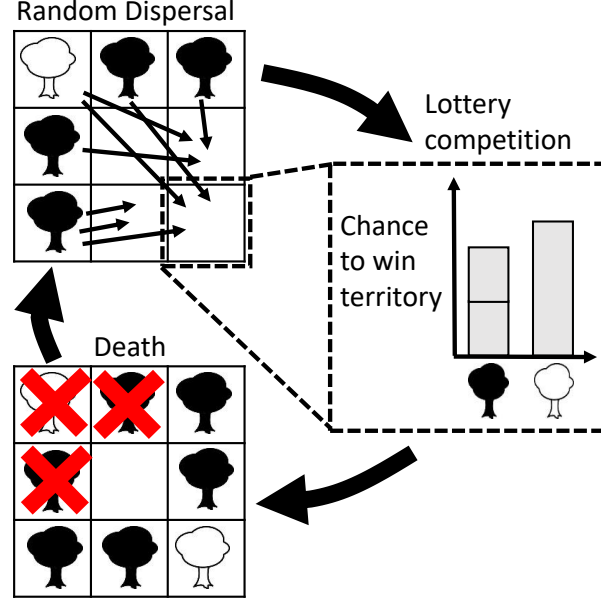


Figure 2: One iteration of our model. Propagules are dispersed by adults at random (only propagules landing on unoccupied territories are shown). Territories can receive zero propagules. Lottery competition then occurs in each territory that receives more than one propagule (only illustrated in one territory). In a given territory, each type has probability proportional to $c_i x_i$ of winning the territory, where c_i measures competitive ability and x_i is the number of i propagules present. In the illustrated territory, more black propagules are present, but white is a stronger competitor and has a higher probability of winning. Territories are made available for the next iteration by the death of adults present at the start of the iteration (red crosses).

Each iteration, adults produce propagules which disperse at random, independently of distance from their parents, and independently of each other. We assume that each adult from type i produces b_i propagules on average, so that the mean number of i propagules dispersing to unoccupied territories is $m_i = b_i n_i U / T$. The parameter b_i can be thought of as a measure of “colonization ability”, which combines fecundity and dispersal ability (Levins and Culver, 1971; Tilman, 1994). Random dispersal is then modeled using a Poisson distribution $p_i(x_i) = l_i^{x_i} e^{-l_i} / x_i!$ for the number x_i of i propagules dispersing to any particular unoccupied territory, where $l_i = m_i / U$ is the mean propagule density in unoccupied territories. The total propagule density will be denoted $L = \sum_i l_i$.

We assume that adults cannot be ousted by juveniles, so that recruitment to adulthood occurs exclusively in unoccupied territories. When multiple propagules land on the same unoccupied territory, the winner is determined by lottery competition: type i wins a territory with probability $c_i x_i / \sum_i c_i x_i$, where c_i is a constant representing relative competitive ability (Fig. 2). Since the expected fraction of unoccupied territories with propagule composition x_1, \dots, x_G is $p_1(x_1) \cdots p_G(x_G)$ where G is the number of types present, and type i is expected to win a proportion $c_i x_i / \sum_i c_i x_i$ of these, type i ’s expected territorial acquisition is given by

$$\Delta_+ n_i = U \sum_{x_1, \dots, x_G} \frac{c_i x_i}{\sum_i c_i x_i} p_1(x_1) \cdots p_G(x_G). \quad (2)$$

Here the sum only includes territories with at least one propagule present. Since we do not consider drift here, we will not analyze the fluctuations around these two expectations.

Adult mortality only occurs in adults present at the start of the iteration, and at a constant, type-specific per-capita rate $0 \leq d_i \leq 1$ (Fig. 2). This gives an overall change in type abundances of

$$\Delta n_i = \Delta_+ n_i - d_i n_i. \quad (3)$$

Connection to the classic lottery model

In the classic lottery model (Chesson and Warner, 1981), unoccupied territories are assumed to be saturated with propagules from every type ($l_i \rightarrow \infty$ for all i). From the law of large numbers, the composition of propagules in each territory will not deviate appreciably from the mean composition l_1, l_2, \dots, l_G . Type i is thus expected to win a proportion $c_i l_i / \sum_i c_i l_i$ of the U available territories,

$$\Delta_+ n_i = \frac{c_i l_i}{\sum_i c_i l_i} U = \frac{c_i l_i}{\bar{c} L} U, \quad (4)$$

where $\bar{c} = \sum_i c_i m_i / \sum_i m_i$ is the mean competitive ability for a randomly selected propagule. Note that all unoccupied territories are filled in a single iteration of the classic lottery model, whereas our more general model Eq. (2) allows for territories to be left unoccupied and hence also accommodates low propagule densities.

Results

Solving the variable-density lottery

Here we evaluate the expectation in Eq. (2) to better understand the dynamics of density-dependent lottery competition. Similarly to the classic lottery model, we replace the x_i , which take different values in different territories, with “effective” mean values. However, since we want to allow for low propagule densities, we cannot simply replace the x_i with the means l_i as in the classic lottery. For a low density type, growth comes almost entirely from territories with $x_i = 1$, for which its mean density $l_i \ll 1$ is not representative. We therefore separate Eq. (2) into $x_i = 1$ and $x_i > 1$ components, taking care to ensure that the effective mean approximations for these components are consistent with each other (details in Appendix B). The resulting variable-density approximation only requires that there are

no large discrepancies in competitive ability (i.e. we do not have $c_i/c_j \gg 1$ for any two types). We obtain

$$\Delta_+ n_i \approx \left[e^{-L} + (R_i + A_i) \frac{c_i}{\bar{c}} \right] l_i U, \quad (5)$$

where

$$R_i = \frac{\bar{c} e^{-l_i} (1 - e^{-(L-l_i)})}{c_i + \frac{\bar{c} L - c_i l_i}{L - l_i} \frac{L - 1 + e^{-L}}{1 - (1+L)e^{-L}}},$$

and

$$A_i = \frac{\bar{c} (1 - e^{-l_i})}{\frac{1 - e^{-l_i}}{1 - (1+l_i)e^{-l_i}} c_i l_i + \frac{\bar{c} L - c_i l_i}{L - l_i} \left(L \frac{1 - e^{-L}}{1 - (1+L)e^{-L}} - l_i \frac{1 - e^{-l_i}}{1 - (1+l_i)e^{-l_i}} \right)}.$$

Comparing Eq. (5) to Eq. (4), the classic lottery per-propagule success rate $c_i/\bar{c}L$ has been replaced by three separate terms. The first, e^{-L} , accounts for propagules which land alone on unoccupied territories; these propagules secure the territories without contest. The second, $R_i c_i/\bar{c}$, represents competitive victories on territories where only a single i propagule lands, and at least one other propagule from a different type (this term dominates the growth of a rare invader in a high density population and determines invasion fitness). The third term, $A_i c_i/\bar{c}$, represents competitive victories in territories where two or more i type propagules are present. The relative importance of these three terms varies with both the overall propagule density L and the relative propagule frequencies l_i/L . If $l_i \gg 1$ for all types, we recover the classic lottery model (only the $A_i c_i/\bar{c}$ term remains, and $A_i \rightarrow 1/L$).

