

# ECS 122A Lecture 12+13 Jasper Lee

## Minimum Spanning Tree

Setting: Given weighted undirected graph  
Compute spanning tree w/ min total edge weight.

Recall: Spanning tree is a tree connecting all vertices, hence w/  $n-1$  edges.

Two standard greedy algorithms

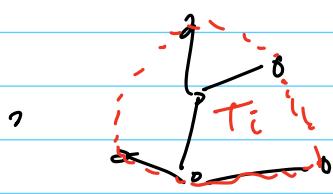
- Prim's alg
- Kruskal's alg

### Prim's alg

Idea: Grow a spanning tree from a seed, one edge at a time.

Let's try deriving the alg

At some intermediate stage:



What does any spanning tree need to do?

Connect  $T_i$  w/ some vertex outside of  $T_i$

Obs: Might as well take min-weight edge b/w  $T_i$  and  $G \setminus T_i$

Alg

connected =  $\{s\}$  //  $s$  arbitrarily chosen

$T \leftarrow \emptyset$  // empty tree, no edges.

while  $\exists$  edge  $b/w$  connected and  $V \setminus$  connected

$(u, v) \leftarrow \min_{(u, v) \in E} W(u, v)$

$u \in \text{connected}$   
 $v \notin \text{connected}$

Add  $(u, v)$  to  $T$

Add  $v$  to connected

return  $T$

Correctness

Induction hypothesis:

At the end of  $i^{th}$  iter,  $\exists$  an MST  $T_i^{\text{opt}}$   
s.t.  $T_i^{\text{opt}}$  contains all edges in  $T$ .

Base case:  $i = 0$ , trivial.

Induction steps:

Assume IH for iter  $i$ , so there is  
an MST  $T_i^{\text{opt}}$  containing all of  $T_i$  (state of  
 $T$  at end  
of iter  $i$ )

Call  $(u, v)$  the new edge added in iter  $i$  if  $u \in T_i$  and  $v \notin T_i$

If  $(u, v) \in T_i^{\text{opt}}$ , then we're done.

Otherwise,  $(u, v) \cup T_i^{\text{opt}}$  has a cycle.

$\exists (a, b) \neq (u, v)$  in cycle s.t.

$a \in T_i$  and  $b \notin T_i$

(Why? Walk along cycle from  $u$ .)

Going to  $u \rightarrow v$  goes from  $T$  to  $V \setminus T$ . Eventually end up back at  $u$  which is in  $T$ .)

$w(a, b) \geq w(u, v)$  by alg.

So swap to get  $T_{i+1}^{\text{opt}}$

$w(T_{i+1}^{\text{opt}}) \leq w(T_i^{\text{opt}})$

$T_{i+1}^{\text{opt}}$  still has  $n-1$  edges, connects all vertices hence is a spanning tree, hence MST,

Wrap up: Upon termination,  $T$  connects all vertices reachable from  $s$ , and  $\exists$  an MST containing all of  $T$ . So  $T$  is an MST.

## Implementation?

Hard part: Find min outgoing edge from  $T$ .

Idea: Use heap data structure

- Heaps:  $\sim (\text{key, value})$
- $\text{Insert}(x)$ , adds  $x$  into DS
  - $\text{ExtractMin}$ , returns element w/ min key and deletes from DS
  - $\text{Delete}(\text{pointer to element } x)$ , deletes  $x$  from DS

Fact: There is a heap implementation s.t. all operations take  $O(\log n)$  time, where  $n$  is the # of elements in the heap at the time.

How to use a heap here?

Store vertices in heap to decide which one to grow  $T$  to

Invariant: At the end of every loop iter, heap  $H$  contains all vertices  $v$  in  $V \setminus \text{connected}$  w/ key  $\min_{u \in \text{connected}} W_{u,v}$ .

Pseudocode:

$\text{connected} \leftarrow \{s\}$ ;  $T \leftarrow \emptyset$ ;  $H \leftarrow \text{empty heap}$

pointers  $\leftarrow$  array indexed by  $V$ , init to NULL

for every  $v \neq s$

if  $(s, v) \in E$  then  $\text{key}(v) \leftarrow w_{s,v}$ ;  
else  $\text{key}(v) \leftarrow \infty$ ;

$\text{edge}(v) \leftarrow (s, v)$ ;

