Computer Vision Mini Project Report

Jasser Abdelfattah UH ID: 21033101

Problem Statement and Dataset Description

Object recognition is a critical computer vision task that involves identifying objects within images. The CIFAR-10 dataset serves as a benchmark for this mini-project, consisting of $60,000~32\times32$ color images distributed equally across ten classes: airplane, automobile, bird, cat, deer, dog, frog, horse, ship, and truck. Each class contains 6,000 images, with 50,000 allocated for training and 10,000 for testing.

The primary objective of this project is to develop and evaluate an object recognition model capable of accurately classifying images into these ten categories. Such a system could have applications in educational tools for nursery students to learn object categories.

Approaches Used

0.1 Loading and Preprocessing the CIFAR-10 Dataset

The CIFAR-10 dataset is loaded and preprocessed to prepare it for training and evaluation. The dataset is divided into training, validation, and test sets. To enhance the model's generalization ability, data augmentation techniques such as random horizontal flipping and random cropping are applied to the training images. Subsequently, the images are converted into tensors and normalized.

0.2 Loading the Pre-trained EfficientNet-b0 Model

A pre-trained EfficientNet-b0 model is loaded and fine-tuned for the CIFAR-10 dataset. The final classification layer is replaced to accommodate the 10 classes in CIFAR-10. The model is then transferred to the appropriate device (GPU or CPU) for further training.

0.3 Training the EfficientNet-b0 Model

The model is trained on the training dataset, utilizing mixed precision training for computational efficiency. The training loop consists of forward passes, loss computation, backpropagation, and weight updates. To prevent overfitting, early stopping is implemented, which monitors validation loss and halts training when no improvement is observed.

0.4 Evaluating the EfficientNet-b0 Model

After training, the model is evaluated on the test dataset. Performance metrics, including accuracy, classification report, and confusion matrix, are computed and presented. Additionally, the model's ability to generalize to unseen images is demonstrated.

0.5 Prediction on Unseen Images

The trained model is used to predict the classes of unseen images. The images undergo preprocessing, and the predictions are displayed alongside the corresponding images.

Discussion of Results

The training and validation loss graph in Figure 2 demonstrates a consistent decrease, indicating that the model's loss is stable throughout the training process. Similarly, the training and validation accuracy graph in Figure 3 shows an upward trend, which is a positive sign, reflecting the stability and effectiveness of the model's learning.

The overall accuracy of the model on the test dataset (10,000 images) is 86 percent, as depicted in Figure 5. The classification report in Figure 4 highlights an average precision of 86 percent, recall of 86 percent, and F1-score of 86 percent, further emphasizing the balanced performance of the model across all classes.

The confusion matrix reveals closely related and comparable values between the classes, suggesting that the model has learned to distinguish them effectively. Moreover, the model's predictions on unseen images show a high success rate, correctly identifying 9 out of 10 images. The only misclassification observed was a dog incorrectly identified as a deer.

Figures

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Layer (type:depth-idx)	Output Shape	Param #
EfficientNet	[64, 10]	
├─Sequential: 1-1	[64, 1280, 1, 1]	
Conv2dNormActivation: 2-1	[64, 32, 16, 16]	
	[64, 32, 16, 16]	864
	[64, 32, 16, 16]	64
	[64, 32, 16, 16]	
└─Sequential: 2-2	[64, 16, 16, 16]	
	[64, 16, 16, 16]	1,448
└Sequential: 2-3	[64, 24, 8, 8]	
	[64, 24, 8, 8]	6,004
	[64, 24, 8, 8]	10,710
└─Sequential: 2-4	[64, 40, 4, 4]	
	[64, 40, 4, 4]	15,350
	[64, 40, 4, 4]	31,290
└Sequential: 2-5	[64, 80, 2, 2]	
	[64, 80, 2, 2]	37,130
_MBConv: 3-10	[64, 80, 2, 2]	102,900
	[64, 80, 2, 2]	102,900
└─Sequential: 2-6	[64, 112, 2, 2]	
	[64, 112, 2, 2]	126,004
	[64, 112, 2, 2]	208,572
	[64, 112, 2, 2]	208,572
└─Sequential: 2-7	[64, 192, 1, 1]	
	[64, 192, 1, 1]	262,492
	[64, 192, 1, 1]	587,952
	[64, 192, 1, 1]	587,952
	[64, 192, 1, 1]	587,952
└─Sequential: 2-8	[64, 320, 1, 1]	
	[64, 320, 1, 1]	717,232
└Conv2dNormActivation: 2-9	[64, 1280, 1, 1]	
	[64, 1280, 1, 1]	409,600
BatchNorm2d: 3-21	[64, 1280, 1, 1]	2,560
	[64, 1280, 1, 1]	
—AdaptiveAvgPool2d: 1-2	[64, 1280, 1, 1]	
—Sequential: 1-3	[64, 10]	
☐Dropout: 2-10	[64, 1280]	
Linear: 2-11	[64, 10] 	12,810
Total params: 4,020,358		
Trainable params: 4,020,358		
Non-trainable params: 0		
Total mult-adds (Units.MEGABYTES): 545.68		
		========
Forward/backward pass size (MB): 145.59		
Params size (MB): 16.08		
Estimated Total Size (MB): 162.46		
ESCINACEU 10001 3120 (10). 102.40		

Figure 1: EfficientNet-b0 model architecture.