Fig. 3 shows that Eq. (5) and its components closely approximate simulations of our variable-density lottery model over a wide range of propagule densities. Two types are present, one of which is at low frequency. The growth of the low-frequency type relies crucially on the low-density competition term $R_i c_i/\bar{c}$. On the other hand, $R_i c_i/\bar{c}$ is negligible for the high-frequency type, which depends instead on high density territorial victories. Fig. 3 also shows the breakdown of the classic lottery model at low propagule densities.

In the special case that all types are competitively equivalent (identical c_i), Eq. (5) takes

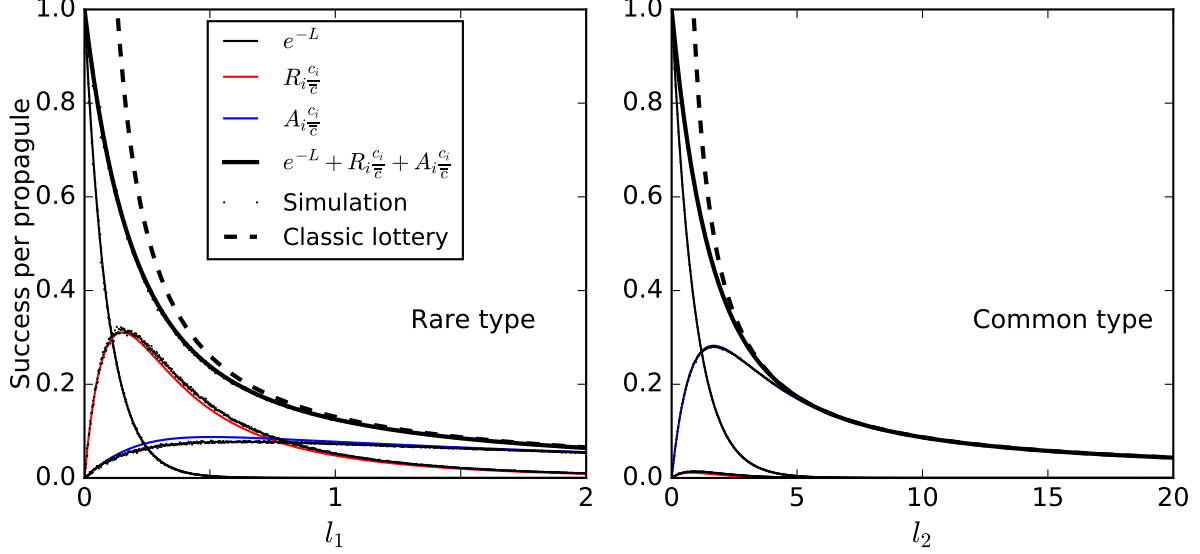


Figure 3: Comparison of Eq. (5), the classic lottery model, and simulations. The vertical axis is per-propagule success rate for all propagules $\Delta_+ n_i / m_i$, and for the three separate components in Eq. (5). Simulations are conducted as follows: x_1, \dots, x_G values are sampled U times from Poisson distributions with respective means l_1, \dots, l_G , and the victor in each territory is then decided by random sampling weighted by the lottery win probabilities $c_i x_i / \sum_j c_j x_j$. Two types are present, a rare type with $c_1 = 1.5$, and a common type with $c_2 = 1$. Simulation points are almost invisible for the common type due to near exact agreement with Eq. (5). Dashed lines show the breakdown of the classic lottery model. Parameters: $U = 10^5$ and $l_1/l_2 = 0.1$ is kept fixed while varying the total density L .

194 a simpler form,

$$\Delta_+ n_i = \frac{l_i}{L}(1 - e^{-L})U. \quad (6)$$

195 This formula can also be deduced directly from Eq. (2): $1 - e^{-L}$ is the fraction of territories
 196 that receive at least one propagule under Poisson dispersal, $(1 - e^{-L})U$ is the total number
 197 of such territories, and type i is expected to receive a fraction l_i/L of these. Total population
 198 density thus grows according to

$$\Delta N = (1 - e^{-L})U - \sum_i d_i n_i \quad (7)$$

199 **Density-dependent selection in the variable-density lottery**

200 We now outline the basic properties of selection on b , c and d . The birth and mortality rates
 201 b and d are the traits which regulate density; b controls the fraction of unoccupied territories
 202 that are contested, while d controls adult mortality. Competitive ability c does not regulate
 203 density since it only affects the relative likelihood for each type to win a contested territory.
 204 Thus, selection between types which only differ in c occurs without causing N to change
 205 (Eq. (7) shows this formally).

206 Selection in the variable density lottery model is density-dependent, by which we mean
 207 that the selection coefficient, measured by the difference in per-capita growth rate $\Delta n_i/n_i$
 208 between types, depends on N . Density-dependent selection is sometimes taken to mean a
 209 qualitative change in which types are fitter than others at different densities (Travis et al.,
 210 2013). While reversal in the order of fitnesses and co-existence driven by density-regulation
 211 are possible in the variable-density lottery (a special case of the competition-colonization
 212 trade-off; Levins and Culver 1971; Tilman 1994; Bolker and Pacala 1999), questions related
 213 to co-existence are tangential to our aims and will not be pursued further here.

214 Selection on c is density-dependent, with the strength of selection peaking at an interme-

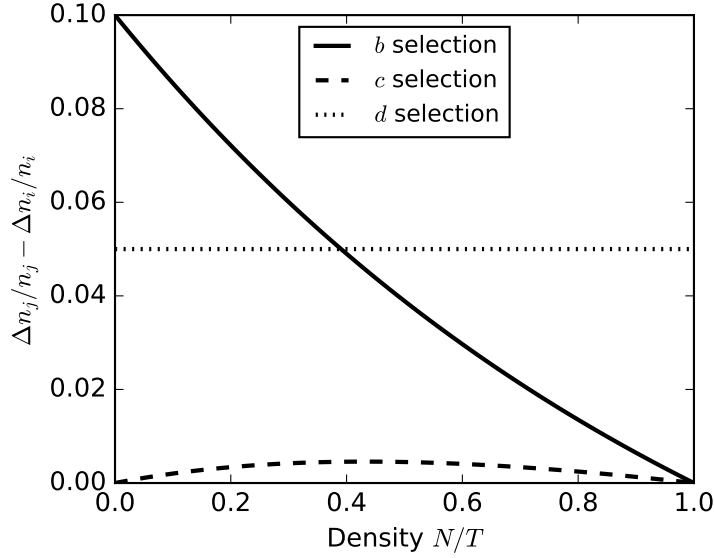


Figure 4: The density-dependence of selection in our variable-density lottery plotted as the difference in propagule success rate $\Delta n_j/n_j - \Delta n_i/n_i$ between an adaptive variant j and a wildtype i present at the same frequency. Here $b_i = 1$, $d_i = 0.5$ and $c_i = 1$. For b -selection we set $b_j = b_i(1 + \epsilon)$, and similarly for c and d , with $\epsilon = 0.1$. d -selection is density-independent, b -selection gets weaker with lower territorial availability, while c -selection initially increases with density as territorial contests become more important, but eventually also declines as available territories become scarce. The equilibrium density for the i type is ≈ 0.4 .

diate density (Fig. 4). This intermediate peak occurs because at low density most territories are claimed without contest, whereas at high density few unoccupied territories are available to be contested. To see how selection on b and d depend on density, we write Eq. (6) in the alternative form

$$\frac{\Delta n_i}{n_i} = \frac{b_i}{\bar{b}} \frac{1 - e^{-\bar{b}N/T}}{N} (T - N) - d_i, \quad (8)$$

where we have used that fact that $L = \bar{b}N/T$, and \bar{b} is the population mean b . It is clear d -selection is independent of density. On the other hand, the strength of b -selection declines with density due to the presence of the $T - N$ factor; in words, the advantage of having greater b gets smaller the fewer territories there are to be claimed (Fig. 4).

