

Bayes' Theorem

Let A_1, \dots, A_n be partitions of S. For any event B:

$$P(A_k|B) = \frac{P(B|A_k)P(A_k)}{\sum_{i=1}^n P(B|A_k)P(A_i)}$$

02. Random Variables

- Motivation: Assign value to outcome of experiment

- **Random Variable** - Let S be sample space. Function X which maps \mathbb{R} to every $s \in S$

Probability Distribution

- Probability assigned to each possible X

- Given RV X with range of R_x :

Discrete - Numbers in R_x are finite or countable

Continuous - R_x is interval

Discrete Probability Distribution

- **Probability Function** - Given $R_x = \{x_1, \dots\}$. For each x_i , there's some probability that $X = x_i$:

$$f(x) = P(X = x)$$

- *p.f.* must satisfy:

1. $f(x_i) = P(X = x_i)$ for $x_i \in R_x$
2. $f(x_i) = 0$ for $x_i \notin R_x$
3. $\sum_{i=1}^{\infty} f(x_i) = 1$
4. $\forall B \subseteq \mathbb{R}, P(X \in B) = \sum_{x_i \in B \cap R_x} f(x_i)$

- **Probability Distribution** - Collection of pairs $(x_i, f(x_i))$

Continuous Probability Distribution

- **Probability Function** - Given R_x is interval. Quantifies probability that X is in some range.

- *p.f.* must satisfy:

1. $f(x) \geq 0$
2. $f(x) = 0$ for $x \notin R_x$
3. $\int_{R_x} f(x)dx = 1$
4. $\forall a, b \text{ s.t. } a \leq b, P(a \leq X \leq b) = \int_a^b f(x)dx$

- Note: $P(X = x_0) = \int_{x_0}^{x_0} f(x)dx = 0$

Cumulative Distributive Function

Given RV X, which can be discrete or continuous:

$$F(x) = P(X \leq x)$$

- $F(x)$ is non-decreasing and $0 \leq F(x) \leq 1$

- **For discrete RV:** Step function

$$F(x) = \sum_{t \in R_x; t \leq x} f(t)$$

- $P(a \leq X \leq b) = F(b) - \lim_{x \rightarrow a^-} F(x)$
- $0 \leq f(x) \leq 1$

- **For continuous RV:**

$$F(x) = \int_{-\infty}^x f(t)dt$$

$$f(x) = \frac{d(F(x))}{dx}$$

- $P(a \leq X \leq b) = P(a < X < b) = F(b) - F(a)$
- $0 \leq f(x)$ e.g. $f(x) = 3x^2$ is a valid *p.f.* since $\int_{R_x} f(x)dx = 1$

Expectation of Random Variable

- **Mean of discrete RV:**

$$\mu = E(X) = \sum_{x \in R_x} x_i f(x_i) = \sum_{i=1}^{\infty} P(X \geq i)$$

- Let g be some function. $E(g(x)) = \sum_{x \in R_x} g(x)f(x)$

- **Mean of continuous RV:**

$$\mu = E(X) = \int_{x \in R_x} x f(x)dx$$

- Let g be some function. $E(g(x)) = \int_{x \in R_x} g(x)f(x)dx$

- $E(aX + b) = aE(X) + b$

- Linearity of expectation: $E(X + Y) = E(X) + E(Y)$

Variance of Random Variable

$$\sigma_X^2 = V(X) = E((X - \mu_X)^2)$$

- **Variance of discrete RV:**

$$V(X) = \sum_{x \in R_x} (x - \mu_X)^2 f(x)$$

- **Variance of continuous RV:**

$$V(X) = \int_{x \in R_x} (x - \mu_X)^2 f(x)dx$$

- $V(X) = 0$ when X is a constant

- $V(aX + b) = a^2 V(X)$

- $V(X) = E(X^2) - (E(X))^2$

- **Standard Deviation** - $\sigma_X = \sqrt{V(X)}$

03. Joint Distributions

- Motivation: What if interested in more than 1 RV simultaneously?

- Given sample space S. Let X and Y be functions mapping $s \in S \rightarrow \mathbb{R}$:

(X, Y) is 2D random vector

Range space: $R_{X,Y} = \{(x, y) | x = X(s), y = Y(s), s \in S\}$

- **Discrete 2D RV** - If no. of possible values of $(X(s), Y(s))$ are finite or countable

- **Continuous 2D RV** - If no. of possible values of $(X(s), Y(s))$ can be any value in Euclidean space \mathbb{R}^2

- If both X and Y are discrete/continuous, then (X, Y) is discrete/countinuous.

