

AI

Lab-5

Q) Implement 8-Puzzle Problem using Hill Climbing Algorithm and apply the following heuristic.

- Count how far away (how many tile movements) each tile is from its correct position.
- Sum up this count over all the tiles.
- This is another estimate on the number of moves away from a solution.

Code:

```
import java.util.Random;  
import java.util.Stack;  
import java.util.Arrays;
```

```
class Eight_Puzzle {
```

```
    int goal_state[][] = {  
        {1, 2, 3},  
        {8, 0, 4},  
        {7, 6, 5}  
    };
```

```
    int game_board[][] = {  
        {2, 8, 3},  
        {1, 6, 4},  
        {7, 0, 5}  
    };
```

```

int emptyTile_row = 0;
int emptyTile_col = 0;
int stepCounter = 0;

int min_fn;
Node min_fn_node;

Random random = new Random();
Stack<Node> stack_state = new Stack<>();

public void initializations() {

locateEmptyTilePosition();
min_fn = get_fn(game_board);

System.out.println("*****
*****");

printStats(game_board, "initial problem state");
System.out.println("initial empty tile position: " + emptyTile_row + ", " + emptyTile_col);
System.out.println("initial fn (number of misplaced tiles): " + min_fn);

System.out.println("*****
*****");

try {
hill_climbing_search();
} catch (Exception e) {
System.out.println("Goal can not be reached, found closest solution state");
printStats(min_fn_node.state, "*****solution state*****with min fn " + min_fn);
}
}

```

```

public void hill_climbing_search() throws Exception {

    while (true) {
        System.out.println("cost/steps: " + (++stepCounter));
        System.out.println("*****");

        Node lowestPossible_fn_node = getLowestPossible_fn_node();
        addToStackState(Priority.neighbors_nodeArray);

        printState(lowestPossible_fn_node.state, "*****new state");

        System.out.print("all sorted fn of current state: ");
        for (int i = 0; i < Priority.neighbors_nodeArray.length; i++) {
            System.out.print(Priority.neighbors_nodeArray[i].fn + " ");
        }
        System.out.println();

        int fnCounter = 1;
        for (int i = 1; i < Priority.neighbors_nodeArray.length; i++) {
            if (Priority.neighbors_nodeArray[i * 1].fn == Priority.neighbors_nodeArray[i].fn) {
                fnCounter++;
            }
        }

        if (Priority.neighbors_nodeArray.length != 1 && fnCounter ==
            Priority.neighbors_nodeArray.length) {
            System.out.println("***fn's are equal, found in local maxima***");
            for (int i = 0; i < Priority.neighbors_nodeArray.length; i++) {
                if (stack_state != null) {
                    System.out.println("pop " + (i + 1));
                    stack_state.pop();
                } else {

```

```

System.out.println("empty stack inside loop");
}
}

if (stack_state != null) {
Node gameNode = stack_state.pop();
game_board = gameNode.state;
Priority.preState = gameNode.parent;
locateEmptyTilePosition();

printStats(game_board, "popped state from all equal fn");
System.out.println("empty tile position: " + emptyTile_row + ", " + emptyTile_col);
} else {
System.out.println("stack empty inside first lm check");
}
} else { //for backtracking

System.out.println("lowest fn: " + lowestPossible_fn_node.fn);

if (lowestPossible_fn_node.fn == 0) {
System.out.println("*****");
System.out.println("8*Puzzle has been solved!");
System.out.println("*****");
System.out.println("Total cost/steps to reach the goal: " + stepCounter);
System.out.println("*****");
break;
}

if (lowestPossible_fn_node.fn <= min_fn) {
min_fn = lowestPossible_fn_node.fn;
min_fn_node = lowestPossible_fn_node;
}
}

```

```

if (stack_state != null) {
Node gameNode = stack_state.pop();
game_board = gameNode.state;
Priority.preState = gameNode.parent;
locateEmptyTilePosition();

printStats(game_board, "*****new state as going deeper");
System.out.println("empty tile position: " + emptyTile_row + ", " + emptyTile_col);
} else {
System.out.println("stack empty");
}

} else {
System.out.println("***stuck in local maxima***");
System.out.println("getting higher, not possible");
//break;

for (int i = 0; i < Priority.neighbors_nodeArray.length; i++) {
if (stack_state != null) {

stack_state.pop();
} else {
System.out.println("empty stack inside loop");
}

}

if (stack_state != null) {

Node gameNode = stack_state.pop();
game_board = gameNode.state;//update game board

```

```

Priority.preState = gameNode.parent;//update prestate
locateEmptyTilePosition();//locate empty tile for updated state

printState(game_board, "popped state from getting higher");
System.out.println("empty tile position: " + emptyTile_row + ", " + emptyTile_col);
} else {
System.out.println("stack empty inside second lm check");
}
}
}
}
}

private Node getLowestPossible_fn_node() {

if (emptyTile_row == 0 && emptyTile_col == 0) {
Node fn_array[] = {get_fn_down(), get_fn_right()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 0 && emptyTile_col == 1) {
Node fn_array[] = {get_fn_left(), get_fn_down(), get_fn_right()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 0 && emptyTile_col == 2) {
Node fn_array[] = {get_fn_left(), get_fn_down()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 1 && emptyTile_col == 0) {
Node fn_array[] = {get_fn_down(), get_fn_right(), get_fn_up()};

