CMSC 420

COMIC REWRITE CONTEST



Advanced Data Structures Section 0101 Mon/Wed, 3:30pm, CSIC1115

Welcome!

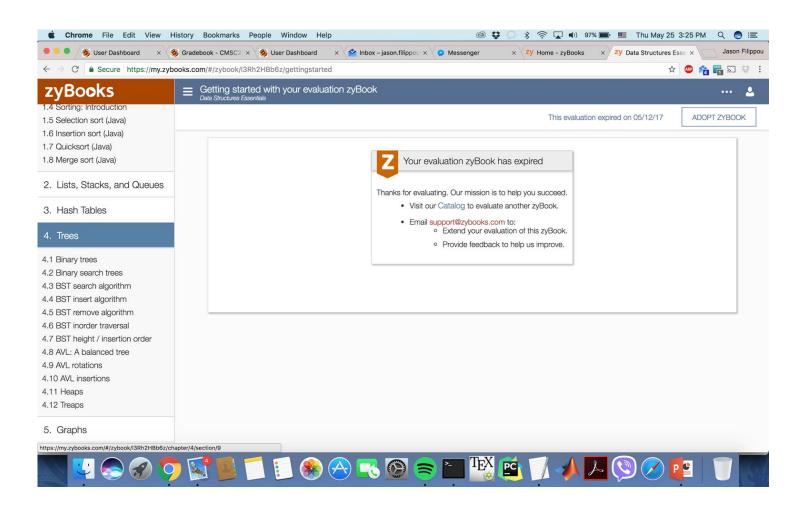
• CMSC420, "Advanced" Data Structures

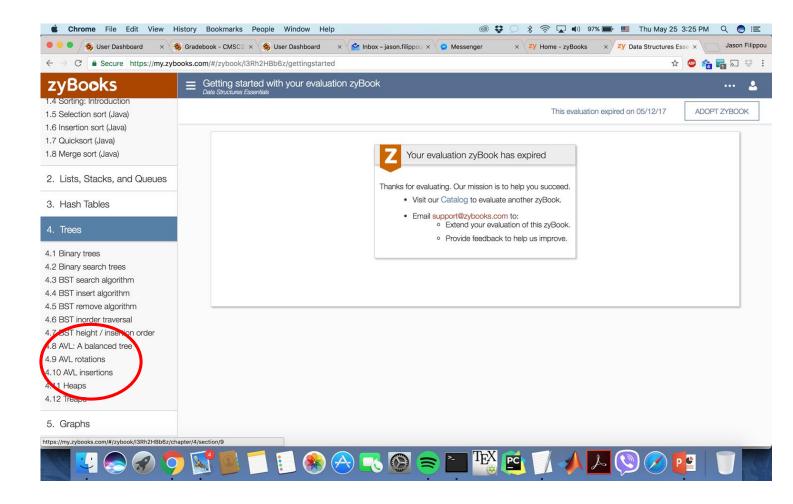
Will explain....

- Elective, generally junior / senior level
- You need 351 and 330 to register!
- Quick facts:
 - 5-6 programming projects in Java, tested on submit.cs.
 - Lecture worksheets. (start Wednesday)
 - Homework assignment every 2-3 weeks (5-6 total).
 - 1 midterm, Wed 10-16, 6-8pm, ESJ (Edward St. John's) 0202
 - 1 final, probably Friday Dec 13 from 1:30 3:30 based on this.

You'll need

- Decent 351 understanding
 - You don't need to remember NP-completeness or MSTs or the knapsack problem, but you will definitely need $\mathcal{O}(\cdot)$ notation, divide-and-conquer, greedy algorithms, heaps, binary search,...
- Strong Java skills
 - 132 and above. Anonymous inner classes, lambdas, iterators, exceptions, interfaces vs abstract classes, tail recursion,...
 - If you have C++ / Scala background, you will learn Java in 2 days.
- Another CS course that is **not** heavy in coding [©]
 - Unless you are really confident you can write correct code, fast!







4. Trees

- 4.1 Binary trees
- 4.2 Binary search trees
- 4.3 BST search algorithm
- 4.4 BST insert algorithm
- 4.5 BST remove algorithm
- 4.6 BST inorder traversal
- 4.7 BST height / insertion order
- 4.8 AVL: A balanced tree
- 4.9 AVL rotations
- 4.10 AVL insertions
- 4.11 Heaps
- 4.12 Treaps



4. Trees

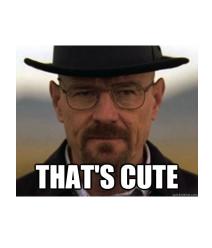
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Very basic for 420 (2nd project)







Lists, queues, stacks, BSTs, simple hashes, graphs, heaps.



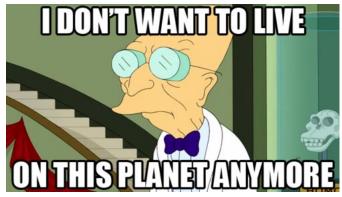
Balanced BSTs, B-Trees, SkipLists, hashing in depth, Tries, Huffman, LZW, KMP, Suffix Trees & Arrays, Huffman, LZW, KD-Trees, QuadTrees, MinHash, LSH....





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Hence
"Advanced"

Data Structures

A 351 question

• Given a **double** (8 bytes) array A of size N, which among the following sorting algorithms offers the best **time complexity?**

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InsertSort

Mergesort

Bubblesort

Selection sort

A 351 question with a 351 answer!

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InsertSort Mergesort Bubblesort Selection sort

- $\mathcal{O}(n \cdot logn)$ worst **and** average time complexity
- $\mathcal{O}(n)$ spatial cost \otimes (not in-place)
- In-place (but non-stable) variants have been proposed, but we won't talk about them

Another 351 question

• Given a <u>linked list</u> of 8 byte integers of size N, does mergesort achieve the same runtime?

Yes No

Another 351 question... with a 351 answer!

 Given a <u>linked list</u> of 8 byte integers of size N, does mergesort achieve the same runtime?



- If you do it <u>bottom-up</u>!
- For more details with pseudocode, you are directed to the <u>Wikipedia article</u>

Yet another 351 question

 Given a <u>sorted linked list</u> of 8 byte integers of size N, what's the best runtime we can achieve for binary search?

