Graph Analytics at Scale using SparkSQL and GraphFrames

Overview

- SparkSQL & GraphFrames
- What is meant by "scale"?
- Graph Algorithms in GraphFrames
- Walkthrough: the Alternating Algorithm (Connected Components)
- Custom Graph Algorithms via AggregateMessages/Pregel
- Demo

Spark and Spark SQL

- The core data abstraction in Spark is a resilient-distributed dataset (RDD)
- Spark SQL sits on top of Spark core to provide a higher-level data abstraction called a DataFrame
- Advantages to Spark SQL when using PySpark
 - Provides data users a familiar interface to query data (SQL)
 - Structure implied by DataFrames allows for additional optimizations (and these optimizations exist whether in using the Scala/Java API or the Python API)

What is GraphFrames?

- Open-source project (not part of Spark Core)
- Implements a core set of graph algorithms on data at scale
- Utilizes DataFrames instead of RDDs to execute a subset of graph algorithms
- Functionality is similar to GraphX
 - "GraphX is to RDDs as GraphFrames are to DataFrames."

What is meant by "scale"?

- Can scale by either:
 - Using more powerful machines (vertical scaling)
 - Using more machines (horizontal scaling)

So... does GraphFrames "scale"?

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GraphFrames

The core data structure in the GraphFrames library is, unsurprisingly, a GraphFrame. It's a class that is instantiated with two SparkSQL DataFrames:

- Vertices (Nodes) A DataFrame of all the unique vertices/nodes of your graph
- Edges (Linkages) A DataFrame of all the edges/linkages between the vertices/nodes in your graph

GraphFrames

```
# Vertex DataFrame
v = spark.createDataFrame([
("a", "Alice", 34),
("b", "Bob", 36),
("c", "Charlie", 30),
("d", "David", 29),
("e", "Esther", 32),
("f", "Fanny", 36),
("g", "Gabby", 60)
], ["id", "name", "age"])
```

```
# Edge DataFrame
e = spark.createDataFrame([
("a", "b", "friend"),
("b", "c", "follow"),
("c", "b", "follow"),
("f", "c", "follow"),
("e", "f", "follow"),
("e", "d", "friend"),
("d", "a", "friend"),
("a", "e", "friend")
], ["src", "dst", "relationship"])
# Create a GraphFrame
g = GraphFrame(v, e)
```

```
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g = GraphFrame(v, e)
```

GraphFrames

```
# Vertex DataFrame
v = spark.createDataFrame([
("a", "Alice", 34),
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("f", "Fanny", 36),
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], ["id", "name", "age"])
```

```
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("a", "b", "friend"),
("b", "c", "follow"),
("c", "b", "follow"),
("f", "c", "follow"),
("e", "f", "follow"),
("e", "d", "friend"),
("d", "a", "friend"),
("a", "e", "friend")
], ["src", "dst", "relationship"])
# Create a GraphFrame
g = GraphFrame(v, e)
```

```
# Create a GraphFrame
g = GraphFrame(v, e)
```

Graph Algorithms in GraphFrames

- Breadth-first Search
- Connected Components
 - Strongly Connected Components
- Label Propagation Algorithm
- PageRank
- Shortest Path
- Triangle Count

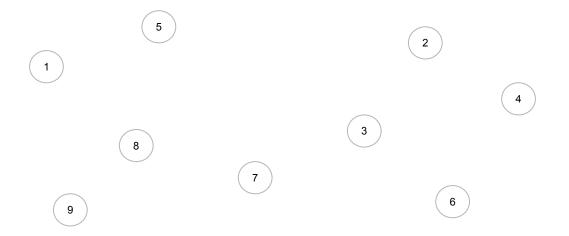
See the docs for more details on each of these.

Connected Components

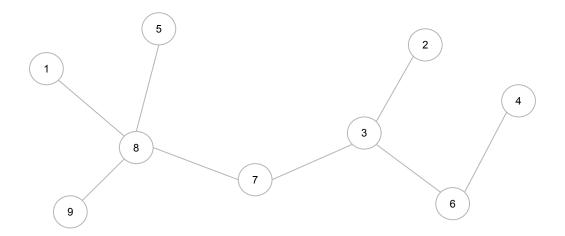
For a given node, what other nodes are connected to it, either directly or indirectly?

