RCRSS中多智能体协作研究 开题报告

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- Background
- WorldModel
- O Descision Maker
- Dynamic Program





- Background
- WorldModel
- Objection Maker
 3
- Dynamic Program





RCRSS

RoboCup Rescue Simulation System

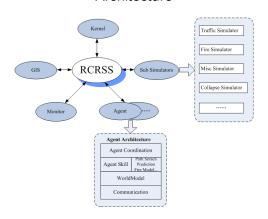


RCRSS

- What
- Aim
- Test Bed



Architecture





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Heteromerous Agents

- Police
- Fire
- Ambulance



- Background
- WorldModel
- Openion Maker
 3
- Dynamic Program





World Model

世界模型



WorldModel

What

what

How

设计合理、有效的算法模型

Go

最终都是数学模型



- Background
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- O Descision Maker
- Dynamic Program



descision



- Background
- WorldModel
- O Descision Maker
- Dynamic Program



路径规划





Thanks!