 $\mathcal{O}(\log_2 n)$

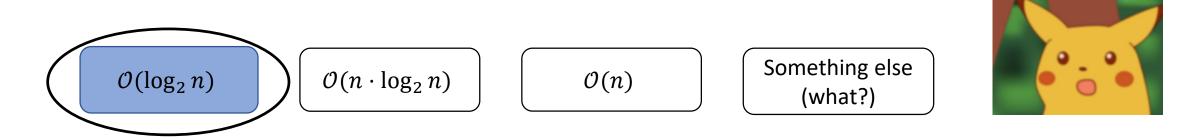
 $\mathcal{O}(n \cdot \log_2 n)$

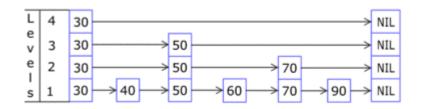
 $\mathcal{O}(n)$

Something else (what?)

Yet another 351 question.. with a 420 answer!

 Given a <u>sorted linked list</u> of 8 byte integers of size N, what's the best runtime we can achieve for binary search?





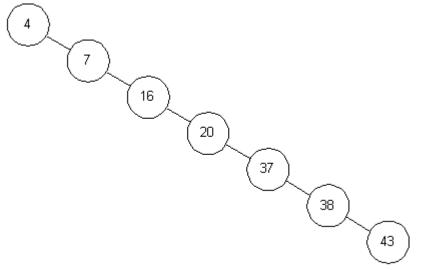
- Use a probabilistic data structure known as a skiplist!
- · We will talk about it later in the semester.

 Suppose I have n integers to store in a binary search tree. In the worst case, how many links will I have to traverse to find one of these integers in the tree?

 $\begin{bmatrix} \log_2 n \end{bmatrix}$ $\begin{bmatrix} 2n \end{bmatrix}$ $\begin{bmatrix} n \end{bmatrix}$

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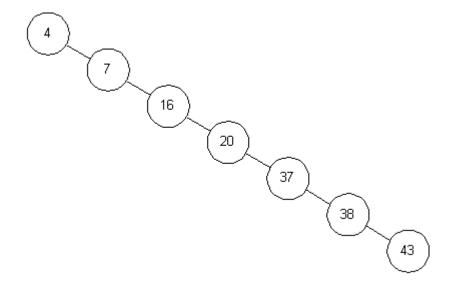
 $\log_2 n \qquad \qquad 2n \qquad \qquad n \qquad \qquad \lceil n/2 \rceil$



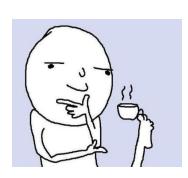
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- Worst case: we receive the input in ascending (or descending) order, and our binary search tree devolves into a linked list ☺
- On average, how many links will I traverse to find any one of these keys?



This term will be very important for us, especially in hashing!

 Suppose I have n integers to store in a binary search tree. In the worst case, how many links will I have to traverse to find one of these integers in the tree?

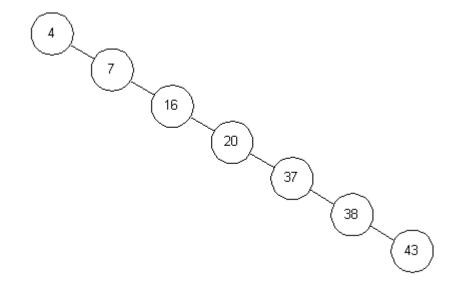
 $\log_2 n$

2n

n

 $[^{n}/_{2}]$

Both "absolute"
worst-case **and**average worst case
search in a linked list
is linear on n.



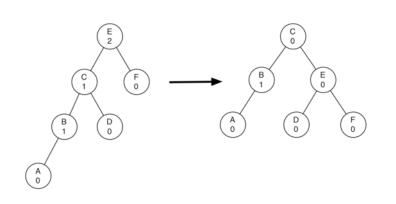
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$$\frac{1+2+3+...+n}{n} = \frac{n(n+1)}{2n} = \frac{n+1}{2} = \frac{1}{2}n + \frac{1}{2} = \mathcal{O}(n)!$$

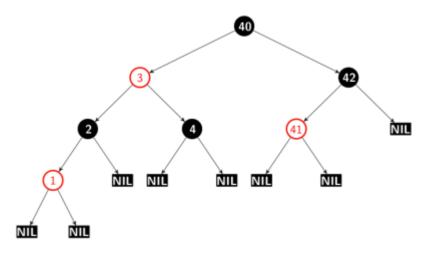


A 420 solution

• To ensure a global height in $O(\log_2 n)$ at all times, we should enhance our BST and make it into an AVL or Red-Black Tree!



Example of rotating a node (in this case, the root) in an AVL tree to restore its balance.



A red-black tree

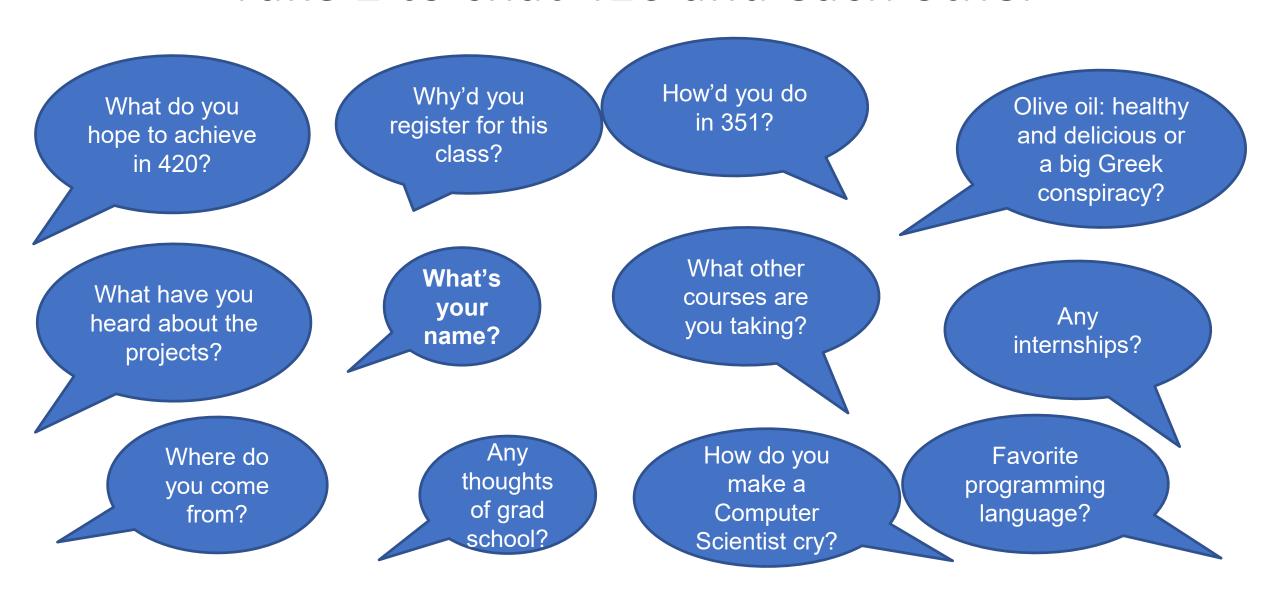
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- You moved from an array to a linked list.
 - Why? What's the chief reason?
 - Non-contiguous storage in memory.
- But what if that breaks your existing operations, or makes them less efficient?
 - You have to make sure this is avoided.
 - Sometimes (e.g mergesort) this might need a radical change to your algorithm.
 - Sometimes (e.g binary search in sorted linked list) you might need a new data structure!