Connected Components algorithms make explicit connections between nodes in a graph by assigning each node a cluster ID. Nodes with the same cluster IDs are connected

Nodes	Edges	
ID	From	To
1	1	8
2	5	8
3	8	9
4	7	8
5	3	7
6	2	3
7	3	6
8	4	6
9		

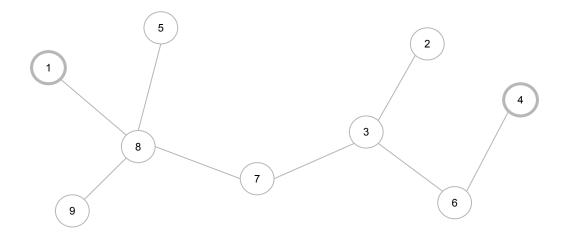


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7	3	6
8	4	6
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8	4	6	
9			

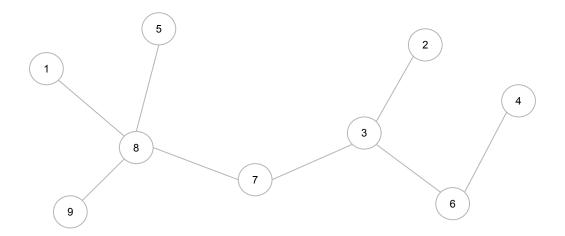
From the edges table, how would we know that nodes 1 and 4 are connected?



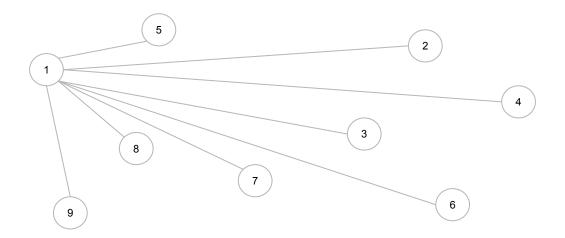
Nodes	Edges	
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3	8	9
4	7	8
5	3	7
6	2	3
7	3	6
8	4	6
9		

We know if nodes are connected only if there is a <u>direct</u> connection in the edge table. Any <u>indirect</u> connections that may exist can be determined via a connected components algorithm.

One approach is to iteratively reformulate the edge table until all nodes that are connected, either directly or indirectly, are made to be explicitly connected directly



Nodes	راء ا		
vodes	EQE	Edges	
ID	From	То	
1	1	8	
2	5	8	
3	8	9	
4	7	8	
5	3	7	
6	2	3	
7	3	6	
8	4	6	
9			



Nodes	Edg	Edges	
ID	From	To	
1	1	2	
2	1	3	
3	1	4	
4	1	5	
5	1	6	
6	1	7	
7	1	8	
8	1	9	
9			

Connected Components

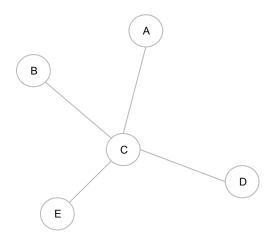
The Connected Component algorithm implemented in GraphFrames is called the <u>Alternating Algorithm</u>, as defined in the Google research paper from 2014:

Connected Components in MapReduce and Beyond

This algorithm works by iteratively reformulating the edge table by alternating two operations - the <u>Large Star</u> operation and the <u>Small Star</u> operation - until convergence.

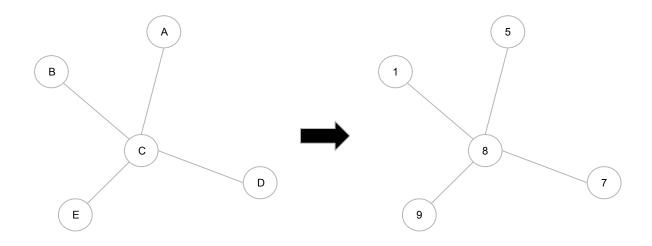
Alternating Algorithm - Initialization

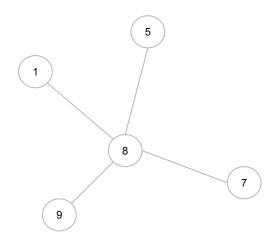
Randomly assign integer IDs to all nodes in graph

