

Answer Key for the Practice Problems.

1 For each of the following vectors \mathbf{x} , find the projection of \mathbf{x} in the direction of \mathbf{v} .

- Find the projection of $\mathbf{x} = (3, 3, 3)$ in the direction of $\mathbf{v} = (2, 4, 6)$.
- Find the projection of $\mathbf{x} = (1, 2, 3)$ in the direction of $\mathbf{v} = (1, 1, 1)$.
- Find the projection of $\mathbf{x} = (1, 2)$ in the direction of $\mathbf{v} = (3, 4)$.

(a) $\text{proj}_{\mathbf{v}} \mathbf{x} = \frac{\langle \mathbf{x}, \mathbf{v} \rangle}{\langle \mathbf{v}, \mathbf{v} \rangle} \mathbf{v}; \langle \mathbf{x}, \mathbf{v} \rangle = \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix} = 6 + 12 + 18 = 36; \langle \mathbf{v}, \mathbf{v} \rangle = \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix} = 4 + 16 + 36 = 56; \text{proj}_{\mathbf{v}} \mathbf{x} = \frac{36}{56} \mathbf{v} = \boxed{\frac{9}{14} \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix}}$

(b) $\text{proj}_{\mathbf{v}} \mathbf{x} = \frac{\langle \mathbf{x}, \mathbf{v} \rangle}{\langle \mathbf{v}, \mathbf{v} \rangle} \mathbf{v}; \langle \mathbf{x}, \mathbf{v} \rangle = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 1 + 2 + 3 = 6; \langle \mathbf{v}, \mathbf{v} \rangle = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = 1 + 1 + 1 = 3; \text{proj}_{\mathbf{v}} \mathbf{x} = \frac{6}{3} \mathbf{v} = \boxed{2 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}}$

(c) $\text{proj}_{\mathbf{v}} \mathbf{x} = \frac{\langle \mathbf{x}, \mathbf{v} \rangle}{\langle \mathbf{v}, \mathbf{v} \rangle} \mathbf{v}; \langle \mathbf{x}, \mathbf{v} \rangle = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = 3 + 8 = 11; \langle \mathbf{v}, \mathbf{v} \rangle = \begin{pmatrix} 3 \\ 4 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \end{pmatrix} = 9 + 16 = 25; \text{proj}_{\mathbf{v}} \mathbf{x} = \boxed{\frac{11}{25} \begin{pmatrix} 3 \\ 4 \end{pmatrix}}$

2 For each of the following lines, provide a **parametrization** of the line in the form $\mathbf{r}(t) = \mathbf{p}_0 + t\mathbf{d}$ for $\mathbf{p}_0, \mathbf{d} \in \mathbb{R}^n$ for appropriate n .

- The line in \mathbb{R}^3 passing through $\mathbf{p} = (1, 2, 3)$ with direction vector $\mathbf{d} = (4, 5, 6)$.
- The line in \mathbb{R}^2 satisfying the equation $y = \frac{3}{2}x + 4$
- The line in \mathbb{R}^3 passing through the points $\mathbf{p} = (3, 2, 1)$ and $\mathbf{q} = (1, 2, 3)$.

(a) $\mathbf{r}(t) = \mathbf{p}_0 + t\mathbf{d} = \mathbf{p} + t\mathbf{d} = \boxed{\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}}$

(b) $y = \frac{3}{2}x + b$: $\mathbf{d} = \begin{pmatrix} q \\ r \end{pmatrix} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$; $\mathbf{p}_0 = \begin{pmatrix} 0 \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$; $\mathbf{r}(t) = \boxed{\begin{pmatrix} 0 \\ 4 \\ t \begin{pmatrix} 2 \\ 3 \end{pmatrix} \end{pmatrix}}$

(c) $\mathbf{d} = \mathbf{q} - \mathbf{p} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \\ 2 \end{pmatrix}$; $\mathbf{r}(t) = \mathbf{p} + t\mathbf{d} = \boxed{\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -2 \\ 0 \\ 2 \end{pmatrix}}$

3 For each of the following planes, determine the **implicit equation** of the plane in the form $ax + by + cz = d$ for scalars $a, b, c, d \in \mathbb{R}$.

- The plane passing through the points $\mathbf{p}_1 = (3, 4, 5)$, $\mathbf{p}_2 = (2, 3, 1)$, and $\mathbf{p}_3 = (5, 5, 2)$.
- The plane with normal vector $\mathbf{N} = (1, 2, 3)$ passing through the point $\mathbf{p} = (3, 2, 1)$.
- The plane with parametrization $P(t, s) = (1, 2, 3) + (1, 2, 0)t + (0, 2, 1)s$ for $t, s \in \mathbb{R}$.
- The plane with direction vectors $\mathbf{d}_1 = (1, 2, 2)$ and $\mathbf{d}_2 = (2, 2, 1)$ intersecting the origin.

(a) $\mathbf{d}_1 = \mathbf{p}_1 - \mathbf{p}_2 = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} - \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}; \mathbf{d}_2 = \mathbf{p}_3 - \mathbf{p}_2 = \begin{pmatrix} 5 \\ 5 \\ 2 \end{pmatrix} - \begin{pmatrix} 2 \\ 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}; \mathbf{N} = \mathbf{d}_1 \times \mathbf{d}_2 = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} \times \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \det \begin{pmatrix} i & j & k \\ 1 & 1 & 4 \\ 3 & 2 & 1 \end{pmatrix} = (i)[(1)(1) - (4)(2)] + (-j)[(1)(1) - (4)(3)] + k[(1)(2) - (3)(1)] = (i)(-7) + (j)(11) + (k)(-1) = \begin{pmatrix} -7 \\ 11 \\ -1 \end{pmatrix}$

implicit equation: $\langle \mathbf{N}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \rangle = \langle \mathbf{N}, \mathbf{p}_0 \rangle; \langle \mathbf{N}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \rangle = \begin{pmatrix} -7 \\ 11 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = -7x + 11y - z; \langle \mathbf{N}, \mathbf{p}_2 \rangle = \langle \mathbf{N}, \mathbf{p}_1 \rangle = \begin{pmatrix} -7 \\ 11 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} = -21 + 44 - 5 = 18; \text{Ans: } -7x + 11y - z = 18$

(b) $\langle N, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \rangle = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = x + 2y + 3z; \langle N, p_0 \rangle = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 4 \\ 3 \end{pmatrix} = 3 + 4 + 3 = 10;$
 implicit eqn: $\underbrace{x + 2y + 3z = 10}_{};$

(c) $d_1 = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}; d_2 = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}; N = d_1 \times d_2 = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} = \det \begin{pmatrix} 1 & 2 & 0 \\ 0 & 2 & 1 \\ 2 & 0 & 1 \end{pmatrix} = i[(1)(1) - (0)(2)]$

$$+ (-j)[(1)(1) - (0)(0)] + k[(1)(2) - (2)(0)] = \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix};$$

$\langle N, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \rangle = \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 2x - y + 2z; p_0 = P(0,0) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}; \langle N, p_0 \rangle = \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$
 $= 2 + (-1) + (6) = 6; \text{ Answer: } \underbrace{2x - y + 2z = 6}_{};$

(d) $N = d_1 \times d_2 = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} \times \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = \det \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 1 \\ 0 & 2 & 1 \end{pmatrix} = i[(2)(1) - (2)(2)] + (-j)[(1)(0) - (2)(2)]$
 $+ k[(1)(2) - (2)(1)] = i(2 - 4) + j(-1 + 4) + k(2 - 4) = \begin{pmatrix} -2 \\ 3 \\ -2 \end{pmatrix}; \langle N, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \rangle = -2x + 3y - 2z;$

passing through the origin: $p_0 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}; \langle N, p_0 \rangle = \begin{pmatrix} -2 \\ 3 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = 0; \text{ Answer: } \underbrace{-2x + 3y - 2z = 0}_{};$

④ For each matrix, determine if the matrix is invertible. If it is invertible, find its inverse.