Take 2 to chat 420 and each other



- Perhaps the simplest abstract data structure that we can come up with is a bag
 - Abstract can mean a lot of things
 - We think of it as "a conceptual piece of data storage that has to have some properties and time/space constraints for common operations"



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- 1. We want to be able to put stuff in the bag
- 2. We want to be able to check if the bag is empty.
- We want to check what its size is.
- 4. We can "shake" the bag, randomly perturbing the order of its elements <u>(key operation)</u>
- 5. We can **loop through (iterate over)** all of its elements, one at a time.



```
package edu.umd.cs.datastructures.bags;

i/**...*/
public interface Bag<Item> extends Iterable<Item>[ // So classes implementing it have to expose a fail-safe iterator.

i/**...*/
   void add(Item i);

i/**...*/
   boolean isEmpty();

i/**...*/
   void shake();

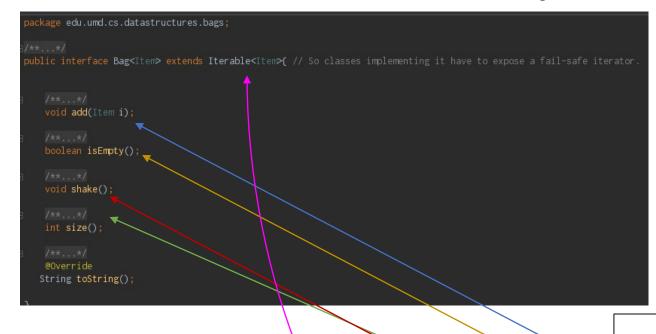
i/**...*/
   int size();

i/**...*/
   @Override
   String toString();

columnts...*/
   columnts...*/
   everride
   String toString();
```

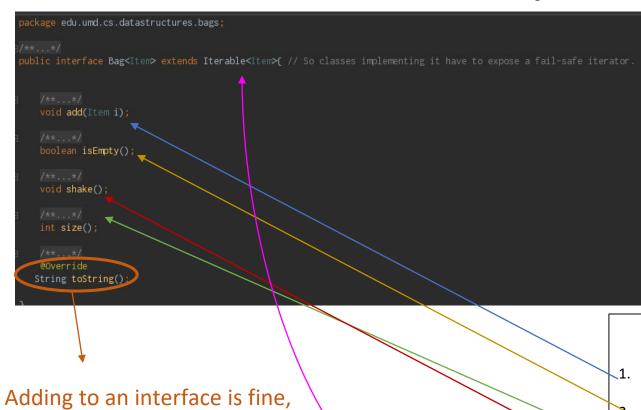
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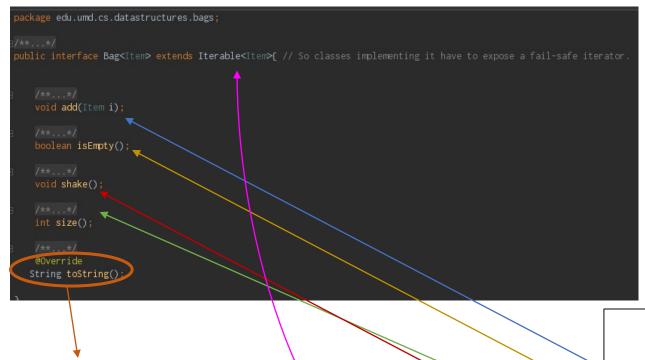




Adding to an interface is fine, as long as you **document** this addition! ©

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Let's switch gears to a Java demo real quick!

Requirements:

- 1. We want to be able to put stuff in the bag
- 2. We want to be able to check if the bag is empty.
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Take-home message #2: <u>Hardware</u> <u>Considerations</u>

- In this demo we saw a classic difference between CS Theory and (hardware) practice...
- Sure, in theory, arrays are constant storage (A[i] requires one to two multiplications and one addition)
- But in practice, if they get too large, not all of them can fit in registers, or even cache!
 - Cache misses make your application (the RandomAccessBag) hurt.
- So even for the simplest possible data structure a language gives us (1D array), theory and practice diverge!

Not allowed in lecture!



If you make a mistake on a worksheet, cross it out with your pen or pencil so that:

- (a) We can grade you fairly and
- (b) You can see your mistake when you study again and remember why you made it (the worksheets will assist you with this)

Worksheets

• Some of our slides will have this icon:



- It means that the question should be answered in your worksheets.
- If you get a question wrong, write the right answer under the line we provide. Also include the reasons for which you got it wrong!
 - Do not erase or cross out the answer! Write down the right answer under the line!

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- Note the docs for the constructors... default starting capacity at 10. When inserting 11th element, we need linear time to copy over to new internal array. ③
 - But! For the next 9 elements, we have constant time! ©
 - So, on average, we have $\frac{30}{20} \approx 1.5$ unit cost for inserting elements!
 - This is an example of a technique called amortized analysis.

- Suppose that we have an ArrayList list1 which begins with 10 cells and adds 10 empty cells every time it gets full.
 - Concretely, it will resize itself at the first insertion that happens while it is already full.
 - So, the first resizing will happen at the eleventh insertion.

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- What is the amortized cost of inserting 50 elements into list1?



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Worksheet time!

- Suppose now that we have an ArrayList list2 which begins with 10 cells and doubles its size every time it gets full!
- What is the amortized cost of inserting 50 elements into list2?