The response of density to selection; c -selection versus K -selection

We now turn to the issue of how density responds to selection, comparing the variable-density lottery and previous models of selection in density-regulated populations (Prout, 1980). Starting with some of the earliest work on the topic (Kostitzin, 1939; Christiansen, 2004), most previous models exhibit some form of “ K -selection” i.e. selection in crowded populations increases equilibrium density. This idea is intuitively appealing because births balance deaths at equilibrium, and adaptive mutants must overcome the existing balance to expand (Kostitzin, 1939, pp. 227). Yet, as we saw in the previous section, c -selection has no effect on population density in the variable-density lottery. To make sense of how c -selection fits with previous population growth models, we now revisit MacArthur’s general treatment of K -selection (MacArthur and Wilson, 1967).

MacArthur considered a population with two types that have densities n_1 and n_2 subject to density-dependent growth,

$$\frac{dn_1}{dt} = f_1(n_1, n_2) \quad \frac{dn_2}{dt} = f_2(n_1, n_2). \quad (9)$$

The environment is assumed to remain constant apart from changing type densities. The functions f_1 and f_2 must decline to zero if n_1 or n_2 are sufficiently large, because the resources required for growth are limited. This defines nullclines $f_1(n_1, n_2) = 0$ and $f_2(n_1, n_2) = 0$ in (n_1, n_2) space. The outcome of selection is then determined by the relationship between these nullclines. Specifically, a type will be excluded if its nullcline is completely contained in the region bounded by the other type’s nullcline. Thus, for a type to have the possibility of persisting, it must be able to keep growing to higher densities than the other type can tolerate in some region of (n_1, n_2) space (Fig. 1a).

MacArthur used “ K ” to label the four intersection points of the nullclines with the axes, specifically $f_1(K_{11}, 0) = 0$, $f_1(0, K_{12}) = 0$, $f_2(K_{21}, 0) = 0$ and $f_2(0, K_{22}) = 0$. These K values

determine whether a region of higher-density growth exists for each type, provided that the nullclines are close to being straight lines. Note that only K_{11} and K_{22} are equilibrium densities akin to the K parameter in the logistic model (Fig. 1a). The other intersection points, K_{12} and K_{21} , are related to competition between types. To be more concrete, in the Lotka-Volterra competition model we have

$$\begin{aligned} f_1(n_1, n_2) &= r_1(1 - \alpha_{11}n_1 - \alpha_{12}n_2)n_1 \\ f_2(n_1, n_2) &= r_2(1 - \alpha_{22}n_1 - \alpha_{21}n_2)n_2 \end{aligned} \tag{10}$$

where $\alpha_{11} = 1/K_{11}$ and $\alpha_{22} = 1/K_{22}$ measure competitive effects within types, while $\alpha_{12} = 1/K_{12}$ and $\alpha_{21} = 1/K_{21}$ measure competitive effects between types. Hence, “fitness is K ” in crowded populations (MacArthur and Wilson, 1967, pp. 149) in the sense that selection either favors the ability to keep growing at ever higher densities (moving a type’s own nullcline outwards), or the ability to suppress the growth of competitors at lower densities (moving the nullcline of competitors inwards). This general idea is much broader than selection for greater equilibrium density (Gill, 1974).

Compared to simple birth-death models (Kostitzin, 1939) or variants of the logistic (Roughgarden, 1979), the Lotka-Volterra model clearly distinguishes between intra- and inter-type competitive effects. Thus, one type can displace another without having a greater equilibrium density (Fig. 5a). Nevertheless, selection drives transient changes in density in the Lotka-Volterra model even if the initial and final densities of a sweep are the same (constant density only occurs for a highly restricted subset of r and α values; further details in Appendix C; also see Mallet 2012; Smouse 1976). Intuitively, for one type to exclude the other, competitive suppression of growth between types must be stronger than competitive suppression of growth within types, causing N to dip over a sweep (Fig. 5a).

By contrast, density trajectories for c -selection in the variable-density lottery converge

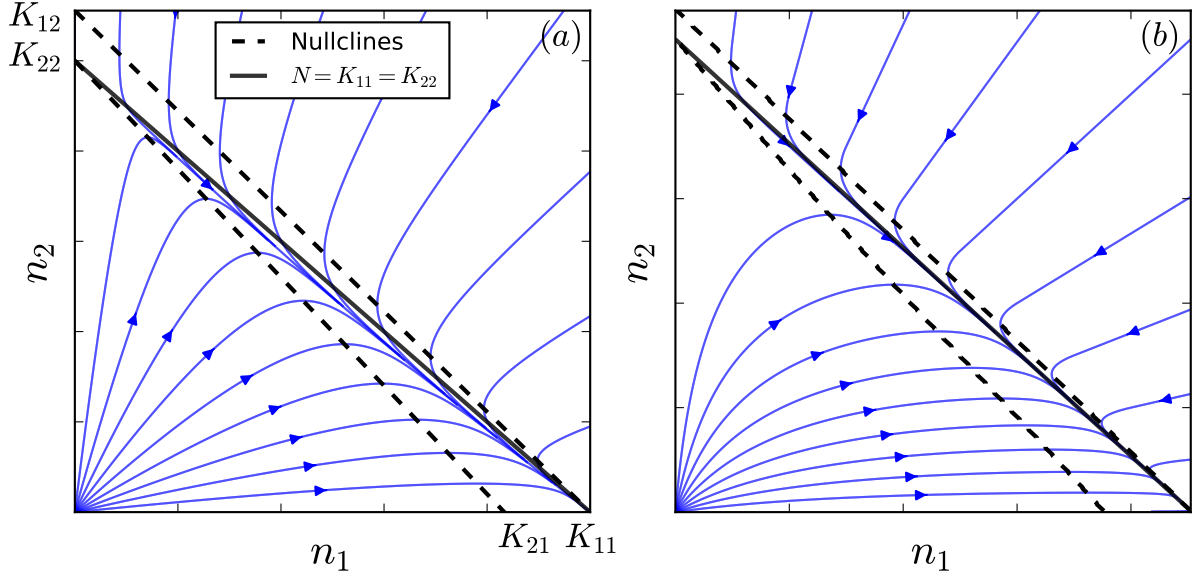


Figure 5: Selection between types with identical equilibrium density but different inter-type competitive ability. (a) Lotka-Volterra competition (Eq. 10) with $r_1 = r_2 = 1$, $\alpha_{11} = \alpha_{22} = 1$, $\alpha_{12} = 0.9$ and $\alpha_{21} = 1.2$. Trajectories do not follow the line $N = K_{11} = K_{22}$. (b) Lottery competition (Eq. 5) with $b_1 = b_2 = 5$, $d_1 = d_2 = 0.1$ and $c_1/c_2 = 5$. Trajectories converge on the line $N = K_{11} = K_{22}$.

on a line of constant equilibrium density (Fig. 5b). This means that once the population reaches demographic equilibrium, it behaves indistinguishably from a constant- N relative fitness model (Fig. 1b). This complete uncoupling of density from c -selection arises due to the presence of an excess of propagules which pay the cost of selection without affecting adult density. As a result, Eq. (1) holds in equilibrium even though c -selection is density-dependent. We discuss the non-equilibrium case in [BLAH].

