Uploading the maps from the cluster

In [8]:

```
filename1 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so skymap deep56 30GHz.fits"
filename2 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so_skymap_deep56_44GHz.fits"
filename3 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so_skymap_deep56_70GHz.fits"
filename4 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so skymap deep56 100GHz.fits"
filename5 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so_skymap_deep56_143GHz.fits"
filename6 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so_skymap_deep56_145GHz.fits"
filename7 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so skymap deep56 217GHz.fits"
filename8 = "/moto/hill/projects/actpol/SO_Sims_LAMBDA/d56/SO_skymaps_deep5
6/so_skymap_deep56_353GHz.fits"
imap30 = enmap.read map(filename1)
imap44 = enmap.read map(filename2)
imap70 = enmap.read map(filename3)
imap100 = enmap.read map(filename4)
imap143 = enmap.read_map(filename5)
imap145 = enmap.read_map(filename6)
imap217 = enmap.read map(filename7)
imap353 = enmap.read map(filename8)
print("Map shape and dtype (same for all the maps):")
print(imap44.shape, imap44.dtype)
fmap30 = np.ndarray.flatten(imap30)
fmap44 = np.ndarray.flatten(imap44)
fmap70 = np.ndarray.flatten(imap70)
fmap100 = np.ndarray.flatten(imap100)
fmap143 = np.ndarray.flatten(imap143)
fmap145 = np.ndarray.flatten(imap145)
fmap217 = np.ndarray.flatten(imap217)
fmap353 = np.ndarray.flatten(imap353)
```

Defining the R Matrix

The r matrix is a matrix of size (n_map X n_map), where each entry is the sum of the multiplied entries of the specified indices in map_array, which is then divided by n_pix. Note that each entry in map_array is the corresponding flattened map.

In []:

```
r = np.zeros([n_map,n_map])

for i in range(n_map):
    for j in range(n_map):
        r[i][j] = np.sum((map_array[i] * map_array[j])) / n_pix
```

Defining the B Matrix

The b matrix here is a 3D matrix of size (n_map X n_map X n_map), where each entry is the sum of the product of the corresponding flattened map, now with another dimension represented by k, and is still divided by n_pix.

In [5]:

```
b = np.zeros([n_map,n_map,n_map])

for i in range(n_map):
    for j in range(n_map):
        for k in range(n_map):
            b[i][j][k] = np.sum(map_array[i] * map_array[j] * map_array[k])
/ n_pix
```

Saving Arrays as Files to Reduce Memory Consumption

In [6]:

```
numpy.save('r_arr',r)
numpy.save('b_arr',b)
```

In [9]:

```
np.save('imap30',imap30)
np.save('imap44',imap44)
np.save('imap70',imap70)
np.save('imap100',imap100)
np.save('imap143',imap143)
np.save('imap145',imap145)
np.save('imap217',imap217)
np.save('imap353',imap353)
```

In []:

```
np.save('map30',fmap30)
np.save('map44',fmap44)
np.save('map70',fmap70)
np.save('map100',fmap100)
np.save('map143',fmap143)
np.save('map145',fmap145)
np.save('map217',fmap217)
np.save('map353',fmap353)
```

DO NOT RUN CODE ABOVE THIS CELL

All the code in the above cells is for informational purposes i.e. displaying how the R and B matrices were initially constructed, and method for saving files so that may be loaded in using the given file name (all files use the .npy extension)

Packages for performing the optimization

In [2]:

```
import numpy as np, numpy.random
import statistics
from statistics import mean, pvariance
import scipy
from scipy.optimize import minimize, NonlinearConstraint
```

Packages for performing map manipulations

In [2]:

```
from __future__ import print_function
from pixell import enmap,utils
import matplotlib.pyplot as plt
from pixell import enplot
import os,sys
import urllib.request
```

Loading in Unflattened Map Data

The unflattened maps are used later on to show CMB maps. For now, the data works with flattened maps, particularly to build the R and B matrices displayed in the cells above. They have already been built, saved, and are loaded in 'map_array' below.

Each map shape represents the number of total pixels, which is of the form (2182,9455,1) and dim=3.

