Jason Xinyu Liu

🏠 jasonxyliu.github.io
✉ xinyu_liu@brown.edu

Education

2018 –   **Brown University**
Ph.D. in Computer Science
Advisor: Stefanie Tellex

2021   **Brown University**
M.S. in Computer Science
Advisor: Stefanie Tellex

2017   **University of California, Berkeley**
B.S. in Electrical Engineering and Computer Sciences
Advisor: Ken Goldberg and David Wagner

Conference Publications

ICRA 2024   **LTL-Transfer: Skill Transfer for Temporally-Extended Task Specifications**
J.X. Liu*, A. Shah*, E. Rosen, M. Jia, G.D. Konidaris, S. Tellex
IEEE International Conference on Robotics and Automation (ICRA) 2024. [PDF, Website]

CoRL 2023   **Grounding Complex Natural Language Commands for Temporal Tasks in Unseen Environments**
J.X. Liu*, Z. Yang*, I. Idrees, S. Liang, B. Schornstein, S. Tellex, A. Shah
Conference on Robot Learning (CoRL) 2023. [PDF, Website]

INTERSPEECH 2023   **Style-transfer based Speech and Audio-visual Scene Understanding for Robot Action Sequence Acquisition from Videos**
C. Hori, P. Peng, D. Harwath, **J.X. Liu***, K. Ota, S. Jain, R. Corcodel, D. Jha, D. Romeres, J. Le Roux
INTERSPEECH 2023. [PDF]

ICRA 2022   **Generalizing to New Domains by Mapping Natural Language to Lifted LTL**
E. Hsiung, H. Mehta, J. Chu, **J.X. Liu**, R. Patel, S. Tellex, G. D. Konidaris
IEEE International Conference on Robotics and Automation (ICRA) 2022. [PDF]

ACNS 2020   **Minority Reports Defense: Defending Against Adversarial Patches**
M. McCoyd, W. Park, S. Chen, N. Shah, R. Roggenkemper, M. Hwang, **J.X. Liu**, D. Wagner
Applied Cryptography and Network Security Workshops 2020. [PDF]

ICRA 2018	**Dex-Net 3.0: Computing Robust Vacuum Suction Grasp Targets in Point Clouds Using a New Analytic Model and Deep Learning** J. Mahler, M. Matl, **J.X. Liu**, A. Li, D. Gealy, K. Goldberg *IEEE International Conference on Robotics and Automation (ICRA) 2018.* [PDF, Website]
ICISS 2018	**Detecting Phone Theft Using Machine Learning** **J.X. Liu**, D. Wagner, S. Egelman *International Conference on Information Science and System 2018.* [PDF]
RSS 2017	**Dex-Net 2.0: Deep Learning to Plan Robust Grasps with Synthetic Point Clouds and Analytic Grasp Metrics** J. Mahler, J. Liang, S. Niyaz, M. Laskey, R. Doan, **JX Liu**, J. A. Ojea, K. Goldberg *Robotics: Science and Systems (RSS) 2017.* [PDF, Website]

Workshop Publications

IJCAI-W 2022	**LTL-Transfer: Skill Transfer for Temporally-Extended Task Specifications** **J.X. Liu***, A. Shah*, E. Rosen, M. Jia, G.D. Konidaris, S. Tellex *IJCAI Workshop on Generalization in Planning 2022.* [PDF, Slides]
RSS-W 2021	**Leveraging Temporal Structure in Safety-Critical Task Specifications for POMDP Planning** X. Liu, E. Rosen, S. Zheng, G. D. Konidaris, S. Tellex *Robotics: Science and Systems (RSS) Workshop Robotics for People 2021.* [PDF, Poster]
RSS-W 2021	**Dialogue Object Search** M. Roy*, K. Zheng*, X. Liu, S. Tellex *Robotics: Science and Systems (RSS) Workshop Robotics for People 2021.* [PDF]

Fellowships, Awards and Honors

Brown	**National Science Foundation Graduate Research Fellowship Program**, 2018 **Jack Kent Cooke Foundation Graduate Scholarship**, 2018
UC Berkeley	**Tau Beta Pi, National Engineering Honor Society**, 2014 **Eta Kappa Nu, National EECS Honor Society**, 2014 **Jack Kent Cooke Foundation Undergraduate Transfer Scholarship**, 2014

Service

Brown	**First-year Ph.D. student mentor**, 2021-2023 **Google exploreCSR** (explorecsr.cs.brown.edu), 2020