Density-dependent selection on density-regulating traits

The previous section underscores the fact that density must be affected by ongoing selection to threaten Eq. (1). We now turn to selection on density-regulating traits such as b and d in the variable density lottery.

As shown in Fig. 4, d -selection is independent of density; the selection coefficient for a d -variant with $d_j = d_i(1 - \epsilon)$ is a constant $s = \epsilon d_i$. Thus, to threaten the constant- s assumption in an equilibrium population we require selection to act on a trait that is both density-dependent and density-regulating.

This is the case for b in the variable-density lottery. However, before we discuss this relatively complicated trait, it is helpful to summarize the threat to Eq. (1) in simpler models of density-regulated growth, as exemplified by the birth-death model (Kostitzin, 1939)

$$\frac{dn_i}{dt} = (b_i - \delta_i N)n_i. \quad (11)$$

Here δ_i is per-capita mortality due to crowding (for simplicity, there are no deaths when uncrowded). Starting from a type i population in equilibrium (we consider the non-equilibrium case in BLAH), a variant with $\delta_j = \delta_i(1 - \epsilon)$ has density-dependent selection coefficient $s = \epsilon \delta_i N$ in Eq. (1). This only affects the sweep if N changes substantially as the population shifts to the new j type equilibrium. From Eq. (11) we have $N_{\text{initial}} = b_i/\delta_i$ and

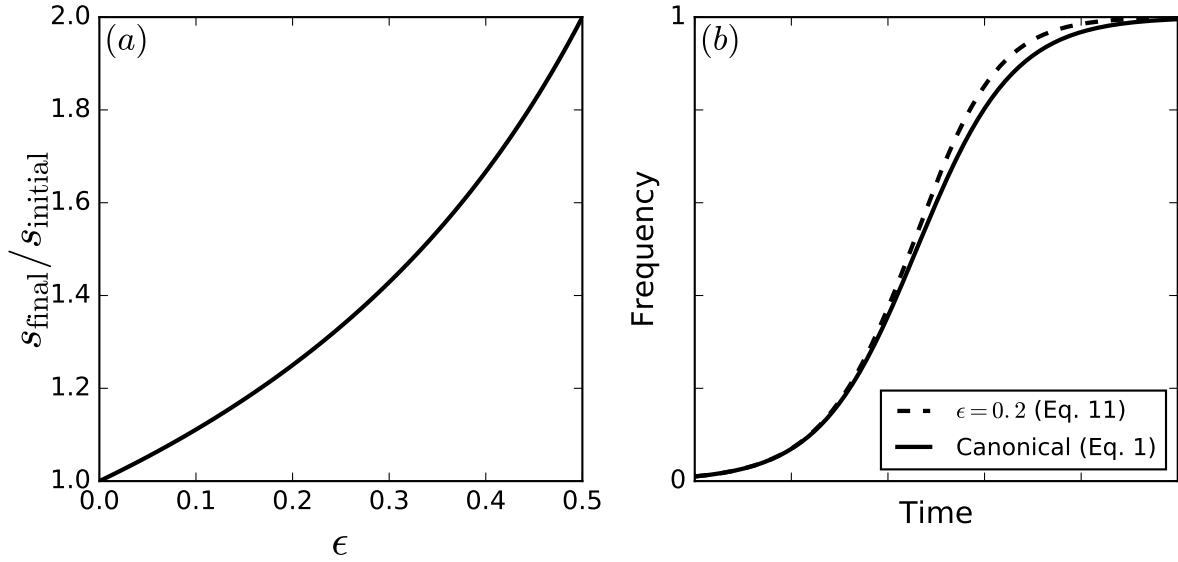


Figure 6: (a) Proportional change in the selection coefficient for a type that experiences proportionally $1 - \epsilon$ fewer deaths induced by crowding. The population is in demographic equilibrium at the start and end of the sweep. (b) Example equilibrium-to-equilibrium sweep.

283 $N_{\text{final}} = b_i/(\delta_i(1 - \epsilon)) = N_{\text{initial}}/(1 - \epsilon)$, and so $s_{\text{initial}} = \epsilon b_i$ and $s_{\text{final}} = s_{\text{initial}}/(1 - \epsilon)$. Con-
 284 sequently, substantial deviations from Eq. (1) requires strong selection on δ (Fig. 6; Kimura
 285 and Crow 1969; Crow et al. 1970).

286 At first glance, b in Eq. (8) appears to be analogous to the δ in Eq. (11) because it regulates
 287 density and is multiplied by the density-dependent term $f(\bar{b}, N) = \frac{1 - e^{-\bar{b}N/T}}{N}(T - N)$. However,
 288 equilibrium-to-equilibrium b -sweeps are qualitatively different from δ sweeps. The reason is
 289 that b is not a simple per-capita birth rate. Greater b means more propagules contesting
 290 territories, but also more territories being contested. The net effect on $f(\bar{b}, N)$ is precisely
 291 zero in equilibrium: in a single-type equilibrium we have $b_i/\bar{b} = 1$ and so $f(\bar{b}, N) = d_i$
 292 exactly at the beginning and end of a b -sweep, even though N increases. Strictly speaking
 293 there is some deviation in $f(\bar{b}, N)$ from d_i during the sweep, but this deviation is an order
 294 of magnitude smaller than for a δ sweep (deviation from Eq. (1) in Fig. 6 is of order ϵ ,
 295 whereas the analogous effect for b sweep in the variable-density lottery is only of order ϵ^2 ;

see Appendix D for details). Since selection must already be quite strong for a δ -sweep to threaten Eq. (1), the constant- s model effectively applies exactly for equilibrium b -sweeps.

Discussion

Summarizing the three traits in the variable-density lottery model: (i) c -selection is density-dependent, but c does not regulate density; (ii) d regulates density, but d -selection is density-independent; (iii) b regulates density and b -selection is density-dependent. This rich variety of behaviors in relation to density is quite different from that found in the classical density-dependent selection literature (Roughgarden, 1979; Christiansen, 2004). Yet despite these differences, pure b , c and d sweeps starting and ending at equilibrium all obey the canonical constant- s relative fitness description of selection.