In [3]:

```
imap30 = np.load('imap30.npy')
imap44 = np.load('imap44.npy')
imap70 = np.load('imap70.npy')
imap100 = np.load('imap100.npy')
imap143 = np.load('imap143.npy')
imap145 = np.load('imap145.npy')
imap217 = np.load('imap217.npy')
imap353 = np.load('imap353.npy')
```

Loading in Matrix Data

```
In [3]:
```

```
r = np.load('r_arr.npy')
b = np.load('b_arr.npy')
```

Defining ΔT

I define the number of maps, number of total pixels, and flattened maps (which are now 1D numpy arrays), as this was necessary for building the matrices and other computations.

In [4]:

```
n_map = 8
n_pix = 2182*9455
map_array = [np.load('map30.npy'),np.load('map44.npy'),np.load('map70.npy'),np.load('map100.npy'),np.load('map143.npy'),np.load('map145.npy'),np.load('map217.npy'),np.load('map353.npy')]
```

Optimizing the variance

```
In [6]:
```

```
w0 = np.array([.125,.125,.125,.125,.125,.125,.125])
a = np.ones(len(w0))
#defines a lambda function that returns dot product of weights and array of
fun = lambda w: np.dot(w,a)
print("The sum of all the weights is:")
print(fun(w0))
#nonlinear constraint that implements the function and sets the constraint
con = NonlinearConstraint(fun,1,1)
#defines a lambda function that implements the variance equation
var = lambda w: np.dot(np.dot(w,r),w)
print("The variance is:")
print(var(w0))
#minimization method ()
mini = minimize(var,w0,method='SLSQP',constraints=con)
weights_var = mini.x
print(mini.x)
print()
print(var(mini.x))
print()
print(fun(mini.x))
The sum of all the weights is:
The variance is:
30332.48984382074
[ 0.16548252  0.10405147 -2.95107189  1.93440481  0.79667526
0.5442029
 0.52879756 -0.12254262]
12885.913669980198
0.9999999999998
```

Optimizing the skewness

In [8]:

```
a = np.ones(len(w0))
#defines a lambda function that returns dot product of weights and array of
ones
fun = lambda w: np.dot(w,a)
print("The sum of all the weights is:")
print(sum(w0))
#nonlinear constraint that implements the function and sets the constraint
bounds
con = NonlinearConstraint(fun,1,1)
#defines a lambda function that implements the variance equation
skew = lambda w: abs(np.dot(np.dot(np.dot(w,b),w), w))
#minimization method
n iter = 100
min_skew_arr = np.zeros(n_iter)
min_skew_weights_arr = np.zeros((n_iter,8))
for i in range(n_iter):
    w0 = np.random.dirichlet(np.ones(8), size=1)[0]
    mini = minimize(skew,w0,method='SLSQP',constraints=con)
    weights_skew = mini.x
    skewness_val = skew(mini.x)
    min_skew_weights_arr[i] = weights_skew
    min_skew_arr[i] = skewness_val
min_skew_val = np.argmin(min_skew_arr) #can plot array values
print()
print("The smallest skewness value for 100 iterations is:")
print(min_skew_arr[min_skew_val])
print()
print("The solution array at the smallest skewness value is:")
print(min_skew_weights_arr[min_skew_val])
```

```
The sum of all the weights is:
1.0

The smallest skewness value for 100 iterations is:
8.102038436174245e-05

The solution array at the smallest skewness value is:
[ -1.93716447   6.68487575   -6.55649399   4.98213832   -42.59911
142
54.78961549 -16.02020995   1.65635026]
```

In [9]:

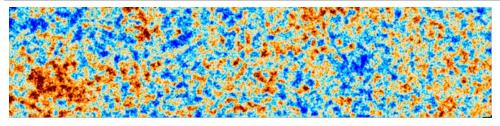
```
imap_array = np.array([imap30,imap44,imap70,imap100,imap143,imap145,imap217
,imap353])
yp_var = imap30.copy()
yp_var *= 0.
for i in range(n_map):
   yp_var += imap_array[i]*weights_var[i]
print(yp_var)
yp_skew = imap30.copy()
yp_skew *= 0
for i in range(n_map):
    yp_skew += imap_array[i]*weights_skew[i]
print(yp_skew)
[[[ 57.07162856
                  58.04260984
                               59.62865946 ... -0.29197655
    -4.50279207 -8.39625092]
 [ 53.02689343
                  53.98265651
                               56.50107275 ...
                                               6.02794916
     4.644423
                  2.18457073]
 [ 50.19762036
                  52.38265102
                               56.01501181 ... 14.66181657
    16.49981471 15.47660926]
 [ 57.48272055 47.8738915
                               40.25440711 ... -170.60003797
  -162.75597507 -152.56591185]
 [ 65.20591467
                57.81174522
                               52.25058953 ... -170.00285968
  -162.82751191 -152.99239267]
                               62.45252181 ... -171.31875561
 [ 70.30875788 65.36743423
  -164.47482965 -154.42585164]]]
[[ 188.16077581 197.89948735 209.89117016 ... -108.54371071
   -99.7150596 -85.79694524]
 [ 200.76516787 214.43740782 228.00239974 ... -153.03997308
  -156.95568315 -139.30556019]
 [ 214.61025162 222.85007831 230.70171599 ... -170.16868434
  -183.29477468 -164.55036843]
 [ 516.01050234 527.76378
                               513.38613503 ... 9.60099222
    33.51908031 44.78903342]
 [ 531.3874654 538.3030439
                              514.55090705 ... -1.62182862
    21.59958397 32.86402372]
 [ 546.37968514 550.27509581 522.32979225 ... -2.34326107
    13.86332205 16.29494863]]]
```

