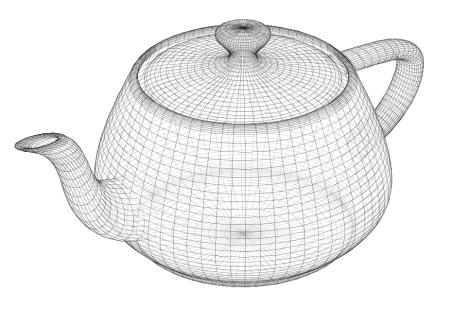
Terrain Generation The Diamond-Square Algorithm Faulting



CS 418: Interactive Computer Graphics
Professor Eric Shaffer



Procedural Modeling of Terrain

Lots of scenes require geometric models of natural objects

- Clouds, Water, Plants, Terrain
- Those last two items are often modeled using fractal techniques
- Allows for the procedural generation of highly detailed models

We'll look at two early modeling techniques for terrain

- Diamond-Square Algorithm
 - Developed by Loren Carpenter in 1980(ish)
- Faulting
 - Developed by Benoit Mandelbrot in 1980(ish)

Graphics and Image Processing James Foley* Editor

Computer Rendering of Stochastic Models

Alain Fournier
University of Toronto
Don Fussell
The University of Texas at Austin
Loren Carpenter
Lucasfilm



Loren Carpenter



- Born in 1947
- Co-founder and chief scientist at Pixar
- One of the designers of Reyes
- One of the authors of RenderMan
- Invented A-Buffer hidden surface algorithm
- Improved Mersenne Twistor RNG (2006)
- Retired in 2014

https://youtu.be/y5moYMIp8iU



Height Maps

Rest of the scientific world uses Z for height...only computer graphics seems to prefer Y.

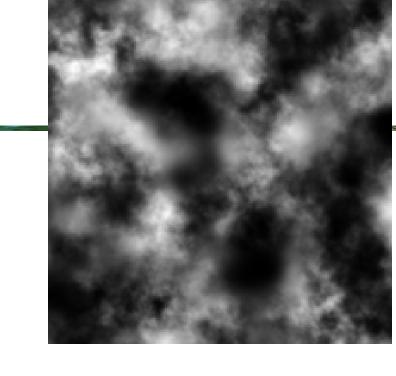
A height map is a simple data structure

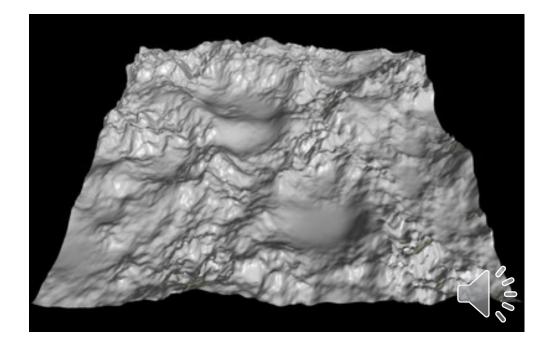
For each point (X,Y) in a 2D domain

Describes a height or Z value

What phenomenon cannot be modeled this way?

- The (X,Y) points are usually discretely sampled
- Typically in a uniform grid
- Images are often used to store height maps
- Stored terrain rather than generated





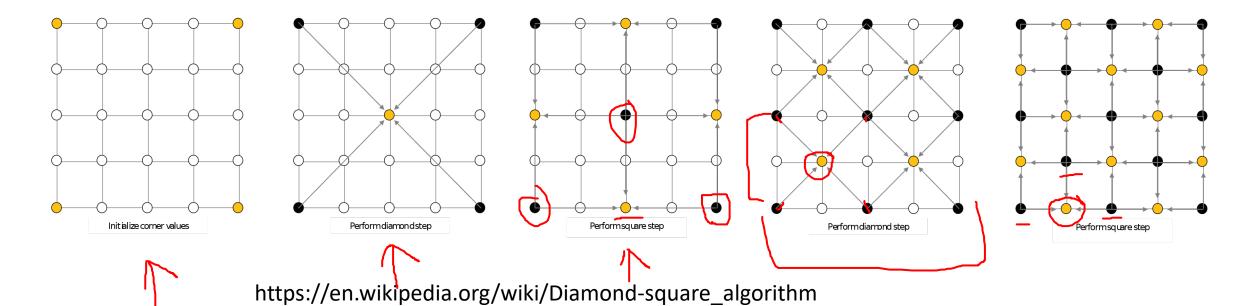
Generating a Terrain

- Lots of different methods
 - Subdivision techniques
 - Faulting
 - Perlin noise
- Methods in industry
 - Usually involve some manual input
 - Simulate more stuff (e.g. erosion)
 - But often based on the above methods



