

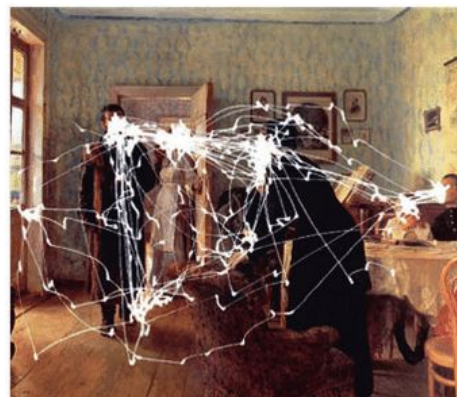
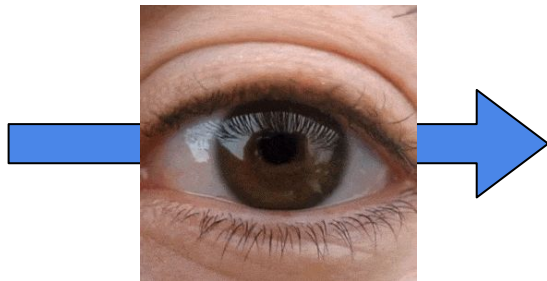
Modeling Human Eye Movements with Neural Networks in a Maze-Solving Task

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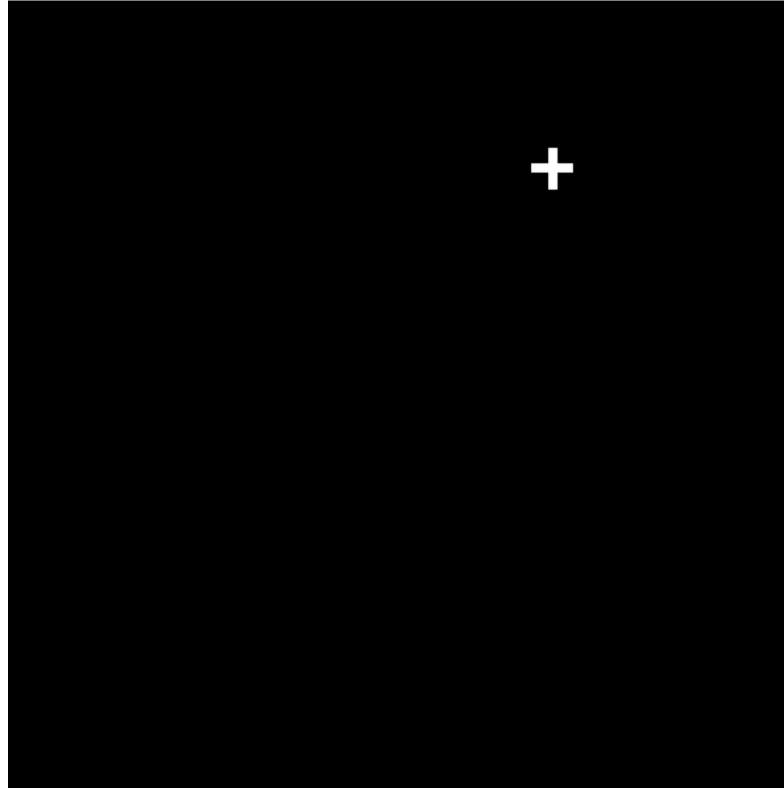
Dec. 3, 2022