Map of the Variance

In [10]:

```
plots = enplot.plot(yp_var, range=300,mask=0)

def eshow(x,**kwargs): enplot.show(enplot.plot(x,**kwargs))
eshow(yp_var)
```

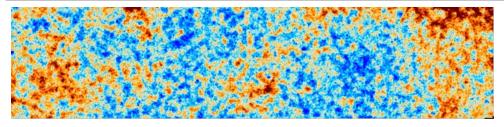


Map of the Skewness

In [11]:

```
plots = enplot.plot(yp_skew, range=300,mask=0)

def eshow(x,**kwargs): enplot.show(enplot.plot(x,**kwargs))
eshow(yp_skew)
```

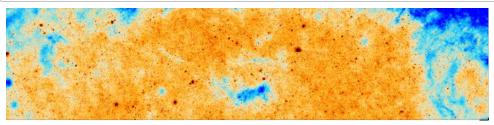


Map of the (Variance - Skewness)

In [12]:

```
plots = enplot.plot(yp_var-yp_skew, range=300,mask=0)

def eshow(x,**kwargs): enplot.show(enplot.plot(x,**kwargs))
eshow(yp_var-yp_skew)
```

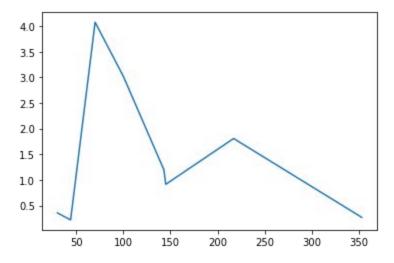


Comparison of the Variance and Skewness

In [13]:

```
freq = np.array([30,44,70,100,143,145,217,353])

diff = weights_var - (weights_skew / 10)
plt.plot(freq, abs(diff))
plt.show()
```

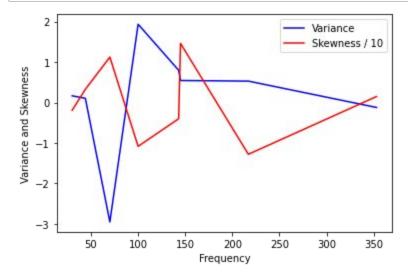


Plot of the Sets of Weights

In [14]:

```
freq = np.array([30,44,70,100,143,145,217,353])

plot = plt.plot(freq, weights_var,'b-',freq,weights_skew/10,'r')
plt.xlabel('Frequency')
plt.ylabel('Variance and Skewness')
plt.legend(['Variance','Skewness / 10'])
plt.show()
print("Note that the skewness weights are reduced to a tenth of their original value to better compare to the variance weights.")
```



Note that the skewness weights are reduced to a tenth of their original value to better compare to the variance weights.