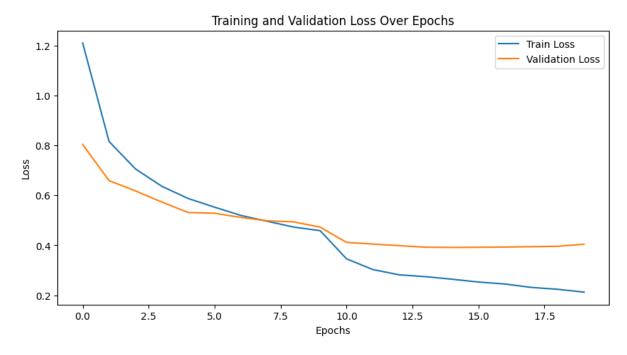


Figure 2: Training and Validation Loss Over Epochs.

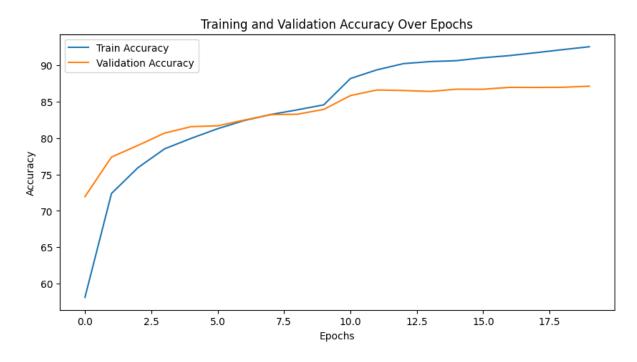


Figure 3: Training and Validation Accuracy Over Epochs.

Classification Report:				
	precision	recall	f1-score	support
plane	0.87	0.89	0.88	1000
automobile	0.93	0.93	0.93	1000
bird	0.84	0.83	0.84	1000
cat	0.75	0.72	0.74	1000
deer	0.85	0.87	0.86	1000
dog	0.80	0.78	0.79	1000
frog	0.89	0.93	0.91	1000
horse	0.89	0.90	0.90	1000
ship	0.93	0.93	0.93	1000
truck	0.91	0.90	0.91	1000
accuracy			0.87	10000
macro avg	0.87	0.87	0.87	10000
weighted avg	0.87	0.87	0.87	10000

Figure 4: Classification Evaluations.

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Accuracy of plane : 89 %
Accuracy of automobile : 92 %
Accuracy of bird : 82 %
Accuracy of cat : 73 %
Accuracy of deer : 86 %
Accuracy of frog : 92 %
Accuracy of horse : 89 %
Accuracy of ship : 92 %
Accuracy of truck : 89 %
Accuracy of the network on the 10000 test images: 86 %
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Figure 5: Model's Accuracy on Test set (10,000 Images).

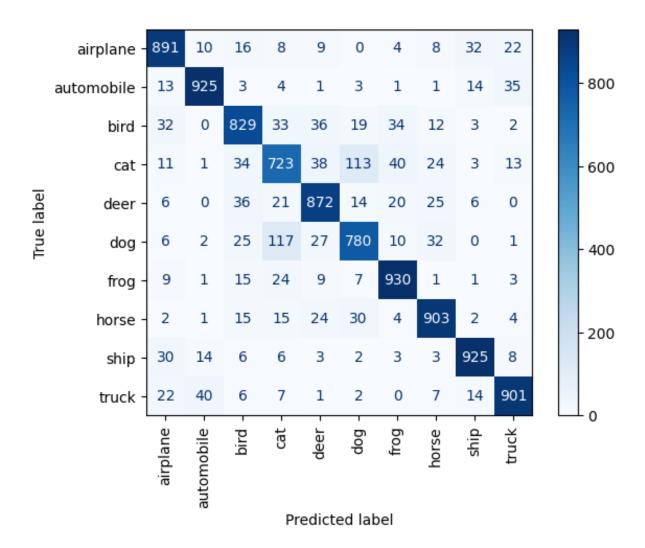


Figure 6: Confusion matrix.

Image Label	Predicted Label
automobile	automobile
bird	bird
cat	cat
deer	deer
dog	deer
frog	frog
horse	horse
plane	plane
ship	ship
truck	truck

Figure 7: Table of Prediction on Unseen Images.