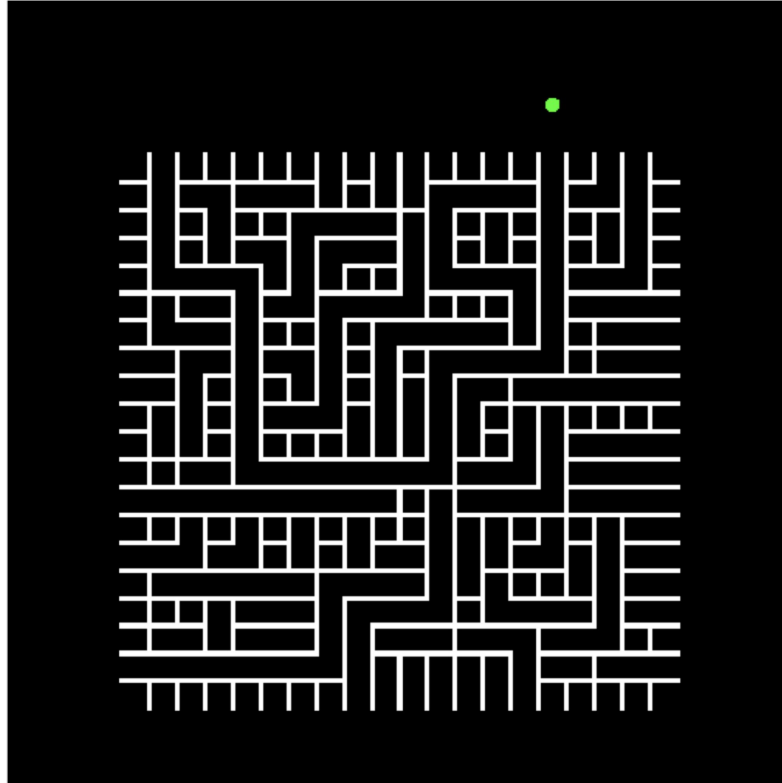
(Yarbus, 1967)

Goal: Build a **generative model of eye movements** that incorporates features of human vision like a fovea and discrete saccades.

