Laboratory 04: Software UART Transmitter and Receiver - Saleae Logic Analyzer and Tera Term Terminal Emulator

Prof. Ken Short

2/4/2022

© Copyright Kenneth Short 2022

1

Overview

- ☐ Asynchronous communication is very common in embedded system design.
- ☐ Writing your own C functions to implement a serial transmitter and receiver clarifies the basic concepts of asynchronous serial transfer. It will also give you some practice in bit manipulation and software delays in C.
- ☐ You will also learn to use Saleae's 16-channel logic analyzer's protocol aware capabilities to view asynchronous serial data decoded based on a specified serial protocol.
- ☐ A terminal emulator software application running on a PC allows you to send and receive ASCII information in the asynchronous serial protocol and see this information displayed on the PC's monitor.

2/4/2022

© Copyright Kenneth Short 2022

Laboratory 04 Laboratory Tasks

- □ Design Task 1: Software UART Transmitter Function
- ☐ Design Task 2: Software UART Receiver Function
- ☐ Design Task 3: Software UART Receiver Interrupt Service Routine
- □ Design Task 4: Interrupt Echo Program
- □ Design Task 5: Message Relay Program

2/4/2022

© Copyright Kenneth Short 2022

3

Design Task 1: Software UART Transmitter Function

- ☐ You must write a program named asynch_sw_send that sends ASCII characters at any of the following three baud rates: 4800, 9600, or 19200 baud.
- ☐ This program must use PB0 as the TX pin for your software transmitter. In the laboratory, this program will be used to test your UART_sw_write function.
- ☐ The characters transmitted will be observed using the oscilloscope, Saleae logic analyzer, and Tera Term. You will use a loop in your program to continuously send the same character with a 1 ms delay between the characters.

2/4/2022

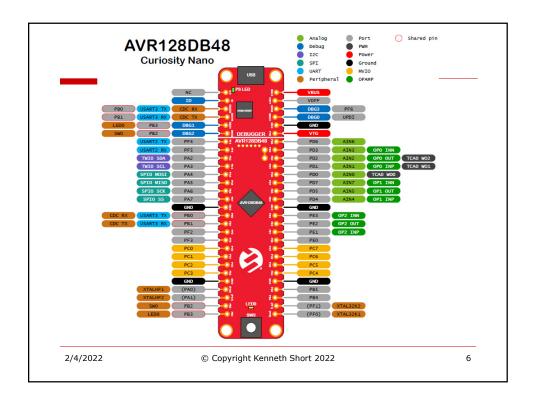
© Copyright Kenneth Short 2022

Curiosity Board

- ☐ You are to use pin PB0 for your TX signal. PB0 appears on two pins of the Curiosity Nano. It appears at pin 16 as PB0 and on pin 4 as CDC TX.
- ☐ Use pin 16 when connecting to the oscilloscope and Saleae Logic Analyzer.
- ☐ The same signal also appears on pin 4 and is connected on the Curiosity board to a virtual serial port (CDC) that provides a general purpose serial bridge between the host PC via the USB cable and the target microcontroller on the Curiosity Nano.

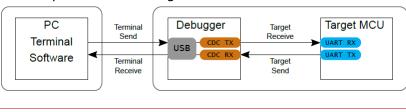
2/4/2022

© Copyright Kenneth Short 2022



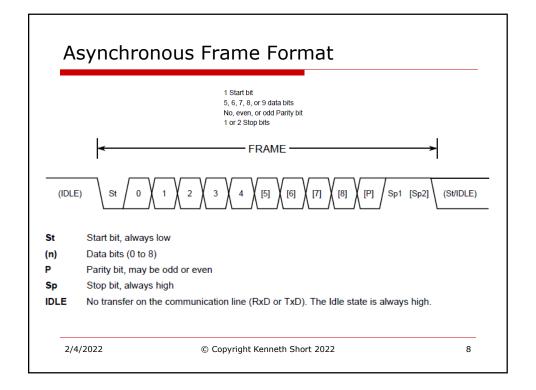
Curiosity Nano Virtual Serial Port (CDC)