(a) $A_1 = \begin{pmatrix} 1 & -2 \\ 3 & -6 \end{pmatrix}$

(c) $A_3 = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 2 & 1 \end{pmatrix}$

(e) $A_5 = \begin{pmatrix} 2 & 0 & 4 \\ 2 & 3 & 0 \\ 0 & 3 & 4 \end{pmatrix}$

(b) $A_2 = \begin{pmatrix} 3 & 2 \\ 2 & 3 \end{pmatrix}$

(d) $A_4 = \begin{pmatrix} 1 & 3 & -5 \\ 2 & 2 & -2 \\ 3 & 1 & 1 \end{pmatrix}$

(f) $A_6 = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$

(a) $\det(A_1) = (1)(-6) - (3)(-2) = -6 + 6 = 0; A_1 \text{ is } \underbrace{\text{not invertible}}_{}$

(b) Using the formula: $\det(A_2) = (3)(3) - (2)(2) = 9 - 4 = 5; A_2^{-1} = \frac{1}{5} \begin{pmatrix} 3 & -2 \\ -2 & 3 \end{pmatrix};$

(c) Method 1: Gaussian Elimination on $(A \ I_3)$ to get $(I_3 \ A^{-1})$;

$$(A_3 \ I_3) = \begin{pmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 3 & 1 & 0 & 1 & 0 \\ 3 & 2 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -5 & -2 & 1 & 0 \\ 3 & 2 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-4R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -5 & -2 & 1 & 0 \\ 0 & 0 & 12 & 5 & -4 & 1 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{12}R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & 5 & -2 & 1 & 0 \\ 0 & 0 & 1 & \frac{5}{12} & -\frac{1}{3} & \frac{1}{12} \end{pmatrix} \xrightarrow{-3R_3 + R_1 \leftrightarrow R_1} \begin{pmatrix} 1 & 2 & 0 & -\frac{1}{4} & 1 & -\frac{1}{4} \\ 0 & -1 & 0 & \frac{1}{12} & -\frac{2}{3} & \frac{5}{12} \\ 0 & 0 & 1 & \frac{5}{12} & -\frac{1}{3} & \frac{1}{12} \end{pmatrix} \xrightarrow{R_1 + 2R_2 \leftrightarrow R_1}$$

$$\begin{pmatrix} 1 & 0 & 0 & -\frac{1}{12} & -\frac{1}{3} & \frac{7}{12} \\ 0 & -1 & 0 & \frac{1}{12} & -\frac{2}{3} & \frac{5}{12} \\ 0 & 0 & 1 & \frac{5}{12} & -\frac{1}{3} & \frac{1}{12} \end{pmatrix} \xrightarrow{(-1)R_2 \leftrightarrow R_2} \begin{pmatrix} I_3 & -\frac{1}{12} & -\frac{1}{3} & \frac{7}{12} \\ & \frac{1}{12} & \frac{2}{3} & -\frac{5}{12} \\ & 0 & -\frac{1}{3} & \frac{1}{12} \end{pmatrix};$$

$$\boxed{A_3^{-1} = \begin{pmatrix} -\frac{1}{12} & -\frac{1}{3} & \frac{7}{12} \\ \frac{1}{12} & \frac{2}{3} & -\frac{5}{12} \\ 0 & -\frac{1}{3} & \frac{1}{12} \end{pmatrix} = \frac{1}{12} \begin{pmatrix} -1 & -4 & 7 \\ -1 & 8 & -5 \\ 5 & -4 & 1 \end{pmatrix};}$$

Method A: Cofactor Matrix. See LN4B. This method will not be in the final exam but you may use it.

$$A_3 = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 2 & 1 \end{pmatrix}; \text{ Calculating the cofactors:}$$

First Row: $C[1,1] = (-1)^{1+1} \det \begin{pmatrix} 3 & 1 \\ 2 & 1 \end{pmatrix} = (3-2) = 1; \quad C[1,2] = (-1)^{1+2} \det \begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix} = (-1)(2-3) = -1;$

$$C[1,3] = (-1)^{1+3} \det \begin{pmatrix} 2 & 3 \\ 3 & 2 \end{pmatrix} = (4-9) = -5;$$

Determinant: $\det(A_3) = (1)C[1,1] + (2)C[1,2] + (3)C[1,3] = (1)(1) + (2)(-1) + (3)(-5) = 1 + 2 - 15 = -12;$

Since $\det(A_3) \neq 0$, A_3 is invertible.

Second Row: $C[2,1] = (-1)^{2+1} \det \begin{pmatrix} 2 & 3 \\ 3 & 1 \end{pmatrix} = (-1)(2-6) = 4; \quad C[2,2] = (-1)^{2+2} \det \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix} = (1-9) = -8;$

$$C[2,3] = (-1)^{2+3} \det \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} = (-1)(2-6) = 4;$$

Third Row: $C[3,1] = (-1)^{3+1} \det \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} = (2-9) = -7; \quad C[3,2] = (-1)^{3+2} \det \begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} = (-1)(1-6) = 5;$

$$C[3,3] = (-1)^{3+3} \det \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} = (3-4) = -1;$$

Cofactor Matrix: $C = \begin{pmatrix} 1 & 1 & -5 \\ 4 & -8 & 4 \\ -7 & 5 & -1 \end{pmatrix}; \text{ Inverse: } A_3^{-1} = \frac{1}{\det(A_3)} C^T = \frac{1}{-12} \begin{pmatrix} 1 & 4 & -7 \\ 1 & -8 & 5 \\ -5 & 4 & -1 \end{pmatrix};$

(d) $A_4 = \begin{pmatrix} 1 & 3 & -5 \\ 2 & 3 & 1 \\ 3 & 2 & -2 \end{pmatrix}$ is not invertible.

Method 1: Determine linear dependence by guessing. Useful if you can see it immediately.

$$\left(\begin{matrix} 1 \\ 2 \\ 3 \end{matrix}\right) + (-2)\left(\begin{matrix} 3 \\ 2 \\ 1 \end{matrix}\right) = \left(\begin{matrix} -5 \\ -4 \\ 1 \end{matrix}\right); \text{ The columns of } A_3 \text{ are lin. dependent} \Rightarrow A_3 \text{ is not invertible.}$$

Method 2: Determine linear dependence by Gaussian Elimination.

$$A_4 = \begin{pmatrix} 1 & 3 & -5 \\ 2 & 3 & 1 \\ 3 & 2 & -2 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 3 & -5 \\ 0 & -4 & 8 \\ 3 & 2 & -2 \end{pmatrix} \xrightarrow{-3R_1 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 3 & -5 \\ 0 & -4 & 8 \\ 0 & -8 & 16 \end{pmatrix}; \text{ The 3rd column does NOT have a pivot.}$$

$\therefore A_4$ has linearly dependent columns; $\therefore A_4$ is not invertible.

Note: Doing Gaussian Elimination on $(A_4 \ I_3)$ will yield the same 3 columns.

Since at least one of the first 3 columns does not have a pivot, A_4 is not invertible.

Method 3: Determine invertibility by the determinant.

$$\begin{aligned} \det(A_3) &= \det \begin{pmatrix} 1 & 3 & -5 \\ 2 & 3 & 1 \\ 3 & 2 & -2 \end{pmatrix} = (1)\det \begin{pmatrix} 2 & -2 \\ 1 & 1 \end{pmatrix} + (-1)(2)\det \begin{pmatrix} 3 & -5 \\ 1 & 1 \end{pmatrix} + (3)\det \begin{pmatrix} 3 & -5 \\ 2 & -2 \end{pmatrix} \\ &= (1)[2 - (-2)] + (-2)[3 - (-5)] + (3)[-6 - (-10)] = (1)(4) + (-2)(8) + (3)(4) \\ &= 4 - 16 + 12 = 0; \end{aligned}$$

Since $\det(A_3) = 0$, A_3 is not invertible.