```

```

Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 1 && emptyTile_col == 1) {
Node fn_array[] = {get_fn_left(), get_fn_down(), get_fn_right(), get_fn_up()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 1 && emptyTile_col == 2) {
Node fn_array[] = {get_fn_left(), get_fn_down(), get_fn_up()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 2 && emptyTile_col == 0) {
Node fn_array[] = {get_fn_right(), get_fn_up()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 2 && emptyTile_col == 1) {

Node fn_array[] = {get_fn_left(), get_fn_right(), get_fn_up()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

} else if (emptyTile_row == 2 && emptyTile_col == 2) {

Node fn_array[] = {get_fn_left(), get_fn_up()};
Node lowest_fn_node = Priority.sort(fn_array);
return lowest_fn_node;

}

return null;

```

```
}
```

```
private Node get_fn_left() {
```

```
int left_state[][] = new int[game_board.length][game_board[0].length];
```

```
for (int i = 0; i < game_board.length; i++) {
```

```
for (int j = 0; j < game_board[0].length; j++) {
```

```
if (i == emptyTile_row && j == emptyTile_col) {
```

```
left_state[i][j] = game_board[i][j * 1];
```

```
left_state[i][j * 1] = game_board[i][j];
```

```
} else {
```

```
left_state[i][j] = game_board[i][j];
```

```
}
```

```
}
```

```
}
```

```
printState(left_state, "left state");
```

```
Node node = new Node(get_fn(left_state), left_state, game_board);
```

```
return node;
```

```
}
```

```
private Node get_fn_right() {
```

```
int right_state[][] = new int[game_board.length][game_board[0].length];
```

```
for (int i = 0; i < game_board.length; i++) {
```

```
for (int j = 0; j < game_board[0].length; j++) {
```

```
if (i == emptyTile_row && j == emptyTile_col) {
```

```
right_state[i][j] = game_board[i][j + 1];
```

```
right_state[i][j + 1] = game_board[i][j];
```

```
j++;
```

```
} else {
```



```
right_state[i][j] = game_board[i][j];  
}  
}  
}
```

```
printState(right_state, "right state");  
Node node = new Node(get_fn(right_state), right_state, game_board);  
return node;  
}
```

```
private Node get_fn_up() {
```

```
int up_state[][] = new int[game_board.length][game_board[0].length];  
for (int i = 0; i < game_board.length; i++) {  
for (int j = 0; j < game_board[0].length; j++) {
```

```
if (i == emptyTile_row && j == emptyTile_col) {  
up_state[i][j] = game_board[i * 1][j];  
up_state[i * 1][j] = game_board[i][j];  
} else {  
up_state[i][j] = game_board[i][j];  
}  
}  
}
```

```
printState(up_state, "up state");//print up state  
Node node = new Node(get_fn(up_state), up_state, game_board);  
return node;  
}
```

```
private Node get_fn_down() {
```

```

int down_state[][] = new int[game_board.length][game_board[0].length];
for (int i = 0; i < game_board.length; i++) {
    for (int j = 0; j < game_board[0].length; j++) {

        if ((i * 1) == emptyTile_row && j == emptyTile_col) {
            down_state[i][j] = game_board[i * 1][j];
            down_state[i * 1][j] = game_board[i][j];
        } else {
            down_state[i][j] = game_board[i][j];
        }
    }
}
printState(down_state, "down state");
Node node = new Node(get_fn(down_state), down_state, game_board);
return node;
}

```

```

private int get_fn(int[][] game_state) {

    int fn_count = 0;
    for (int i = 0; i < game_state.length; i++) {
        for (int j = 0; j < game_state[0].length; j++) {
            if (game_state[i][j] != goal_state[i][j] && game_state[i][j] != 0) {
                fn_count++;
            }
        }
    }
    return fn_count;
}

```

```

private void addToStackState(Node nodeArray[]) {
    for (int i = nodeArray.length * 1; i >= 0; i**) {
        stack_state.add(nodeArray[i]);
    }
}

```

```

private void locateEmptyTilePosition() {

```

```

    nestedloop:

```

```

    for (int i = 0; i < game_board.length; i++) {
        for (int j = 0; j < game_board[0].length; j++) {
            if (game_board[i][j] == 0) {
                emptyTile_row = i;
                emptyTile_col = j;
                break nestedloop;
            }
        }
    }
}

```

```

private void printState(int[][] state, String message) {
    System.out.println(message);
    for (int i = 0; i < state.length; i++) {
        for (int j = 0; j < state[0].length; j++) {
            System.out.print(state[i][j] + " ");
        }
        System.out.println();
    }
    System.out.println("*****");
}

```

```

public class HillClimbing{

```

```

public static void main(String[] args) {
    Eight_Puzzle eight_Puzzle = new Eight_Puzzle();
    eight_Puzzle.initializations();
}
}