Maze task: Fixation at Entrance



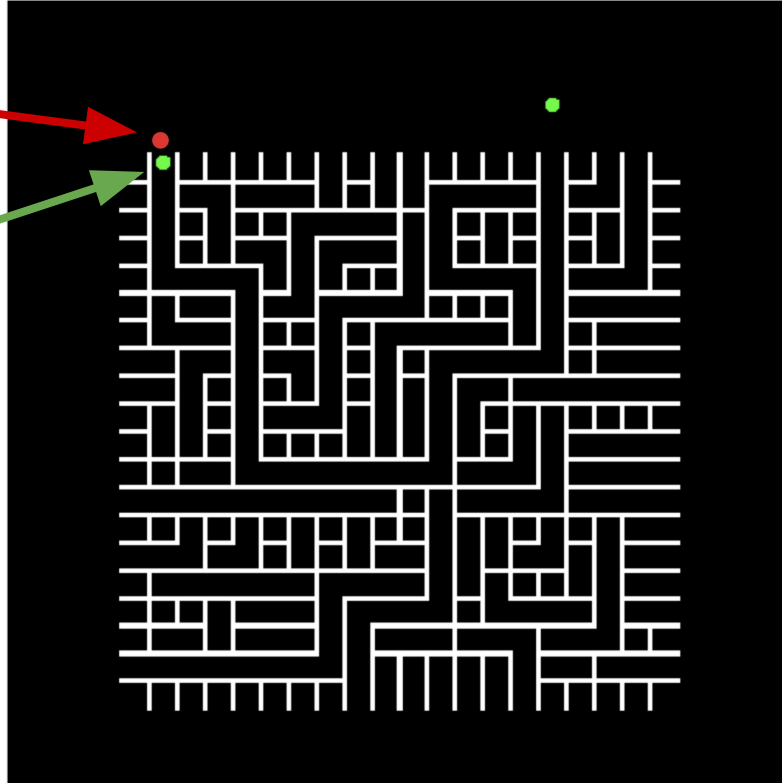
Maze task: Maze Presentation



Maze task: Saccade to the Exit

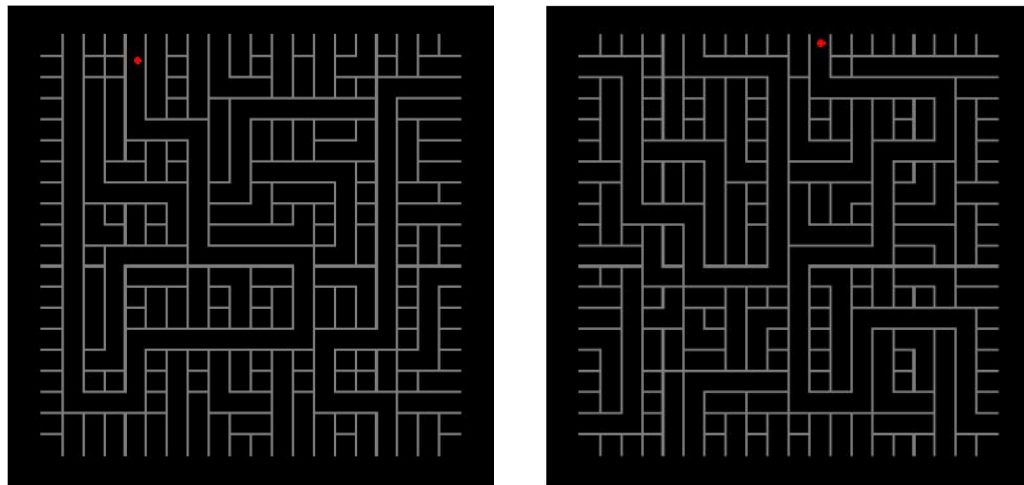
Key press to report
gaze position

Correct maze exit



Maze task

- Rich variety of spatial plans allows study of task-driven saccade sequences
- Eye movements are largely consistent across humans
- Allows us to test mental simulation as a strategy guiding eye movements



(videos shown 30% full speed)

Maze task

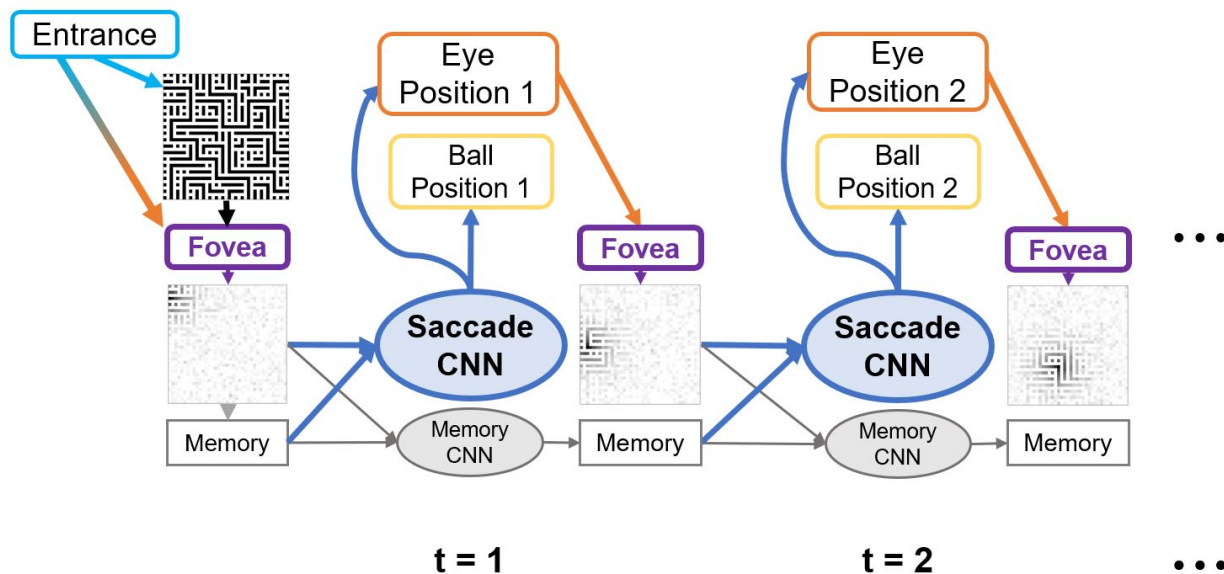
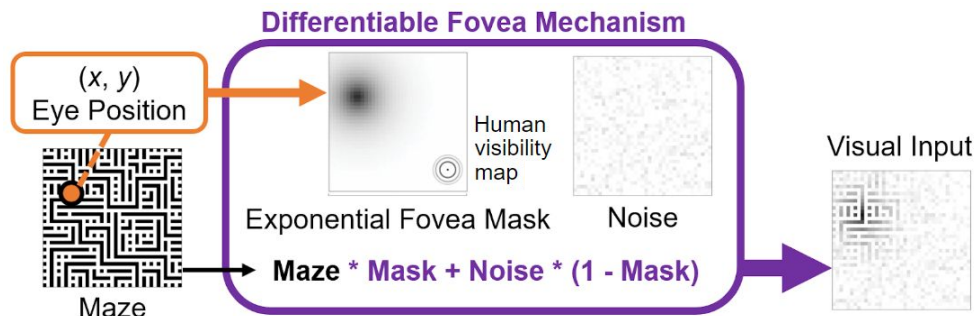
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Human data collection