(e) **Method 1.** We can use Gaussian Elimination on $(A_3 \ I_3)$ to get $(I_3 \ A_3^{-1})$:

$$(A_3 \ I_3) = \begin{pmatrix} 2 & 0 & 4 & 1 & 0 & 0 \\ 2 & 3 & 0 & 0 & 1 & 0 \\ 0 & 3 & 4 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 2 & 0 & 4 & 1 & 0 & 0 \\ 0 & 3 & -4 & -1 & 1 & 0 \\ 0 & 3 & 4 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{-R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 2 & 0 & 4 & 1 & 0 & 0 \\ 0 & 3 & -4 & -1 & 1 & 0 \\ 0 & 0 & 8 & 1 & -1 & 1 \end{pmatrix}$$

$$\xrightarrow{\frac{2R_1}{8} \leftrightarrow R_1} \begin{pmatrix} 4 & 0 & 8 & 2 & 0 & 0 \\ 0 & 6 & -8 & -2 & 2 & 0 \\ 0 & 0 & 8 & 1 & -1 & 1 \end{pmatrix} \xrightarrow{R_1 + (-1)R_3 \leftrightarrow R_1} \begin{pmatrix} 4 & 0 & 0 & 1 & 1 & 1 \\ 0 & 6 & 0 & -1 & 1 & 1 \\ 0 & 0 & 8 & 1 & -1 & 1 \end{pmatrix} \xrightarrow{\frac{1}{4}R_1 \leftrightarrow R_1} \begin{pmatrix} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 6 & 0 & -1 & 1 & 1 \\ 0 & 0 & 8 & 1 & -1 & 1 \end{pmatrix} \xrightarrow{\frac{6}{8}R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -\frac{1}{4} & \frac{1}{4} & \frac{1}{4} \\ 0 & 0 & 1 & -\frac{1}{8} & -\frac{1}{8} & \frac{1}{8} \end{pmatrix};$$

$$A_5^{-1} = \begin{pmatrix} \frac{1}{6} & \frac{1}{6} & -\frac{1}{4} \\ -\frac{1}{6} & \frac{1}{6} & \frac{1}{6} \\ \frac{1}{6} & -\frac{1}{6} & \frac{1}{6} \end{pmatrix} = \boxed{\frac{1}{24} \begin{pmatrix} 6 & 6 & -6 \\ -4 & 4 & 4 \\ 3 & -3 & 3 \end{pmatrix}};$$

Method 2. Branching from Method 1.

$$(A_5 I_3) \rightarrow \cdots \rightarrow \begin{pmatrix} 4 & 0 & 0 & 1 & 1 & -1 \\ 0 & 6 & 0 & -1 & 1 & 1 \\ 0 & 0 & 8 & 1 & -1 & 1 \end{pmatrix} \xrightarrow[3R_3 \leftrightarrow R_3]{6R_1 \leftrightarrow R_1} \begin{pmatrix} 24 & 0 & 0 & 6 & 6 & -6 \\ 0 & 24 & 0 & -4 & 4 & 4 \\ 0 & 0 & 24 & 3 & -3 & 3 \end{pmatrix} = (24I_3 \quad \frac{6}{3} \quad \frac{6}{3} \quad \frac{-6}{3}) ;$$

$$\boxed{A_5^{-1} = \frac{1}{24} \begin{pmatrix} 6 & 6 & -6 \\ -4 & 4 & 4 \\ 3 & -3 & 3 \end{pmatrix}} ; \text{ Algebraically: let } B = \begin{pmatrix} 6 & 6 & -6 \\ -4 & 4 & 4 \\ 3 & -3 & 3 \end{pmatrix} ; A_5(A_5^{-1}) = I_3 \text{ yields } 24I_3(A_5^{-1}) = B ; \text{ Then, } A_5^{-1} = \frac{1}{24}B ;$$

$$(4) (A_6 I_3) = \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow[-R_1 + R_3 \leftrightarrow R_3]{R_1 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & -1 & 1 & -1 & 0 & 1 \end{pmatrix} \xrightarrow[R_2 + R_3 \leftrightarrow R_3]{2R_1 \leftrightarrow R_1} \begin{pmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 2 & -1 & 1 & 1 \end{pmatrix} \xrightarrow[2R_2 \leftrightarrow R_2]{R_2 + (-1)R_3 \leftrightarrow R_2} \begin{pmatrix} 2 & 2 & 0 & 2 & 0 & 0 \\ 0 & 2 & 0 & 1 & 1 & -1 \\ 0 & 0 & 2 & -1 & 1 & 1 \end{pmatrix} \xrightarrow[R_1 + (-1)R_2 \leftrightarrow R_1]{R_1 + (-1)R_2 \leftrightarrow R_1} \begin{pmatrix} 2 & 0 & 0 & 1 & -1 & 1 \\ 0 & 2 & 0 & 1 & 1 & -1 \\ 0 & 0 & 2 & -1 & 1 & 1 \end{pmatrix} = (2I_3 A_6^{-1}) ;$$

$$\boxed{A_6^{-1} = \frac{1}{2} \begin{pmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & 1 \end{pmatrix}} ;$$

- (5) Determine the solution set of the following systems, i.e. identify all solutions. If there are infinite solutions, express them as a linear combination of vectors with free variables as the scalars.

$$(a) \begin{pmatrix} 1 & 2 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$$

$$(f) \begin{pmatrix} 2 & 3 & 4 \\ 3 & 4 & 5 \\ 6 & 7 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$(b) \begin{pmatrix} 2 & -4 \\ -3 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$(g) \begin{pmatrix} 1 & 2 & 3 & 4 \\ -1 & 2 & -3 & -4 \\ 1 & -2 & 3 & -4 \\ 1 & 2 & -3 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \\ 5 \\ 5 \end{pmatrix}$$

$$(c) \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 7 \\ 14 \end{pmatrix}$$

$$(h) \begin{pmatrix} 1 & 2 & 3 & 4 \\ -1 & -2 & 3 & 4 \\ 1 & 2 & -3 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 5 \\ -5 \\ 5 \end{pmatrix}$$

$$(e) \begin{pmatrix} 1 & 2 & 3 \\ 2 & 5 & 8 \\ 3 & 4 & 9 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 5 \end{pmatrix}$$

$$(a) \begin{pmatrix} 1 & 2 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix} ; \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 0 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \frac{1}{3-0} \begin{pmatrix} 3 & -2 \\ -0 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 12-10 \\ 5 \end{pmatrix} = \boxed{\frac{1}{3} \begin{pmatrix} 2 \\ 5 \end{pmatrix}}$$

$$(b) \begin{pmatrix} 2 & -4 \\ -3 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix} ; \text{ Remark: } \begin{pmatrix} 2 & -4 \\ -3 & 6 \end{pmatrix} \text{ is NOT invertible.}$$

$$\text{Aug. Mat: } \begin{pmatrix} 2 & -4 & 1 \\ -3 & 6 & 2 \end{pmatrix} \xrightarrow[2R_2 \leftrightarrow R_2]{3R_1 \leftrightarrow R_1} \begin{pmatrix} 4 & -12 & 3 \\ -4 & 12 & 4 \end{pmatrix} \xrightarrow{R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 4 & -12 & 3 \\ 0 & 0 & 7 \end{pmatrix} ; \text{ Last column has a pivot.} \quad \therefore \boxed{\text{NO SOLUTIONS.}}$$

$$(c) \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 7 \\ 14 \end{pmatrix} ; \text{ Remark: } \begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix} \text{ is NOT invertible.}$$

$$\text{Aug. Mat: } \begin{pmatrix} 1 & -3 & 7 \\ 2 & -6 & 14 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & -3 & 7 \\ 0 & 0 & 0 \end{pmatrix} ; \text{ Infinitely many solutions since } x_2 \text{ is a free variable!}$$