To briefly review: based on a diploid, bi-allelic variant of the logistic model, the r/K scheme proposed a dichotomy between r -selection (uncrowded) and K -selection (crowded) (MacArthur, 1962), with the latter taken to mean selection for greater equilibrium density (Gill, 1974). A more general Lotka-Volterra model introduces the inter-type α_{ij} competition coefficients, with selection on these termed “ α -selection” (Gill, 1974; Joshi et al., 2001). Setting aside r which confers no selective advantage at equilibrium, we are left with K and α , which both behave like δ in Eq. (11) in that they are density-dependent and cause density to change over a sweep (although N only dips transiently during an α -sweep). Thus, strong selection is sufficient for relative fitness to break down in the classical view of density-dependent selection. Indeed, in the defense of Eq. (1) given by Kimura and Crow (1969), it was assumed that s will be a few percent at most. While this may be reasonable for adaptive mutations, there is no reason to expect selection on standing variation to be so weak, wild *Drosophila* being an obvious counter-example (Bergland et al., 2014).

Our variable-density lottery model shows that it is not simply a lack of ecological re-

alism that underlies the contrast between relative fitness and the classical view of density-dependent selection. Rather, in many population growth models, only one life-history stage is represented, and the competitive effects resulting from crowding appear as a reduction in absolute fitness that only depends on the type densities at this life-history stage (e.g. the n_i^2 and $n_i n_j$ terms in the Lotka Volterra equation). As noted in the introduction, this precludes selection concentrated at a fragile juvenile stage as a result of a reproductive excess (Chesson, 1983; Turner and Williamson, 1968; Kimura and Crow, 1969; Nei, 1971).

Reproductive excesses appear in the variable-density lottery model when the number of propagules is greater than the number of available territories. Then only $\approx 1/L$ of the juveniles contesting available territories survive to adulthood. Unlike the role of adult density n_i in single-life-stage models, it is the propagule densities l_i that represent the crowding that drives competition (a “critical age-group”; Charlesworth 1994, pp. 54). In general, reproductive excesses will tend to produce strictly-relative lottery-type contests in which fitter types grow at the expense of others by preferentially filling the available adult “slots”. The number of slots can remain fixed or change independently of selection at the juvenile stage. By ignoring reproductive excesses, single life-stage models are biased to have total population density be sensitive to ongoing selection. In this respect, the viability selection heuristics that are common in population genetics (Gillespie, 2010, pp. 61) actually capture an important ecological process.

We now turn to the breakdown of Eq. (1). We first discuss the problem shown in Fig. 6, which occurs when strong selection changes population density and is also density-dependent. In the variable-density lottery, this occurs if and only if types differ in more than one trait. The c and d traits represent the two distinct directions in which density and selection interact: selection may depend on density, and density may depend on selection (Prout, 1980). The combination is necessary to pose a threat to Eq. (1). However, the b trait remarkably demonstrates that the combination is not sufficient, since the density-dependence of

b -selection disappears over equilibrium-to-equilibrium b -sweeps. Thus, the simple linear models that have become standard in discussions of density-dependent selection (Roughgarden, 1979; Christiansen, 2004; Mallet, 2012; Travis et al., 2013) actually represent a complicated form of the interaction between density and selection, and their parameters confound the underlying issues.

While this is a conceptual reason to be wary of the classical density-dependent selection models, it is not clear how we should expect the trait variation in nature to align. For instance, should we expect mutations to generally affect b , c and d independently of each other, or pleiotropically such that δ -like selection is prevalent? In the case of well-mixed indirect exploitation competition for consumable resources, the R^* rule suggests that δ -like selection will be prevalent. However, for many populations consumable resources are not well-mixed. Spatial localization of consumable resources (e.g. due to restricted movement of nutrients through soils) will tend to create a territorial situation similar to the lottery model, where resource competition only occurs locally and both it and interference competition are subsumed into the competitive ability c , which does not affect N .

Relative fitness models truly break down when N is far from equilibrium and selection is density-dependent (as seems likely; Travis et al. 2013). For example, wild *Drosophila* experience large seasonal boom-bust cycles in population density coupled to strong selection that drives large swings in allele frequency (Bergland et al., 2014). In this case there is no choice but to abandon relative fitness, and our model provides one potentially suitable option. Whether or not our density-dependent lottery model is a good description of *Drosophila* ecology, the close connection between our model and Wright-Fisher is useful [BLAH], because drift in our model should behave broadly similarly. Thus, our model should provide a useful starting point for analyzing evolution in this and other far-from-equilibrium situations.

Another issue with the constant- N relative fitness description of selection is that it precludes consideration of longer-term aspects of the interplay between evolution and ecology

such as population extinction. A variety of approaches have been developed for dealing with these issues in quantitative genetics (Burger and Lynch, 1995; Engen et al., 2013), population genetics (Bertram et al., 2017) and adaptive dynamics (Ferriere and Legendre, 2013; Dieckmann and Ferrière, 2004). Although density-dependent selection is pertinent to these longer-term issues (Travis et al., 2013), our focus here has been the description of the time-dependent process by which selection changes allele frequencies. This is particularly critical for making sense of evolution at the genetic level, for which we now have abundant data.

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461 Appendix A: Growth equation derivation

462 In this appendix we derive Eq. (5). Following the notation in the main text, the Poisson
 463 distributions for the x_i (or some subset of the x_i) will be denoted p , and we use P as a
 464 general shorthand for the probability of particular outcomes.

465 We start by separating the right hand side of Eq. (2) into three components

$$\Delta_+ n_i = \Delta_u n_i + \Delta_r n_i + \Delta_a n_i, \quad (12)$$

466 which vary in relative magnitude depending on the propagule densities l_i . The first compo-
 467 nent, $\Delta_u n_i$, accounts for territories where only one focal propagule is present ($x_i = 1$ and
 468 $x_j = 0$ for $j \neq i$; u stands for “uncontested”). The proportion of territories where this occurs
 469 is $l_i e^{-L}$, and so

$$\Delta_u n_i = U l_i e^{-L} = m_i e^{-L}. \quad (13)$$

470 The second component, $\Delta_r n_i$, accounts for territories where a single focal propagule is
 471 present along with at least one non-focal propagule ($x_i = 1$ and $X_i \geq 1$ where $X_i = \sum_{j \neq i} x_j$
 472 is the number of nonfocal propagules; r stands for “rare”). The number of territories where
 473 this occurs is $U p_i(1) P(X_i \geq 1) = m_i e^{-l_i} (1 - e^{-(L-l_i)})$. Thus

$$\Delta_r n_i = m_i e^{-l_i} (1 - e^{-(L-l_i)}) \left\langle \frac{c_i}{c_i + \sum_{j \neq i} c_j x_j} \right\rangle_{\tilde{p}}, \quad (14)$$

474 where $\langle \rangle_{\tilde{p}}$ denotes the expectation with respect to the probability distribution \tilde{p} of nonfocal

475 propagule abundances x_j , in those territories where exactly one focal propagule, and at least
 476 one non-focal propagule, landed.

477 The final contribution, $\Delta_a n_i$, accounts for territories where two or more focal propagules
 478 are present ($x_i \geq 2$; a stands for “abundant”). Similar to Eq. (14), we have

$$\Delta_a n_i = U(1 - (1 + l_i)e^{-l_i}) \left\langle \frac{c_i x_i}{\sum_j c_j x_j} \right\rangle_{\hat{p}} \quad (15)$$

479 where \hat{p} is the probability distribution of both focal and nonfocal propagule abundances in
 480 those territories where at least two focal propagules landed.

