

Linux V4L2 ALSA 架构 简介and 外围IO 控制

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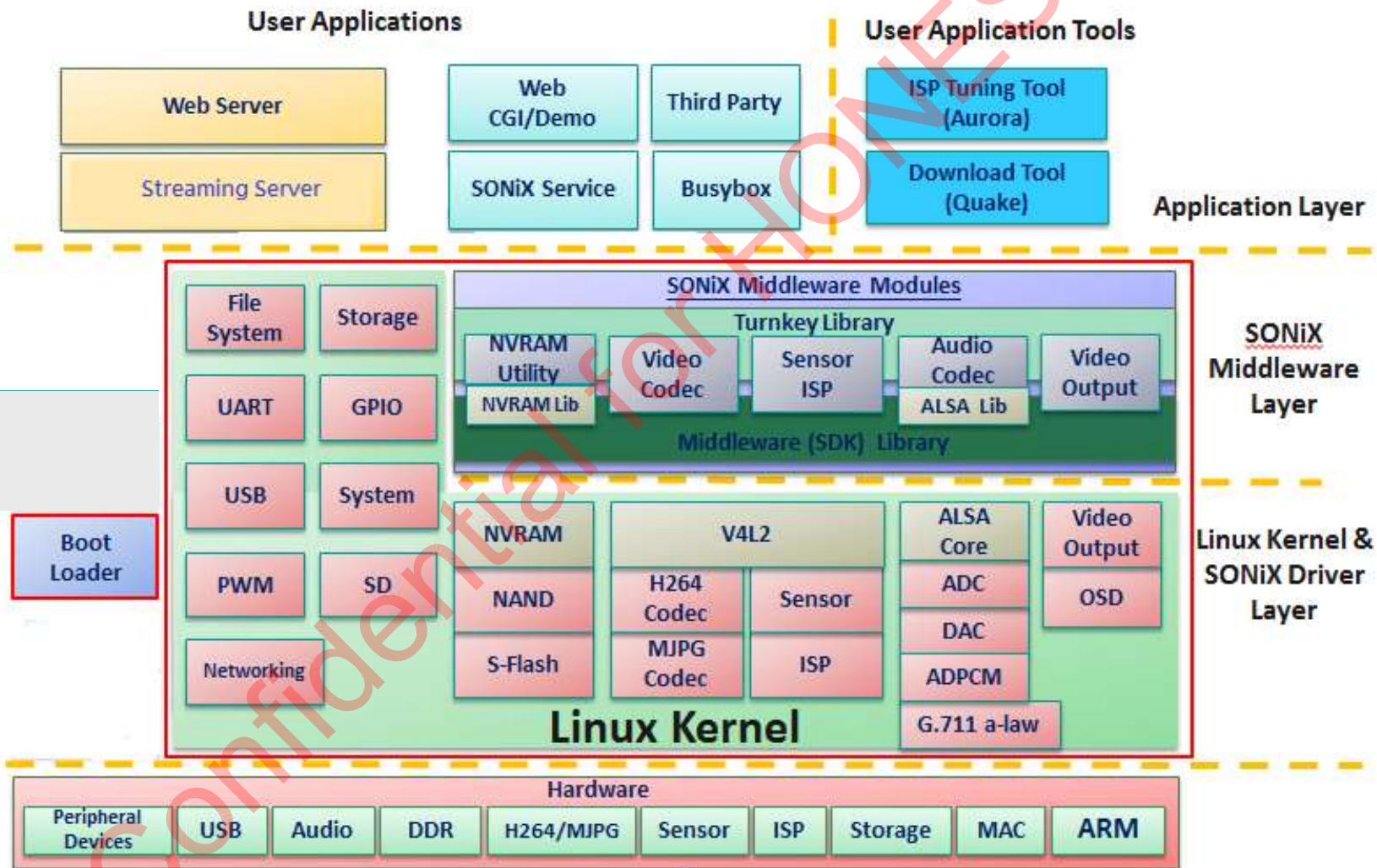


大纲

- ◆ SN98600 SDK 架构
 - Example code 目录说明
- ◆ Video Programming
 - Video encode 场景说明
 - Sonix Video Middleware
- ◆ Audio Programming
 - Alsa library
- ◆ Peripherals
 - GPIO
 - SPI
 - I2C
 - PWM
 - AES/DES/3DES/CRC
 - WDT / Timer / RTC
- ◆ Video output programming



SN98600 SDK 架构





SN986 Series SDK 范例程序目录

◆ App/example/src

Directory Name	Descriptions
Audio	Audio 录放音范例程序
Crypto	AES/DES/3DES/CRC16 范例程序
Gpio	Gpio 控制范例程序
I2c	I2c 控制范例程序
Pwm	Pwm 控制范例程序
Rtc	RTC 控制范例程序
Spi	Spi 控制范例程序
Timer	HW timer 范例程序
Video	Video 多路streaming 范例程序
Video_output	Video output 范例程序
Watchdog	Watchdog 范例程序

