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Deep Learning Final Exam No 2

Importing Libraries and mount drive from google drive for the large image dataset

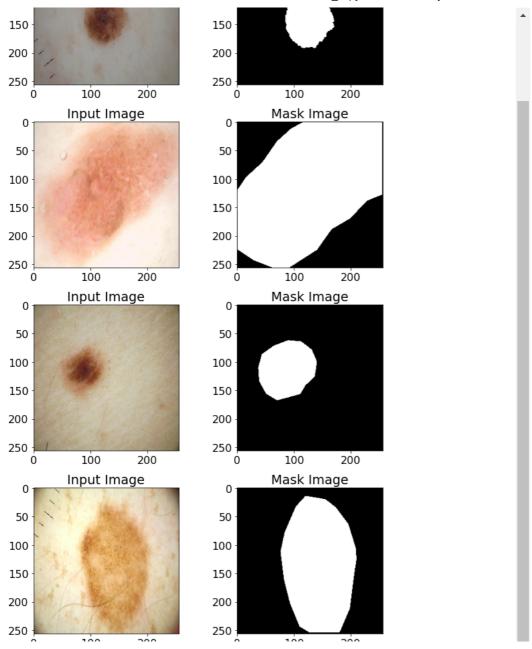
```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import os
import random
import cv2
import tensorflow as tf
import matplotlib.pvplot as plt
from keras import backend as K
from tensorflow.python.keras.models import Sequential
from keras.utils import load_img, img_to_array
from keras.preprocessing.image import ImageDataGenerator
from tensorflow.python.keras.callbacks import ModelCheckpoint, EarlyStopping
from tensorflow.keras.layers import Conv2D, BatchNormalization, Activation, MaxPool2D, Conv2DTranspose, Concatenate, Input, Dropout, Mult
from tensorflow.keras.models import Model
from google.colab import drive
drive.mount('/drive')
plt.rcParams['figure.figsize'] = (20,8)
plt.rcParams['font.size'] = 16
     Drive already mounted at /drive; to attempt to forcibly remount, call drive.mount("/drive", force_remount=True).
```

Loading and splitting image and groundtruth dataset using ImageDataGenerator from Keras Processing Image Library, here i split the validation by 15%

```
base_directory = './Skin Cancer/'
images_folder = os.path.join(base_directory, 'Training_Data')
masks_folder = os.path.join(base_directory, 'Training_GroundTruth')
img_dim = 256
image_datagen = ImageDataGenerator(rescale=1./255,validation_split=0.15)
mask_datagen = ImageDataGenerator(rescale=1./255,validation_split=0.15)
train_image_generator = image_datagen.flow_from_directory(
        base_directory,
        target_size=(img_dim, img_dim),
        class_mode = None,
        classes = ['Training_Data'],
        batch_size = 32,
        seed=2401960183,
        subset='training')
train_mask_generator = mask_datagen.flow_from_directory(
        base_directory,
        target_size=(img_dim, img_dim),
        class mode = None,
        classes = ['Training_GroundTruth'],
        color_mode = 'grayscale',
batch_size = 32,
        seed=2401960183,
        subset='training')
val_image_generator = image_datagen.flow_from_directory(
        base_directory,
        target_size=(img_dim, img_dim),
        class mode = None.
        classes = ['Training_Data'],
        batch_size = 32,
        seed=2401960183.
        subset='validation')
val_mask_generator = mask_datagen.flow_from_directory(
        base_directory,
        target_size=(img_dim, img_dim),
        class_mode = None,
        classes = ['Training GroundTruth'],
        color_mode = 'grayscale',
        batch_size = 32,
```

```
seed=2401960183,
        subset='validation')
train generator = zip(train image generator, train mask generator)
val_generator = zip(val_image_generator, val_mask_generator)
     Found 765 images belonging to 1 classes.
     Found 765 images belonging to 1 classes.
     Found 135 images belonging to 1 classes.
     Found 135 images belonging to 1 classes.
test_image_generator = image_datagen.flow_from_directory(
        base directory,
        target_size=(img_dim, img_dim),
        class_mode = None,
        classes = ['Test_Data'],
        batch_size = 32,
        seed= 2401960183,
        subset='validation')
test_mask_generator = mask_datagen.flow_from_directory(
        base_directory,
       target_size=(img_dim, img_dim),
        class_mode = None,
        classes = ['Test_GroundTruth'],
        color_mode = 'grayscale',
        batch_size = 32,
        seed= 2401960183,
        subset='validation')
test_generator = zip(test_image_generator, test_mask_generator)
     Found 56 images belonging to 1 classes.
     Found 56 images belonging to 1 classes.
training_samples_size = train_image_generator.samples
val_samples_size = val_image_generator.samples
Plot sample of input and mask image using the ImageDataGenerator instanstiated before
n = 0
```

```
for i,m in train_generator:
   img,mask = i,m
   current_mask = mask[0].astype(np.uint8)
   current_mask = current_mask[:,:,0]
   if n < 5:
       fig, axs = plt.subplots(1 , 2, figsize=(10,4))
       axs[0].imshow(img[0])
       axs[0].set_title('Input Image')
       axs[1].imshow(current_mask, cmap='gray')
       axs[1].set_title('Mask Image')
       plt.show()
       n+=1
   else:
        break
```