$$\text{Solutions: } \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -3x_2 + 7 \\ x_2 \end{pmatrix} = x_2 \begin{pmatrix} -3 \\ 1 \end{pmatrix} + \begin{pmatrix} 7 \\ 0 \end{pmatrix} ; \text{ Ans: } \boxed{\left\{ x_2 \begin{pmatrix} -3 \\ 1 \end{pmatrix} + \begin{pmatrix} 7 \\ 0 \end{pmatrix} : x_2 \in \mathbb{R} \right\}}$$

$$(d) \begin{pmatrix} 1 & 2 & 3 \\ 2 & 5 & 8 \\ 3 & 4 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \\ 9 \end{pmatrix} ;$$

$$\text{Aug. Mat: } \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 5 & 8 & 4 \\ 3 & 4 & 5 & 4 \end{pmatrix} \xrightarrow[-3R_1 + R_3 \leftrightarrow R_3]{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -4 \\ 0 & -2 & -4 & 8 \end{pmatrix} \xrightarrow[2R_2 + R_3 \leftrightarrow R_3]{0R_1 \leftrightarrow R_1} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -4 \\ 0 & 0 & 0 & -16 \end{pmatrix} ; \boxed{\text{No Solutions.}}$$

$$(e) \begin{pmatrix} 1 & 2 & 3 \\ 2 & 5 & 8 \\ 3 & 4 & 9 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix};$$

$$\text{Aug. Mat: } \begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 5 & 8 & 5 \\ 3 & 4 & 9 & 6 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 3 & 4 & 9 & 6 \end{pmatrix} \xrightarrow{2R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & 4 & -12 \end{pmatrix} \xrightarrow{\frac{1}{4}R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & 1 & -3 \end{pmatrix};$$

Option 1: Back Sub Now.

$$x_1 + 2x_2 + 3x_3 = 4 \quad x_2 = -3 - 2x_3 = -3 - 2(-3) = -3 + 6 = 3;$$

$$x_2 + 2x_3 = -3 \quad ; \quad x_1 = 4 - 2x_2 - 3x_3 = 4 - 2(3) - 3(-3) = 4 - 6 + 9 = 7; \quad \text{Ans: } \boxed{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \\ -3 \end{pmatrix}};$$

$$x_3 = -3$$

Option 2. Proceed to RREF, then Back Sub.

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & -3 \\ 0 & 0 & 1 & -3 \end{pmatrix} \xrightarrow{R_1 - 3R_3 \leftrightarrow R_1} \begin{pmatrix} 1 & 2 & 0 & 13 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & -3 \end{pmatrix} \xrightarrow{R_1 - 2R_2 \leftrightarrow R_1} \begin{pmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & -3 \end{pmatrix}; \quad \text{Ans: } \boxed{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \\ -3 \end{pmatrix}};$$

$$(f) \begin{pmatrix} 2 & 3 & 4 \\ 3 & 4 & 5 \\ 6 & 7 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix};$$

$$\text{Aug. Mat: } \begin{pmatrix} 2 & 3 & 4 & 0 \\ 3 & 4 & 5 & 0 \\ 6 & 7 & 8 & 0 \end{pmatrix} \xrightarrow{2R_2 \leftrightarrow R_2} \begin{pmatrix} 2 & 3 & 4 & 0 \\ 6 & 8 & 10 & 0 \\ 4 & 7 & 8 & 0 \end{pmatrix} \xrightarrow{-3R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 2 & 3 & 4 & 0 \\ 0 & -1 & -2 & 0 \\ 4 & 7 & 8 & 0 \end{pmatrix} \xrightarrow{-3R_1 + R_3 \leftrightarrow R_3} \begin{pmatrix} 2 & 3 & 4 & 0 \\ 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{-2R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 2 & 3 & 4 & 0 \\ 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{R_1 + 3R_2 \leftrightarrow R_1} \begin{pmatrix} 2 & 0 & -2 & 0 \\ 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \xrightarrow{\frac{1}{2}R_1 \leftrightarrow R_1} \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & -1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}; \quad x_3 \text{ is a free variable.}$$

$$\text{Back Sub: } x_1 - x_3 = 0 \quad ; \quad x_1 = x_3 \quad ; \quad \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_3 \\ -2x_3 \\ x_3 \end{pmatrix} = x_3 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}; \quad \text{Solution: } \boxed{\left\{ x_3 \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} : x_3 \in \mathbb{R} \right\}};$$

$$(g) \begin{pmatrix} 1 & 2 & 3 & 4 \\ -1 & 2 & -3 & -4 \\ 1 & -2 & 3 & -4 \\ 1 & 2 & 3 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \\ 5 \\ 5 \end{pmatrix};$$

$$\text{Aug. Mat: } \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ -1 & 2 & -3 & -4 & 5 \\ 1 & -2 & 3 & -4 & 5 \\ 1 & 2 & 3 & -4 & 5 \end{pmatrix} \xrightarrow{R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 4 & 0 & 0 & 10 \\ 1 & -2 & 3 & -4 & 5 \\ 1 & 2 & 3 & -4 & 5 \end{pmatrix} \xrightarrow{R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 4 & 0 & 0 & 10 \\ 0 & 0 & 0 & -8 & 0 \\ 1 & 2 & 3 & -4 & 5 \end{pmatrix} \xrightarrow{R_3 + R_4 \leftrightarrow R_4} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 4 & 0 & 0 & 10 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 4 & 0 & 0 & 10 \\ 0 & 0 & 6 & 8 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}; \quad \text{Back-Sub: } x_1 + 2x_2 + 3x_3 + 4x_4 = 5 \quad x_2 = \frac{5}{2}; \quad x_3 = \frac{5}{3}; \quad x_4 = -\frac{5}{4};$$

$$4x_2 = 10; \quad ; \quad x_1 = -2x_2 - 3x_3 - 4x_4 + 5$$

$$6x_3 = 10; \quad ; \quad = -2\left(\frac{5}{2}\right) - 3\left(\frac{5}{3}\right) - 4\left(-\frac{5}{4}\right) + 5$$

$$-8x_4 = 10; \quad ; \quad = -5 - 5 + 5 + 0;$$

$$\boxed{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{5}{2} \\ \frac{5}{3} \\ -\frac{5}{4} \end{pmatrix}};$$

$$(h) \begin{pmatrix} 1 & 2 & 3 & 4 \\ -1 & 2 & 3 & 4 \\ 1 & 2 & -3 & -4 \\ 1 & 2 & -3 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 5 \\ 5 \\ 5 \\ 5 \end{pmatrix},$$

$$\text{Aug. Mat: } \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ -1 & 2 & 3 & 4 & 5 \\ 1 & 2 & -3 & -4 & 5 \\ 1 & 2 & -3 & -4 & 5 \end{pmatrix} \xrightarrow{R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 6 & 8 & 0 \\ 1 & 2 & -3 & -4 & 5 \\ 1 & 2 & -3 & -4 & 5 \end{pmatrix} \xrightarrow{R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 6 & 8 & 0 \\ 0 & 0 & 0 & -8 & 0 \\ 1 & 2 & -3 & -4 & 5 \end{pmatrix} \xrightarrow{\frac{1}{6}R_2 + R_2} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 6 & 8 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 2 & -3 & -4 & 5 \end{pmatrix}$$

$$\xrightarrow{R_1 - R_2 \leftrightarrow R_1} \begin{pmatrix} 1 & 2 & 0 & 0 & 5 \\ 0 & 0 & 3 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}; \quad x_2 \text{ and } x_4 \text{ are free variables.}$$

$$\text{Back-Sub: } x_1 + 2x_2 = 5 \quad ; \quad x_1 = -2x_2 + 5;$$

$$3x_3 + 4x_4 = 0 \quad ; \quad x_3 = -\frac{4}{3}x_4;$$

$$\text{Solution: } \boxed{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -2x_2 + 5 \\ x_2 \\ -\frac{4}{3}x_4 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ 0 \\ -\frac{4}{3} \\ 1 \end{pmatrix} + \begin{pmatrix} 5 \\ 0 \\ 0 \\ 0 \end{pmatrix} \text{ for all } x_2, x_4 \in \mathbb{R}.}$$

(6)

Determine the left multiplication matrices for the following linear transformations.