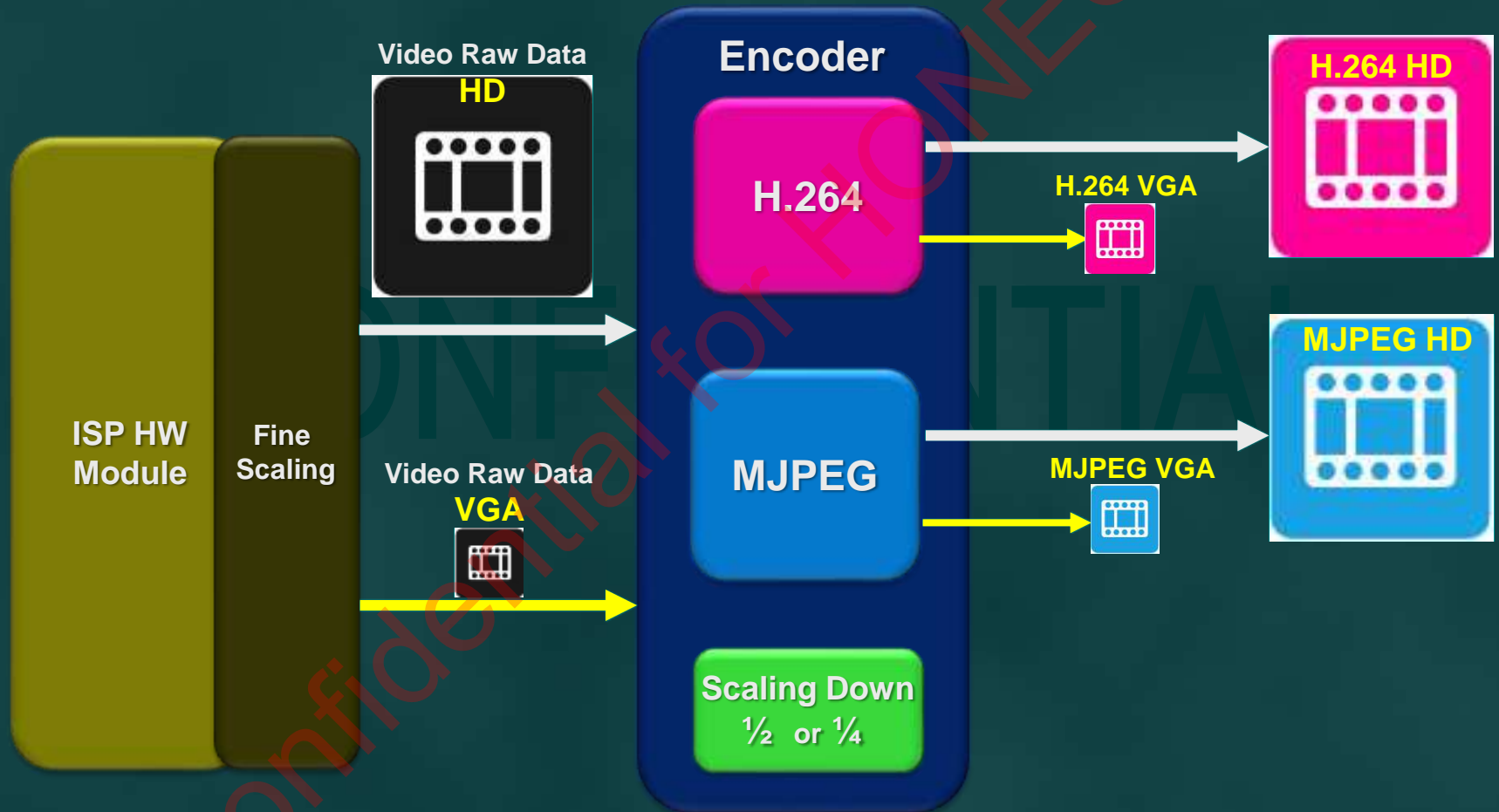
Video Programming

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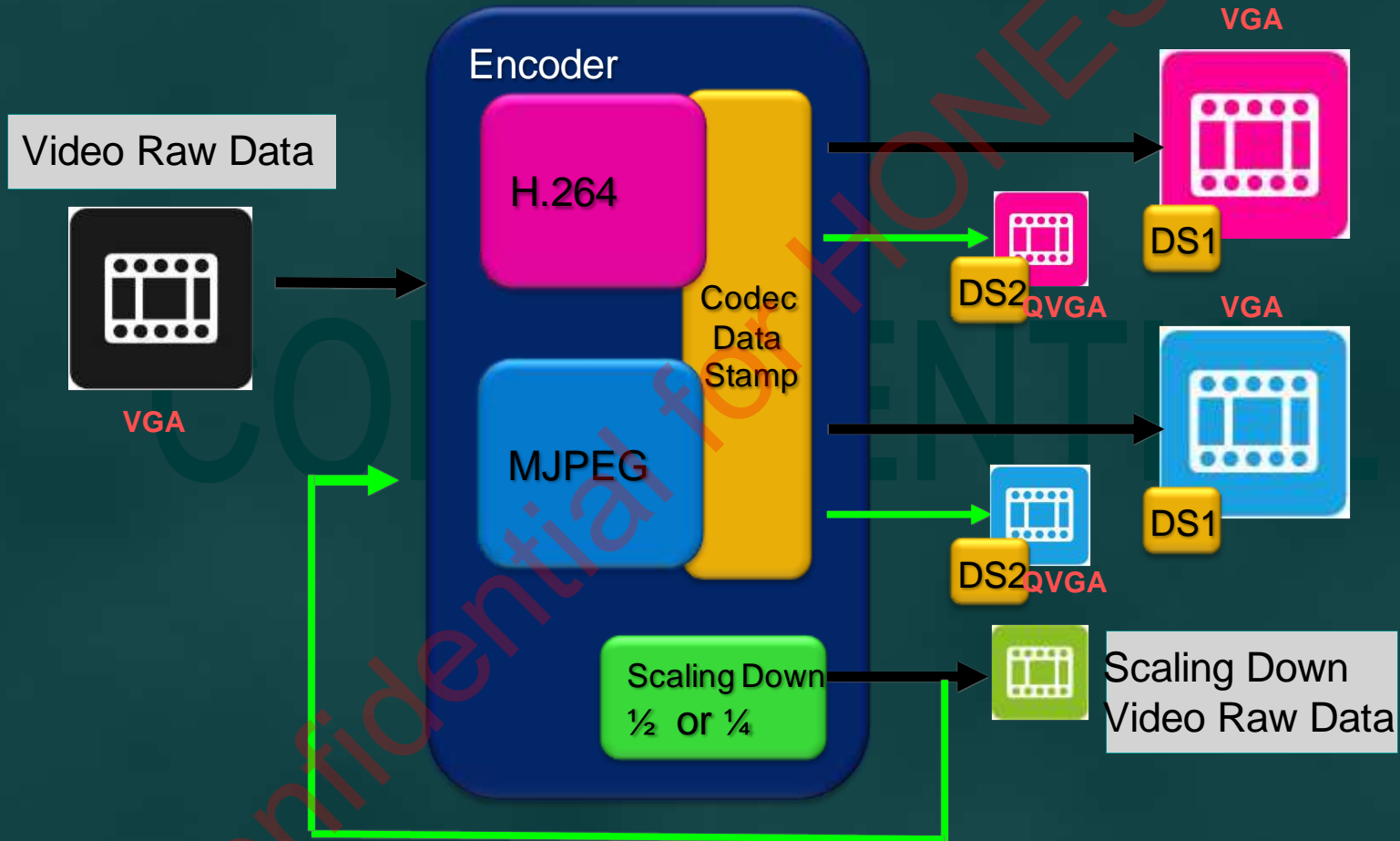


