

A Simple Physics Engine

Interactive Computer Graphics
Professor Eric Shaffer



Newtonian Physics

- We will animate particles (aka point masses)
- Position is changed by velocity
- Velocity is changed by acceleration
- Forces alter acceleration

- Our physics engine will integrate to compute
 - Position
 - Velocity
- We set the acceleration by applying forces



Force and Mass and Acceleration

- How do we update acceleration when force is applied?
- To find the acceleration due to a force we have

$$\ddot{\mathbf{p}} = \frac{1}{m}\mathbf{f}$$

- So we need to know the inverse mass of the particle
 - You can model infinite mass objects by setting this value to 0
- For the MP, you can use a uniform mass of 1
 - Or make the masses different if you want...



Force: Gravity

Law of Universal Gravitation

$$f = G \frac{m_1 m_2}{r^2}$$

- G is a universal constant
- m_i is the mass of an object
- r is the distance between object centers
- if we care only about gravity of the Earth
 - m1 and r are constants
 - r is about 6400 km on Earth
- We simplify to f = mg
 - g is about 10ms⁻²

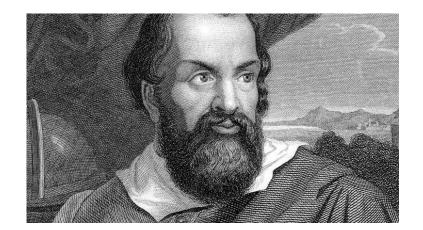


Acceleration due to Gravity

• If we consider acceleration due to gravity we have

$$\ddot{p} = \frac{1}{m}(mg) = g$$

So acceleration due to gravity is independent of mass





Acceleration due to Gravity

• In your MP the magnitude and direction of acceleration would be

$$\mathbf{g} = \langle 0, -g, 0 \rangle$$

- For gaming, 10ms⁻² tends to look boring
 - Shooters often use 15ms⁻²
 - Driving games often use 20ms⁻²
 - Some tune g object-by-object



Force: Drag

- Drag dampens velocity
 - Caused by friction with the medium the object moves through
- Even neglecting drag, you need to dampen velocity
 - Otherwise numerical errors likely drive it higher than it should be
- A velocity update with drag can be implemented as

$$\dot{\mathbf{p}}_{new} = \dot{\mathbf{p}}d^t$$

- important to incorporate time so drag changes if the frame rate varies
- for the MP, have all objects have the same drag, calculate once per frame
- What range should **d** be in?



The Integrator

• The position update can found using Euler's Method:

$$P_{new} = P_{old} + \dot{P}t$$

- This is a pretty inaccurate approximation of analytical integration
 - formula gets more inaccurate as acceleration gets larger
 - why?
 - In general we can characterize Euler method error as O(t)
 - ...good enough for the MP
- The velocity update is computed using Euler integration as well

$$\dot{\mathbf{p}}_{new} = \dot{\mathbf{p}}d^t + \ddot{\mathbf{p}}t$$



The Integrator

- You should ideally use actual time for t
 - or some scaled version of it
- In JavaScript, Date.now() returns current time in ms
 - so keep a previous time variable
 - each frame find out how much time has elapsesd
- ...or you could use some uniform timestep you like

