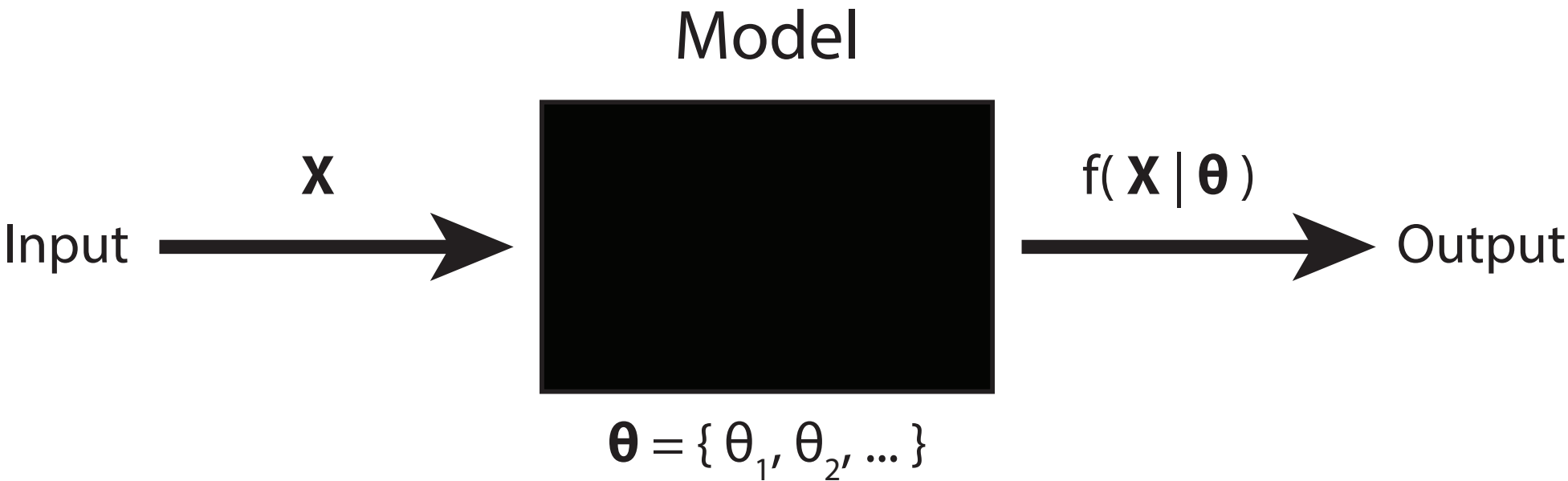
Model
Input
X
f( X | θ )
Output
θ = { θ1, θ2, ... }