压缩工作场景





压缩工作场景 2





Video Encode

◆ ISP

- Driver `snx_isp.ko`
- 预设节点
 - ◆ `/dev/video0`

◆ Video encode

- Driver `snx_vb2.ko` and `snx_vc.ko`
- 预设节点
 - ◆ `/dev/video1` and `video2`

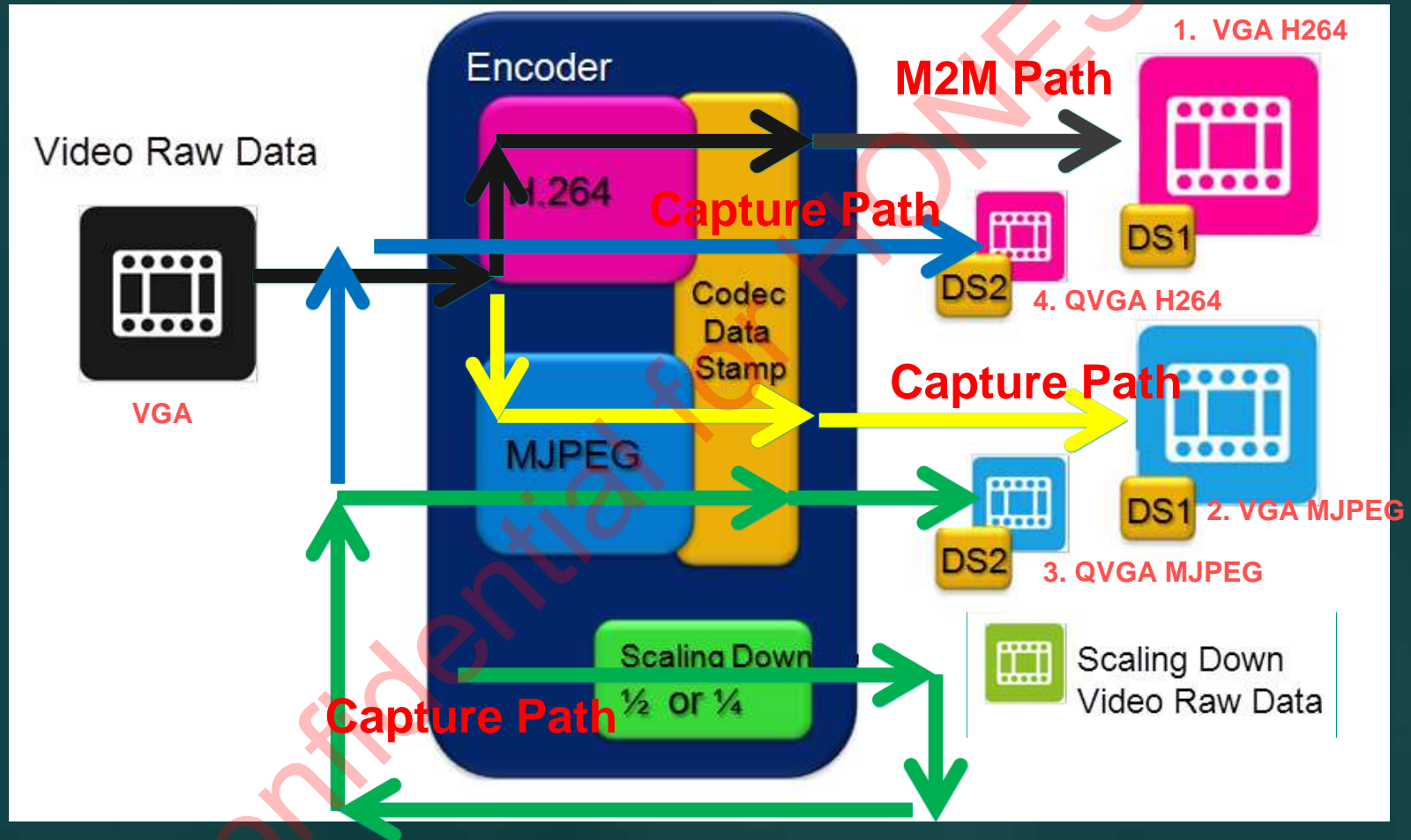


Video encode 流程描述

- ◆ 多码流 by time interleaving
- ◆ M2M Path
 - Encode source is from ISP capture
 - 可以独立存在
 - 最多同时2组m2m path存在 (isp0, isp1)
- ◆ Capture Path
 - Encode source is from existed path
 - 必须有对应的m2m path



M2M/Capture Path 说明





Video Codec 架构

Video
middleware

libsnx_vc.so
libsnx_rc.so

Driver
Interface

/dev/Video0
ISP

/dev/Video1 Codec

/proc/codec
Data Stamp

Linux
Kernel
&
ISP/Codec
Driver

ISP

Codec

V4L2-m2m

Videobuf2-core

Codec
hardware control

vb2-dma-conting

snx-vb2



Video Middleware

- ◆ 基于V4L2 Memory2Memory架构开发的中间层
 - 省去study V4L2 library 的时间
 - 简单了解开发的Sonix Video Middleware APIs
- ◆ 包含 Video Encode, Rate Control, Data Stamp
 - Video Encode 包括 H264, MJPEG, JPEG Encode APIs
 - Rate Control
 - ◆ Set QP for VBR (HW)
 - ◆ Sonix RC APIs for CBR (SW)
 - Data Stamp
 - ◆ Encode时添加图标或文字