481 To derive Eq. (5) we approximate the expectations in Eq. (14) and Eq. (15) by replacing
 482 x_i and the x_j with “effective” mean values as follows

$$\left\langle \frac{c_i}{c_i + \sum_{j \neq i} c_j x_j} \right\rangle_{\hat{p}} \approx \frac{c_i}{c_i + \sum_{j \neq i} c_j \langle x_j \rangle_{\tilde{q}}}. \quad (16)$$

483

$$\left\langle \frac{c_i x_i}{\sum_j c_j x_j} \right\rangle_{\hat{p}} \approx \frac{c_i \langle x_i \rangle_{\hat{q}}}{\sum_j c_j \langle x_j \rangle_{\hat{q}}}. \quad (17)$$

484 Here the effective means $\langle \rangle_{\tilde{q}}$ and $\langle \rangle_{\hat{q}}$ are taken with respect to new distributions \tilde{q} and \hat{q} ,
 485 respectively. In the following subsection we define \tilde{q} and \hat{q} and explain our reasoning for
 486 using these distributions to take the effective means.

487 The effective distributions \tilde{q} and \hat{q}

488 The approximations (16) and (17) must be consistent between rare and common types. To
 489 illustrate, suppose that two identical types (same b , c and d) are present, with low $l_1 \ll 1$
 490 and high density $l_2 \approx L \gg 1$ respectively. Since L is large, uncontested territories make
 491 up a negligible fraction of the total. The rare type grows almost entirely due to $\Delta_r n_1$,
 492 while the common type grows almost entirely due to $\Delta_a n_2$. To ensure consistency, the ap-

proximate per-capita growth rates implied by the approximations (16) and (17) must be equal $\Delta_r n_1/m_1 = \Delta_a n_2/m_2$. Even small violations of this consistency condition would mean exponential growth of one type relative to the other. This behavior is clearly pathological, because any single-type population can be arbitrarily partitioned into identical rare and common subtypes. Thus, predicted growth or decline would depend on an arbitrary assignment of rarity.

For example, suppose that we use \tilde{p} and \hat{p} to calculate the effective means. The right hand side of Eq. (16) is then approximately $1/(L+1)$, and since $l_1 \ll 1$ and $L \gg 1$ we have $\Delta_r n_1 \approx 1/(L+1)$ in Eq. (14). Similarly, for the common type, $\sum_j \langle x_j \rangle_{\hat{p}} = L$ in Eq. (17), and so $\Delta_a n_2 \approx 1/L$. Thus, the identical rare type is pathologically predicted to decline in frequency.

The effective distributions \tilde{q} and \hat{q} are devised to avoid this pathology. The idea is to make the approximation that the distribution for the total number of propagules per territory is the same in all territories. This is only an approximation because conditioning on focal propagules being present does change the distribution of X in the corresponding subset of territories (in the above example, the mean propagule density across all territories is L , but in the territories responsible for the growth of the rare type we have $\langle X \rangle_{\tilde{p}} = L+1$).

More formally, let \mathbf{x} denote the vector of propagule abundances (x_1, \dots, x_G) in a given territory, and $\mathbf{x}_i = (x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_G)$ similarly denote the vector of non-focal abundances, so that $p(\mathbf{x}_i) = p_1(x_1) \cdots p_{i-1}(x_{i-1}) p_{i+1}(x_{i+1}) \cdots p_G(x_G)$. The corresponding total propagule numbers are denoted $X = \sum_j x_j$ and $X_i = X - x_i$. Then, in territories where one focal propagule and at least one non-focal propagule are present, the effective distribution is defined by

$$\tilde{q}(\mathbf{x}_i) = \sum_{X=2}^{\infty} P(X|X \geq 2) p(\mathbf{x}_i | X_i = X - 1), \quad (18)$$

where the total number of propagules X follows a Poisson distribution with mean L , and

517 $P(X|X \geq 2) = P(X)/P(X \geq 2) = P(X)/(1 - (1 + L)e^{-L})$. Similarly, in territories where
 518 more than one focal propagule is present, the effective distribution is defined by

$$\hat{q}(\mathbf{x}) = \sum_{X=2}^{\infty} P(X|X \geq 2)p(\mathbf{x}|x_i \geq 2, X). \quad (19)$$

519 Calculating the effective means

Here we calculate the effective means, starting with the $\Delta_r n_i$ component. We have

$$\begin{aligned} \langle x_j \rangle_{\tilde{q}} &= \sum_{\mathbf{x}_i} \tilde{q}(\mathbf{x}_i) x_j \\ &= \frac{1}{1 - (1 + L)e^{-L}} \sum_{X=2}^{\infty} P(X) \sum_{\mathbf{x}_i} p(\mathbf{x}_i|X_i = X - 1) x_j. \end{aligned} \quad (20)$$

The inner sum over \mathbf{x}_i is the mean number of propagules of a given nonfocal type j that will be found in a territory which received $X - 1$ nonfocal propagules in total, which is equal to $\frac{l_j}{L - l_i}(X - 1)$. Thus,

$$\begin{aligned} \langle x_j \rangle_{\tilde{q}} &= \frac{l_j}{1 - (1 + L)e^{-L}} \frac{1}{L - l_i} \sum_{X=2}^{\infty} P(X)(X - 1) \\ &= \frac{l_j}{1 - (1 + L)e^{-L}} \frac{L - 1 + e^{-L}}{L - l_i}, \end{aligned} \quad (21)$$

520 where the last line follows from $\sum_{X=2}^{\infty} P(X)(X - 1) = \sum_{X=1}^{\infty} P(X)(X - 1) = \sum_{X=1}^{\infty} P(X)X -$
 521 $\sum_{X=1}^{\infty} P(X)$. Substituting Eqs. (16) and (21) into Eq. (14), we obtain

$$\Delta_r n_i \approx m_i R_i \frac{c_i}{\bar{c}}, \quad (22)$$

522 where R_i is defined in Eq. (6).

Turning now to the $\Delta_a n_i$ component, the mean focal abundance is

$$\begin{aligned}
\langle x_i \rangle_{\hat{q}} &= \sum_{\mathbf{x}} \hat{q}(\mathbf{x}) x_i \\
&= \sum_{x_i} p(x_i | x_i \geq 2) x_i \\
&= \frac{1}{1 - (1 + l_i) e^{-l_i}} \sum_{x_i \geq 2} p(x_i) x_i \\
&= l_i \frac{1 - e^{-l_i}}{1 - (1 + l_i) e^{-l_i}}.
\end{aligned} \tag{23}$$

For nonfocal types $j \neq i$, we have

$$\begin{aligned}
\langle x_j \rangle_{\hat{q}} &= \sum_{X=2}^{\infty} P(X | X \geq 2) \sum_{\mathbf{x}} p(\mathbf{x} | x_i \geq 2, X) x_j \\
&= \sum_{X=2}^{\infty} P(X | X \geq 2) \sum_{x_i} p(x_i | x_i \geq 2, X) \sum_{\mathbf{x}_i} p(\mathbf{x}_i | X_i = X - x_i) x_j \\
&= \sum_{X=2}^{\infty} P(X | X \geq 2) \sum_{x_i} p(x_i | x_i \geq 2, X) \frac{l_j (X - x_i)}{L - l_i} \\
&= \frac{l_j}{L - l_i} \left[\sum_{X=2}^{\infty} P(X | X \geq 2) X - \sum_{x_i} p(x_i | x_i \geq 2) x_i \right] \\
&= \frac{l_j}{L - l_i} \left(L \frac{1 - e^{-L}}{1 - (1 + L) e^{-L}} - l_i \frac{1 - e^{-l_i}}{1 - (1 + l_i) e^{-l_i}} \right).
\end{aligned} \tag{24}$$

523 In going from line 2 to 3, we used the same logic used to evaluate the inner sum in Eq. (20),
524 and in going from 3 to 4 we have separately evaluated the contributions from the X and x_i
525 terms in the numerator. Combining these results with Eqs. (15) and (17), we obtain

$$\Delta_a n_i = m_i A_i \frac{c_i}{\bar{c}}, \tag{25}$$

526 where A_i is defined in Eq. (6).