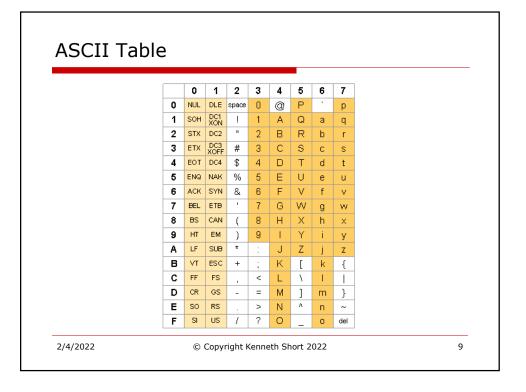
- ☐ The virtual serial port (CDC) is a general purpose serial bridge between a host PC and the target microcontroller on Curiosity Nano.
- ☐ The on-board debugger implements a composite USB device that includes a standard Communications Device Class (CDC) interface, which appears to the host as a virtual serial port. The CDC can be used to stream arbitrary data in both directions between the host computer and the target.



2/4/2022

© Copyright Kenneth Short 2022



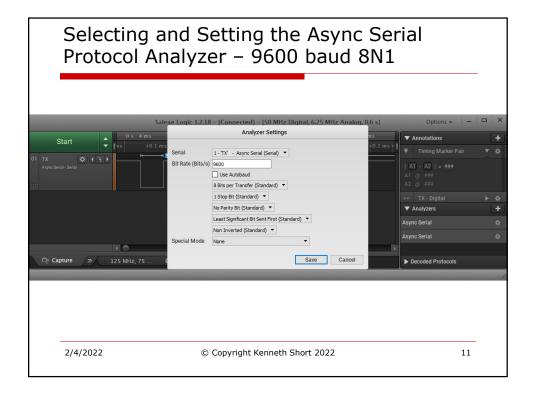


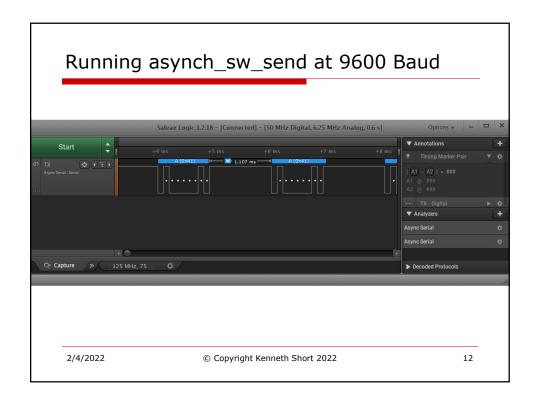
Setting Up Saleae Logic Analyzer to View Transmitted Frame

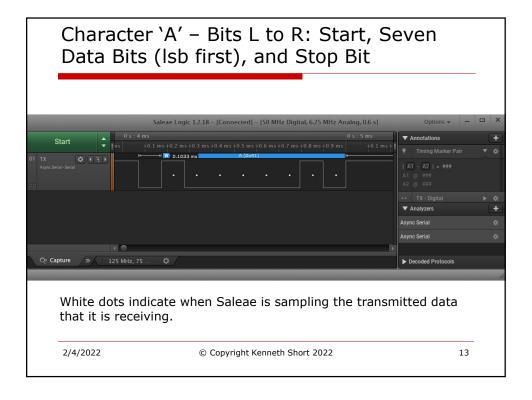
☐ Using the Saleae Logic Analyzer requires some setup to select the protocol to be decoded and set the format of the frames within the protocol.