Video Middleware APIs

Middleware
API

libsnx_vc & libsnx_rc

snx_open_device

snx_isp_init

snx_isp_start

snx_isp_uninit

snx_isp_stop

snx_codec_init

snx_codec_start

snx_codec_read

snx_codec_uninit

snx_codec_stop

snx_codec_reset

snx_codec_
set_qp

snx_codec_
get_qp

snx_codec_
rc_update

snx_codec_
rc_init

Driver
interface

/dev/Video0 ISP

/dev/Video1 /dev/Video2
Codec

详细内容请参考:

SN986 Series Video Codec Programming Guide





Video Encode Middleware APIs

Function Name	Descriptions
snx_open_device(char *dev_name)	Open device name
snx_isp_init(struct snx_m2m * m2m)	Integrate V4L2 I/O control: VIDIOC_QUERYCAP, VIDIOC_S_CTRL and VIDIOC_S_FMT
snx_isp_start(struct snx_m2m * m2m)	Integrate V4L2 I/O control: VIDIOC_REQBUFS, VIDIOC_QUEERBUF, VIDIOC_QBUF, VIDIOC_STREAMON
snx_isp_stop(struct snx_m2m * m2m)	Integrate V4L2 I/O control: VIDIOC_STREAMOFF
snx_isp_uninit(struct snx_m2m * m2m)	release memory



Video Encode Middleware APIs (2)

Function Name	Descriptions
<code>snx_codec_init(struct snx_m2m * m2m)</code>	Integrate V4L2 I/O control: VIDIOC_QUERYCAP, VIDIOC_S_CTRL and VIDIOC_S_FMT
<code>snx_codec_start(struct snx_m2m * m2m)</code>	Integrate V4L2 I/O control: VIDIOC_REQBUFS, VIDIOC_QUERBUF, VIDIOC_QBUF, VIDIOC_STREAMON
<code>snx_codec_read(struct snx_m2m * m2m)</code>	Integrate V4L2 I/O control: VIDIOC_DQBUF, VIDIOC_QBUF
<code>snx_codec_reset(struct snx_m2m * m2m)</code>	Integrate V4L2 I/O control: VIDIOC_DQBUF, include snx_isp_read() API
<code>snx_codec_stop(struct snx_m2m * m2m)</code>	Integrate V4L2 I/O control: VIDIOC_STREAMOFF
<code>snx_codec_uninit(struct snx_m2m * m2m)</code>	release memory



Video Rate Control Middleware APIs

Function Name	Descriptions
<code>snx_codec_set/gp_qp</code>	set / get QP
<code>snx_codec_rc_init</code>	Rate control function init function
<code>snx_codec_rc_update</code>	software algorithm calculator new QP value



Video Data Stamp Middleware APIs

Function Name	Descriptions
snx_cds_get_enable	Get codec data stamp enable/disable status
snx_cds_set_enable	Set codec data stamp enable/disable
snx_cds_set/get_scale	Set / get codec data stamp scale ratio
snx_cds_set/get_color_attr	Set / get codec data stamp color attribut
snx_cds_set/get_color	Set / get codec data stamp foreground/background color
snx_cds_set/get_position	Set / get codec data stamp position/dimension
snx_cds_set/get_datastamp	Set / get codec data stamp value (binary)
snx_cds_set_string	Set string to codec data stamp (ascii)
snx_cds_set_bmp	Set bitmap file to codec data stamp (bitmap)