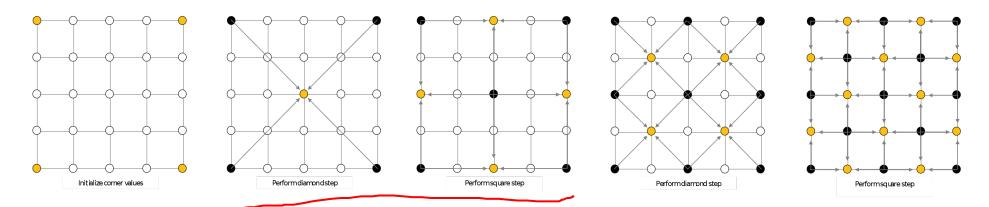
Diamond Square Algorithm

- For now, we will focus only on the Diamond-Square algorithm
- Basic idea:





Diamond Square Algorithm



Grid size is $2^K + 1$ by $2^K + 1$

Initialize height of four corner vertices to random values

Every other vertex has height set as:

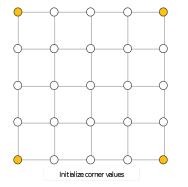
$$h_v = roughness + \frac{1}{4} \sum_{i=1}^{4} h_i$$

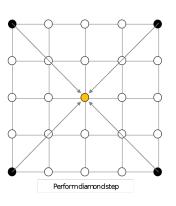
The average of four other heights plus some random value called "roughness" After performing a diamond & square step \rightarrow reduce the roughness value

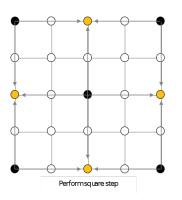


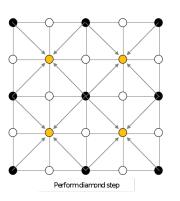
Diamond Square Algorithm

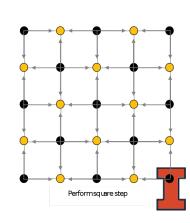
- Parameters
 - K (grid size)
 - Roughness
 - Reduction (e.g. reduce roughness by ½ each iteration)
- Can implement recursively or iteratively
 - I think recursion is harder....guesses as to why?
 - But recursion is doable...so do it if you want to...