## 1. Architecture Of Model for Skin Lesion Segmentation, U-Net: Segmentation Architecture

For the Model reference i will be using U-Net Model. For tasks involving picture segmentation, deep learning architecture U-Net is employed. Its distinctive "U" shape, which consists of a bottleneck layer connecting an encoding path (downsampling) and a decoding path (upsampling), gave rise to its name. The decoding path stretches the features back to the original picture size through transpose convolutional layers and concatenation with features from the encoding path, while the encoding path retrieves features from the input image through a succession of convolutional and max pooling layers. This enables the resulting segmentation map to recover fine details and precisely localize features. U-Net has demonstrated strong performance in a number of areas and is frequently used for biomedical picture segmentation.

Architecture itself consists a total of 4 encoder\_block layers after the input layer, then have access to the hidden layer of CNN before going into four more decoder\_block layers. Output is sigmoid because of the prediction results only in pixel values between 0 and 1.

```
def conv_block(input, num_filters):
    x = Conv2D(num_filters, 3, padding="same")(input)
    x = BatchNormalization()(x)
    x = Activation("relu")(x)

    x = Conv2D(num_filters, 3, padding="same")(x)
    x = BatchNormalization()(x)
    x = Activation("relu")(x)
    return x

def encoder_block(input, num_filters):
```

```
x = conv_block(input, num_filters)
    p = MaxPool2D((2, 2))(x)
    return x, p
def decoder_block(input, skip_features, num_filters):
    x = Conv2DTranspose(num_filters, (2, 2), strides=2, padding="same")(input)
    x = Concatenate()([x, skip_features])
    x = conv_block(x, num_filters)
    return x
def build_unet(input_shape):
    inputs = Input(input_shape)
    s1, p1 = encoder_block(inputs, 32)
    s2, p2 = encoder_block(p1, 64)
    s3, p3 = encoder_block(p2, 128)
    s4, p4 = encoder_block(p3, 256)
    b1 = conv_block(p4, 512)
    d1 = decoder_block(b1, s4, 256)
    d2 = decoder_block(d1, s3, 128)
    d3 = decoder_block(d2, s2, 64)
    d4 = decoder_block(d3, s1, 32)
    outputs = Conv2D(1, 1, padding="same", activation="sigmoid")(d4)
    model = Model(inputs, outputs, name="U-Net")
    return model
```