Approximation limits

Eq. (16) and (17) must not only be consistent with each other, they must also be individually good approximations. Here we evaluate these approximations.

The fundamental requirement for making the replacement in Eqs. (16) and (17) is that we can ignore the fluctuations in the x_i and hence replace them with a constant effective mean value. Mathematically, we require that the standard deviations $\sigma_{\tilde{q}}(\sum_{j \neq i} c_j x_j)$ and $\sigma_{\hat{q}}(\sum_j c_j x_j)$ must be sufficiently small compared to the corresponding means $\langle \sum_{j \neq i} c_j x_j \rangle_{\tilde{q}}$ and $\langle \sum_j c_j x_j \rangle_{\hat{q}}$ in Eqs. (16) and (17) respectively.

To evaluate these standard deviations, we will work with \tilde{p} and \hat{p} distributions instead of \tilde{q} and \hat{q} . This is mathematically much simpler because the x_i are independent under \tilde{p} and \hat{p} , and is justified by the fact that \tilde{p} and \hat{p} are closely related to \tilde{q} and \hat{q} respectively, and so we expect the relevant means and standard deviations will be similar.

Starting with Eq. (16), we have $\langle x_j \rangle_{\tilde{p}} = l_j/C$, where $C = 1 - e^{-(L-l_i)}$, and the corresponding variances and covariances are given by

$$\begin{aligned} \sigma_{\tilde{p}}^2(x_j) &= \langle x_j^2 \rangle_{\tilde{p}} - \langle x_j \rangle_{\tilde{p}}^2 \\ &= \frac{l_j^2 + l_j}{C} - \frac{l_j^2}{C^2} \\ &= \left(1 - \frac{1}{C}\right) \frac{l_j^2}{C} + \frac{l_j}{C}, \end{aligned} \tag{26}$$

and

$$\begin{aligned} \sigma_{\tilde{p}}(x_j, x_k) &= \langle x_j x_k \rangle_{\tilde{p}} - \langle x_j \rangle_{\tilde{p}} \langle x_k \rangle_{\tilde{p}} \\ &= \frac{1}{C} \langle x_j x_k \rangle_p - \frac{l_j l_k}{C^2} \\ &= \left(1 - \frac{1}{C}\right) \frac{l_j l_k}{C} \quad j \neq k. \end{aligned} \tag{27}$$

539 Note that $1 - 1/C$ is negative because $C < 1$. Decomposing the variance in $\sum_{j \neq i} c_j x_j$,

$$\sigma_{\hat{p}}^2(\sum_{j \neq i} c_j x_j) = \sum_{j \neq i} \left[c_j^2 \sigma_{\hat{p}}^2(x_j) + 2 \sum_{k > j, k \neq i} c_j c_k \sigma_{\hat{p}}(x_j, x_k) \right], \quad (28)$$

540 we obtain

$$\frac{\sigma(\sum_{j \neq i} c_j x_j)}{\langle \sum_{j \neq i} c_j x_j \rangle} = C^{1/2} \frac{\left(\sum_{j \neq i} c_j^2 l_j + (1 - \frac{1}{C}) \left(\sum_{j \neq i} c_j l_j \right)^2 \right)^{1/2}}{\sum_{j \neq i} c_j l_j}. \quad (29)$$

541 Eq. (29) reveals two key points. First, when the c_j have similar magnitudes (their ratios
 542 are of order one), Eq. (16) is an excellent approximation. In this case, the right hand side of
 543 Eq. (29) is approximately equal to $C^{1/2} \left(\frac{1}{L-l_i} + 1 - \frac{1}{C} \right)^{1/2}$, which is small for both low and
 544 high nonfocal densities. The worst case scenario occurs when $L - l_i$ is of order one, and it
 545 can be directly verified that Eq. (16) is then still a good approximation (see Fig. 7). Second,
 546 if some of the c_j are much larger than the others, the relative fluctuations in $\sum_{j \neq i} c_j x_j$ can
 547 be large. Specifically, in the presence of a rare, strong competitor ($c_j l_j \gg c_{j'} l_{j'}$ for all other
 548 nonfocal types j' , and $l_j \ll 1$), then the right hand side of Eq. (29) can be large and we
 549 cannot make the replacement Eq. (16). Fig. 7 shows the breakdown of the effective mean
 550 approximation when there are large differences in c .

551 Turning now to Eq. (17), all covariances between nonfocal types are now zero, so that
 552 $\sigma_{\hat{p}}^2(\sum c_j x_j) = \sum c_j^2 \sigma_{\hat{p}}^2(x_j)$, where $\sigma_{\hat{p}}^2(x_j) = l_j$ for $j \neq i$. Here

$$\sigma_{\hat{p}}^2(x_i) = \frac{l_i}{D} \left(l_i + 1 - e^{-l_i} - \frac{l_i}{D} (1 - e^{-l_i})^2 \right), \quad (30)$$

553 where $D = 1 - (1 + l_i)e^{-l_i}$, and

$$\frac{\sigma_{\hat{p}}(\sum c_j x_j)}{\langle \sum c_j x_j \rangle} = \frac{\left(\sum_{j \neq i} c_j^2 l_j + c_i^2 \sigma_{\hat{p}}^2(x_i) \right)^{1/2}}{\sum_{j \neq i} c_j l_j + c_i l_i (1 - e^{-l_i})/D}. \quad (31)$$