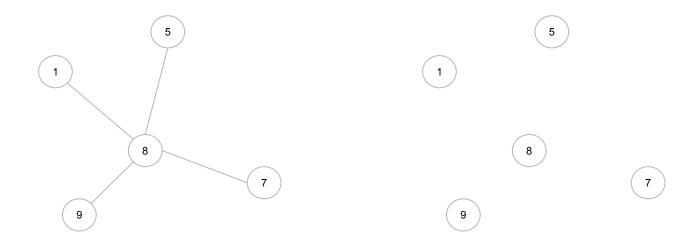


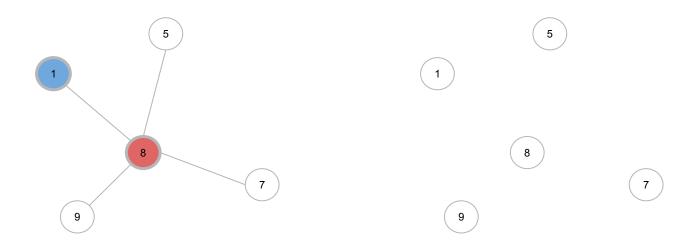
Alternating Algorithm - Initialization

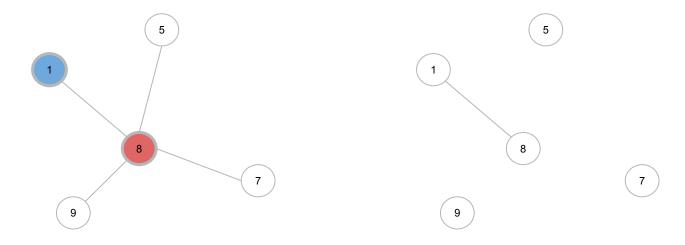
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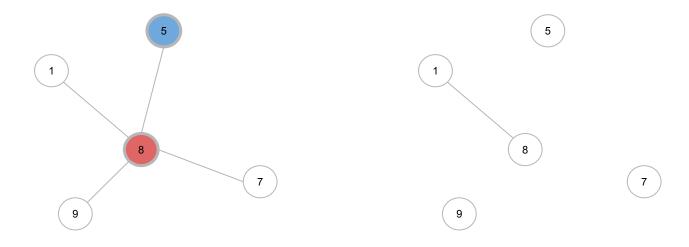