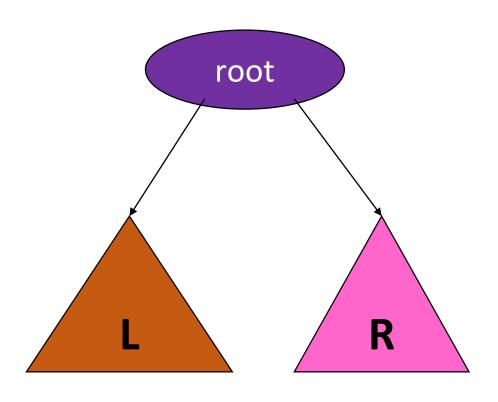
Take-home message #3: <u>Amortized</u> <u>Complexity</u>

- If most of the time our operation runs very fast, are we willing to accept bad performance once in a while?
 - Amortized analysis can answer this question.
- ArrayLists, Splay Trees and Self-organizing hash tables are all data structures where certain operations have amortized constant complexity!

Take-home message #3: <u>Amortized</u> Complexity

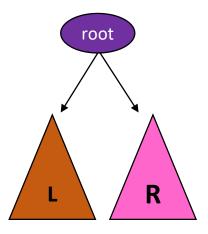
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- ArrayLists, Splay Trees and Self-organizing hash tables are all data structures where certain operations have amortized constant complexity!
- Amortized complexity: An expression in big-Oh notation or English
 - Examples: $\mathcal{O}(n)$, $\mathcal{O}(n^2)$, constant, linear, exponential....
- Amortized cost: The exact cost in terms of elementary operations (e.g swaps, reference assignments) that we incur for an operation.
 - Examples: 2n, 2.5, $1.53n^2 + 2n$



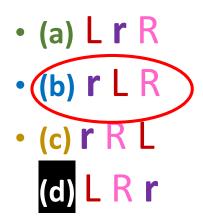


- **Pre**order traversal is...
 - (a) L r R
 - (b) r L R
 - (c) r R L

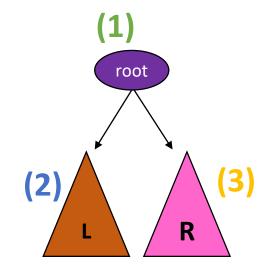




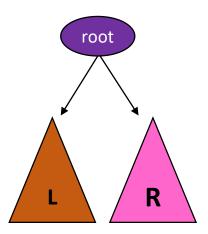
• **Pre**order traversal is...



Mnemonic rule (maybe?): pre-order traversal, as in pre-visit the root before the subtrees



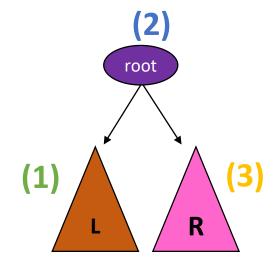
- <u>In</u>order traversal is...
 - (a) L r R
 - (b) r L R
 - (c) r R L
 - (d) LRr



• *In*order traversal is...

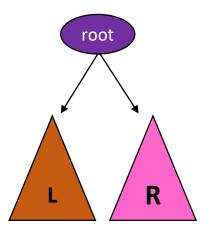


Mnemonic rule (maybe?):
in-order traversal, as in
"visit the root in-between
the subtrees"



- **Post**order traversal is...
 - (a) L r R
 - (b) r L R
 - <u>(c)</u> r R L

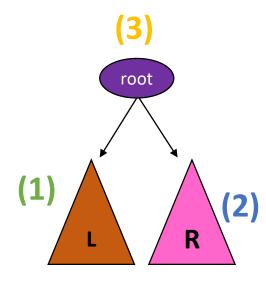




- **Post**order traversal is...
 - (a) L r R
 - (b) r L R
 - (c) r R L

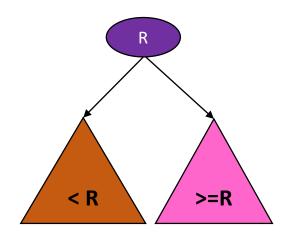


Mnemonic rule (maybe?): post-order traversal, as in "visit the root post-visiting the subtrees"



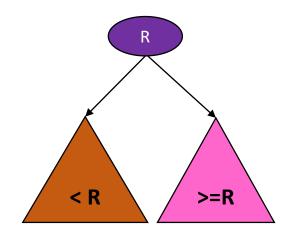
Question for you

• Suppose that our binary tree is a binary search tree



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Which tree traversal is the most useful one for BSTs, and why?

Preorder

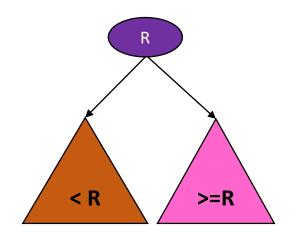
Inorder

Postorder



Question for you

Suppose that our binary tree is a binary search tree

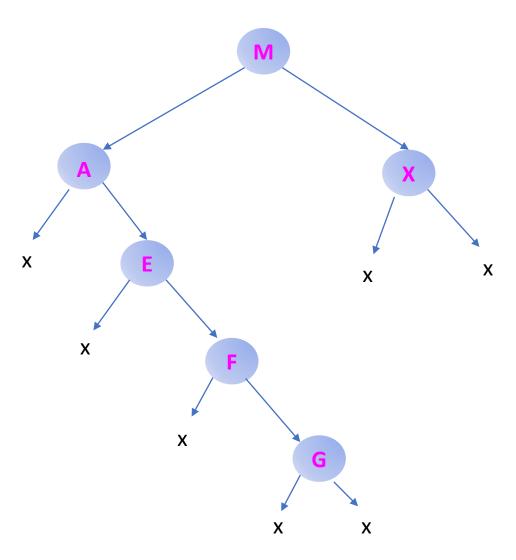


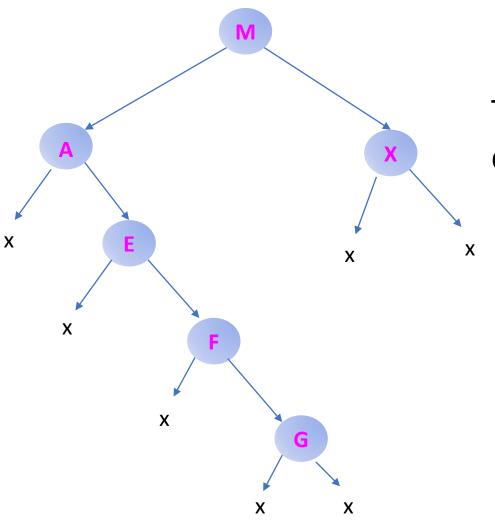
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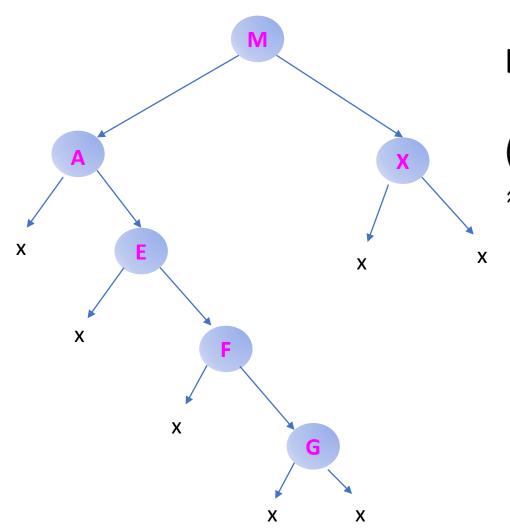