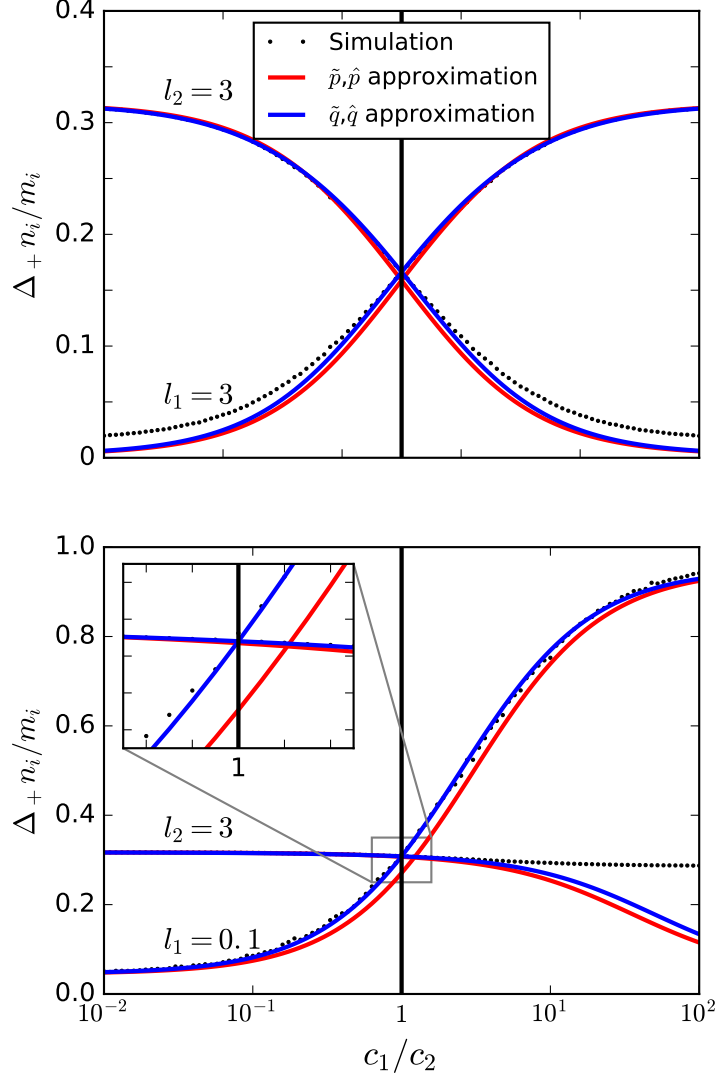


Figure 7: Comparison of our \tilde{q}, \hat{q} approximation with simulations, and also with the naive \tilde{p}, \hat{p} approximation, as a function of the relative c difference between two types. Our approximation breaks down in the presence of large c differences. The inset shows the pathology of the \tilde{p}, \hat{p} approximation — growth rates are not equal in the neutral case $c = 1$. Simulation procedure is the same as in Fig. 3, with $U = 10^5$.

Similarly to Eq. (29), the right hand side of Eq. (31) is small for both low and high nonfocal densities. Again, the worst case scenario occurs when l_i and $L - l_i$ are of order 1, but Eq. (17) is still a good approximation in this case. Again, the approximation breaks down in the presence of a rare, strong competitor (Fig. 7).

Appendix B: Total density in the Lotka-Volterra competition model

Here we show that under the Lotka-Volterra model of competition, total density N does not in general remain constant over a selective sweep in a crowded population even if the types have the same equilibrium density (for a related discussion on the density- and frequency-dependence of selection in the Lotka-Volterra model, see (Smouse, 1976; Mallet, 2012)).

We assume equal effects of crowding within types $\alpha_{11} = \alpha_{22} = \alpha_{\text{intra}}$ and $N = 1/\alpha_{\text{intra}}$ and check whether it is then possible for $\frac{dN}{dt}$ to be zero in the sweep ($n_1, n_2 \neq 0$). Substituting these conditions into Eq. (10), we obtain

$$\begin{aligned}\frac{dn_1}{dt} &= r_1(\alpha_{11} - \alpha_{12})n_1n_2 \\ \frac{dn_2}{dt} &= r_2(\alpha_{22} - \alpha_{21})n_1n_2\end{aligned}\tag{32}$$

Adding these together, $\frac{dN}{dt}$ can only be zero if

$$r_1(\alpha_{\text{intra}} - \alpha_{12}) + r_2(\alpha_{\text{intra}} - \alpha_{21}) = 0.\tag{33}$$

To get some intuition for Eq. (33), suppose that a mutant arises with improved competitive ability but identical intrinsic growth rate and equilibrium density ($r_1 = r_2$ and $\alpha_{11} = \alpha_{22}$). This could represent a mutation to an interference competition trait, for example (Gill,

1974). Then, according the above condition, for N to remain constant over the sweep, the mutant must find the wildtype more tolerable than itself by exactly the same amount that the wildtype finds the mutant less tolerable than itself.

Even if we persuaded ourselves that this balance of inter-type interactions is plausible in some circumstances, when multiple types are present the requirement for constant N becomes

$$\sum_{ij} r_i(\alpha_{\text{intra}} - \alpha_{ij})p_i p_j = 0, \quad (34)$$

which depends on frequency and thus cannot be satisfied in general for constant inter-type coefficients α_{ij} . Therefore, Lotka-Volterra selection will generally involve non-constant N .

Appendix C: Density-dependence of b -selection

In section “Density-regulating traits and the threat of strong selection” we argued that the density-dependent factor $f(\bar{b}, N)$ is unchanged at the beginning and end points of an equilibrium-to-equilibrium b . Here we estimate the magnitude of the deviation in $f(\bar{b}, N)$ during the sweep.

For simplicity, we introduce the notation $D = N/T$ and assume that D is small. We can thus make the approximation $1 - e^{-\bar{b}D} \approx \bar{b}D$ and $f(\bar{b}, N) \approx \bar{b}(1 - D)$. We expect this to be a conservative approximate based on the worst case scenario, because N is most sensitive to an increase in b in this low-density linear regime. We first calculate the value of $f(\bar{b}, N)$ at the halfway point in a sweep, where the halfway point is estimated with simple linear averages for b and N . The sweep is driven by a b variant with $b_j = b_i(1 + \epsilon)$, and we denote the corresponding initial and final densities by D_i and D_j respectively, where we

have $d_i = b_i(1 - D_i) = b_j(1 - D_j)$. We obtain

$$\begin{aligned}
f_{\text{half}} &= f\left(\frac{b_i + b_j}{2}, \frac{N_i + N_j}{2}\right) = \frac{b_i + b_j}{2} \left(1 - \frac{D_i + D_j}{2}\right) \\
&= \frac{1}{4}(b_i + b_j)(2 - D_i - D_j) \\
&= \frac{1}{4}(2d_i + b_i(1 - D_j) + b_j(1 - N_i)). \tag{35}
\end{aligned}$$

Dividing by d_i , the proportional deviation in $f(N)$ at the midpoint of the sweep is

$$\begin{aligned}
\frac{f_{\text{half}}}{d_i} &= \frac{1}{4} \left(2 + \frac{b_i}{b_j} + \frac{b_j}{b_i}\right) \\
&= \frac{1}{4} \left(2 + \frac{1}{1 + \epsilon} + 1 + \epsilon\right) \\
&= 1 + \frac{1}{4}(\epsilon^2 - \epsilon^3 + \dots), \tag{36}
\end{aligned}$$

581 where we have used the Taylor expansion $\frac{1}{1+\epsilon} = 1 - \epsilon + \epsilon^2 - \epsilon^3 + \dots$

582 By contrast, for a δ sweep in Eq. (11), the density-dependent term N increases by a
583 factor of $\frac{1}{1-\epsilon} = 1 + \epsilon + \epsilon^2 + \dots$. Thus, the deviations in $f(N)$ are an order of magnitude
584 smaller than those shown in Fig. (6).