(a) $T_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ such that $T(\mathbf{e}_1) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$, $T(\mathbf{e}_2) = \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix}$, and $T(\mathbf{e}_1) = \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix}$

(b) $T_2 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ given by $T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 + 2x_2 + 3x_3 \\ 4x_2 + 5x_3 \\ 6x_1 + 7x_3 \end{pmatrix}$

(c) The reflection $T_3 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ across the line $y = \frac{1}{2}x$.

(d) The rotation $T_4 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by $\theta = \frac{5\pi}{6}$ counterclockwise.

(e) The orthogonal projection $T_5 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ by onto the line spanned by $\mathbf{v} = \begin{pmatrix} 3 \\ -5 \end{pmatrix}$

(f) The reflection transformation $T_6 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ across the plane given by $x + 2x - 3z = 0$.

(g) The orthogonal projection $T_7 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ onto the plane with normal vector $\mathbf{N} = (1, -2, 3)^\top$ passing through the origin.

(a) $A_1 = \left(T(\mathbf{e}_1) \ T(\mathbf{e}_2) \ T(\mathbf{e}_3) \right) = \boxed{\begin{pmatrix} 1 & 3 & 7 \\ 2 & 4 & 8 \\ 3 & 5 & 9 \end{pmatrix}}$

(b) $T \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$; $T \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix}$; $T \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ 7 \end{pmatrix}$; $A_2 = \boxed{\begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 6 & 0 & 7 \end{pmatrix}}$

(c) The line $y = \frac{1}{2}x$ is spanned by $\mathbf{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$; let $\mathbf{w} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$. Observe that $\mathbf{v} \perp \mathbf{w}$ and $\{\mathbf{v}, \mathbf{w}\}$ is a basis of \mathbb{R}^2 ; Since T_3 is a reflection: $T(\mathbf{v}) = \mathbf{v}$ and $T(\mathbf{w}) = -\mathbf{w}$;

$$\therefore A_3 \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix}; A_3 = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix}^{-1} = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} \frac{1}{4 - (-1)} \begin{pmatrix} 2 & 1 \\ -1 & 2 \end{pmatrix} = \boxed{\frac{1}{5} \begin{pmatrix} 3 & 4 \\ 4 & -3 \end{pmatrix}}$$

(d) The formula is $A_{\text{rot}\theta} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$; with $\theta = \frac{5\pi}{6}$: $\cos\left(\frac{5\pi}{6}\right) = -\frac{\sqrt{3}}{2}$; $\sin\left(\frac{5\pi}{6}\right) = \frac{1}{2}$;

Then, $\boxed{A_4 = \frac{1}{2} \begin{pmatrix} -\sqrt{3} & -1 \\ 1 & -\sqrt{3} \end{pmatrix}}$

(e) The line is spanned by $\mathbf{v} = \begin{pmatrix} 3 \\ -5 \end{pmatrix}$; let $\mathbf{w} = \begin{pmatrix} 5 \\ 3 \end{pmatrix}$; Observe that $\mathbf{v} \perp \mathbf{w}$ and $\{\mathbf{v}, \mathbf{w}\}$ is a basis for \mathbb{R}^2 ; Since T_5 is an orthogonal projection: $T(\mathbf{v}) = \mathbf{v}$ and $T(\mathbf{w}) = \mathbf{0}$;

$$\therefore A_5 \begin{pmatrix} 3 & 5 \\ -5 & 3 \end{pmatrix} = \begin{pmatrix} 3 & 0 \\ -5 & 0 \end{pmatrix}; A_5 = \begin{pmatrix} 3 & 0 \\ -5 & 0 \end{pmatrix} \begin{pmatrix} 3 & 5 \\ -5 & 3 \end{pmatrix}^{-1} = \begin{pmatrix} 3 & 0 \\ -5 & 0 \end{pmatrix} \frac{1}{9 - (-25)} \begin{pmatrix} 3 & -5 \\ 5 & 3 \end{pmatrix} = \boxed{\frac{1}{34} \begin{pmatrix} 9 & -15 \\ -15 & 25 \end{pmatrix}}$$

(f) Use the formula $A_6 = \frac{1}{\langle \mathbf{N}, \mathbf{N} \rangle} (\langle \mathbf{N}, \mathbf{N} \rangle \mathbf{I}_3 - 2\mathbf{N}\mathbf{N}^\top)$ for normal vector \mathbf{N} . For T_6 : $\mathbf{N} = \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}$,

$$\langle \mathbf{N}, \mathbf{N} \rangle = \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} = 1 + 4 + 9 = 14; -2\mathbf{N}\mathbf{N}^\top = -2 \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} (1 \ 2 \ -3) = -2 \begin{pmatrix} 1 & 2 & -3 \\ 2 & 4 & -6 \\ -3 & -6 & 9 \end{pmatrix} = \boxed{\begin{pmatrix} -2 & -4 & 6 \\ -4 & -8 & 12 \\ 6 & 12 & -18 \end{pmatrix}}$$

$$\langle \mathbf{N}, \mathbf{N} \rangle \mathbf{I}_3 - 2\mathbf{N}\mathbf{N}^\top = \begin{pmatrix} -2+14 & -4 & 6 \\ -4 & -8+14 & 12 \\ 6 & 12 & -18+14 \end{pmatrix} = \begin{pmatrix} 12 & -4 & 6 \\ -4 & 6 & 12 \\ 6 & 12 & -4 \end{pmatrix}; A_6 = \frac{1}{14} \begin{pmatrix} 12 & -4 & 6 \\ -4 & 6 & 12 \\ 6 & 12 & -4 \end{pmatrix} = \boxed{\frac{1}{7} \begin{pmatrix} 6 & -2 & 3 \\ -2 & 3 & 6 \\ 3 & 6 & -2 \end{pmatrix}}$$

Alternate Method: Use change of basis method with $T(\mathbf{N}) = -\mathbf{N}$, $T(\mathbf{d}_1) = \mathbf{d}_1$, $T(\mathbf{d}_2) = \mathbf{d}_2$ for direction vectors $\mathbf{d}_1, \mathbf{d}_2$ for P .

Choices for direction vectors include: $\begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}$; e.g. $A_6 = \begin{pmatrix} -1 & -2 & 3 \\ -2 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix}^{-1}$;

(g) Use the formula $A_7 = \frac{1}{\langle \mathbf{N}, \mathbf{N} \rangle} (\langle \mathbf{N}, \mathbf{N} \rangle \mathbf{I}_3 - \mathbf{N}\mathbf{N}^\top)$ with normal vector \mathbf{N} . For T_7 : $\mathbf{N} = \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}$,

$$\langle \mathbf{N}, \mathbf{N} \rangle = \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} = 1 + 4 + 9 = 14; (-1)\mathbf{N}\mathbf{N}^\top = (-1) \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} (1 \ 2 \ -3) = (-1) \begin{pmatrix} 1 & 2 & -3 \\ 2 & 4 & -6 \\ -3 & -6 & 9 \end{pmatrix} = \boxed{\begin{pmatrix} -1 & 2 & -3 \\ 2 & 4 & -6 \\ -3 & -6 & 9 \end{pmatrix}}$$

$$\langle \mathbf{N}, \mathbf{N} \rangle \mathbf{I}_3 - \mathbf{N}\mathbf{N}^\top = \begin{pmatrix} -1+14 & -2 & 3 \\ -2 & -4+14 & 6 \\ 6 & 6 & -9+14 \end{pmatrix} = \begin{pmatrix} 13 & -2 & 3 \\ -2 & 10 & 6 \\ 6 & 6 & 5 \end{pmatrix}; A_7 = \frac{1}{14} \begin{pmatrix} 13 & -2 & 3 \\ -2 & 10 & 6 \\ 6 & 6 & 5 \end{pmatrix} = \boxed{\frac{1}{14} \begin{pmatrix} 13 & -2 & 3 \\ -2 & 10 & 6 \\ 6 & 6 & 5 \end{pmatrix}}$$

Alternate Method: Use the change of basis method with $T(\mathbf{N}) = \mathbf{0}$, $T(\mathbf{d}_1) = \mathbf{d}_1$, $T(\mathbf{d}_2) = \mathbf{d}_2$ for direction vectors $\mathbf{d}_1, \mathbf{d}_2$ for P .