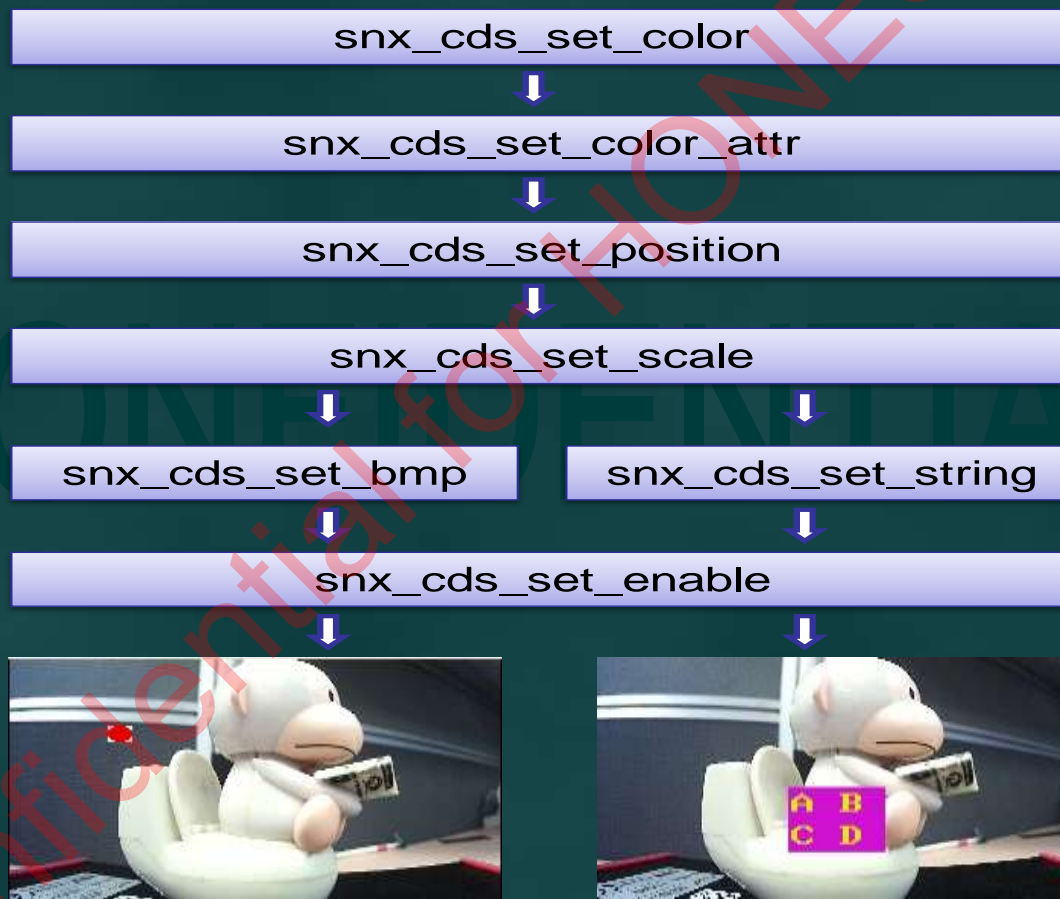


Data Stamp

- ◆ 4096 color with transparent
- ◆ 支持前景色和背景色
- ◆ x1 x2 x4 scaling
- ◆ 16x16 pixels per char
- ◆ Time interleaving



Data stamp programming流程





Video Example Code

◆ Example/Video/

- snx_m2m_one_stream
- snx_m2m_two_stream
- snx_m2m_capture_2stream
- snx_m2m_capture_4stream
- snx_m2m_one_stream_with_rc
- snx_m2m_capture_2stream_with_rc
- snx_vc_ds

Audio Programming

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Audio Codec Feature

- ◆ Driver `snx_aud_core.ko` `snx_aud_sigma.ko`
`snx_aud_r2r.ko`
- ◆ Audio codec formats:
 - Hardware audio codec
 - ◆ MS-ADPCM
 - ◆ A-LAW
 - Software audio codec
 - ◆ A-LAW
 - ◆ Mu-LAW
 - ◆ G.722
 - ◆ G.726
- ◆ Audio Codec sample rate
 - 8/16/24/32/44.1/48K bps

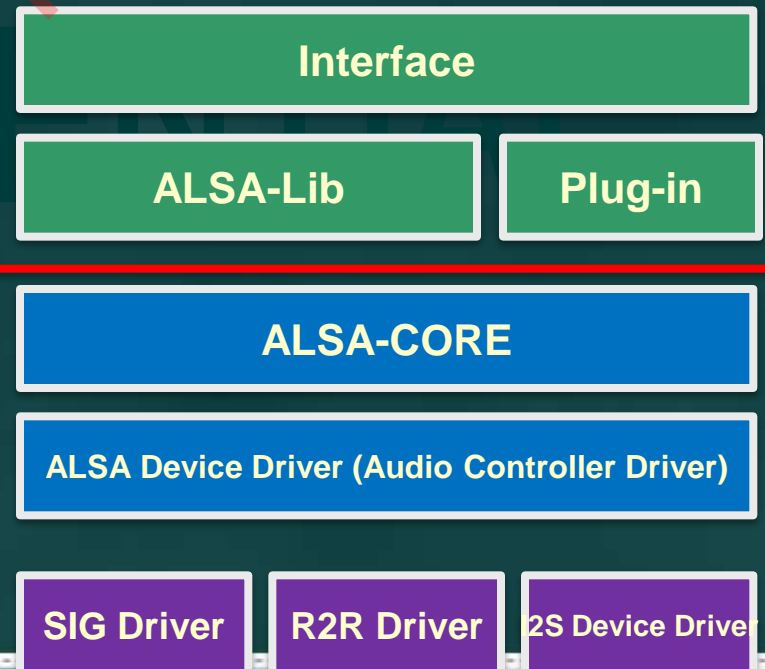


Audio SDK 架构

- ◆ 使用ALSA 架构 (Advanced Linux Sound Architecture)
- ◆ Driver部分包括:
 - sigma-delta driver, R2R driver (internal sub-module)
 - AIC23, tw2866 driver (external)
- ◆ 使用alsa-lib提供上层APP 接口
- ◆ Plug-in
 - A-LAW,
 - Mu-LAW,
 - G.722, G.726

User Space

Kernel





Audio Middleware

◆ 支持ALSA-LIB APIs

Functions	Descriptions
<code>snd_pcm_open</code>	Open a pcm device
<code>snd_pcm_hw_params_alloca</code>	Allocate a hardware parameters object.
<code>snd_pcm_hw_params_any</code>	Fill it in with default values
<code>snd_pcm_hw_params_set_access</code>	Set Access mode INTERLEAVED , NONINTERLEAVED , etc.
<code>snd_pcm_hw_params_set_format</code>	Set Format
<code>snd_pcm_hw_params_set_channels</code>	Set channel
<code>snd_pcm_hw_params_set_rate</code>	Set sample rate
<code>snd_pcm_hw_params_set_period_size</code>	Set Period Size (frame number)
<code>snd_pcm_hw_params</code>	Write the parameters to the driver
<code>snd_pcm_readi</code>	Read frames to the buffer
<code>snd_pcm_writei</code>	Write frames from the buffer
<code>snd_pcm_drain</code>	Change the pcm state to standby
<code>snd_pcm_close</code>	Close the pcm device



SONiX Audio Middleware APIs

Function Name	Descriptions
<code>int snx_audio_mic_vol_get_items(int card_num, int *items)</code>	Get the items of microphone volume adjustment.
<code>int snx_audio_mic_vol_set(int card_num, int vol)</code>	Set the volume of microphone.
<code>int snx_audio_mic_vol_get(int card_num, int *vol)</code>	Get the volume of microphone.
<code>int snx_audio_mic_vol_set_mute(int card_num, int mute)</code>	Set the microphone mute.
<code>int snx_audio_mic_vol_get_mute(int card_num, int *mute)</code>	Determine whether the microphone is mute.
<code>int snx_audio_spk_vol_get_items(int card_num, int *items)</code>	Get the items of speaker volume adjustment.
<code>int snx_audio_spk_vol_set(int card_num, int vol)</code>	Set the volume of speaker.
<code>int snx_audio_spk_vol_get(int card_num, int *vol)</code>	Get the volume of speaker.
<code>int snx_audio_spk_vol_set_mute(int card_num, int mute)</code>	Set the speaker mute.
<code>int snx_audio_spk_vol_get_mute(int card_num, int *mute)</code>	Determine whether the speaker is mute.