In BSTs, Inorder is Sorted order! :)





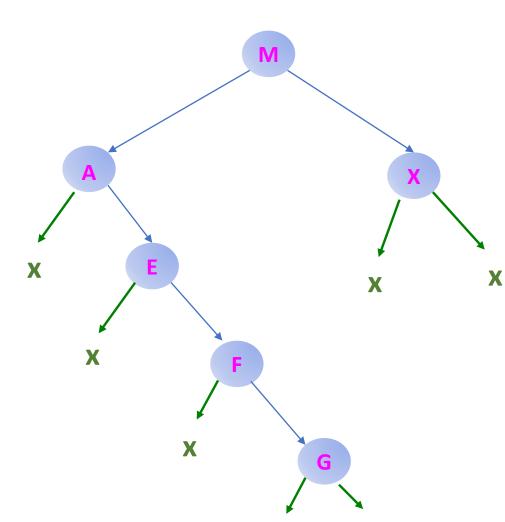
Tell me **THREE** things you don't like about this tree.



Here are three things Jason doesn't like.

(1) Very unbalanced, say goodbye to

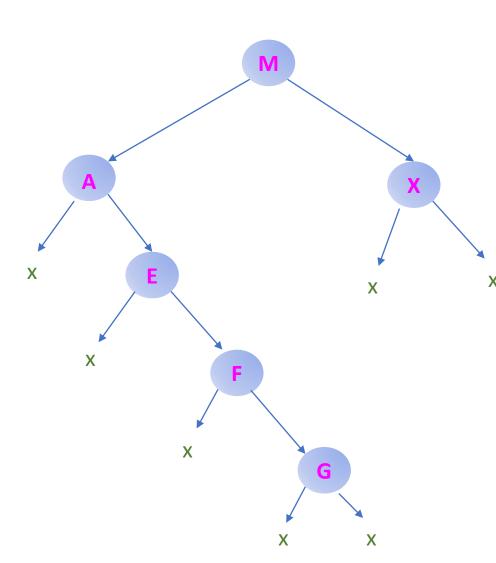
 $\approx \log_2 n$ search.... \otimes



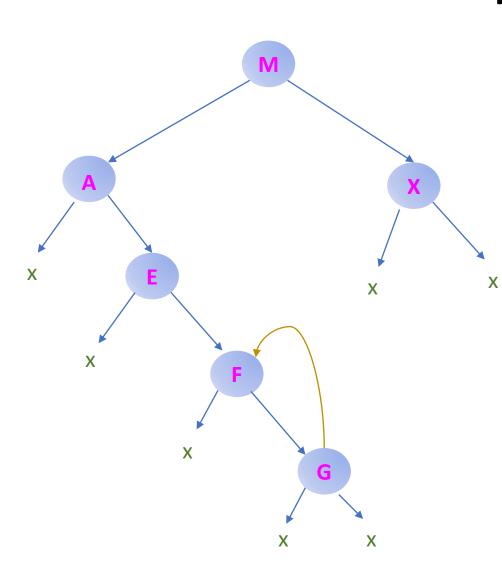
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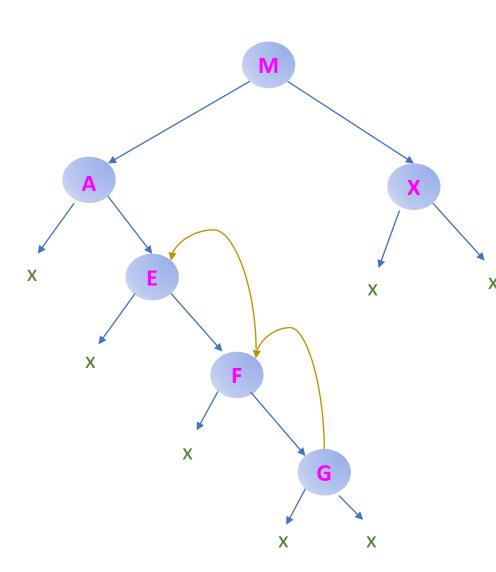
(2) Wasting 8 bytes per null pointer 🕾



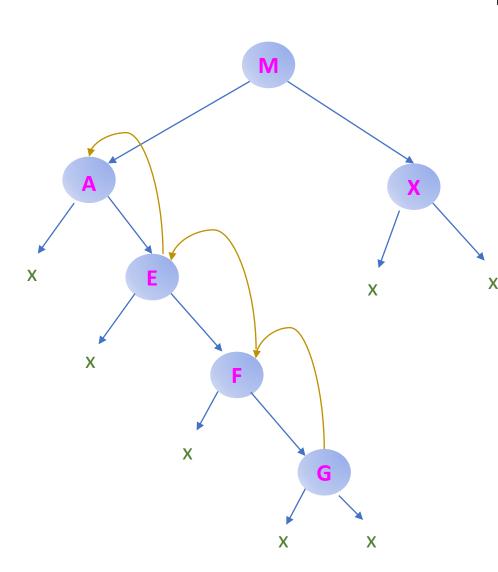
- (1) Very unbalanced, say goodbye to $\approx \log_2 n$ search.... \odot
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- (3) Inorder successor of 'G' will take 4 stack pops to reach ⊗