Intersection over Union (IoU) measures the overlap between the predicted segmentation and the ground truth segmentation, represented by binary masks. IoU is widely used in image segmentation tasks because it provides a scalar value that summarizes the degree of overlap between the predicted and ground truth segmentations. This makes it a convenient metric for comparing different models and for tuning the parameters of a model.

```
def iou_coef(y_true, y_pred, smooth=1):
    intersection = K.sum(K.abs(y_true * y_pred), axis=[1,2,3])
    union = K.sum(y_true,[1,2,3])+K.sum(y_pred,[1,2,3])-intersection
    iou = K.mean((intersection + smooth) / (union + smooth), axis=0)
    return iou
def iou_coef_loss(y_true, y_pred):
    return -iou_coef(y_true, y_pred)
def iou_metric(y_true_in, y_pred_in, print_table=False):
    labels = label(y_true_in > 0.5)
    y_pred = label(y_pred_in > 0.5)
    true_objects = len(np.unique(labels))
    pred_objects = len(np.unique(y_pred))
    intersection = np.histogram2d(labels.flatten(), y_pred.flatten(), bins=(true_objects, pred_objects))[0]
    area_true = np.histogram(labels, bins = true_objects)[0]
    area_pred = np.histogram(y_pred, bins = pred_objects)[0]
    area_true = np.expand_dims(area_true, -1)
    area_pred = np.expand_dims(area_pred, 0)
    union = area_true + area_pred - intersection
    intersection = intersection[1:,1:]
    union = union[1:,1:]
    union[union == 0] = 1e-9
    iou = intersection / union
    def precision_at(threshold, iou):
        matches = iou > threshold
        true_positives = np.sum(matches, axis=1) == 1
        false_positives = np.sum(matches, axis=0) == 0
        false_negatives = np.sum(matches, axis=1) == 0
        tp, fp, fn = np.sum(true_positives), np.sum(false_positives), np.sum(false_negatives)
       return tp, fp, fn
    prec = []
    if print_table:
       print("Thresh\tTP\tFP\tFN\tPrec.")
    for t in np.arange(0.5, 1.0, 0.05):
        tp, fp, fn = precision_at(t, iou)
        if (tp + fp + fn) > 0:
```

```
p = tp / (tp + fp + fn)
        else:
           p = 0
        if print table:
            print("\{:1.3f\}\t{}\t{}\t{}.i.3f\}".format(t, tp, fp, fn, p))
        prec.append(p)
    if print_table:
       print("AP\t-\t-\t{:1.3f}".format(np.mean(prec)))
    return np.mean(prec)
def iou_metric_batch(y_true_in, y_pred_in):
   batch_size = y_true_in.shape[0]
   metric = []
   for batch in range(batch_size):
       value = iou_metric(y_true_in[batch], y_pred_in[batch])
       metric.append(value)
   return np.array(np.mean(metric), dtype=np.float32)
def my_iou_metric(label, pred):
   metric_value = tf.compat.v1.py_func(iou_metric_batch, [label, pred], tf.float32)
    return metric_value
Model training using the above architecture and iou coefficient metrics
input shape = (img dim, img dim, 3)
model = build_unet(input_shape)
\verb|model.compile(optimizer = tf.keras.optimizers.Adam(lr = 0.001), \ loss = ['binary\_crossentropy'], \ metrics=[iou\_coef, 'accuracy'])|
model.summary()
```

## 3x. U-Net Model Fitting and Evaluation Metrics

Below the vanilla u-net model training resulting in an accuracy of 0.9286, val\_accuracy: 0.8641, and val\_iou\_coef: 0.6133. The accuracy are high enough but the iou coefficient values are rather low considering that this is the metrics that is important for image segmentation. We will see a difference in the ground truths and predictions later below. However because of the high accuracy the mask itself also won't differ it shapes and likeness.

```
history = model.fit(train_generator,
             steps per epoch=training samples size//32,
             validation_data=val_generator,
             validation_steps=val_samples_size//32,
             epochs=10)
   Epoch 1/10
                23/23 [===
   Epoch 2/10
   23/23 Γ====
           Epoch 3/10
                ==========] - 45s 2s/step - loss: 0.2834 - iou_coef: 0.4706 - accuracy: 0.8944 - val_loss: 13.3666 - val
   23/23 [====
   Epoch 4/10
                ==========] - 41s 2s/step - loss: 0.2607 - iou_coef: 0.4975 - accuracy: 0.9043 - val_loss: 4.3185 - val_
   23/23 [=====
   Epoch 5/10
   23/23 [===:
                   ========] - 46s 2s/step - loss: 0.2276 - iou_coef: 0.5335 - accuracy: 0.9137 - val_loss: 4.2930 - val_
   Epoch 6/10
   Epoch 7/10
   23/23 [============ ] - 42s 2s/step - loss: 0.2283 - iou coef: 0.5412 - accuracy: 0.9121 - val loss: 0.3828 - val
   Epoch 8/10
   23/23 [============= ] - 43s 2s/step - loss: 0.1958 - iou_coef: 0.5788 - accuracy: 0.9254 - val_loss: 0.5856 - val_
   Epoch 9/10
   23/23 [====
                 Epoch 10/10
   23/23 [=====
                 ========] - 43s 2s/step - loss: 0.1870 - iou_coef: 0.6002 - accuracy: 0.9286 - val_loss: 0.4827 - val_
```

Generate a random validation images, masks, and predict their ground truth mask, the predicton will be mapped to 0 or 1 depending on their predicted values