Choices for $\mathbf{d}_1, \mathbf{d}_2$ include: $\begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$; e.g. $A_7 = \begin{pmatrix} 0 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix}^{-1}$;

7

Determine if the following sets of vectors are linearly independent. If the set is linearly dependent, determine a linearly independent spanning set.

(a) $V_1 = \left\{ \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \end{pmatrix} \right\}$

(d) $V_4 = \left\{ \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}, \begin{pmatrix} -4 \\ 5 \\ 6 \end{pmatrix} \right\}$

(b) $V_2 = \left\{ \begin{pmatrix} 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -2 \\ 6 \end{pmatrix}, \begin{pmatrix} -1 \\ 4 \end{pmatrix} \right\}$

(e) $V_5 = \left\{ \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}, \begin{pmatrix} -4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 7 \\ -8 \\ 9 \end{pmatrix}, \begin{pmatrix} -1 \\ -2 \\ 3 \end{pmatrix} \right\}$

(c) $V_3 = \left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} \right\}$

(f) $V_6 = \left\{ \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}, \begin{pmatrix} -4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 7 \\ -8 \\ 9 \end{pmatrix} \right\}$

Denote the lin. ind. spanning sets as W_i .

(a) $\det \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix} = (1)(3) - 2(4) = 3 - 8 = -5 \neq 0; \therefore V_1 \text{ is linearly independent.}$

(b) $\begin{pmatrix} 1 & -2 & -1 \\ -2 & 6 & 4 \end{pmatrix} \xrightarrow{2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & -2 & -1 \\ 0 & 2 & 2 \end{pmatrix}; V_2 \text{ is linearly dependent.}$
Keep vectors 1 and 2.
 $W_2 = \left\{ \begin{pmatrix} 1 \\ -2 \end{pmatrix}, \begin{pmatrix} -2 \\ 6 \end{pmatrix} \right\}$

(c) $\begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{pmatrix} \xrightarrow{-2R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 4 & 7 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{pmatrix};$
V₃ is lin. dependent.
Keep first two vectors.
 $W_3 = \left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} \right\}$

(d) Method 1: $\begin{pmatrix} 1 & -4 \\ -3 & 5 \\ 0 & 0 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & -4 \\ 0 & 13 \\ 0 & 0 \end{pmatrix}; \text{ Each column has a pivot.}$
 $V_4 \text{ is linearly independent.}$

Method 2: $\begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} \text{ is not a scalar multiple of } \begin{pmatrix} -4 \\ 5 \\ 6 \end{pmatrix}; \therefore V_4 \text{ is lin. independent.}$

(e) V_5 has 4 vectors but is a set in \mathbb{R}^3 . Since $4 \geq 3+1$, V_5 is linearly dependent.

$\begin{pmatrix} 1 & -4 & 7 & -1 \\ 2 & 5 & -8 & -2 \\ -3 & 6 & 9 & 3 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & -4 & -1 & -1 \\ 0 & 13 & -22 & 0 \\ 0 & -6 & 30 & 0 \end{pmatrix} \xrightarrow{\frac{1}{13}R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & -4 & 7 & -1 \\ 0 & 13 & -22 & 0 \\ 0 & 0 & \frac{258}{13} & 0 \end{pmatrix}; \text{ Keep the first 3 vectors.}$
non-zero
 $W_5 = \left\{ \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}, \begin{pmatrix} -4 \\ 5 \\ 6 \end{pmatrix}, \begin{pmatrix} 7 \\ -8 \\ 9 \end{pmatrix} \right\}$

(f) Method 1: $\begin{pmatrix} 1 & -4 & 7 \\ 2 & 5 & -8 \\ -3 & 6 & 9 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} 1 & -4 & 7 \\ 0 & 13 & -22 \\ 0 & -6 & 30 \end{pmatrix} \xrightarrow{\frac{6}{13}R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & -4 & 7 \\ 0 & 13 & -22 \\ 0 & 0 & \frac{258}{13} \end{pmatrix}; \boxed{V_6 \text{ is lin. independent.}}$

Method 2: From part (e), $V_6 = W_5$ has been shown to be linearly independent.

8

Find the determinant of the following matrices.

(a) $B_1 = \begin{pmatrix} 2 & 2 & 2 \\ 1 & 2 & 3 \\ -2 & -8 & -10 \end{pmatrix}$

(c) $B_3 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

(b) $B_2 = \begin{pmatrix} 3 & 4 & -5 \\ 4 & 3 & -2 \\ 1 & 1 & -1 \end{pmatrix}$

(d) $B_4 = \begin{pmatrix} 4 & 5 \\ 7 & 8 \end{pmatrix}$

(a) Method 1: Direct Calculation by Laplace Expansion.

$\det \begin{pmatrix} 2 & 2 & 2 \\ 1 & 2 & 3 \\ -2 & -8 & -10 \end{pmatrix} = 2 \det \begin{pmatrix} 2 & 3 \\ -8 & -10 \end{pmatrix} + (-1)(2) \det \begin{pmatrix} 1 & 3 \\ -2 & -10 \end{pmatrix} + (2) \det \begin{pmatrix} 1 & 2 \\ -2 & -8 \end{pmatrix}$
 $= (2)[-20 - (-24)] + (-2)[-10 - (-6)] + (2)[(-8) - (-4)] = 2(4) + (-2)(-4) + 2(-4) = 8 + 8 - 8 = 8;$

Method 2: Simplify using Gaussian Elimination.

$B_1 = \begin{pmatrix} 2 & 2 & 2 \\ 1 & 2 & 3 \\ -2 & -8 & -10 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 2 & 2 \\ -2 & -8 & -10 \end{pmatrix} \xrightarrow{2R_1 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 2 \\ 0 & -2 & -4 \\ 0 & -4 & -4 \end{pmatrix} \xrightarrow{-2R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 2 \\ 0 & -2 & -4 \\ 0 & 0 & 4 \end{pmatrix};$

Swap, $m = (-1)$

$m = -1$ (no change)

$m = -1$ (no change)

$\det(B_1) = m \det \begin{pmatrix} 1 & 2 & 2 \\ 0 & -2 & -4 \\ 0 & 0 & 4 \end{pmatrix} = (-1)(1)(-2)(4) = \boxed{8};$

(b) Method 1: Direct Calculation.

$$\det(B_2) = \det \begin{pmatrix} 3 & 4 & -5 \\ 4 & 3 & -2 \\ 1 & 1 & -1 \end{pmatrix} = (3)\det \begin{pmatrix} 3 & -2 \\ 1 & -1 \end{pmatrix} + (-4)(4)\det \begin{pmatrix} 4 & -5 \\ 1 & -1 \end{pmatrix} + (1)\det \begin{pmatrix} 4 & -5 \\ 3 & -2 \end{pmatrix}$$

$$= (3)[-3 - (-2)] + (-4)[-4 - (-5)] + (1)[-6 - (-15)] = (3)(-1) + (-4)(1) + (1)(7) = -3 - 4 + 7 = \boxed{0};$$

