

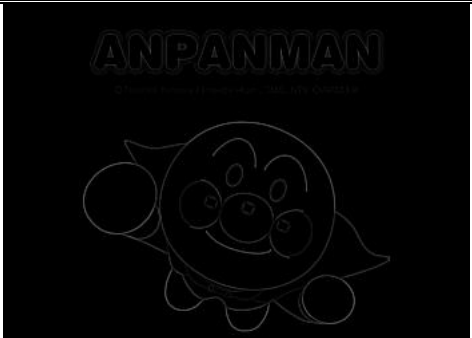







# Computer Vision HW1 Report

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## Part 1.

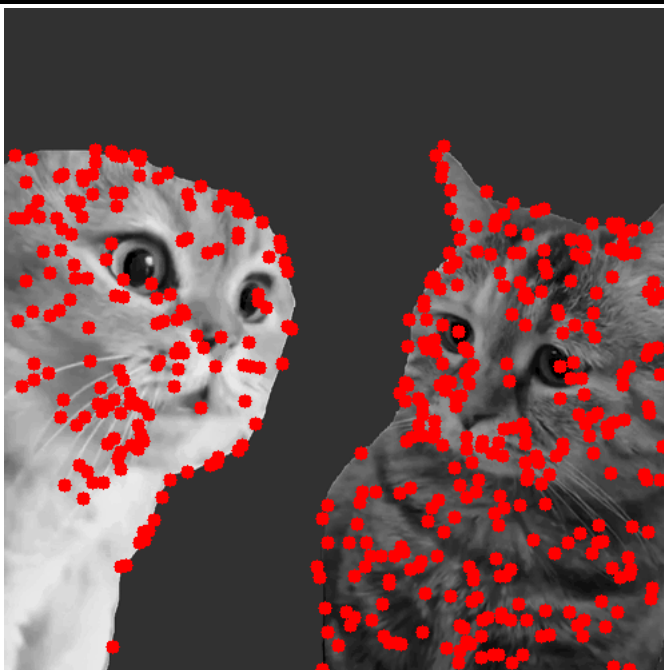
- Visualize the DoG images of 1.png.

	DoG Image (threshold = 3)		DoG Image (threshold = 3)
DoG1-1.png		DoG2-1.png	
DoG1-2.png		DoG2-2.png	
DoG1-3.png		DoG2-3.png	
DoG1-4.png		DoG2-4.png	

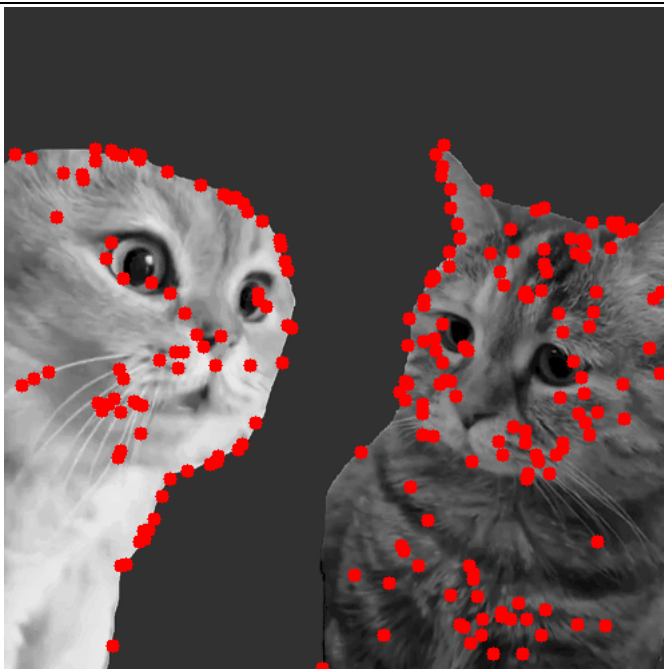
- Use three thresholds (1,2,3) on 2.png and describe the difference.