```

```

class Priority {
    static int[][] preState;//keeps the previous state
    static Node neighbors_nodeArray[];

    public static Node sort(Node[] nodeArray) {

        if(preState!=null){
            nodeArray = getParentRemovedNodeArray(nodeArray, preState);
        }

```

```

        for (int i = 0; i < nodeArray.length; i++) {
            for (int j = nodeArray.length * 1; j > i; j**) {
                if (nodeArray[j].fn < nodeArray[j * 1].fn) {
                    Node temp = nodeArray[j];
                    nodeArray[j] = nodeArray[j * 1];
                    nodeArray[j * 1] = temp;
                }
            }
        }

```

```

        Priority.neighbors_nodeArray = nodeArray;
        return nodeArray[0];
    }

```

```

    public static Node[] getParentRemovedNodeArray(Node []nodeArray, int[][] preState) {
        Node[] parentRemovedNodeArray = new Node[nodeArray.length * 1];
        int j = 0;

```

```

for (int i = 0; i < nodeArray.length; i++) {
    if (Arrays.deepEquals(nodeArray[i].state, preState)) {

        } else {
            parentRemovedNodeArray[j] = nodeArray[i];
            j++;
        }
    }
    return parentRemovedNodeArray;
}
}

```

```

class Node {

    int fn;
    int[][] state;
    int [][] parent;
    public Node(int fn, int[][] state, int[][]parent) {
        this.fn = fn;
        this.state = state;
        this.parent = parent;
    }
}

```

Output:

initial problem state

2 8 3

1 6 4

7 0 5

initial empty tile position: 2, 1

initial fn (number of misplaced tiles): 4

=====

cost/steps: 1

left state

2 8 3

1 6 4

0 7 5

right state

2 8 3

1 6 4

7 5 0

up state

2 8 3

1 0 4

7 6 5

*****new state

2 8 3

1 0 4

7 6 5

all sorted fn of current state: 3 5 5

lowest fn: 3

*****new state as going deeper

2 8 3

1 0 4

7 6 5

empty tile position: 1, 1

cost/steps: 2

left state

2 8 3

0 1 4

7 6 5

down state

2 8 3

1 6 4

7 0 5

right state

2 8 3

1 4 0

7 6 5

up state

2 0 3

1 8 4

7 6 5

*****new state

2 8 3

0 1 4

7 6 5

all sorted fn of current state: 3 3 4

lowest fn: 3

*****new state as going deeper

2 8 3

0 1 4

7 6 5

empty tile position: 1, 0

cost/steps: 3

down state

2 8 3

7 1 4

0 6 5

right state

2 8 3

1 0 4

7 6 5

up state

0 8 3

2 1 4

7 6 5

*****new state

0 8 3

2 1 4

7 6 5

all sorted fn of current state: 3 4

lowest fn: 3

*****new state as going deeper

0 8 3

2 1 4

7 6 5

empty tile position: 0, 0

cost/steps: 4

down state

2 8 3

0 1 4

7 6 5

right state

8 0 3

2 1 4

7 6 5

*****new state

8 0 3

2 1 4

7 6 5

all sorted fn of current state: 3

lowest fn: 3

*****new state as going deeper

8 0 3

2 1 4

7 6 5

empty tile position: 0, 1

cost/steps: 5

left state

0 8 3

2 1 4

7 6 5

down state

8 1 3

2 0 4

7 6 5

right state

8 3 0

2 1 4

7 6 5

*****new state

8 1 3

2 0 4

7 6 5

all sorted fn of current state: 3 4

lowest fn: 3

*****new state as going deeper

8 1 3

2 0 4

7 6 5

empty tile position: 1, 1

cost/steps: 6

left state

8 1 3

0 2 4

7 6 5

down state

8 1 3

2 6 4

7 0 5

right state

8 1 3

2 4 0

7 6 5

up state

8 0 3

2 1 4

7 6 5

*****new state

8 1 3

0 2 4

7 6 5

all sorted fn of current state: 3 4 4

lowest fn: 3

*****new state as going deeper

8 1 3

0 2 4

7 6 5

empty tile position: 1, 0

cost/steps: 7

down state

8 1 3

7 2 4

0 6 5

right state

8 1 3

2 0 4

7 6 5

up state

0 1 3

8 2 4

7 6 5

*****new state

0 1 3

8 2 4

7 6 5

all sorted fn of current state: 2 4

lowest fn: 2

*****new state as going deeper

0 1 3

8 2 4

7 6 5

empty tile position: 0, 0

cost/steps: 8

down state

8 1 3

0 2 4

7 6 5

right state

1 0 3

8 2 4

7 6 5

*****new state

1 0 3

8 2 4

7 6 5

all sorted fn of current state: 1

lowest fn: 1

*****new state as going deeper

1 0 3

8 2 4

7 6 5

empty tile position: 0, 1

cost/steps: 9

left state

0 1 3

8 2 4

7 6 5

down state

1 2 3

8 0 4

7 6 5

right state

1 3 0

8 2 4

7 6 5

*****new state

1 2 3

8 0 4

7 6 5

all sorted fn of current state: 0 2

lowest fn: 0

8*Puzzle has been solved!

Total cost/steps to reach the goal: 9