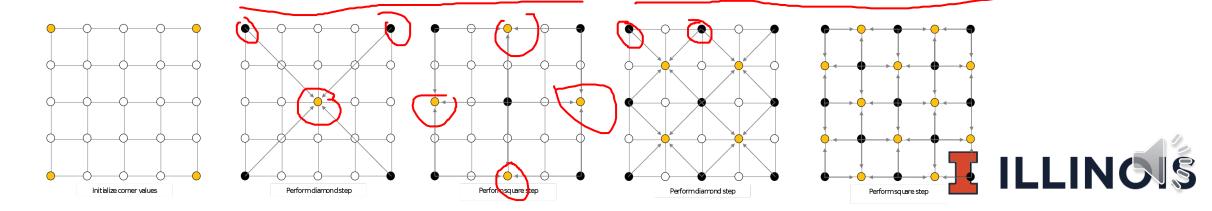




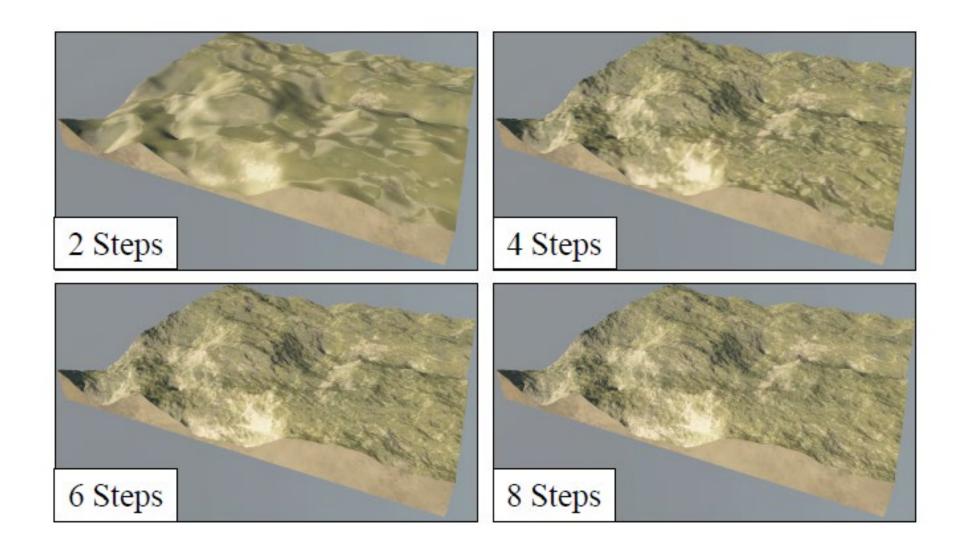
Diamond Square: Implementation

For an iterative implementation one approach is Consider an outer loop and two inner nested loops

- Outer loop changes the radius of neighborhoods used for averages
 - For example, in the first diamond step below the radius is 4 steps, in the second it is 2 steps
 - How many iterations of the outer loop will there be?
- Inner 2 nested loops iterate over the grid generating the (i,j) coordinates of vertices
 - One nested loop does diamond
 - One nested loop does square
 - Step size is set to generate only the indices needed for each step
 - For example first diamond is (2,2) and first square is (0,2), (2,0), (2,4), (4,2)



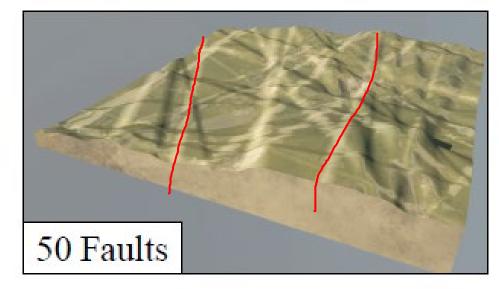
Diamond Square – Example Output

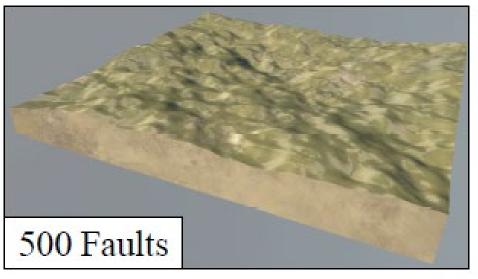




Faulting Method

- Start from a flat terrain
- Generate random vertical fault lines
 - ...like a plane cutting through the terrain
- ...inc a plane catting through the terrain
- Points on one side of the fault are displaced upward by some random amount
- Points on the other side are displaced downward by same random amount
- ...repeat





To generate a random cutting plane you need:

A random direction $(n_x,n_y,0)$ that will be the normal of the plane

A random point (x,y,0) in terrain



Faulting: Varying Perturbation with Distance

Can vary the height perturbation depending on distance from fault

Distance of point p to fault i: $d(\mathbf{p}, \phi_i)$

Sum of all the perturbations on point p is then

$$f(\mathbf{p}) = \sum_{i=0}^{i < n} f_i(\mathbf{p}) \qquad f_i(\mathbf{p}) = \underline{a_i g \circ d(\mathbf{p}, \phi_i)}$$

The random vertical displacements are the a_i

The function $f_i(\mathbf{p})$ is a function that decreases the displacement based on distance



Faulting: Smooth Step Function

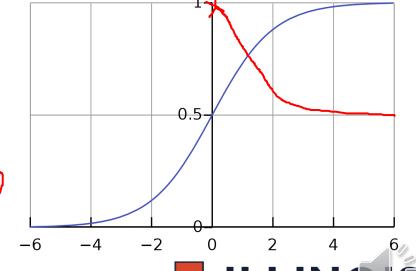
Use a smooth step function to decrease perturbation with distance

$$g(r) = \left(1 - (r/R)^2\right)^2$$
 if $\underline{r} < \underline{R}$ $g(r) = 0$ otherwise

$$f_i(\mathbf{p}) = a_i g \circ d(\mathbf{p}, \phi_i)$$

Distance of point p to fault i: $d(\mathbf{p}, \phi_i)$

Example of a smooth step function L ...we use 1 –L to modify perturbation



Distance from Point to Line in 2D

$$\operatorname{distance}(\underline{ax+by+c}=0,(x_0,y_0)) = \frac{|ax_0+by_0+c|}{\sqrt{a^2+b^2}}$$

If your normal vector for the plane is $(n_x, n_y, 0)$ with anchor point $(p_x, p_y, 0) \rightarrow a = n_x$ and $b = n_y$ and $c = -(n_y p_y + n_x p_x)$