Audio Codec Plug-in

- ◆ **ALSA lib** 支持物理和虚拟的设备创建
 - `/usr/share/alsa/alsa.conf`
- ◆ 目前支持的设备

Device Name	Descriptions
hw:0	Hardware audio codec (PCM, A-LAW)
snx_audio_pcm	Hardware audio codec (PCM)
snx_audio_alaw	Software A-LAW codec
snx_audio_mulaw	Software Mu-LAW codec
snx_audio_g722	Software G.722 codec
snx_audio_g726	Software G.726 codec



Audio Test Tools and Example

- ◆ Aplay and Arecord
 - ALSA official utilities
- ◆ Example/audio
 - snx_audio_record
 - snx_audio_playback
 - snx_audio_vol_ctl

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GPIO

- ◆ 4 个通用GPIO for SN98600 / 98601
- ◆ 6个通用GPIO for SN98610
- ◆ snx_gpio.ko
- ◆ 通用GPIO 支持
 - GPIO 方向设置
 - GPIO input/output value set /get
 - GPIO interrupt request
 - 可透过/sys/class/gpio读写操作
- ◆ Pin muxing GPIO
 - MS-1 (11 pins)
 - PWM (2 pins)
 - SPI (4 pins)



GPIO 设备操作

Function Name	Description
/sys/class/gpio/export	export control of a GPIO to user space
/sys/class/gpio/unexport	unexport control of a GPIO to user space
/sys/class/gpio/gpioN/direction	Set/get gpio pin direction. Read/write as either “in” or “out”
/sys/class/gpio/gpioN/value	Set/get gpio value. Read/write as either 0 (low) or 1 (high)
/sys/class/gpio/gpioN/edge	set interrupt edge none/rasing/falling/both



GPIO Middleware

- ◆ 整合GPIO 设备操作
 - 提供APIs
- ◆ 提供PWM, SPI, MS-1等 pin-muxing GPIO APIs



GPIMO Middleware APIs

General-purpose gpio function	description
snx_gpio_open	Open gpio device (export to user space)
snx_gpio_close	Close gpio device (unexport)
snx_gpio_write	Set gpio mode and value
snx_gpio_read	Read gpio mode and value
snx_gpio_set_interrupt	Set gpio interrupt trigger method
snx_gpio_poll	GPIO polling
ms1 gpio function	description
snx_ms1_gpio_open	Open ms-1 gpio device
snx_ms1_gpio_close	Close ms-1 gpio device
snx_ms1_gpio_write	Set gpio mode and value
snx_ms1_gpio_read	Read gpio mode and value



GPIMO Middleware APIs

spi gpio function	description
snx_spi_gpio_open	Open spi gpio device
snx_spi_gpio_close	Close spi gpio device
snx_spi_gpio_write	Set gpio mode and value
snx_spi_gpio_read	Read gpio mode and value
pwmgpio function	description
snx_pwm_gpio_open	Open pwm gpio device
snx_pwm_gpio_close	Close pwm gpio device
snx_pwm_gpio_write	Set gpio mode and value
snx_pwm_gpio_read	Read gpio mode and value



GPIO Middleware Library

- ◆ 支持各GPIO以及pin muxing gpio mode的定义设定
 - 不支持pin mux动态调整，先在板级设定好
 - /board-info/gpio/sn986xx/gpio.txt

```
8 */
9 GPIO Initial Setting
10 ---
11 PIN                PINMUX  MODE      OUTPUTVALUE      Interrupt
12 ===
13 GPIO_00            ENABLE  OUTPUT    1                 EDGE_SINGLE_RISE
14 GPIO_01            ENABLE  OUTPUT    1                 DISABLE
15 GPIO_02            ENABLE  OUTPUT    1                 EDGE_BOTH
16 GPIO_03            ENABLE  OUTPUT    1                 DISABLE
17 GPIO_04            ENABLE  OUTPUT    1                 EDGE_SINGLE_FALL
18 GPIO_05            ENABLE  OUTPUT    1                 EDGE_BOTH
```

- 透过gpio_init去套用设定
- ◆ 详细APIs 使用方式请参考
 - middleware/gpio/src/gpio-init/
 - middleware/gpio/src/gpio-led
 - app/example/src/gpio



I2C

- ◆ SN98600/98601 支持 1个I2C
- ◆ SN98610支持2个I2C
- ◆ 支持标准Linux I2C接口
- ◆ The I2C features include:
 - 支持100Khz and 400KHz
 - 支持7-bit, 10-bit, and general call addressing modes
 - Linux I2C sub-system



I2C Programming

◆ Kernel Space API

<code>i2c_transfer</code>	execute a single or combined I2C message
---------------------------	--

◆ User Space (IOCTL)

<code>I2C_RDWR</code>	<code>ioctl cmd</code>	Combined R/W transfer
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`/dev/i2c-0`

◆ Example 请参考

– `app/example/src/i2c`



SPI

- ◆ 2 SPI instance for SN98610
- ◆ 4-wire serial bus
- ◆ Feature
 - 支持SPI master / SPI slave / GPIO mode
 - 支持read/write/write_read operation
 - Programmable bits per word
 - Programmable max speed
 - Programmable serial bit data sequence (MSB or LSB first)
 - 支持 标准Linux SPI dev 接口
 - /dev/spidev0.0
 - /dev/spidev1.0 (SN98610)