Create  $(\text{key}(v), (v, \text{edge}(v)))$  w/ pointer  $p_v$

pointers  $[v] \leftarrow p_v$

add

to  $H$

while  $H$  is non-empty

$(\text{key}(u), (u, \text{edge}(u))) \leftarrow \text{ExtractMin}(H)$

add  $u$  to  $\text{connected}$ ,  $\text{edge}(u)$  to  $T$

for each edge  $(u, v)$  where  $v \notin \text{connected}$

if  $\text{key}(v) > w_{u,v}$

delete  $v$  from  $H$

$\text{key}(v) \leftarrow w_{u,v}$ ;  $\text{edge}(v) \leftarrow (u, v)$

create ... w/ pt  $p_v$   
 $\text{pointers}[v] \leftarrow p_v$ , add ... to  $H$

return  $T$

$O(mn \log n)$  time

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## Dijkstra's algorithm

Single-source shortest path again

Bellman-Ford :  $O(|V||E|)$  time, allows negative weights

Dijkstra's : Greedy  $O(|V| \log |V|)$  time,  
no negative weights

Presentation slightly different from "standard" sources

## Def Shortest Path Tree

A (directed) tree  $T$  is a shortest path tree w.r.t. directed graph  $G$  and source vertex  $s$   
if 1.  $T$  contains all reachable vertices from  $s$   
2.  $T$  is a subgraph of  $G$

and 3. for all such vertex  $v$ ,  
 $s \xrightarrow{T} v$  is a shortest path in  $G$ .

## Existence

For any vertex  $v$  (reachable from  $s$ ),  
choose any shortest path  $s \xrightarrow{G} v$  with fewest hops.

Let  $\text{prev}(v)$  be vertex before  $v$  on this path.  
 $\text{hop}(v)$  be # hops on chosen path.

Obs:  $\text{hop}(\text{prev}(v)) = \text{hop}(v) - 1$ .

Exercise to prove.

$n-1$  edges  $\rightarrow$  construct shortest path tree hop-by-hop, adding edges  $\text{prev}(v) \rightarrow v$  for every  $v$ .

Exercise to show this is a shortest path tree.  
(by induction on # hops).

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Idea: Greedily grow shortest path tree from source  $s$ . (Like Prim's).

Alg

$$\text{Connected} \leftarrow \{s\}$$
$$T \leftarrow \emptyset$$

while  $\exists$  edge from  $\text{Connected}$  to  $V \setminus \text{Connected}$

$$\text{Find } v = \arg \min_{v \notin \text{Connected}} \min_{u \in \text{Connected}} w_{u \rightarrow v} + \text{dist}_T(s, u)$$

Add  $u \rightarrow v$  to  $T$   
 $v$  to  $\text{Connected}$

return  $T$  (and its dist is shortest path dist in  $G$ )

Exercise: Figure out how to implement this in  $O(|V| \log |V|)$  time.

Correctness:

Induction hypothesis:

At the end of every iter  $i$ ,  $T_i$  is such that

1.  $\text{connected}_i$  is set of  $v$  reachable from  $s$  in  $T_i$  and # edges in  $T_i = |\text{connected}_i| - 1$

2.  $\exists$  shortest path tree  $T_i^{\text{opt}}$  containing all edges in  $T_i$ .

Cor:  $\text{dist}_{T_i}(s, v) = \text{dist}_{T_i^{\text{opt}}}(s, v)$

$\geq$  since  $T_i^{\text{opt}}$  is shortest path tree

$\leq$  since  $T_i^{\text{opt}}$  contains all of  $T_i$

Induction step:

1. is super basic. Every  $v$  we add is reachable from by induction

2. Suppose  $T_i^{\text{opt}}$  is a shortest path tree containing all of  $T_i$  (state of  $T$  after  $i$ th iter)

Let  $u \rightarrow v$  be edge chosen in iter  $i$ .  
 $u \in T_i$   $v \notin T_i$

Suppose  $u \rightarrow v \notin T_i^{\text{opt}}$ , then in  $T_i^{\text{opt}}$ , the path

$s \rightsquigarrow_{T_i^{\text{opt}}} v$  must contain  $a \rightarrow b$  where  $a \rightarrow b$   
 $a \in T_i$   $b \notin T_i \Rightarrow u \rightarrow v$

So  $s \rightsquigarrow_{T_i^{\text{opt}}} a \rightarrow b \rightsquigarrow_{T_i^{\text{opt}}} \text{prev}(v) \rightarrow v$

By alg,  $\text{dist}_{T_i}(s, a) + w_{a \rightarrow b} \geq \text{dist}_{T_i}(s, u) + w_{u \rightarrow v}$

$\text{So } \text{dist}_{T_i^{\text{opt}}}(s, v) \geq \text{dist}_{T_i^{\text{opt}}}(s, a) + w_{a \rightarrow b}$

$\stackrel{\text{alg}}{\geq} \text{dist}_{T_i^{\text{opt}}}(s, u) + w_{u \rightarrow v}$

So remove  $\text{prev}(v) \rightarrow v$ , add  $u \rightarrow v$  to get  $T_{i+1}^{\text{opt}}$ .

Reachability preserved, dist no worse.,,

Wrap up: At termination,  $T^{\text{opt}}$  contains  $T$ , has same number of vertices. So edge count the same (1-connected 1-1)  $\Rightarrow$  same tree  $\square$