robustDiff

Table of Contents

Inputs	. 1
Outputs	
Description	
Example	
Formula	
References	3

differentiator using smooth noise-robust differentiator formula

```
y_dot = robustDiff(y, dt, N)
```

Inputs

- y signal/vector
- **dt** time or distance between points in y
- N Number of points to use in differentiation. This value must be positive odd integer greater than 5.

Outputs

y_dot - differentiated signal/vector

Description

robustDiff differentiates a signal/vector numerically using N points. Both future information and past information are used to calculate the derivative. In signal processing, this is called non-causal. The larger the value of N, the more high frequency noise is suppressed unlike Savitsky-Golay (Lanczos differentiation) filters and Central Difference methods (see references). Note that the derivative is not estimated at the edges of y. This means that (N-1)/2 points at the beginning and end of y are NaN. See the example.

Example

```
dt = 0.001; % sampling rate of 1000Hz
t = 0:dt:3; % sec
noiseFrequency = 450; % Hz
noise = 10*rand(size(t)); % Noise is 10% of signal
frequency = 1; %Hz
y = 100*sin(2*pi*frequency*t) + noise;
N = 21; % Number of points to use to estimate derivative
y_dot_estimate = robustDiff(y, dt, N);
y_dot_actual = 100*2*pi*frequency*cos(2*pi*frequency*t);
figure('position',[1000 628 834 710]);
subplot(211);
plot(t, y);
title('y vs. t');
```

```
subplot(212);
plot(t, y_dot_actual, 'DisplayName', 'y''_{actual} of sin(t)','lineWidth',3);
hold('all')
plot(t, y_dot_estimate, 'DisplayName', 'y''_{estimate} of sin(t) + noise');
a = legend('show');
set(a,'position',[0.6653 0.4068 0.2410 0.0761])
hold('off');
disp(['Beginning and ending (N-1)/2 points of ' ...
     'y_dot_estimate are NaN']);
y_dot_estimate(1:(N-1)/2)
y_dot_estimate(end-(N-1)/2+1:end)
         Beginning and ending (N-1)/2 points of y_dot_estimate are NaN
         ans =
            NaN
                   NaN
                          NaN
                                               NaN
                                                      NaN
                                                                          NaN
                                 NaN
                                        NaN
                                                             NaN
                                                                    NaN
         ans =
            NaN
                   NaN
                          NaN
                                 NaN
                                        NaN
                                               NaN
                                                      NaN
                                                             NaN
                                                                    NaN
                                                                           NaN
                                        y vs. t
        150
        100
        50
         0
        -50
       -100 L
                   0.5
                                         1.5
                                                             2.5
                                                          y'actual of sin(t)
       1500
                                                           y'<sub>estimate</sub> of sin(t) + noise
       1000
        500
         0
       -500
       -1000
      -1500 L
                   0.5
                                                             2.5
```

Formula

This is the the formula that robustDiff implements. This is a direct quote of Pavel Holoborodko's website. Please, refer to the link for more information.

$$f'(x^*) pprox rac{1}{h} \sum_{k=1}^M c_k \cdot \left(f_k - f_{-k}
ight),$$

where

$$c_k = \frac{1}{2^{2m+1}} \left[\binom{2m}{m-k+1} - \binom{2m}{m-k-1} \right], \quad m = \frac{N-3}{2}, \quad M = \frac{N-1}{2}$$

- N Number of points used to estimate derivative
- f_k k points in front of current point
- f_{-k} k points behind current point
- h Time or distance between points

References

This function is based on the formulas by Pavel Holoborodko from his website: http://www.holoborodko.com/pavel/numerical-methods/numerical-derivative/smooth-low-noise-differentiators/ A big thanks is due to Pavel Holoborodko for developing this family of formulas.

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