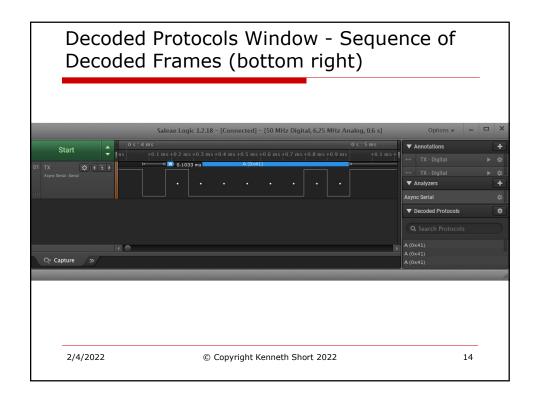
2/4/2022

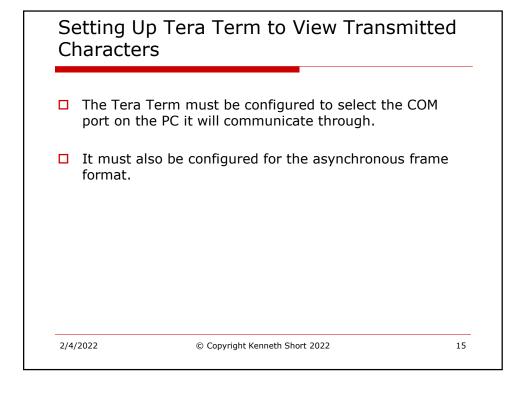
© Copyright Kenneth Short 2022

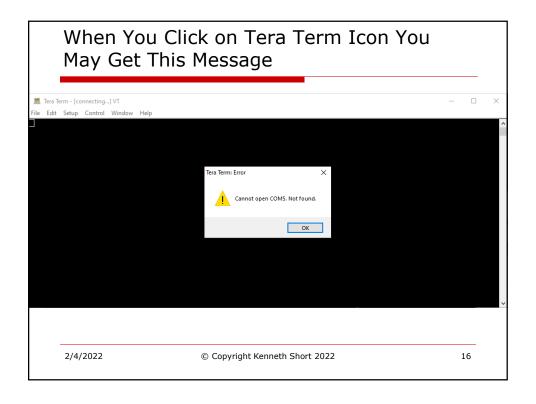


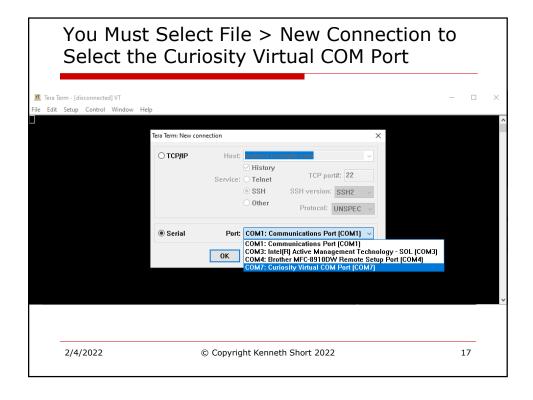


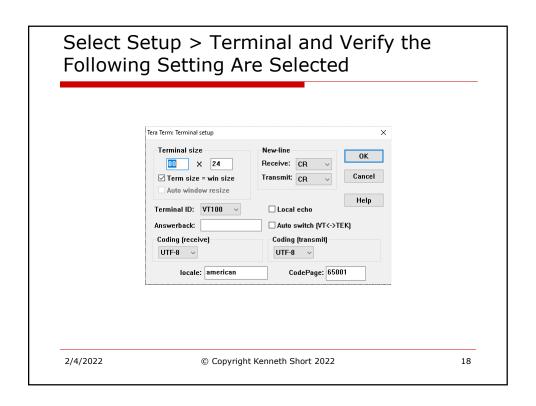


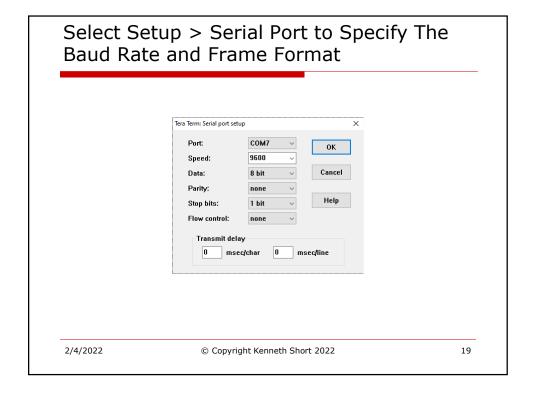


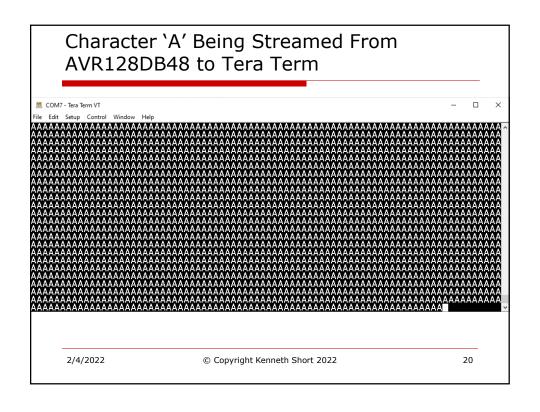










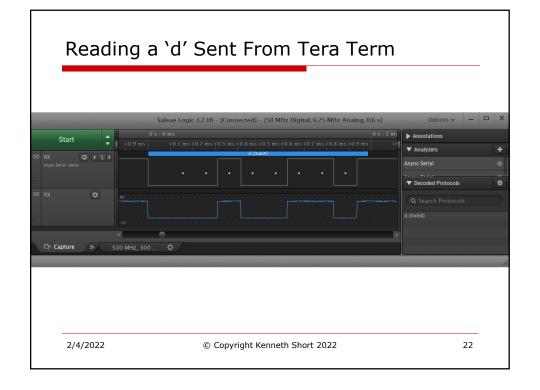


Design Task 2: Software UART Receiver Function

- ☐ You must write a function to read an asynchronous character with a format of 8N1 and baud rates of either 4800, 9600, 19200 baud.
- ☐ The RX pin is PB1 Curiosity Nano pin 17 and pin 3 (for the CDC).
- ☐ This software receiver routine must use polling to detect the start of a character frame and must implement a false start check at the middle of the start bit. This check determines if the signal is still 0. If not, a false start is assumed and the reception of the character is terminated and polling resumed to detect the next start bit.

2/4/2022

© Copyright Kenneth Short 2022



Design Task 3: Software UART Receiver Interrupt Service Routine

☐ The polling receive function UART_sw_read must be modified to be an interrupt service routine using the pin change interrupt of pin PB1.

2/4/2022

© Copyright Kenneth Short 2022

23

Pin Change Interrupt Code

- ☐ Include the header file <avr/interrupt.h>
- Name the interrupt service routine:
 - ISR (PORTB_PORT_vect) { }
- ☐ Enable the interrupt locally in PORTB.PIN1CTRL
- Enable the interrupts globally:
 - sei();
- ☐ In the while (1) statement in main(), put only the single instruction:
 - asm volatile ("nop");

2/4/2022

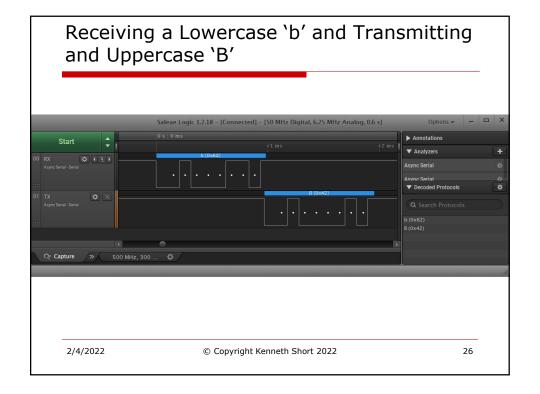
© Copyright Kenneth Short 2022

Design Task 4: Interrupt Echo Program

- ☐ You must write a program named interrupt_echo that combines the code from Task 1 and Task 3 to create a program that uses an interrupt to receive an alphabetic character from Tera Term and echo the character back to the Tera Term with its case changed.
- ☐ So, if you send a lower case `a' it sends back an upper case `A'. The inputs are assumed to be limited to alphabetic characters.

2/4/2022

© Copyright Kenneth Short 2022



Design Task 5: Message Relay Program

- ☐ You must modify your program from Design Task 4 to create a program named interrupt_echo_line that uses interrupts to receive a line of ASCII characters from the Tera Term.
- ☐ The characters received must be buffered in an 80 character array until a carriage return 'CR' control character (0x0D) is received.
- Once a carriage return character is received, the program must send (echo or relay) the entire line back to the Tera Term. After a line is echoed back, the Tera Term's cursor should be moved to the beginning of the next line.

2/4/2022

© Copyright Kenneth Short 2022