- 14 human volunteers
- Each subject completed ~400 trials
- Saccades extracted by filtering and thresholding eye velocity

Gaze RNN Models

- Novel differentiable fovea mechanism allows end-to-end training
- ConvRNN architecture unrolls through time for any number of saccades



3 Gaze RNN Variations

- **EXIT**: Reach exit in as few saccades as possible

Minimize
$$L_{\text{EXIT}} = \frac{1}{n} \sum_{i=1}^n (\hat{p}_i^{\text{eye}} - p^{\text{exit}})^2$$

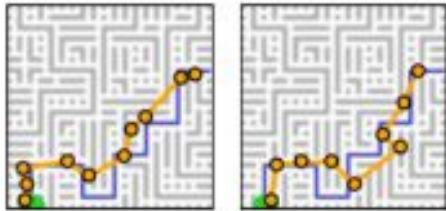
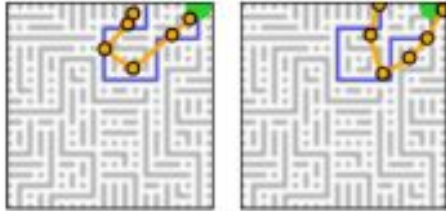
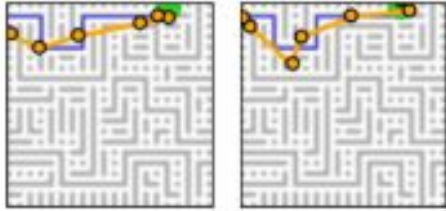
- **SIM**: Track an imaginary “ball” moving through the maze

Minimize
$$L_{\text{SIM}} = \frac{1}{n} \sum_{i=1}^n (\hat{p}_i^{\text{ball}} - p_i^{\text{ball}})^2$$

- **HYBRID**: Weighted sum of the two loss terms

Minimize
$$L_{\text{HYBRID}} = \beta \cdot L_{\text{EXIT}} + (1 - \beta) \cdot L_{\text{SIM}}$$

Results: Qualitative Behavior



Human 1

Human 2

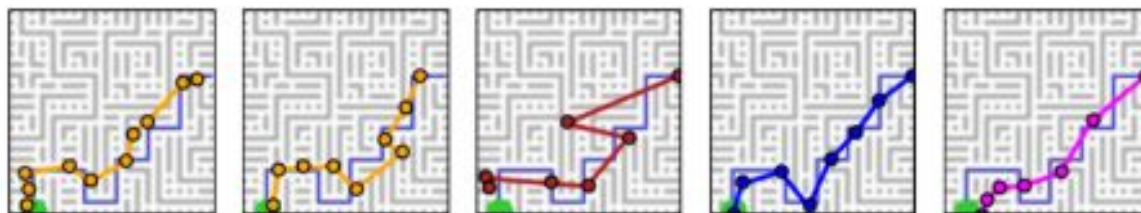
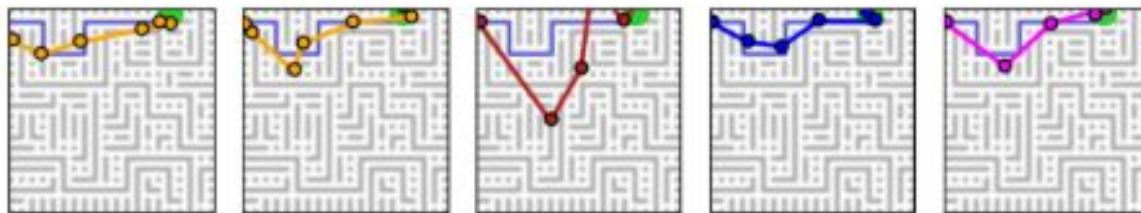
● Exit