Optimizing for Both Variance and Skewness

```
In [15]:
```

```
n_{iter} = 100
a = np.ones(len(w0))
#defines a lambda function that returns dot product of weights and array of
fun = lambda w: np.dot(w,a)
#nonlinear constraint that implements the function and sets the constraint
hounds
con = NonlinearConstraint(fun,1,1)
x_arr = []
vy_arr = []
sy_arr = []
#minimization method
def multi_mini(x,y):
    min_combo_weights_arr = np.zeros((n_iter,8))
    min_combo_arr = np.zeros(n_iter)
    for i in range(n_iter):
        w0 = np.random.dirichlet(np.ones(8),size=1)[0]
        #defines a lambda function that implements the variance equation
        var = lambda w: np.dot(np.dot(w,r),w)
        skew = lambda w: abs(np.dot(np.dot(np.dot(w,b),w), w))
        combo_func = lambda w: x*var(w) + y*skew(w)
        minimum = minimize(combo_func,w0,method='SLSQP',constraints=con)
        weights combo = mini.x
        combo_val = combo_func(mini.x)
        min_combo_weights_arr[i] = weights_combo
        min_combo_arr[i] = combo_val
    #appends to x and var/skew arrays after finding smallest var/skew
    x_{arr.append(x)}
    vy_arr.append(var(minimum.x))
    sy_arr.append(skew(minimum.x))
    min_combo_val = np.argmin(min_skew_arr)
    #checking that the var and skew arrays are the same as the combined arr
ays when the weights eliminate one statistic
    if (x == 1 \text{ and } y == 0):
        if (weights var.all() == minimum.x.all()):
            print("Variance end-checker: passed")
        else:
```

```
print("Variance end-checker: failed")
    if (x == 0 \text{ and } y == 1):
        if (weights_skew.all() == minimum.x.all()):
            print("Skewness end-checker: passed")
        else:
            print("Skewness end-checker: failed")
    print()
    print("Variance weight:")
    print(x)
    print("Skewness weight:")
    print(y)
    #print("The solution array for the given linear combination of var and
 skew:")
    #print(minimum.x)
    print("Variance:")
    print(var(minimum.x))
    print("Skewness:")
    print(skew(minimum.x))
    print()
    print()
multi mini(0,1)
multi_mini(.5,.5)
multi_mini(.7,.3)
multi_mini(.8,.2)
multi_mini(.85,.15)
multi_mini(.9,.1)
multi_mini(.95,.05)
multi_mini(.96,.04)
multi_mini(.969,.031)
multi_mini(.97,.03)
multi_mini(.971,.029)
multi_mini(1,0)
\#x-axis = x
#y-axis = var/skew
```

```
Skewness end-checker: passed

Variance weight:
0
Skewness weight:
1
Variance:
57836.64283599049
Skewness:
0.3852223605033438

Variance weight:
0.5
Skewness weight:
```

Variance weight: 0.7 Skewness weight: 0.3 Variance: 251469.1530190134 Skewness: 48.70291581094653

41715.79041558348

1.7455476616205907

0.5

Variance:

Skewness:

Variance weight: 0.8 Skewness weight: 0.2 Variance: 13751.827863396591 Skewness: 0.1602044224174267

Variance weight: 0.85
Skewness weight: 0.15

Variance:

15365.257682387759

Skewness:

0.13841367847255956

Variance weight:

0.9

Skewness weight:

0.1

Variance:

13106.314745245772

Skewness:

0.2660811406662528

Variance weight:

0.95

Skewness weight:

0.05

Variance:

13021.042637229444

Skewness:

0.003929609624402662

Variance weight:

0.96

Skewness weight:

0.04

Variance:

12997.941075352011

Skewness:

0.0002748141465079666

Variance weight:

0.969

Skewness weight:

0.031

Variance:

12953.872739668457

Skewness:

0.01039761776564922

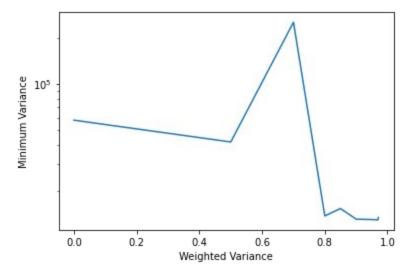
```
Variance weight:
0.97
Skewness weight:
0.03
Variance:
13088.190329160256
Skewness:
0.001081158529326577
Variance weight:
0.971
Skewness weight:
0.029
Variance:
13439.310181988509
Skewness:
0.775646545489677
Variance end-checker: passed
Variance weight:
Skewness weight:
Variance:
12885.91368755922
Skewness:
80891.409531262
```

Plot of the Minimum Variance Values

In [22]:

```
plt.plot(x_arr, vy_arr)
plt.yscale("log")

plt.xlabel("Weighted Variance")
plt.ylabel("Minimum Variance")
plt.show()
```



Plot of the Minimum Skewness Values

In [23]:

```
plt.plot(x_arr, sy_arr)
plt.yscale("log")

plt.xlabel('Weighted Variance')
plt.ylabel('Minimum Skewness')
plt.show()
```