Plotting the image, mask, with it's predicted mask

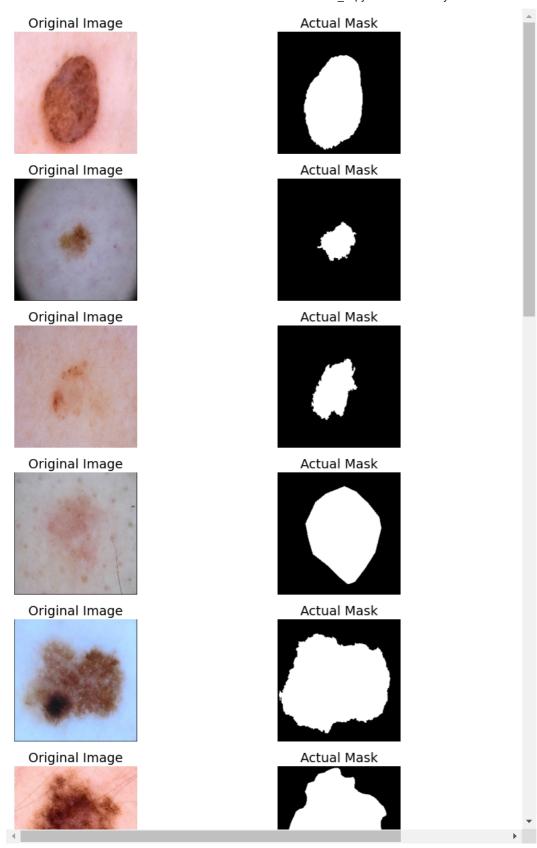
```
f, axarr = plt.subplots(15,3,figsize=(20, 60))
for i in range(0,15):
    axarr[i,0].imshow(val_image_samples[i])
    axarr[i,0].title.set_text('Original Image')
    axarr[i,0].axis('off')

    current_val_mask = val_mask_samples[i].astype(np.uint8)
    current_val_mask = current_val_mask[:,:,0]

    axarr[i,1].imshow(current_val_mask, cmap='gray')
    axarr[i,1].title.set_text('Actual Mask')
    axarr[i,1].axis('off')

    current_predicted_mask = predicted_masks[i].astype(np.uint8)
    current_predicted_mask = current_predicted_mask[:,:,0]

    axarr[i,2].imshow(current_predicted_mask, cmap='gray')
    axarr[i,2].title.set_text('Predicted_Mask')
    axarr[i,2].axis('off')
```



## 2. Adding a soft attention block to the architecture

When focusing on certain areas of an input image, such as a feature map produced by a Convolutional Neural Network (CNN), soft attention are usually used. In order to determine each element's importance in the final prediction, soft attention scores or weights are calculated for each pixel (for example) in the feature map. After that, the attended features are obtained by multiplying the feature map by the element-wise attention weights.

The soft attention block takes the features from the encoding path as input and returns the attended features and the attention weights. The attended features are then concatenated with the features from the decoding path and passed through the remaining layers to produce the final segmentation map.

```
def attention_block(input, num_filters):
    x = Conv2D(num_filters, 3, padding="same")(input)
    x = BatchNormalization()(x)
    x = Activation("relu")(x)
    x = Conv2D(num_filters, 3, padding="same")(x)
    x = BatchNormalization()(x)
    x = Activation("relu")(x)
    attention = Conv2D(1, 1, activation='sigmoid')(x)
    attended_features = Multiply()([input, attention])
    return attended_features
def build_unet_attention(input_shape):
    inputs = Input(input_shape)
    s1, p1 = encoder_block(inputs, 32)
    s2, p2 = encoder_block(p1, 64)
    s3, p3 = encoder_block(p2, 128)
    s4, p4 = encoder_block(p3, 256)
    b1 = attention_block(p4, 512)
    d1 = decoder_block(b1, s4, 256)
    d2 = decoder_block(d1, s3, 128)
    d3 = decoder_block(d2, s2, 64)
    d4 = decoder_block(d3, s1, 32)
    outputs = Conv2D(1, 1, padding="same", activation="sigmoid")(d4)
    model = Model(inputs, outputs, name="U-Net-Soft-Attention")
    return model
input_shape = (img_dim, img_dim, 3)
model attention = build unet attention(input shape)
model_attention.compile(optimizer = tf.keras.optimizers.Adam(lr = 0.001), loss = ['binary_crossentropy'], metrics=[iou_coef,'accuracy'])
model_attention.summary()
```