— Path

Fixation points

● Human

Results: Qualitative Behavior



Human 1

Human 2

EXIT

SIM

HYBRID

● Exit

— Path

Fixation points

● Human

● EXIT

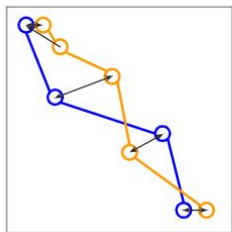
● SIM

● HYBRID

Results: Quantitative Metrics

Nearest Neighbors Distance

Mean of the nearest point in path **A** to every point in path **B** and vice versa



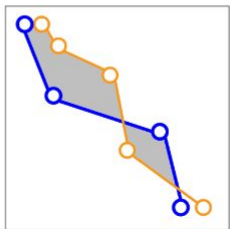
Example

—○— Human

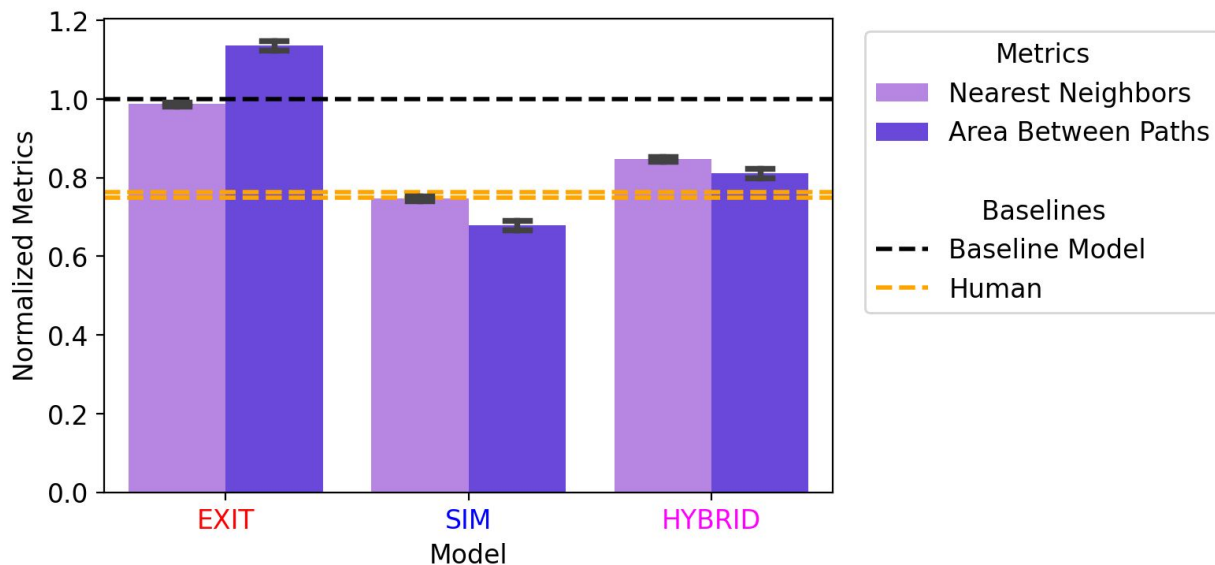
—○— SIM model

Area Between Paths

Total plane area of the polygon(s) formed between paths **A** and **B**



Metric scores between model and human eye paths



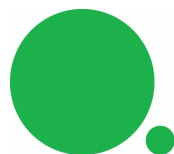
Conclusions & Future Work

- In the maze-solving task, a gaze RNN trained to run an internal simulation of a ball moving through the maze generates more human-like eye movements than a model trained to solve the task optimally
- Humans may employ a similar mental simulation when solving this task
- Future work may address:
 - Biological accuracy of model fovea hyperparameters
 - Introducing non-constant simulation speed
 - Allow gaze RNN to control fixation durations
 - Apply gaze RNNs to other task domains

Acknowledgements



brain+cognitive
sciences



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Thank you!