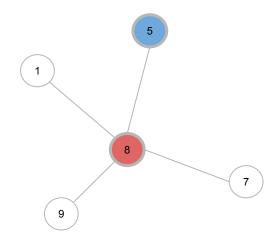


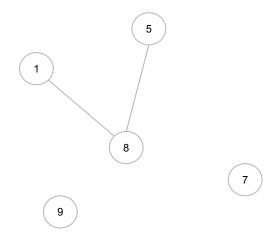


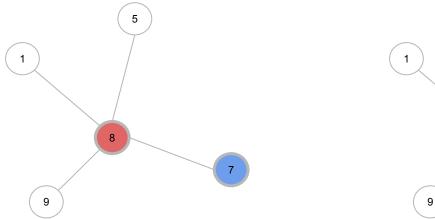


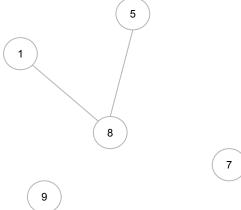


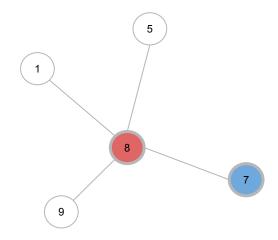


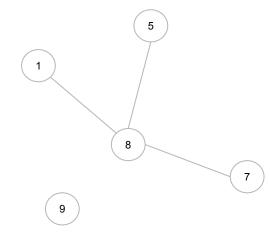


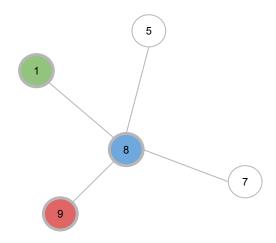


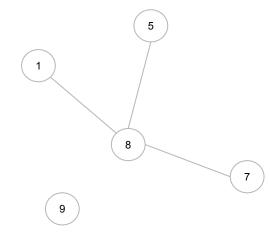


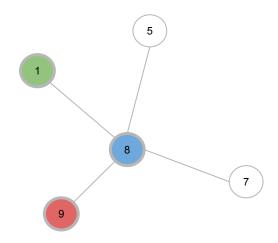


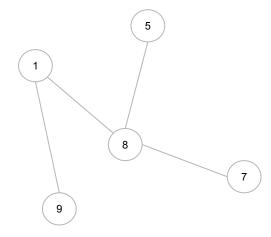


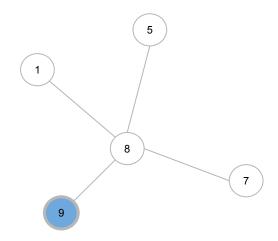


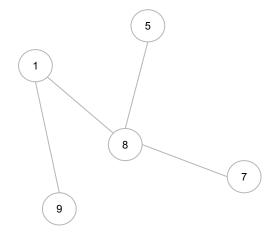






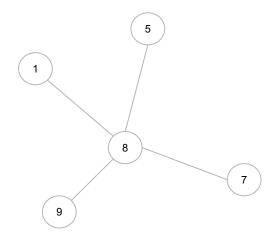


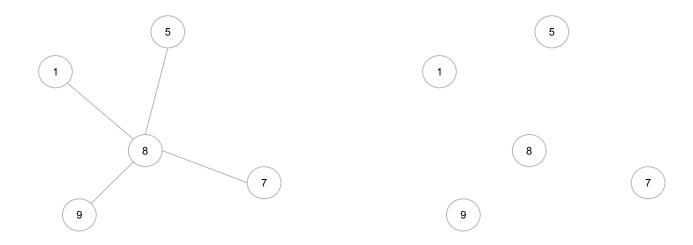


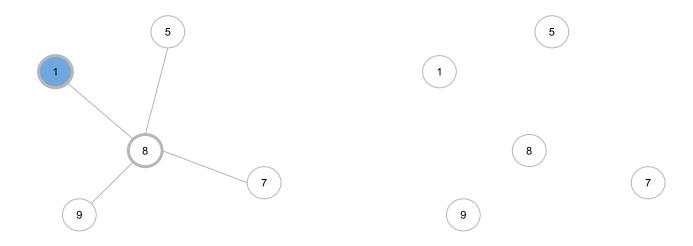


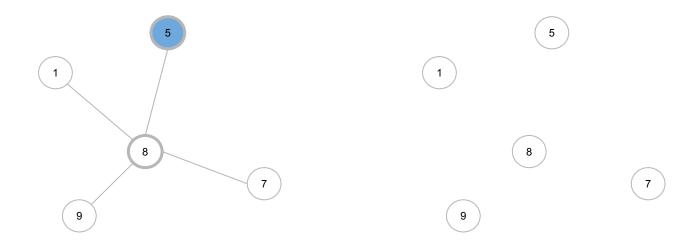
The large star operation has two theoretical guarantees:

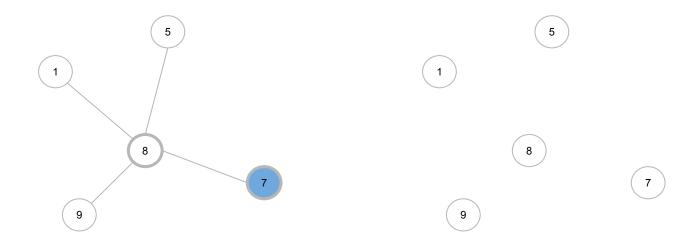
- 1. Preserves connectivity of components
- 2. Never increases the number of edges in the graph