01. Basic Concepts of Probability**Event Operations**

- **Mutually Exclusive** - $A \cap B = \emptyset$

- **Contained** - $A \subset B$

- **Equivalence** - $A \subset B$ and $A \supset B \rightarrow A = B$

- **Distributive** - $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$

- **DeMorgan's** - $(A \cup B)' = A' \cap B'$

- $A = (A \cap B) \cup (A \cap B')$

Counting Methods

- **Multiplication Principle** - Given r experiments performed sequentially and each has n_1, n_2, \dots, n_r outcomes. After r experiments, there are $n_1 n_2 \dots n_r$ outcomes.

- **Addition Principle** - Given experiment can be done in k different ways and each has n_1, n_2, \dots, n_r ways. There are $n_1 + n_2 + \dots + n_k$ total ways.

- **Permutation** - $nPr = \frac{n!}{(n-r)!}$

- **Combination** - $\binom{n}{r} = \frac{n!}{(n-r)!r!}$

Probability**Axioms of Probability**

1. For any event A, $0 \leq P(A) \leq 1$
2. $P(S) = 1$
3. If $A \cap B = \emptyset$, then $P(A \cup B) = P(A) + P(B)$

- $P(A') = 1 - P(A)$

- $P(A) = P(A \cap B) + P(A \cap B')$

- $P(A \cup B) = P(A) + P(B) - P(A \cap B)$

- If $A \subset B$, then $P(A) < P(B)$

Finite Sample Space with Equally Likely Outcomes

Given sample space $S = \{a_1, \dots, a_k\}$ and all outcomes are **equally likely**, i.e. $P(a_1) = \dots = P(a_k)$:

$$\text{For any event } A \subset S, P(A) = \frac{\text{No. of sample points in } A}{\text{No. of sample points in } S}$$

Conditional Probability

$$P(B|A) = \frac{P(B \cap A)}{P(A)} = \frac{P(A|B)P(B)}{P(A)}$$

Independence

- $A \perp B \leftrightarrow P(A \cap B) = P(A)P(B)$

- $A \perp B \leftrightarrow P(A|B) = P(A)$

Law of Total Probability

- **Partition** - If A_1, \dots, A_n are mutually exclusive events and $\bigcup_{i=1}^n A_i = S$, then A_1, \dots, A_n are partitions

- If A_1, \dots, A_n are partitions of S, then for any event B:

$$P(B) = \sum_{i=1}^n P(B \cap A_i) = \sum_{i=1}^n P(B|A_i)P(A_i)$$

Joint Probability Function

• For discrete:

f_{X,Y}(x,y) = P(X = x, Y = y)

- f_{X,Y}(x,y) ≥ 0 for any (x,y) ∈ R_{X,Y}
- f_{X,Y}(x,y) = 0 for any (x,y) ∉ R_{X,Y}
- ∑_{i=1}^∞ ∑_{j=1}^∞ P(X = x_i, Y = y_j) = 1
- Let A ⊆ R_{X,Y}. P((X,Y) ∈ A) = ∑ ∑_{(x,y) ∈ A} f_{X,Y}(x,y)

• For continuous:

P(a ≤ X ≤ b, c ≤ Y ≤ d) = ∫_a^b ∫_c^d f_{X,Y}(x,y) dy dx

- f_{X,Y}(x,y) ≥ 0 for any (x,y) ∈ R_{X,Y}
- f_{X,Y}(x,y) = 0 for any (x,y) ∉ R_{X,Y}
- ∫_{-∞}^∞ ∫_{-∞}^∞ f_{X,Y}(x,y) dx dy = 1

Marginal Probability Function

Let (X,Y) be a 2D RV with joint probability function f_{X,Y}(x,y):

If Y is discrete, f_X(x) = ∑_y f_{X,Y}(x,y)

If Y is continuous, f_X(x) = ∫_{-∞}^∞ f_{X,Y}(x,y) dy

- f_Y(y) defined similarly
- Intuition: Marginal distribution for X ignores presence of Y
- f_X(x) is a p.f.

Conditional Distribution

Let (X,Y) be a 2D RV with joint probability function f_{X,Y}(x,y). Then ∀x s.t. f_X(x) > 0:

f_{Y|X}(y|x) = f_{X,Y}(x,y) / f_X(x)

- Intuition: Distribution of Y given X = x
- Only defined for x s.t. f_X(x) > 0
- f_{Y|X}(y|x) is a p.f. if we fix x
- But, f_{Y|X}(y|x) is not a p.f. for x
- P(Y ≤ y | X = x) = ∫_{-∞}^y f_{Y|X}(y|x) dy
- E(Y | X = x) = ∫_{-∞}^∞ y f_{Y|X}(y|x) dy

Independent Random Variables

X ⊥ Y ⇔ ∀x,y, f_{X,Y}(x,y) = f_X(x) f_Y(y)

- Necessary condition: R_{X,Y} must be a product space. Else, dependent.