SPI Programming

◆ Kernel space

- spi_message_init
- spi_message_add_tail
- spi_sync



SPI Programming

◆ User Space

Function Name	Category	Description
SPI_IOC_RD_MODE	ioctl	Get the current SPI mode
SPI_IOC_WR_MODE	ioctl	Set SPI mode
SPI_IOC_RD_LSB_FIRST	ioctl	Get the transmission setting (LSB first or not)
SPI_IOC_WR_LSB_FIRST	ioctl	Set LSB first or not in transmission
SPI_IOC_RD_BITS_PER_WORD	ioctl	Get how many bits per word for this device
SPI_IOC_WR_BITS_PER_WORD	ioctl	Set how many bits per word for this device
SPI_IOC_RD_MAX_SPEED_HZ	ioctl	Get the max speed of the spi device
SPI_IOC_WR_MAX_SPEED_HZ	ioctl	Set the max speed of the spi device
SPI_IOC_MESSAGE(num)	ioctl	SPI operation (num: numbers of the transmissions)
read	io	Read operation to SPI device
write	io	Write operation to SPI device





SPI Programming

- ◆ Example 请参考
 - `app/example/src/spi`

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PWM

- ◆ 2 PWM pins output
- ◆ Driver `snx_pwm.ko`
- ◆ 预设节点
 - `/dev/pwm`
- ◆ 可调整的period, duty 时间



PWM Programming

Function Name	Category	Description
SONIX_PWM_REQUEST	ioctl cmd	request a usable pwm device for pwm fd, the arg must be pwm_ID_1 or pwm_ID_2. these pwm_ID is defined in the struct of SNX_PWM_ID
SONIX_PWM_FREE	ioctl cmd	free a usable pwm device
SONIX_PWM_ENABLE	ioctl cmd	Enable pwm device
SONIX_PWM_DISABLE	ioctl cmd	disable pwm device
SONIX_PWM_READ	ioctl cmd	use pwm read mode and read the value
SONIX_PWM_INVERSE	ioctl cmd	inverse the square wave of pwm output
SONIX_PWM_CONFIG	ioctl cmd	config pwm device duty and period time, the arg is struct of pwm_config_param, (defined in snx_pwm.h)



PWM Programming

◆ Example 请参考

- `app/example/src/pwm`
- `middleware/gpio/src/pwm-period`



AES/DES/3DES/CRC

- ◆ 共享的IP
- ◆ 功能不能同时使用
- ◆ CRC16
 - 计算方程 $X^{16} + X^{15} + X^2 + 1$
 - /dev/crypto
- ◆ AES/DES/3DES
 - Cipher key only with lengths of 128 bits (AES-128)
 - Supports ECB mode
 - Supports DMA function
 - /dev/crypto



CRC16 Programming

◆ Kernel Space

- `snx_crypto_buffer_alloc`
- `snx_crc16_calculate`

◆ User Space

Function Name	Category	Description
SNX_INIT_BUF	ioctl cmd	Initial the buffer for CRC calculation
SNX_CRC_CALCULATE	ioctl cmd	Enable the calculate



AES/DES/3DES Programming

◆ Kernel Space

- `snx_crypto_buffer_alloc`
- `snx_crypto`

◆ User Space

Function Name	Category	Description
SNX_INIT_BUF	ioctl cmd	Initial buffer
SNX_CRYPTO_CRYPT	ioctl cmd	Enable the encrypt/decrypt, use struct <code>snx_cipher_info</code> (define in <code>snx_cipher.h</code>)



AES/DES/3DES/CRC Programming

- ◆ Example 请参考
 - `app/example/src/crypto`

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WDT/Timer/RTC

◆ WDT

- /dev/watchdog
- 请参考

- ◆ app/example/src/watchdog/snx_watchdog_test.c

◆ Timer

- 请参考

- ◆ app/example/src/timer

◆ RTC

- /dev/rtc
- snx_rtc.ko
- 请参考

- ◆ app/example/rtc/ snx_rtc_test.c



Reference

◆ Documents

- SN986 Series Audio Codec Programing Guide
- SN986 Series Video Codec Programing Guide
- SN986 Series Video Output Programing Guide
- SN986 Series SDK Programming Guide