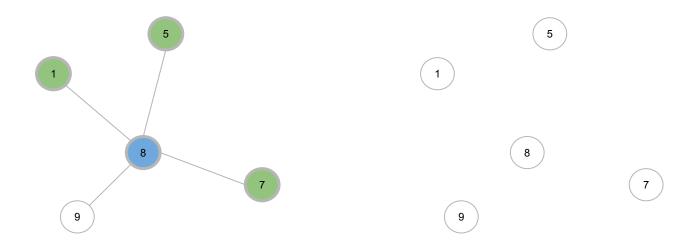


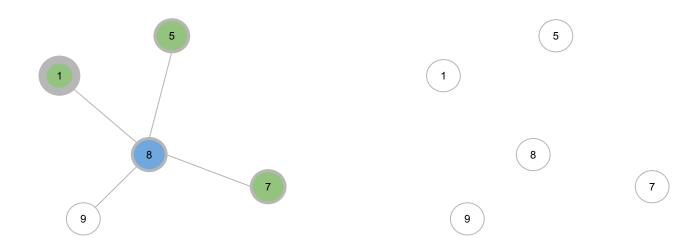


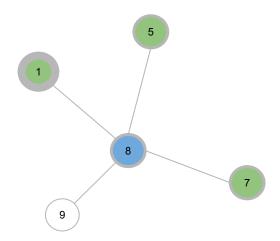


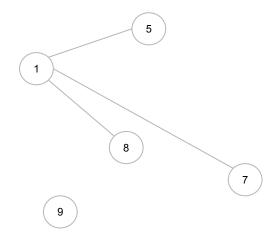


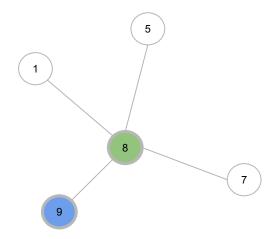


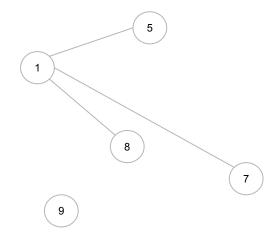


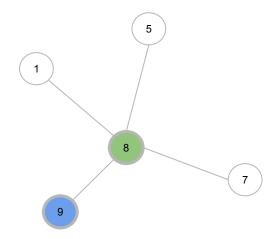


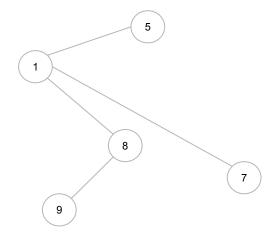






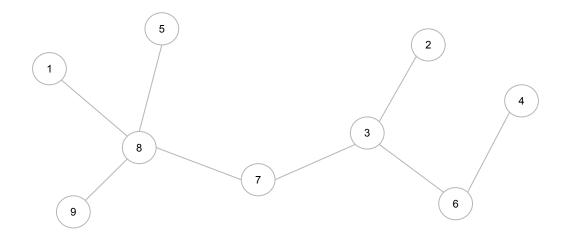






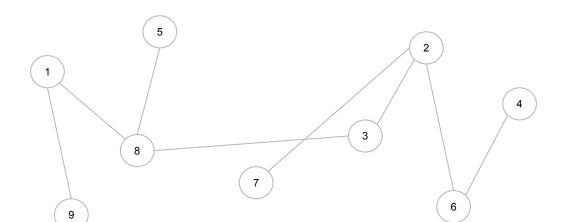
The small star operation has the same theoretical guarantees as the large star operation:

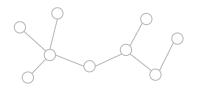
- 1. Preserves connectivity of components
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Nodes	Edges	
ID	From	To
1	1	8
2	5	8
3	8	9
4	7	8
5	3	7
6	2	3
7	3	6
8	4	6
9		

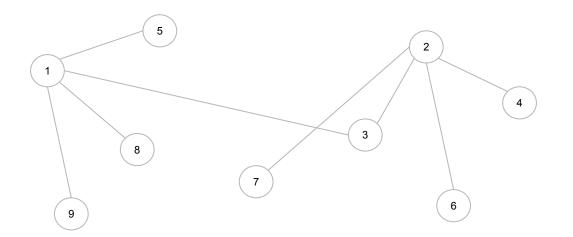
Step 1 - Large Star (1)