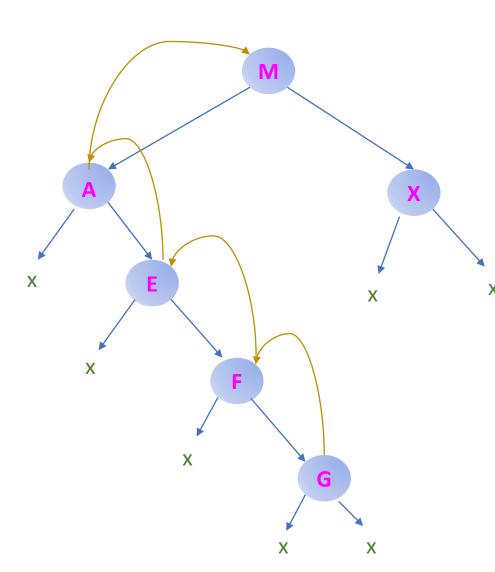
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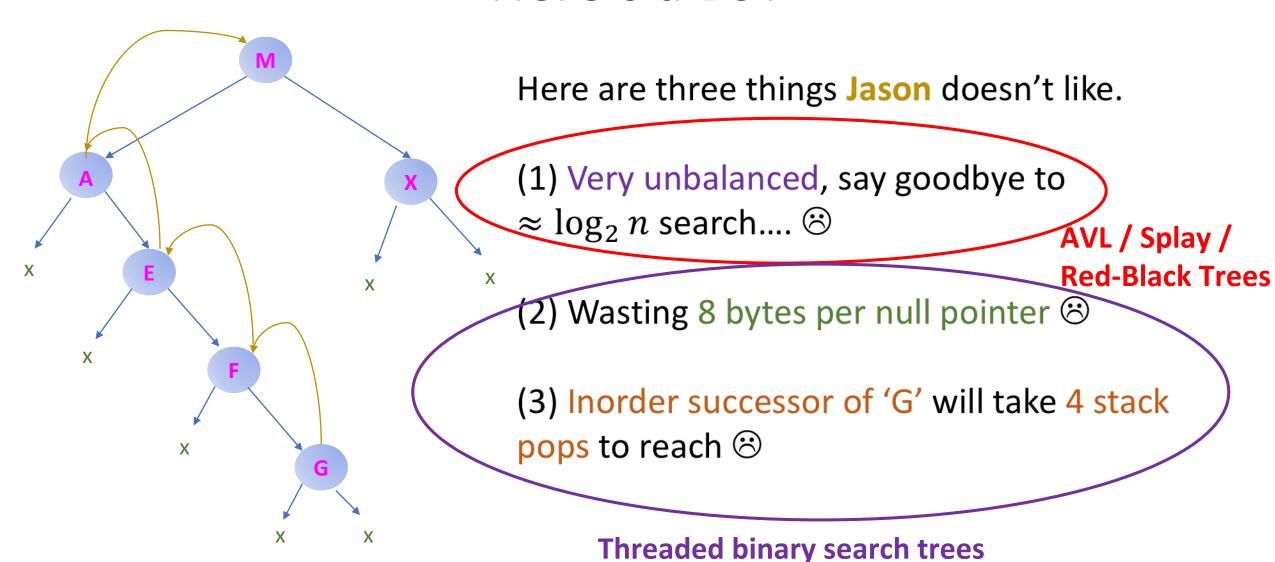
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Take-home message #4: <u>improvements of</u> <u>basic structures</u>

- Even "boring" data structures like binary trees can be majorly improved.
- The linked representation of a binary tree wastes space (by default)
 - Complete binary trees can be represented as an array without NULL references in it...
 - Prefer this over 2^{h+1} null pointers, for a tree of height h=0,1,2,...

We talked storage; what about operations?

Which among the following Java sum calculations will run faster?
 (1) (3)

```
long sum = 0;
for(int i = 0; i < 1000; i++)
    for(int j = 0; j < 1000; j++)
        sum += A[i][j];</pre>
```

```
long sum = 0;
for(int i = 0; i < 1000; i++)
for(int j = 0; j < 1000; j++)
sum += A[j][i];
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They will both need about the same amount of CPU cycles to run.

We talked storage; what about operations?

• Which among the following Java sum calculations will run faster?

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• This "classic" loop leverages row-major order!

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        sum += A[j][i];
```

They will both need about the same amount of CPU cycles to run.

- This "classic" loop leverages row-major order!
- Time for another Java demo!



Any languages that do column-major order?

Yes (which?) No (why?)

Any languages that do column-major order?

Yes (which?)

No (why?)

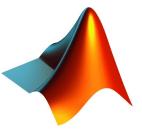
- MATLAB, GNU Octave, LISP...
- Semantics of M[i][j] the same
 - Only storage different, with whatever that implies about operations...

Any languages that do column-major order?

Yes (which?)

No (why?)

- MATLAB, GNU Octave, LISP...
- Semantics of M[i][j] the same
 - Only storage different, with whatever that implies about operations...
- Time for a MATLAB demo!



Here's a matrix M of 8 byte doubles:

M

| 2.33 | 8.145 | 67.9823 | 17.02 | 8.1 | 96.480 | -25.05 |
|---------|----------|---------|---------|---------|---------|--------|
| 5.67012 | 4.2 | -100.02 | -5600.1 | 32 | 25.789 | 89.01 |
| 521.23 | -0.16 | 45.89 | 49 | 3.21 | -1 | -34.2 |
| 0.01 | -32 | 34.578 | -0.07 | 2.899 | 390245 | 87.1 |
| 567.98 | 89.56923 | -897.6 | 90 | 0.45923 | -67.45 | 25.6 |
| -40.23 | 17.32 | 0 | -6.43 | 100.56 | 0.01 | 5.23 |
| 702.97 | 14.56 | 56.79 | 100 | 12.6 | -0.0001 | -4.1 |

| uble **M | | | | | | | |
|---------------|---------------------|----------------|---------|---------|---------|---------|----------------|
| d | \ louble M[0][1] | double M[0][2] | | • | • • | | double M[0][6] |
| double* M[0] | 2.33 | 8.145 | 67.9823 | 17.02 | 8.1 | 96.480 | -25.05 |
| double* M[1] | 5.6701 | 4.2 | -100.02 | -5600.1 | 32 | 25.789 | 89.01 |
| | 521.23 | -0.16 | 45.89 | 49 | 3.21 | -1 | -34.2 |
| | 0.01 | -32 | 34.578 | -0.07 | 2.899 | 390245 | 87.1 |
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| dou | uble **M | | | | | | | |
|-----|---------------|---------------|------------------|---------|---------|---------|---------|----------------|
| | | | | | | | | |
| | + | double M[0][| 1] double M[0][2 |] | • | • • • | | double M[0][6] |
| | double* M[0] | 2.33 | 8.145 | 67.9823 | 17.02 | 8.1 | 96.480 | -25.05 |
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| | | double M[6][1 |] double M[6][2] | | | | | double M[6][6] |
| \ \ | | | | | | | | |

So you need another column for pointers, and another cell for the initial pointer.

| dοι | ıble **M | | | | | | | |
|-----|---------------|----------------|------------------|---------|---------|---------|---------|----------------|
| | | dabla.04[0][0] | 11 double MIOI 2 | 1 | | | | |
| - | • | double M[0][3 | 1] double M[0][2 | | | | | double M[0][6] |
| | double* M[0] | 2.33 | 8.145 | 67.9823 | 17.02 | 8.1 | 96.480 | -25.05 |
| | double* M[1] | 5.6701 | 4.2 | -100.02 | -5600.1 | 32 | 25.789 | 89.01 |
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So you need another column for pointers, and another cell for the initial pointer.