Properties

Suppose X,Y are independent RV:

- If A, B ⊆ ℝ, then events X ∈ A and Y ∈ B are independent:

P(X ∈ A; Y ∈ B) = P(X ∈ A) P(Y ∈ B)

- g_1(X) and g_2(Y) are independent
- Independence is related with conditional distribution:

f_X(x) > 0 → f_{Y|X}(y|x) = f_Y(y)

f_Y(y) > 0 → f_{X|Y}(x|y) = f_X(x)

Quick way to check independence

1. R_{X,Y} is a product space. i.e. R_X does not depend on Y and vice versa.
2. f_{X,Y}(x,y) can be written as c g_1(x) g_2(y) where g_1 depends on x only and g_2 depends on y only.
3. For discrete: f_X(x) = ∑_{t ∈ R_X} g_1(t) / g_1(x)
4. For continuous: f_X(x) = ∫_{t ∈ R_X} g_1(t) dt / ∫_{t ∈ R_X} g_1(t) dt

Expectation

Given 2 variable function g(x,y):

If (X,Y) is discrete, E(g(X,Y)) = ∑_x ∑_y g(x,y) f_{X,Y}(x,y)

If (X,Y) is continuous, E(g(X,Y)) = ∫_{-∞}^∞ ∫_{-∞}^∞ g(x,y) f_{X,Y}(x,y) dy dx

- E(XY) = E(X)E(Y) if X ⊥ Y

Covariance

cov(X,Y) = E((X - E(X))(Y - E(Y)))

If (X,Y) is discrete, cov(X,Y) = ∑_x ∑_y (x - μ_X)(y - μ_Y) f_{X,Y}(x,y)

If (X,Y) is cont., cov(X,Y) = ∫_{-∞}^∞ ∫_{-∞}^∞ (x - μ_X)(y - μ_Y) f_{X,Y}(x,y) dx dy

- cov(X,Y) = E(XY) - E(X)E(Y)
- X ⊥ Y → cov(X,Y) = 0. But converse is not always true.
- cov(aX + b, cY + d) = (ac)cov(X,Y)
- V(aX + bY) = a^2V(X) + b^2V(Y) + 2abcov(X,Y)
- X ⊥ Y → V(X + Y) = V(X) + V(Y)

04. Special Probability Distributions

Discrete Uniform Distribution

- If X has values x_1, x_2, ..., x_k with equal probability
- p.f.: f_X(x) = 1/k where x = x_1, ..., x_k and 0 otherwise
- Expectation: μ_X = E(X) = ∑_{i=1}^k x_i f_X(x_i) = 1/k ∑_{i=1}^k x_i
- Variance: σ_X^2 = V(X) = E(X^2) - (E(X))^2 = 1/k ∑_{i=1}^k x_i^2 - μ_X^2

Bernoulli

- **Bernoulli Trial** - Random experiment with 2 possible outcomes (success and failure)

Bernoulli Random Variable

- Number of successes in Bernoulli trial (Either 1 or 0)
- Let 0 ≤ p ≤ 1 be the probability of success in Bernoulli trial

f_X(x) = P(X = x) = { p x=1, 1-p x=0, 0 otherwise

- f_X(x) = p^x(1-p)^{1-x} for x = 0 or 1
- Notation: X ~ Ber(p) and q = 1 - p
- μ_X = E(X) = p and σ_X^2 = V(X) = p(1-p)

Bernoulli Process

- Sequence of repeatedly performed independent and identical Ber. trials
- Generates sequence of independent and identically distributed (i.i.d.) Ber. RVs: X_1, X_2, ...

Binomial Distribution

- **Binomial RV** - Counts the number of successes in n trials in a Ber. process
- Given n trials with each trial having probability p of success:

P(X = x) = (n choose x) p^x (1-p)^{n-x}

- Notation: X ~ B(n,p)
- E(X) = np and V(X) = np(1-p)

Negative Binomial Distribution

- Let X = Number of i.i.d. Bernoulli(p) trials until kth success occurs

P(X = x) = (x-1 choose k-1) p^k (1-p)^{x-k}

- Notation: X ~ NB(k,p)
- E(X) = 1/p and V(X) = (1-p)/p^2

Geometric Distribution

- Let X = Number of i.i.d. Bernoulli(p) trials until 1st success occurs

P(X = x) = p(1-p)^{x-1}

- Notation: X ~ G(p)
- E(X) = 1/p and V(X) = (1-p)/p^2

Poisson Distribution

- **Poisson RV** - Denotes number of events happening in fixed period of time

P(X = k) = e^{-λ} λ^k / k!

- Notation: X ~ Poisson(λ) where λ > 0 is expected number of occurrences during some period
- E(X) = λ and V(X) = λ
- **Poisson Process** - Continuous time process, where we count number of correucesn within some interval of time