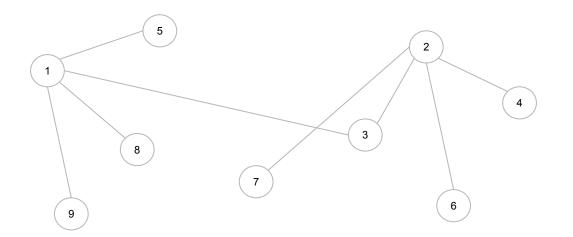
Nodes	Edges	
ID	From	To
1	1	9
2	1	8
3	5	8
4	3	8
5	2	7
6	2	3
7	2	6
8	4	6
9		

Step 2 - Small Star (1)



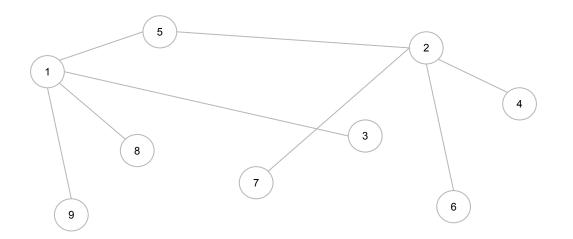
Nodes	Edges	
ID	From	To
1	1	9
2	1	8
3	1	5
4	1	3
5	2	7
6	2	3
7	2	6
8	2	4
9		

Step 3 - Large Star (2)



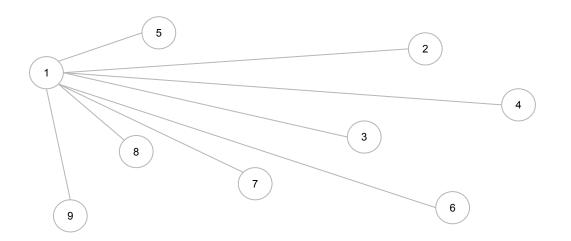
Nodes	Edges	
ID	From	To
1	1	9
2	1	8
3	1	5
4	1	3
5	2	7
6	2	3
7	2	6
8	2	4
9		

Step 4 - Small Star (2)



Edges	
From	To
1	9
1	8
1	5
1	3
2	7
2	5
2	6
2	4
	From 1 1 1 2 2 2

Step 5 - Large Star (2)



Nodes	Edges	
ID	From	To
1	1	9
2	1	8
3	1	5
4	1	3
5	1	7
6	1	5
7	1	6
8	1	4
9	o.	

GraphFrames - Large Star and Small Star

```
while (!converged) {
  val minNbrs1 = minNbrs(ee) // src >= min nbr
   ..persist(intermediateStorageLevel)
  ee = skewedJoin(ee, minNbrs1, broadcastThreshold, logPrefix)
    .select(col(DST).as(SRC), col(MIN_NBR).as(DST)) // src > dst
 ....distinct()
   .persist(intermediateStorageLevel)
  val-minNbrs2 = ee.groupBy(col(SRC)).agg(min(col(DST)).as(MIN NBR), count("*").as(CNT)) // src >> min nbr
    .persist(intermediateStorageLevel)
  ee = skewedJoin(ee, minNbrs2, broadcastThreshold, logPrefix)
 .select(col(MIN_NBR).as(SRC), col(DST)) // src <= dst
    .filter(col(SRC) =!= col(DST)) // src < dst</pre>
  ee = ee.union(minNbrs2.select(col(MIN_NBR).as(SRC), col(SRC).as(DST))) · //·src < dst
    .distinct()
```

GraphFrames - Convergence

```
val (currSum, cnt) = ee.select(sum(col(SRC).cast(DecimalType(20, 0))), count("*")).rdd
  .map { r =>
(r.getAs[BigDecimal](0), r.getLong(1))
-- }.first()
if (cnt != 0L && currSum == null) {
 throw new ArithmeticException(
       |The total sum of edge src IDs is used to determine convergence during iterations.
       |However, the total sum at iteration $iteration exceeded 30 digits (1e30),
        | which should happen only if the graph contains more than 200 billion edges.
       | If not, please file a bug report at https://github.com/graphframes/graphframes/issues.
       """.stripMargin)
·logInfo(s"$logPrefix Sum of assigned components in iteration $iteration: $currSum.")
if (currSum == prevSum) {
   converged = true
} else {
   prevSum = currSum
iteration += 1
```

Custom Graph Algorithms

GraphFrames provides primitives for developing graph algorithms

- aggregateMessages API
- Pregel API

Example: Belief propagation

Demo