Model: "U-Net"

Layer (type)	Output Shape	Param #	Connected to
input_4 (InputLayer)	[(None, 256, 256, 3 )]	0	[]
conv2d_41 (Conv2D)	(None, 256, 256, 32)	896	['input_4[0][0]']
<pre>batch_normalization_38 (BatchNormalization)</pre>	(None, 256, 256, 32	2 128	['conv2d_41[0][0]']
activation_38 (Activation)	(None, 256, 256, 32)	0	['batch_normalization_38[0][0]']
conv2d_42 (Conv2D)	(None, 256, 256, 32)	9248	['activation_38[0][0]']
<pre>batch_normalization_39 (BatchNormalization)</pre>	(None, 256, 256, 32	2 128	['conv2d_42[0][0]']
activation_39 (Activation)	(None, 256, 256, 32	0	['batch_normalization_39[0][0]']

```
max_pooling2d_12 (MaxPooling2D (None, 128, 128, 32 0
                                                           ['activation_39[0][0]']
                                                           ['max_pooling2d_12[0][0]']
     conv2d 43 (Conv2D)
                               (None, 128, 128, 64 18496
     batch_normalization_40 (BatchN (None, 128, 128, 64 256
                                                           ['conv2d_43[0][0]']
     ormalization)
     activation_40 (Activation)
                               (None, 128, 128, 64 0
                                                           ['batch_normalization_40[0][0]']
     conv2d 44 (Conv2D)
                               (None, 128, 128, 64 36928
                                                           ['activation 40[0][0]']
     batch_normalization_41 (BatchN (None, 128, 128, 64 256
                                                           ['conv2d_44[0][0]']
     ormalization)
     activation_41 (Activation)
                               (None, 128, 128, 64 0
                                                           ['batch_normalization_41[0][0]']
     max_pooling2d_13 (MaxPooling2D (None, 64, 64, 64) 0
                                                           ['activation_41[0][0]']
                               (None, 64, 64, 128) 73856
                                                           ['max_pooling2d_13[0][0]']
     conv2d 45 (Conv2D)
     batch normalization 42 (BatchN (None, 64, 64, 128) 512
                                                           ['conv2d_45[0][0]']
     ormalization)
     activation_42 (Activation)
                               (None, 64, 64, 128) 0
                                                           ['batch_normalization_42[0][0]']
history = model_attention.fit(train_generator,
                steps_per_epoch=training_samples_size//32,
                 validation_data=val_generator,
                validation_steps=val_samples_size//32,
    Epoch 1/10
    Epoch 2/10
    23/23 [====
               Epoch 3/10
    23/23 [====
                            ========] - 41s 2s/step - loss: 0.2905 - iou_coef: 0.4666 - accuracy: 0.8958 - val_loss: 0.8236 - val_
    Epoch 4/10
    23/23 [============ ] - 42s 2s/step - loss: 0.2766 - iou_coef: 0.4735 - accuracy: 0.8958 - val_loss: 0.7615 - val_
    Epoch 5/10
    23/23 [============ ] - 44s 2s/step - loss: 0.2594 - iou coef: 0.5032 - accuracy: 0.9035 - val loss: 0.8820 - val
    Epoch 6/10
    23/23 [============= ] - 44s 2s/step - loss: 0.2390 - iou_coef: 0.5257 - accuracy: 0.9097 - val_loss: 0.7317 - val_
    Epoch 7/10
    23/23 [====
                     ==========] - 44s 2s/step - loss: 0.2090 - iou_coef: 0.5582 - accuracy: 0.9248 - val_loss: 0.9885 - val_
```

23/23 [============= ] - 39s 2s/step - loss: 0.2205 - iou\_coef: 0.5761 - accuracy: 0.9166 - val\_loss: 1.0008 - val\_

23/23 [=========== ] - 40s 2s/step - loss: 0.1975 - iou coef: 0.5915 - accuracy: 0.9258 - val loss: 0.6422 - val

==========] - 44s 2s/step - loss: 0.2152 - iou\_coef: 0.5608 - accuracy: 0.9197 - val\_loss: 1.5790 - val\_

Using the test\_generator to generate samples from test images folder

Epoch 8/10

Epoch 9/10 23/23 [===:

Epoch 10/10

## 2. Adding a soft attention block to the architecture