Method 2: Simplify first by Gaussian Elimination,

$$B_2 = \begin{pmatrix} 3 & 4 & -5 \\ 4 & 3 & -2 \\ 1 & 1 & -1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{pmatrix} 1 & 1 & -1 \\ 4 & 3 & -2 \\ 3 & 4 & -5 \end{pmatrix} \xrightarrow{-4R_1 + R_2 \rightarrow R_2} \begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 2 \\ 3 & 4 & -5 \end{pmatrix} \xrightarrow{-3R_1 + R_3 \rightarrow R_3} \begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 2 \\ 0 & 1 & -2 \end{pmatrix} \xrightarrow{R_2 + R_3 \rightarrow R_3} \begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{pmatrix};$$

swap, $m = (-1)$ $m = -1, \text{ no change}$ $m = -1, \text{ no change}$

Option 2.1: The columns of B_2 are lin. dependent $\Leftrightarrow \det(B_2) = \boxed{0};$

$$\text{Option 2.2: } \det(B_2) = m \det \begin{pmatrix} 1 & 1 & -1 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{pmatrix} = (-1)(1)(-1)(0) = \boxed{0};$$

(c) Method 1: Direct Calculation. $\det(B_3) = \det \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} = (0)(\dots) + (-1)(1)\det \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} + (0)(\dots) = \boxed{-1};$

Method 2: $B_3 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3; \det(B_3) = m \det(I_3) = (-1)(1) = \boxed{-1};$

$$(d) \det \begin{pmatrix} 4 & 5 \\ 7 & 8 \end{pmatrix} = (4)(8) - (5)(7) = 32 - 35 = \boxed{-3};$$

⑨

For each of the following matrices M , determine the following:

1) the characteristic polynomial of M ,

2) the real eigenvalues of M ,

3) the eigenvectors corresponding to the real eigenvalues of M

$$(a) M_1 = \begin{pmatrix} 3 & -4 \\ 4 & 3 \end{pmatrix}$$

$$(e) M_5 = \begin{pmatrix} -2 & -1 & 8 \\ 12 & 6 & -16 \\ 6 & -1 & 0 \end{pmatrix}$$

$$(b) M_2 = -\frac{1}{5} \begin{pmatrix} 1 & 3 \\ 18 & 4 \end{pmatrix}$$

$$(f) M_6 = \begin{pmatrix} 6 & -2 & -3 \\ -2 & 3 & -6 \\ -3 & -6 & -2 \end{pmatrix}$$

$$(c) M_3 = \begin{pmatrix} -20 & 11 \\ 4 & 0 \end{pmatrix}$$

$$(g) M_7 = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & -2 \\ 0 & 2 & 1 \end{pmatrix}$$

$$(d) M_4 = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 4 \end{pmatrix}$$

$$(a) M_1 = \begin{pmatrix} 3 & -4 \\ 4 & 3 \end{pmatrix};$$

$$p(\lambda) = \det(M_1 - \lambda I_2) = \det \begin{pmatrix} 3-\lambda & -4 \\ 4 & 3-\lambda \end{pmatrix} = (3-\lambda)^2 - (4)(-4) = 9 - 6\lambda + \lambda^2 + 16 = \boxed{\lambda^2 - 6\lambda + 25};$$

$$\text{Discriminant: } b^2 - 4ac = (-6)^2 - 4(1)(25) = 36 - 100 < 0; \quad \boxed{\text{No real eigenvalues.}}$$

$$(b) M_2 = -\frac{1}{5} \begin{pmatrix} 1 & 3 \\ 18 & 4 \end{pmatrix};$$

$$p(\lambda) = \det(M_2 - \lambda I_2) = \left(-\frac{1}{5}\right)^2 \det(-5M_2 + 5\lambda I_2) = \frac{1}{25} \det \begin{pmatrix} 1+5\lambda & 3 \\ 18 & 4+5\lambda \end{pmatrix}$$

$$= \frac{1}{25} [(1+5\lambda)(4+5\lambda) - (18)(3)] = \frac{1}{25} [4 + 5\lambda + 20\lambda + 25\lambda^2 - 54] = \frac{1}{25} (25\lambda^2 + 25\lambda - 50) = \boxed{\lambda^2 + \lambda - 2};$$

$$p(\lambda) = \lambda^2 + \lambda - 2 = (\lambda + 2)(\lambda - 1) = 0; \quad \boxed{\lambda = -1, 2};$$

Next, solve the system: $(M_2 - \lambda I_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$; equivalently, solve $-\frac{1}{5}(-5M_2 + 5\lambda I_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = -\frac{1}{5} \begin{pmatrix} 0 \\ 0 \end{pmatrix}$;

For $\lambda=1$: $-5M_2 + 5(1)I_2 = \begin{pmatrix} 1+5 & 3 \\ 18 & 4+5 \end{pmatrix} = \begin{pmatrix} 6 & 3 \\ 18 & 9 \end{pmatrix} \xrightarrow{-3R_1+R_2 \leftrightarrow R_2} \begin{pmatrix} 6 & 3 \\ 0 & 0 \end{pmatrix}$; x_2 is a free variable.

By back-sub: $6x_1 + 3x_2 = 0$; $x_1 = -\frac{1}{2}x_2$; let $x_2 = 2$; Eigenvector $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$;

For $\lambda=-2$: $-5M_2 + 5(-2)I_2 = \begin{pmatrix} 1-10 & 3 \\ 18 & 4-10 \end{pmatrix} = \begin{pmatrix} -9 & 3 \\ 18 & -6 \end{pmatrix} \xrightarrow{2R_1+R_2 \leftrightarrow R_2} \begin{pmatrix} -9 & 3 \\ 0 & 0 \end{pmatrix}$; x_2 is a free variable.

By back-sub: $-9x_1 + 3x_2 = 0$; $x_1 = \frac{1}{3}x_2$; let $x_2 = 3$; Eigenvector $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$;

(c) $M_3 = \begin{pmatrix} -20 & 11 \\ 4 & 0 \end{pmatrix}$;

$$p(\lambda) = \det \begin{pmatrix} -20-\lambda & 11 \\ 4 & -\lambda \end{pmatrix} = -\lambda(-20-\lambda) - (4)(11) = \boxed{\lambda^2 + 20\lambda - 44};$$

$$\lambda^2 + 20\lambda - 44 = (\lambda + 22)(\lambda - 2) = 0; \boxed{\lambda = -2, -22} \text{ Next: Solve } (M_3 - \lambda I_2) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ for each } \lambda.$$

For $\lambda=2$: $M_3 - \lambda I_2 = \begin{pmatrix} -20-2 & 11 \\ 4 & -2 \end{pmatrix} = \begin{pmatrix} -22 & 11 \\ 4 & -2 \end{pmatrix} \xrightarrow{1 \leftrightarrow R_1 \leftrightarrow R_2} \begin{pmatrix} -2 & 1 \\ 4 & -2 \end{pmatrix} \xrightarrow{2R_1+R_2 \leftrightarrow R_2} \begin{pmatrix} -2 & 1 \\ 0 & 0 \end{pmatrix}$; x_2 is free.

By back-sub: $-2x_1 + x_2 = 0$; $x_1 = \frac{1}{2}x_2$; let $x_2 = 2$; Eigenvector $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$;

For $\lambda=-22$: $M_3 - \lambda I_2 = \begin{pmatrix} -20+22 & 11 \\ 4 & 22 \end{pmatrix} = \begin{pmatrix} 2 & 11 \\ 4 & 22 \end{pmatrix} \xrightarrow{-2R_1+R_2 \leftrightarrow R_2} \begin{pmatrix} 2 & 11 \\ 0 & 0 \end{pmatrix}$; x^2 is free.

By back-sub: $2x_1 + 11x_2 = 0$; $x_1 = -\frac{11}{2}x_2$; let $x_2 = 2$; Eigenvector $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -11 \\ 2 \end{pmatrix}$;

(d) $M_4 = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 4 \end{pmatrix}$;

Char. Poly: $p(\lambda) = \det(A - \lambda I_3) = \det \begin{pmatrix} 2-\lambda & 0 & 0 \\ 0 & -3-\lambda & 0 \\ 0 & 0 & 4-\lambda \end{pmatrix} = \boxed{(2-\lambda)(-3-\lambda)(4-\lambda)}$

Eigenvalues: $\boxed{\lambda = 2, -3, 4}$.