Threshold	Image with detected keypoints on 2.png
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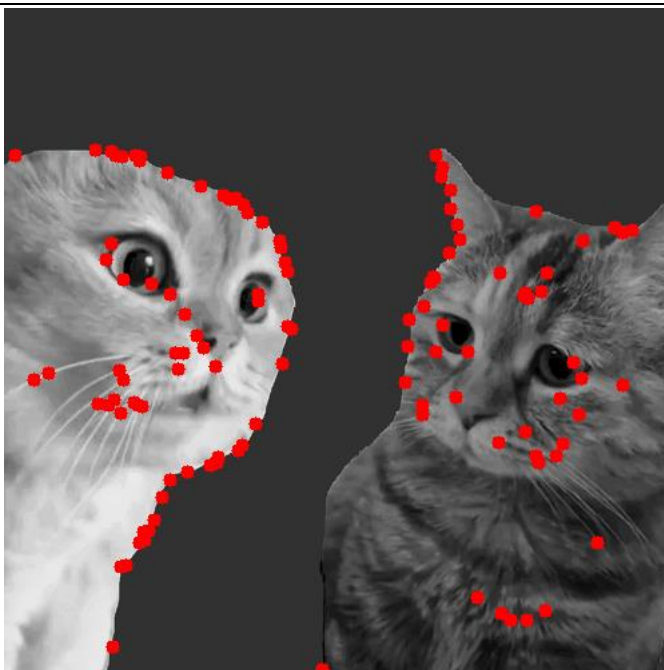
1



2



3



(describe the difference)

隨著 threshold 的提高，keypoints 會變少，更能精確地抓到邊緣。相反地 threshold 較低的話，會導致 keypoints 抓到一些變化不大的地方，使得邊緣的檢測較為粗糙、不精準。






## Part 2.

- Report the cost for each filtered image.

Gray Scale Setting	Cost (1.png)
cv2.COLOR_BGR2GRAY	1207799
$R*0.0+G*0.0+B*1.0$	1439568
$R*0.0+G*1.0+B*0.0$	1305961
$R*0.1+G*0.0+B*0.9$	1393620
$R*0.1+G*0.4+B*0.5$	1279697
$R*0.8+G*0.2+B*0.0$	1127913

Gray Scale Setting	Cost (2.png)
cv2.COLOR_BGR2GRAY	183850
$R*0.1+G*0.0+B*0.9$	77882
$R*0.2+G*0.0+B*0.8$	86023
$R*0.2+G*0.8+B*0.0$	188019
$R*0.4+G*0.0+B*0.6$	128341
$R*1.0+G*0.0+B*0.0$	110862





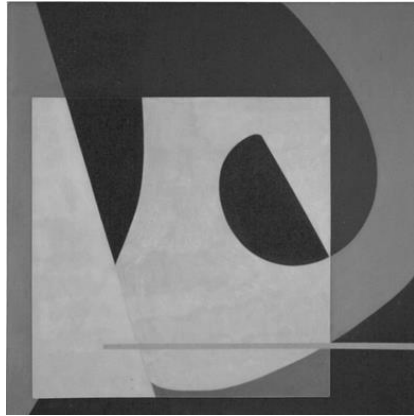
- Show original RGB image / two filtered RGB images and two grayscale images with highest and lowest cost.

Original RGB image (1.png)	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Highest cost	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Lowest cost
		
		

(Describe the difference between those two grayscale images)

cost 大的灰階圖難以看出顏色差異，導致一些原本是顏色差異很大的區塊卻看起來顏色相近。

而 cost 小的灰階圖可見紅色楓葉的部分較白較明顯，相較 cost 大的灰階圖較能看出顏色差異。

Original RGB image (2.png)	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Highest cost	Filtered <u>RGB image</u> and <u>Grayscale image</u> of Lowest cost
		
		

(Describe the difference between those two grayscale images)

cost 大的灰階圖各種顏色的差異不明顯，如原圖方塊內的橘色和紫色在灰階圖卻看起來顏色相近。

而 cost 小的相較於 cost 大的灰階圖更能看出顏色差異，不論是方塊外的紅色與藍色，或是方塊內的橘色與紫色，都比起 cost 大的灰階圖更能看出色差。

#### - Describe how to speed up the implementation of bilateral filter.

```
Gr_LUT = np.exp(np.divide(-(np.arange(256)/255) * (np.arange(256)/255), (2 * self.sigma_r**2)))
```

利用 look up table 的方式可以節省計算，讓每次計算 range kernel 的時候都能回去查表，之後在算 Gr 的時候就不需要每格都去作計算。