Assumed array size: 49 * 8 = 392 bytes . Real size: 49* 8 for data + 7*8 for row references + 1*8 for initial reference = 456 bytes!

| dou | ble **M | | | | | | | |
|-----|--------------|---------------|------------------|---------|---------|---------|---------|----------------|
| | | double M[0][| 1] double M[0][2 |] | | • • • | | double M[0][6] |
| | double* M[0] | 2.33 | 8.145 | 67.9823 | 17.02 | 8.1 | 96.480 | -25.05 |
| | double* M[1] | 5.6701 | 4.2 | -100.02 | -5600.1 | 32 | 25.789 | 89.01 |
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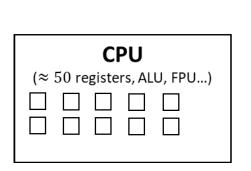
That's $\approx 16.33\%$ on top!

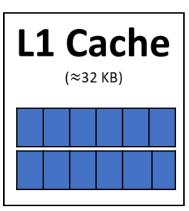
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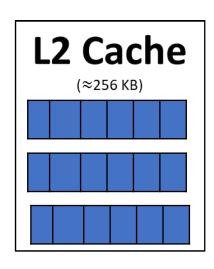
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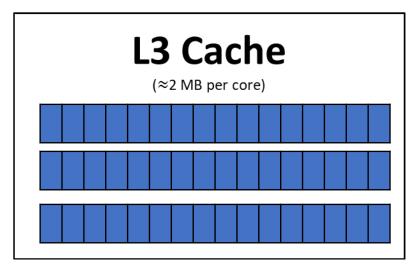
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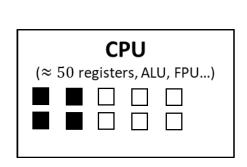


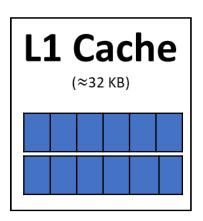


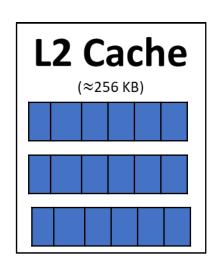


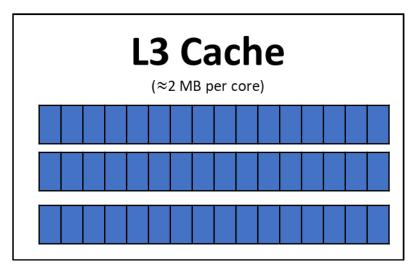


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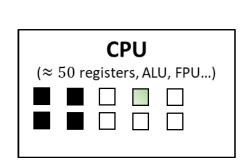


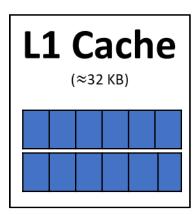


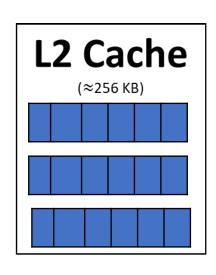


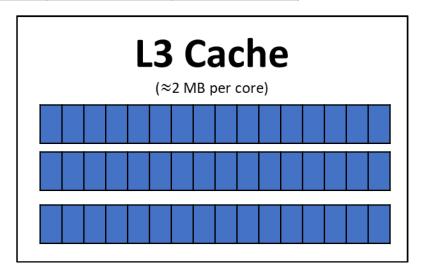


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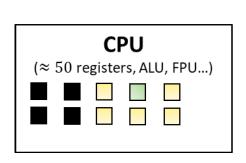


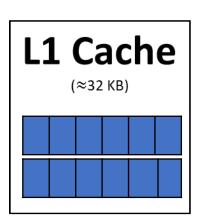


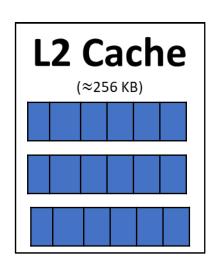


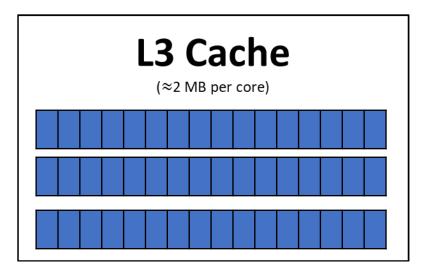


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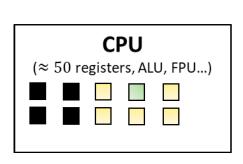


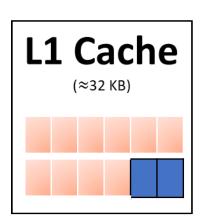


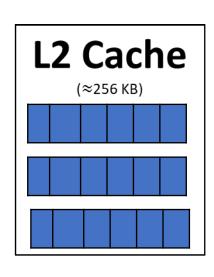


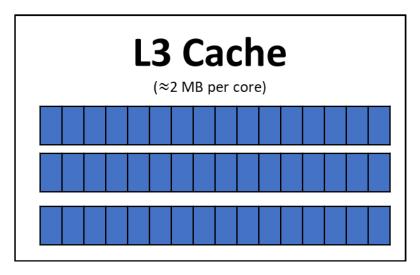


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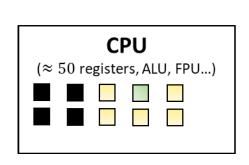