◆ Example code

- App/example

Video Output Programming

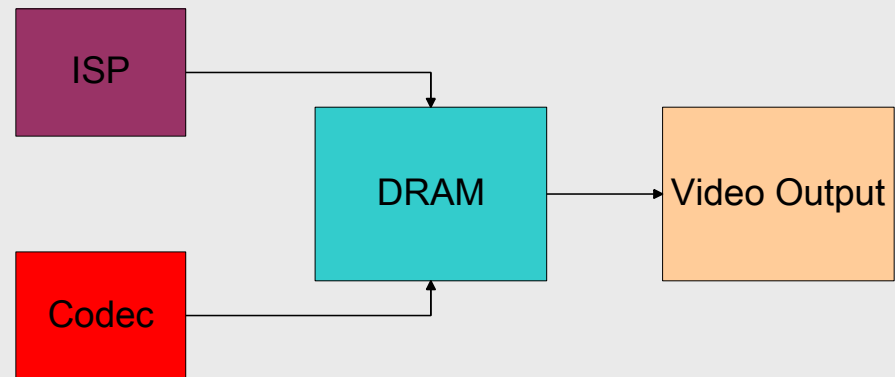
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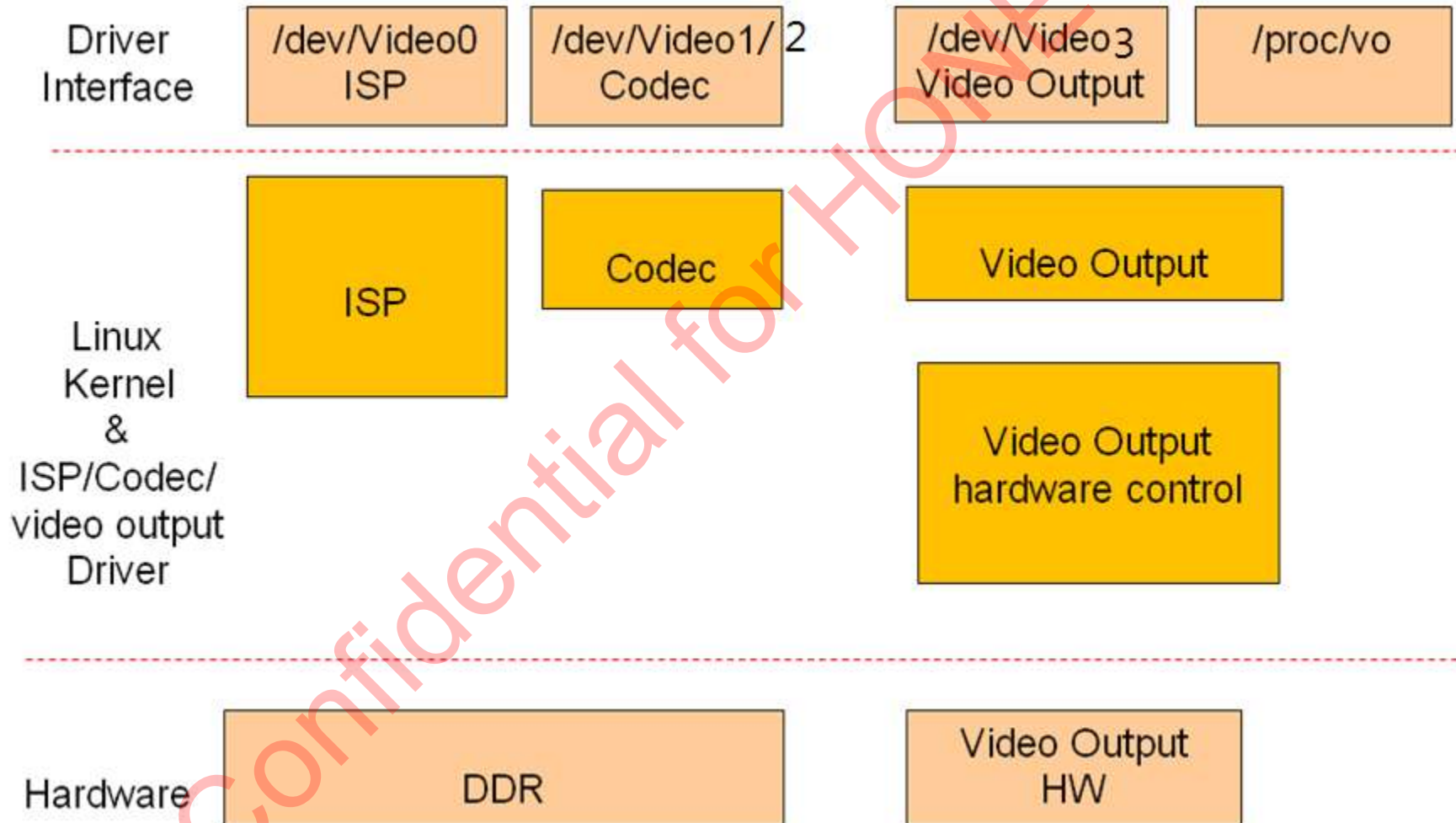
Video Output

- ◆ SN98600 / SN98610 support TV output
- ◆ SN98610 support digital video output
- ◆ 支持ISP / Code source image
- ◆ 支持OSD, crop, scaling 功能
- ◆ snx_vo.ko





Video Output 架构





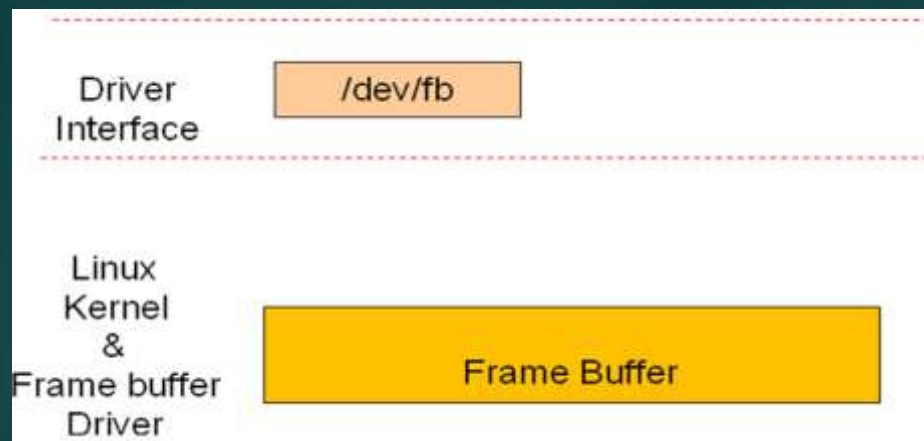
Video Output Programming

Name	Descriptions
VIDIOC_QUERYCAP	Query device capabilities
VIDIOC_S_OUTPUT	select the current video output
VIDIOC_CROPCAP	Information about the video cropping and scaling abilities
VIDIOC_S_CROP	set the current cropping rectangle
VIDIOC_S_FMT	set the data format
VIDIOC_REQBUFS	Initiate Memory Mapping or User Pointer I/O
VIDIOC_QUERYBUF	Query the status of a buffer
VIDIOC_QBUF	Exchange a buffer with the driver
VIDIOC_DQBUF	Exchange a buffer with the driver
VIDIOC_STREAMON	Start streaming I/O
VIDIOC_STREAMOFF	Stop streaming I/O



OSD

- ◆ 支持255 color and 1 transparent color
- ◆ 使用frame buffer device
- ◆ dev/fb0





OSD programming

Name	Descriptions
FBIOGET_VSCREENINFO	gets the variable screen information from the framebuffer, things like resolution, margins, color properties.
FBIOGET_FSCREENINFO	gets the fixed information about a framebuffer, such as the start and length of framebuffer memory, line length

- ◆ 透过ioctl 取得framebuffer info 然后使用mmap将更新的内容写入
- ◆ 详细请参考
 - SN986 Series Video Output Programing Guide



Video Output Programming

- ◆ Example :
 - App/example/video_output

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Thanks

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