RCRSS中多智能体协作研究 开题报告

沈杰

南京邮电大学





- Background
- WorldModel
- Objection Maker
 3
- Dynamic Program





- Background
- WorldModel
- 3 Descision Maker
- Dynamic Program





RCRSS

RoboCup Rescue Simulation System



RCRSS

- What
- Aim
- Test Bed



图,系统结构



Heteromerous Agents

- Police
- Fire
- Ambulance



- Background
- WorldModel
- Openion Maker
 3
- Dynamic Program





World Model

世界模型



- Background
- WorldModel
- O Descision Maker
- Dynamic Program





descision





- Background
- WorldModel
- 3 Descision Maker
- Dynamic Program





路径规划





Thanks!



