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...Atmel Studio\7.0\usart3_init_test\usart3_init_test\main.c
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* usart3_init_test.c
 * Created: 3/3/2022 12:23:17 PM
 * Author : jason
#include <avr/io.h>
#define F CPU 4000000
#define USART3_BAUD_RATE(BAUD_RATE) ((float)(F_CPU * 64 / (16 *(float)BAUD_RATE))) //>
  Calculation of baud rate from data sheet
#include <avr/io.h>
#include <util/delay.h>
//Header function
void USART_sw_write(char c);
void USART3_init (uint16_t baud, uint8_t data_bits, unsigned char parity);
int main(void)
    /* Replace with your application code */
    uint16 t baudRate = 9600; //For the baud rate of USART3
    uint8_t dataBits = USART_CHSIZE_8BIT_gc;
                                               //For the (character size) CHSIZE
      [2:0]
    unsigned char parity = 0x00;
                                    //PMODE[1:0]
    USART3_init(baudRate, dataBits, parity);
    while (1)
        //Send a character to the Tera Term (TX pin)
        USART_sw_write('U');
        _delay_ms(2);
    }
}
//In Laboratory 05 you were not required to organize your program using functions,
  even though
//this approach was discussed in class. A simple function to configure a USART might 🔻
  have a single parameter that specifies the desired baud rate.
//The function that you must write for this task goes further than that, it allows
  both baud rate and
//the frame format to be specified
void USART3_init (uint16_t baud, uint8_t data_bits, unsigned char parity){
    PORTB_DIR |= PINO_bm; //To transmit the data
    //Specify the baud rate value for the USART3
    USART3.BAUD = (uint16_t)USART3_BAUD_RATE(baud);
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//Initialize the data bits and the parity bits type
   USART3_CTRLC |= data_bits | parity;
   USART3.CTRLB |= USART_TXEN_bm; //Enable USART transmitter
}
//Function to be able to transmit characters
//to the TX pin and display on the Tera Term
void USART_sw_write(char c)
{
   //Poll until the transmit buffer register are empty
   //when they contain data that has not been moved to
   //transmit shift register
   while (!(USART3.STATUS & USART_DREIF_bm))
       ;
    }
   //Load data to transmit shift register and
   //output each of the bits serially to the TXD pin
   USART3.TXDATAL = c;
}
```