Eigenvectors: For $\lambda=2$: $M_4 - \lambda I_3 = \begin{pmatrix} 2-2 & 0 & 0 \\ 0 & -3-2 & 0 \\ 0 & 0 & 4-2 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -5 & 0 \\ 0 & 0 & 2 \end{pmatrix}$;

Back Sub: x_1 is free.

$$-5x_2 = 0; x_2 = 0; \quad \text{let } x_1 = 1. \quad \text{Eigenvector: } \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix};$$

$$2x_3 = 0; x_3 = 0;$$

Similar calculations for $\lambda = -3$: $\boxed{\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}}$ and $\lambda = 4$: $\boxed{\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}}$

(e) $M_5 = \begin{pmatrix} -2 & -1 & 8 \\ 12 & 6 & -16 \\ 6 & -1 & 0 \end{pmatrix}$;

Char Poly: $p(\lambda) = \det(M_5 - \lambda I_3) = \det \begin{pmatrix} -2-\lambda & -1 & 8 \\ 12 & 6-\lambda & -16 \\ 6 & -1 & -\lambda \end{pmatrix}$

$$= (-2-\lambda) \det \begin{pmatrix} 6-\lambda & -16 \\ -1 & -\lambda \end{pmatrix} + (-1)(-1) \det \begin{pmatrix} 12 & -16 \\ 6 & -\lambda \end{pmatrix} + (8) \det \begin{pmatrix} 12 & 6-\lambda \\ 6 & -1 \end{pmatrix}$$

$$= (-2-\lambda)[-6\lambda + \lambda^2 - 16] + [-12\lambda + 96] + (8)[-12 - 36 + 6\lambda]$$

$$\begin{aligned}
 &= 12\lambda^3 - 2\lambda^2 + 3\lambda + 6\lambda^2 - \lambda^3 + 16\lambda - 10\lambda + 96 - 384 + 48\lambda \\
 &= -\lambda^3 + 4\lambda^2 + 64\lambda - 256 = -\lambda^3 + 4\lambda^2 + 4^3\lambda - 4^4 \\
 &= (-\lambda^2)(\lambda - 4) + 4^3(\lambda - 4) \xrightarrow{\lambda - 4} \underline{(\lambda - 4)(-\lambda^2 + 64)} ;
 \end{aligned}$$

Eigenvalues: $\boxed{\lambda = 4, \pm 8}$;

Eigenvectors: for $\lambda = 4$: $M_5 - 4I_3 = \begin{pmatrix} -2 & -4 & -1 \\ 12 & 6 & -4 \\ 6 & -1 & -4 \end{pmatrix} = \begin{pmatrix} -6 & -1 & 8 \\ 12 & 2 & -16 \\ 6 & -1 & -4 \end{pmatrix} \xrightarrow{2R_1 + R_2 \leftrightarrow R_2} \xrightarrow{R_1 + R_3 \leftrightarrow R_3}$

$$\begin{pmatrix} -6 & -1 & 8 \\ 0 & 0 & 0 \\ 0 & -2 & 4 \end{pmatrix}; x_3 \text{ is free variable; Back Sub: } -6x_1 - x_2 + 8x_3 = 0; -2x_2 + 4x_3 = 0;$$

$$\begin{matrix} x_1 & x_2 & x_3 \end{matrix}$$

$$x_2 = 2x_3; -6x_1 = x_2 - 8x_3 = 2x_3 - 8x_3 = -6x_3; x_1 = x_3;$$

let $x_3 = 1$. Eigenvector: $\boxed{\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}}$; for $\lambda = 4$;

for $\lambda = 8$: $M_5 - 8I_3 = \begin{pmatrix} -2 & -8 & -1 & 8 \\ 12 & 6 & -8 & -16 \\ 6 & -1 & -8 & -8 \end{pmatrix} = \begin{pmatrix} -10 & -1 & 8 \\ 12 & -2 & -16 \\ 6 & -1 & -8 \end{pmatrix} \xrightarrow{6R_1 \leftrightarrow R_1} \xrightarrow{5R_2 \leftrightarrow R_2} \xrightarrow{10R_3 \leftrightarrow R_3} \begin{pmatrix} -60 & -6 & 48 \\ 60 & -10 & -80 \\ 60 & -10 & -80 \end{pmatrix}$

$$\xrightarrow{-R_2 + R_3} \begin{pmatrix} -60 & -6 & 48 \\ 60 & -10 & -80 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{R_1 + R_2 \leftrightarrow R_2} \begin{pmatrix} -60 & -6 & 48 \\ 0 & -16 & -32 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{-\frac{1}{6}R_1 \leftrightarrow R_1} \xrightarrow{-\frac{1}{16}R_2 \leftrightarrow R_2} \begin{pmatrix} 10 & 1 & -8 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}; x_3 \text{ is free. Back Sub: } 10x_1 + x_2 - 8x_3 = 0; x_2 + 2x_3 = 0;$$

$$x_2 = -2x_3; 10x_1 = -x_2 + 8x_3 = -(-2x_3) + 8x_3 = 10x_3; x_1 = x_3;$$

Choose $x_3 = 1$: Eigenvalue: $\boxed{\begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}}$; for $\lambda = 8$

for $\lambda = -8$: $M_5 + 8I_3 = \begin{pmatrix} -2 & 8 & -1 & 8 \\ 12 & 6 & 6 & -16 \\ 6 & -1 & 8 & 8 \end{pmatrix} = \begin{pmatrix} 6 & -1 & 8 \\ 12 & 14 & -16 \\ 6 & -1 & 8 \end{pmatrix} \xrightarrow{-2R_1 + R_2 \leftrightarrow R_2} \xrightarrow{-R_1 + R_3 \leftrightarrow R_3} \begin{pmatrix} 6 & -1 & 8 \\ 0 & 16 & -32 \\ 0 & 0 & 0 \end{pmatrix} \xrightarrow{\frac{1}{16}R_2 \leftrightarrow R_2}$

$$\begin{pmatrix} 6 & -1 & 8 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{pmatrix}; x_3 \text{ is free. Back Sub: } 6x_1 - x_2 + 8x_3 = 0; x_2 - 2x_3 = 0;$$

$$x_2 = 2x_3; 6x_1 = x_2 - 8x_3 = 2x_3 - 8x_3 = -6x_3; x_1 = -x_3;$$

Choose $x_3 = 1$; Eigenvalue: $\boxed{\begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}}$ for $\lambda = -8$

(f) See lecture 4B.

(g) $M_7 = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$;

Char Poly: $p(\lambda) = \det \begin{pmatrix} 2-\lambda & 0 & 0 \\ 0 & 1-\lambda & -2 \\ 0 & 2 & 1-\lambda \end{pmatrix} = (2-\lambda)\det \begin{pmatrix} 1-\lambda & -2 \\ 2 & 1-\lambda \end{pmatrix} + (0)(...) = \boxed{(2-\lambda)[(1-\lambda)^2 + 4]}$

Eigenvalues: $p(\lambda) = 0: 2-\lambda = 0; \lambda = 2;$

$(1-\lambda)^2 + 4 = 0; (1-\lambda)^2 = -4$; No real solutions.

Eigenvalue: $\boxed{\lambda = 2}$

Eigenvector for $\lambda = 2$:

$$M_7 - 2I_3 = \begin{pmatrix} 2-2 & 0 & 0 \\ 0 & 1-2 & -2 \\ 0 & 2 & 1-2 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & -2 \\ 0 & 2 & 1 \end{pmatrix} \xrightarrow{2R_2 + R_3 \leftrightarrow R_3} \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & -2 \\ 0 & 0 & -3 \end{pmatrix}; x_1 \text{ is free. Back Sub: } -x_2 - 2x_3 = 0; -3x_3 = 0;$$

$x_3 = 0; -x_2 - 2(0) = 0; x_2 = 0$; Choose $x_1 = 1$: Eigenvalue: $\boxed{\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}}$ for $\lambda = 2$