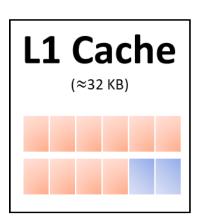


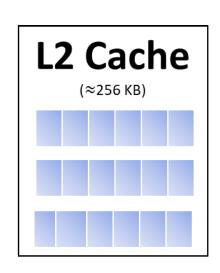


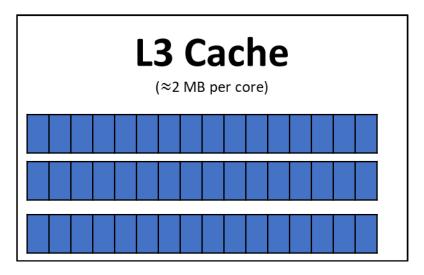


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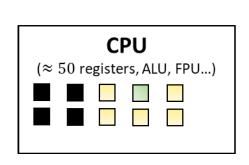


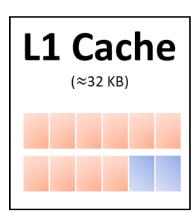


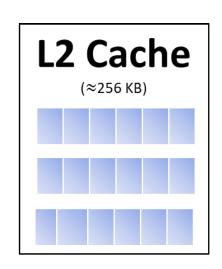


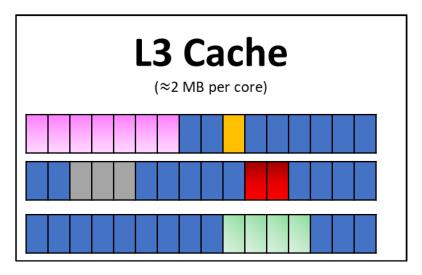


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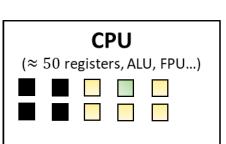


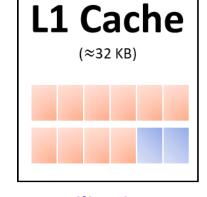


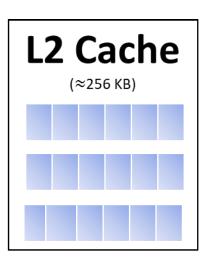


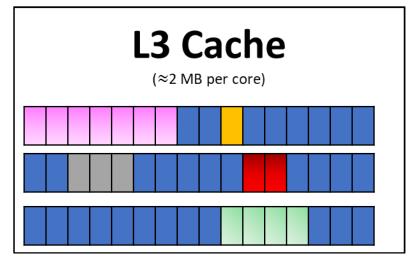


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Over-utilization

Over-utilization + partial overlap with L2

Over-utilization

Under-utilization + fragmentation

Take-home message #5: programming language intricacies affect design

- Modern languages have HUGE and very complex compilers / interpreters, and teams of developers working at the lowest levels (as close to the hardware as possible).
 - If you want to be such a developer, the teaching staff applauds your choice.

Take-home message #5: programming language intricacies affect design

- Modern languages have HUGE and very complex compilers / interpreters, and teams of developers working at the lowest levels (as close to the hardware as possible).
 - If you want to be such a developer, the teaching staff applauds your choice.
- Unless you know what you're doing, never attempt to do the compiler's job for it!
 - Modern compilers can do their job better than you can.
 - Optimization flags -01, -02, -03, -Wall, for gcc
 - JIT ("Just-in-time") compiling in the JVM does stuff like loop unrolling, optimized tail recursion...
 - register keyword in C!

What we'll cover

- 1. Building dictionaries: Abstract data structures that store <Key, Value> pairs
 - Balanced binary trees
 - Skiplist
 - B-Trees
 - Hashing (peering under under the java.util.Hashmap hood)
- 2. Data structures to support efficient operations on string data
 - Huffman coding
 - String compression (LZW)
 - Tries
 - Suffix Tries / Trees / Arrays
- 3. Multi-dimensional data structures to model 2D, 3D, ..., ND and perform similarity tasks.
 - KD-Trees
 - Quadtrees: Fink's, P-R (classic, bucketed, loose), MX-CIF, Region

- 4. Elective topics:
 - Range Trees
 - Priority Search Trees
 - Binomial and Fibonacci heaps
 - MinHash for document similarity
 - Locality Sensitive Hashing (LSH)
 - Consistent Hashing

Notable things we won't cover (a lot)

- We won't talk a ton about B+ (B-plus) trees (extension of B-Trees to disk)
 - According to Nick Roussopoulos, the most successful data structure ever!
- Treaps (random balanced binary trees)
- Brent's and Gunnot-Monroe algorithms for self-organizing collision chain hash tables.

Assessment

- 5-6 projects on Java (40%)
 - Score from submit.cs unit tests
 - Manual inspection of code to verify grading for some methods.
 - Moss!
 - Please install OpenJDK for licensing reasons
- About 5 homeworks, every 2 /3 weeks (15%)
- Lecture worksheets, which will start Wednesday! (5%)
 - Short and sweet(?) questions on stuff we talk about on lecture
 - TA assistance / supervision
- 1 Midterm, see ELMS for date/time/place (20%)
- 1 Final, see ELMS for details (20%)

Webpages



• ELMS: Static information (syllabus), files and your gradebook.

Code demos will also be shared on the GitHub repo for you.

• Recordings, resources, programming project handouts, breakdown of lectures,...



Piazza: We talk. Teaching staff announces future materials, resources, you post your questions.



 Submit server: You submit your projects. Refer to the programming project handouts for specifics of how you can do this.



Jason's GitHub: Skeleton code for your projects on my GitHub so that you can download it and fill in the class implementations.



 Gradescope: You will be uploading your homeworks there, and we will be scanning in and grading worksheets and exams there as well. This means that you can see all of your answers <u>and</u> mistakes until the end of the semester!



Textbooks

- None required, all recommended
- 1. Shaffer, Data Structures & Algorithm Analysis

Freely available, Link on ELMS. Very broad, with both C++ and Java pseudocode versions printed. Has great detail on Hashing and Skiplists. Does *not* assume key rotations in B-Trees, which *we* will later on (don't worry, we will explain in time).

2. Sedgewick & Wayne, *Algorithms*, 5th ed. (4th is good too), Pearson

This is probably in the top 5 of books you want to read in the entire major. Spatial and temporal analysis using Java examples, very mature treatment of hashing, red-black trees, lots of paragraphs about APIs and programming practices.

3. Samet, *Multidimensional and Metric Data Structures*, Morgan Kaufman

If you like this course and you want to do some work (personal project, MSc, PhD, job,...) on Spatial Data Structures, you want this book. It is the holy book of its field.

AMA

